

Title (en)
PROCESSING METHOD AND PROCESSING DEVICE

Title (de)
BEARBEITUNGSVERFAHREN UND BEARBEITUNGSVORRICHTUNG

Title (fr)
PROCEDE ET DISPOSITIF DE TRAITEMENT

Publication
EP 1620235 A1 20060201 (DE)

Application
EP 04726847 A 20040410

Priority
• EP 2004003836 W 20040410
• DE 20306257 U 20030417

Abstract (en)
[origin: WO2004091867A1] The invention relates to a processing device (5) for body parts (2), comprising a multiaxial conveying robot (6) on which at least one support (7) is disposed. The at least one support (7) is provided with one or several multiaxial processing units, preferably small robots (10). The small robots (10) support different tools and can be controlled individually.

IPC 1-7
B25J 15/00

IPC 8 full level
A61P 3/10 (2006.01); **B23Q 39/02** (2006.01); **B25J 15/00** (2006.01); **C07D 207/16** (2006.01)

CPC (source: EP US)
A61P 3/10 (2017.12 - EP); **B23Q 39/026** (2013.01 - EP US); **B25J 15/0052** (2013.01 - EP US); **B25J 15/0061** (2013.01 - EP US); **C07D 207/16** (2013.01 - EP US)

Citation (search report)
See references of WO 2004091867A1

Citation (examination)
• JP 2000190265 A 20000711 - NAT SPACE DEV AGENCY
• JP H081558 A 19960109 - TOKYO ELECTRIC POWER CO, et al
• JP S59214590 A 19841204 - HITACHI LTD

Designated contracting state (EPC)
DE ES FR GB IT SE

DOCDB simple family (publication)
DE 20306257 U1 20040819; EP 1620235 A1 20060201; US 2007164009 A1 20070719; WO 2004091867 A1 20041028

DOCDB simple family (application)
DE 20306257 U 20030417; EP 04726847 A 20040410; EP 2004003836 W 20040410; US 55215704 A 20040410