

Publication

EP 0712805 A3 19960605

Application

EP 95119390 A 19930518

Priority

- EP 95119390 A 19930518
- EP 93108095 A 19930518

Abstract (en)

[origin: EP0712805A2] A reach forklift comprises: a forklift body; left and right straddle arms; a pair of load wheels supported in a steerable manner in the vicinity of front ends of the left and right straddle arms, respectively; driving means for steering the load wheels, the load wheels and the driving means being housed in the straddle arms; a drive wheel disposed in a rear portion of the forklift body; and a steering wheel for steering the drive wheel; steering angle detecting means for detecting steering angles of the left and right load wheels and the drive wheel; a control device (116) for, in a first mode, determining a steering angle (θ_L, θ_R) of one of said load wheels (105, 106) by multiplying a steering angle (θ_D) of said drive wheel (104) by a predetermined steering angle gain (GL, GR), for calculating a turning centre from a geometric relationship between said drive wheel (104) and said one load wheel, and for controlling the steering so that an extension line (HR, HL) of the rotation axis of the other load wheel passes through said turning centre. <IMAGE>

IPC 1-7

B66F 9/075

IPC 8 full level

B66F 9/075 (2006.01); **B66F 9/10** (2006.01)

CPC (source: EP)

B66F 9/07568 (2013.01); **B66F 9/10** (2013.01)

Citation (search report)

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- [A] EP 0512591 A1 19921111 - GEN MOTORS CORP [US]
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- [A] PATENT ABSTRACTS OF JAPAN vol. 16, no. 135 (M - 1230) 6 April 1992 (1992-04-06)

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