

Title (en)

METHOD AND COMPENSATION OF THE DISTURBED PARTS OF THE SIGNALS IN A MEASURING SYSTEM

Publication

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Application

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Priority

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Abstract (en)

[origin: EP0392036A1] The system has a specific number ($i = 1$ to I) of measuring channels, each measuring signal ($x_{(i)}$) having a channel-independent component(s) which is weighted with a channel-dependent compensation coefficient ($A_{(i)}$), and an additive, channel-dependent interfering component ($u_{(i)}$). Initially, a preliminary compensation value (sum) is formed from the measuring signals and the compensation coefficients and preliminary compensated measuring signal values ($sk_{(i)}$) are formed with said compensation value. Measuring channels ($j = 1$ to J) with a high degree of interference are then sought. For these channels a respective approximation value (\hat{n}) of the interference signal is determined and used to form a correction value ($@$). A final compensation value (sum'), with which the final compensated measuring signal values (sk') are calculated is formed using the correction values ($@$).

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