

Title (en)
IMPROVED ROBOTIC ARM.

Title (de)
VERBESSERTER ROBOTERARM.

Title (fr)
BRAS ROBOTIQUE AMELIORE.

Publication
EP 0124540 A4 19860710 (EN)

Application
EP 83903263 A 19830921

Priority
US 43831482 A 19821101

Abstract (en)
[origin: WO8401740A1] The invention pertains to robot arms. It is directed at eliminating the movement of robot arm segments caused by external forces such as inadvertent bumping, movement caused by motor slippage and movement caused to one arm segment by the movement of the other arm segments. The invention includes a robot arm (10) comprising a multi-axis, open-loop system of coupled structural members (16, 28, 32, 36) wherein each structural member (16, 28, 32, 36) is pivotably coupled to one another to form a member of joints (26, 30, 34, 38) wherein position calibration is provided by way of position sensors (124, 152, 156) disposed at each joint (26, 30, 34, 38), and control means (12, 24, 22) for manipulating each joint (26, 30, 34, 36) in a predetermined manner and for monitoring the output of each position sensor (124, 152, 156), the control means (12, 14, 22) first causing all structural members (16, 28, 32, 36) to move with respect to one another so that each position sensor (124, 152, 156) outputs a home signal, the control means (24, 12, 22) then manipulating each structural member (16, 28, 32, 36) in a predetermined sequence until each structural member (16, 28, 32, 36) is caused to be within a predetermined distance from its home position.

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- No relevant documents have been disclosed
- No relevant documents have been disclosed

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