

Title (en)

VEHICLE VIBRATION-SUPPRESSION CONTROL DEVICE AND VEHICLE VIBRATION-SUPPRESSION CONTROL METHOD

Title (de)

VORRICHTUNG ZUR STEUERUNG EINER FAHRZEUGSCHWINGUNGSUNTERDRÜCKUNG UND VERFAHREN ZUR STEUERUNG EINER FAHRZEUGSCHWINGUNGSUNTERDRÜCKUNG

Title (fr)

DISPOSITIF DE CONTRÔLE DE VÉHICULE À SUPPRESSION DES VIBRATIONS ET PROCÉDÉ DE CONTRÔLE DE VÉHICULE À SUPPRESSION DES VIBRATIONS

Publication

EP 2840707 B1 20160803 (EN)

Application

EP 13778059 A 20130307

Priority

- JP 2012094717 A 20120418
- JP 2013056294 W 20130307

Abstract (en)

[origin: EP2840707A1] A vehicle vibration suppression control device includes: a first torque target value calculation unit that inputs a motor torque instruction value and that uses a previously modeled transmission characteristic of the vehicle to calculate a first torque target value; a second torque target value calculation unit that includes a filter having a characteristic of a model $H(s)/G_p(s)$ formed with a model $G_p(s)$ of a transmission characteristic of a torque input to the vehicle and a motor angular velocity and a bandpass filter $H(s)$ in which a frequency in the vicinity of a torsional vibration frequency in the vehicle is a center frequency, that inputs a deviation between a detection value of the vehicle state amount and an estimation value of the vehicle state amount and that calculates a second torque target value; and a motor torque control unit that controls a motor torque according to a final torque target value obtained by adding the first torque target value and the second torque target value. The vehicle state amount is estimated based on the first torque target value on which the lag processing has been performed and the second torque target value.

IPC 8 full level

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CPC (source: EP US)

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B60L 2270/145 (2013.01 - EP US); **Y02T 10/64** (2013.01 - EP US); **Y02T 10/72** (2013.01 - EP US)

Cited by

AT522508A1; AT522508B1; WO2018162195A1

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JP 2013223374 A 20131028; JP 5861554 B2 20160216; US 2015127202 A1 20150507; US 9150117 B2 20151006;
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