

Title (en)

VEHICLE STEERING AID METHOD AND IMPROVED RELATED DEVICE

Title (de)

VERFAHREN ZUR FAHRZEUGLENKHILFE UND VERBESSERTE ZUGEHÖRIGE VORRICHTUNG

Title (fr)

PROCEDE D'ASSISTANCE A LA CONDUITE D'UN VEHICULE ET DISPOSITIF ASSOCIE AMELIORE

Publication

**EP 1922706 A1 20080521 (FR)**

Application

**EP 06808298 A 20060908**

Priority

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Abstract (en)

[origin: WO2007028932A1] The invention concerns a vehicle steering aid method comprising an object sensing detector, including the following steps which consists in: defining an occupation grid corresponding to discretization into N cells of a field of kinematic parameters of the detected object; and, at each time k, acquiring an observation  $z_{k-1}$  produced by the sensor and determining a sensor probability modelling the behaviour thereof; calculating for each cell X, a predicted occupation probability providing the probability that the cell X is, at time k, in occupied state having knowledge of a density of estimated probability of occupation of the grid at the preceding time; calculating for each cell X, an estimated probability of occupation providing the sensor probability and the predicted occupation probability; the predicted occupation probability at time k being determined by supposing that a single cell of the grid constitutes, at time k-1, the antecedent of the cell X concerned; evaluating, for each cell X, a collision probability, based on the estimated probability at time k and emitting a signal to avoid the object.

IPC 8 full level

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CPC (source: EP KR US)

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Citation (search report)

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