

Title (en)
VICE

Publication
EP 0372563 A3 19910710 (DE)

Application
EP 89122632 A 19891208

Priority
DE 3841527 A 19881209

Abstract (en)
[origin: EP0372563A2] On a stationary basic body (10), the vice has a movable gripping jaw (11) and a stationary gripping jaw (12). Furthermore, there are draw-down jaws which enable the workpiece to be secured in the correct position during clamping by means of the drive device (16). Due to the fact that the draw-down jaw (18) can be moved up to a stop on the basic body (10), the draw-down forces, which essentially counteract the clamping force, being derived from a force-transmitting element (13) known per se which absorbs the deformations of the vice, greater positional constancy and thus greater precision is achieved. <IMAGE>

IPC 1-7
B23Q 3/06; **B25B 1/10**; **B25B 1/24**

IPC 8 full level
B25B 1/10 (2006.01); **B25B 1/24** (2006.01)

CPC (source: EP)
B25B 1/103 (2013.01); **B25B 1/2473** (2013.01)

Citation (search report)

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