

Title (en)

DRIVER CONTROLLED AUTOMOTIVE ALL-TERRAIN PLATFORM

Title (de)

SELBSTFAHRENDE, GELÄNDEGÄNGIGE UND DEN FAHRER TRAGENDE PLATTFORM

Title (fr)

PLATE-FORME AUTO-MOTRICE TOUT-TERRAIN A CONDUCTEUR PORTE

Publication

**EP 1042157 A1 20001011 (FR)**

Application

**EP 99949062 A 19991018**

Priority

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- FR 9813058 A 19981019

Abstract (en)

[origin: WO0023314A1] The invention concerns an automotive platform (1) for transporting at a speed varying between 0 and 20 km/h an operator (2) maintained in a standing position by a frame (12) with its load (3). Said vehicle with multiple driving wheels (6) with or without tracks is capable of running on all types of grounds and terrain. It is highly manoeuvrable by means of its centralised control (10) and can turn around on itself, get past obstacles such as pavements, climb up slopes of 15 to 20 % . The centralised control (10) can be removed from the frame (12) so as to be taken over and managed directly by the operator (2). The steering can be radio-controlled by code to remotely control the platform and prevent theft in case the operator is not at hand. The driver controlled all-terrain automotive platform is designed for outside or inside uses and applications. The following are examples of areas where the all-terrain platform can be used for easy and quick transport of loads: express, hotel and catering, food service, mass merchandising, golf courses, factories, offices, administrative premises, for handicapped people among others.

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IPC 8 full level

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