

Title (en)

THREE-WHEEL VEHICLE ELECTRONIC STABILITY SYSTEM

Title (de)

ELEKTRONISCHES STABILISIERUNGSSYSTEM FÜR EIN DREIRADFAHRZEUG

Title (fr)

SYSTÈME ÉLECTRONIQUE DE STABILITÉ POUR VÉHICULE À TROIS ROUES

Publication

**EP 1981743 A1 20081022 (EN)**

Application

**EP 06752340 A 20060505**

Priority

US 2006017477 W 20060505

Abstract (en)

[origin: WO2007130043A1] The present invention provides a three-wheel vehicle (10) having an electronic vehicle stability system and a method for stabilizing a three-wheel vehicle. The three-wheel vehicle (10) features a left (22) and right front wheel (24) laterally spaced apart and a single centered rear wheel (18) each having a tire contact patch which together define a triangular pattern of contact tire patches defining left and right rollover axis. The electronic vehicle stability system is adapted to calculate a dynamic status of the vehicle (10) based on inputs received from sensors and to output signals to the braking system to generate a specific moment about one of the left and right rollover axis when the calculated dynamic status of the vehicle exceeds a predetermined threshold indicative of a precursory condition of rollover. The present invention also provides a three-wheel vehicle having a yaw sensor positioned within a radius of 25 cm about the vertical axis (Z) to improve the accuracy of the yaw measurements provided to the electronic vehicle stability system.

IPC 8 full level

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Citation (search report)

See references of WO 2007130043A1

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Cited by

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