

Title (en)

LORENTZ MOTOR CONTROL SYSTEM FOR A PAYLOAD

Title (de)

STEUERUNGSSYSTEM EINES LORENTZ-MOTORS FÜR EINE NUTZLAST

Title (fr)

SYSTEME DE COMMANDE DE MOTEURS DE LORENZ POUR CHARGE UTILE

Publication

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Application

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Priority

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Abstract (en)

[origin: WO2005013027A1] Control arrangement for and method of controlling a plurality of Lorentz motors (1, 2) actuating a payload (4) where the payload has a center of gravity (12). Height signals (z1,z2) are received from sensors sensing heights of said payload. At least one angle of rotation of the center of gravity about a horizontal axis is calculated from these height signals (z1, z2) and from this at least one angle of rotation control signals (C1, C2) for the Lorentz motors (1, 2) are calculated such that a predetermined rotational stiffness for supporting the payload (4) is achieved. A typical application is a suspension for floor vibration isolation of an electron microscope or of a lithographic apparatus.

IPC 1-7

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IPC 8 full level

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F16F 7/1011 (2013.01 - EP US); **F16F 15/005** (2013.01 - EP US); **F16F 15/03** (2013.01 - EP US); **G03F 7/70758** (2013.01 - EP US); **G03F 7/70816** (2013.01 - EP US); **G03F 7/709** (2013.01 - EP US)

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