

Title (en)  
STEERING ACTUATOR FOR A STEER-BY-WIRE SHIP'S CONTROL SYSTEM AND METHOD FOR OPERATING SAID STEERING ACTUATOR

Title (de)  
LENKAKTUATOR FÜR EIN STEER-BY-WIRE SCHIFFSTEUERSYSTEM UND VERFAHREN ZUM BETREIBEN DES LENKAKTUATORS

Title (fr)  
ACTIONNEUR DE DIRECTION POUR UN SYSTÈME DE PILOTAGE DE NAVIRE STEER-BY-WIRE (PILOTAGE PAR CÂBLE) ET PROCÉDÉ DE FONCTIONNEMENT DE L'ACTIONNEUR DE DIRECTION

Publication  
**EP 2212190 A2 20100804 (DE)**

Application  
**EP 08804775 A 20080926**

Priority

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- DE 102007048061 A 20071005

Abstract (en)  
[origin: WO2009047131A2] The invention relates to a steering actuator (1) for a ship's control system, designed as a linear electromechanical actuator and comprising an electric motor (2), a controller (11) that is connected to the electronic control unit of the ship's control system (ECU) via a CAN bus and an angle sensor (12) that is connected to the controller (11) for determining the angular position of the rudder (13). The electric motor (2) is designed as a vector-controlled brushless motor.

IPC 8 full level  
**B63H 25/24** (2006.01)

CPC (source: EP US)  
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Citation (search report)  
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