

Title (en)
MECHANICAL MODEL OF AN ANIMAL

Title (de)
MECHANISCHE TIERNACHBILDUNG

Title (fr)
MODELE MECANIQUE D'UN ANIMAL

Publication
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Application
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Abstract (en)
[origin: US6210249B1] The invention relates to a mechanical model of an animal, especially a toy dog with forelegs and hind legs which are pivotally arranged around a first pivot with a rotation axis perpendicular to the direction of movement of the animal model, wherein the forelegs are articulated by a first drive mechanism with a first gear unit and a first drive axis. Said arrangement is configured in such a way that at least one hind leg is pivotally arranged around a second pivot, wherein the rotation axes of the hind leg are tilted in relation to each other at a given angle and a second drive mechanism is provided for selectable movement of the hind leg around the second pivot.

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