

Title (en)

CORRECTION OF THE RELATIVE MOTION BETWEEN GRIPPING OR MACHINING TOOLS AND WORK PIECES

Title (de)

KORREKTUR DER RELATIVBEWEGUNG ZWISCHEN GREIF- ODER BEARBEITUNGSWERKZEUGEN UND WERKSTÜCKEN

Title (fr)

CORRECTION DU MOUVEMENT RELATIF ENTRE DES OUTILS DE PREHENSION OU D'USINAGE ET DES PIECES A USINER

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Application

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Abstract (en)

[origin: WO03033219A2] The invention relates to a method and a device for three-dimensionally correcting the relative motion, with many degrees of freedom, between work pieces on the one hand and grippers or tools on the other hand, in a setting mode and/or automatic mode, by means of a robot and an imaging device comprising one or several cameras, whereby said imaging device and/or work piece is reproducibly movable.

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