

Title (en)  
KINEMATIC AND PARAMETERIZED MODELING FOR PATIENT-ADAPTED IMPLANTS, TOOLS, AND SURGICAL PROCEDURES

Title (de)  
KINEMATISCHE UND PARAMETRISIERTE MODELLIERUNG FÜR PATIENTENADAPTIERTE IMPLANTATE, WERKZEUGE UND CHIRURGISCHE EINGRIFFE

Title (fr)  
MODÉLISATION CINÉMATIQUE ET PARAMÉTRÉE POUR DES IMPLANTS, OUTILS ET PROCÉDURES CHIRURGICALES ADAPTÉS AU PATIENT

Publication  
**EP 2967813 A4 20161109 (EN)**

Application  
**EP 14765606 A 20140315**

Priority  
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Abstract (en)  
[origin: WO2014145267A1] Patient-adapted articular repair systems, including implants, instruments, and surgical plans, and methods of making and using such systems, are disclosed herein. In particular, various embodiments include methods of selecting and/or designing patient-adapted surgical repair systems using parameterized models and/or multibody simulations.

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Citation (search report)  
• [X] US 2011029093 A1 20110203 - BOJARSKI RAY [US], et al  
• See references of WO 2014145267A1

Cited by  
US11250561B2; US11526988B2; US11645749B2; US9990720B2; US10672124B2; US11282195B2

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DOCDB simple family (publication)  
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**US 2014030001 W 20140315**; EP 14765606 A 20140315; HK 16108411 A 20160715; US 201414775190 A 20140315; US 201815956378 A 20180418; US 202016822865 A 20200318; US 202117544288 A 20211207; US 202318192362 A 20230329