

Title (en)

PARALLEL KINEMATICS ROBOT WITH FIVE LEGS

Title (de)

FÜNFBEINIGER ROBOTER MIT PARALLELER KINEMATIK

Title (fr)

ROBOT CINÉMATIQUE PARALLÈLE À CINQ PATTES

Publication

**EP 2528715 A1 20121205 (EN)**

Application

**EP 11703503 A 20110127**

Priority

- NL 2004167 A 20100128
- NL 2011050051 W 20110127

Abstract (en)

[origin: WO2011093703A1] Robot with multiple degrees of freedom comprising five legs (2) linked at a first of their ends to a base ( 3), and at a second of their ends opposite to the first ends to a mobile platform (4), which platform carries at least one tool (5, 6, 121, 12"), and wherein the robot further comprises an actuator for operating the tool or tools, which actuator is embodied by the joint operation of the motor drives ( 9 ) of the legs that are positioned at the base.

IPC 8 full level

**B25J 17/02** (2006.01)

CPC (source: EP)

**B25J 9/0051** (2013.01); **B25J 17/0266** (2013.01)

Citation (search report)

See references of WO 2011093703A1

Designated contracting state (EPC)

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DOCDB simple family (publication)

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