

Title (en)

Automated installation to put bricks onto the interior face of a vessel.

Title (de)

Automatisierte Vorrichtung zum Ausmauern eines Gefäßes.

Title (fr)

Installation automatisée pour briqueter la paroi intérieure d'une enceinte.

Publication

EP 0248251 A1 19871209 (FR)

Application

EP 87107127 A 19870516

Priority

LU 86458 A 19860605

Abstract (en)

[origin: US4786227A] The apparatus of the present invention utilizes a bricklaying robot which comprises an automatic brick-handling or grabbing device fastened to the end of a main arm which is carried by a frame mounted on a work platform; and which is radially movable relative to the platform. Circular movement of the arm and of the grabbing device relative to the vertical axis of the work platform is generated as result of a rotation of the platform about this vertical axis. The present invention also utilizes a storage table which is mounted underneath the main arm of the robot, so as to be movable along a vertical axis and rotatable about the axis. The present invention further includes an automatic depalletizing mechanism comprising a pivoting arm, of which one of the ends is equipped with a brick-grasping device and the other end is mounted pivotally on a support sliding parallel to the main arm of the robot between two rails of the frame. This brick lining apparatus is less bulky than known prior art apparatuses and offers monitoring personnel a greater degree of safety.

Abstract (fr)

L'installation comporte une plate-forme de travail (20) déplaçable verticalement et capable de tourner autour de son axe vertical, un dispositif pour monter et descendre des palettes de briques (42), un automate de dépalettisation (78), un robot de manutention (62), ainsi qu'un poste de surveillance (24). Le robot (62) est constitué essentiellement d'un grappin automatique (70) de manutention des briques, fixé à l'extrémité d'un bras principal (64) qui est porté par un châssis (22) monté sur la plate-forme (20) et qui est déplaçable radialement par rapport à la plate-forme (20). Pour réduire l'encombrement, le déplacement circulaire du bras (64) et du grappin (70) par rapport à l'axe vertical est engendré par une rotation de la plate-forme (20) autour de cet axe vertical.

IPC 1-7

F27D 1/16; **C21C 5/44**

IPC 8 full level

C21C 5/44 (2006.01); **F27D 1/16** (2006.01)

CPC (source: EP US)

C21C 5/441 (2013.01 - EP US); **F27D 1/1621** (2013.01 - EP US)

Citation (search report)

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Designated contracting state (EPC)

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EP 0248251 A1 19871209; **EP 0248251 B1 19900228**; AT E50632 T1 19900315; DE 3761783 D1 19900405; ES 2013271 B3 19900501; JP 2584231 B2 19970226; JP S62293084 A 19871219; LU 86458 A1 19880120; US 4786227 A 19881122

DOCDB simple family (application)

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