Title (en)

Compliant parallel manipulator system

Title (de)

Nachgiebiges Parallelrobotersystem

Title (fr)

Système de manipulateur parallèle souple

Publication

EP 2679349 A1 20140101 (EN)

Application

EP 12174050 A 20120628

Priority

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Abstract (en)

The invention provides a Compact XYZ Compliant Parallel Manipulator with Well-Constrained Parasitic Rotations. The invention provides a compliant parallel manipulator system comprising: a motion stage controlled by three linear actuators, mounted on a base adapted to produce three output translations, characterised by three leg support portions, each leg comprising a compliant active P joint, connected to the base and adapted to be actuated by a linear actuator, and a compliant passive PPRR chain, connected to the motion stage.

IPC 8 full level

B25J 7/00 (2006.01); **B25J 17/02** (2006.01)

CPC (source: EP)

B25J 7/00 (2013.01); **B25J 17/0266** (2013.01)

Citation (applicant)

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BA ME

DOCDB simple family (publication)

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