

## Title (en)

METHODS, SYSTEMS, AND APPARATUS FOR MULTI-SENSORY STEREO VISION FOR ROBOTICS

## Title (de)

VERFAHREN, SYSTEME UND VORRICHTUNGEN FÜR EINE MULTISENSORISCHE STEREOVISION FÜR ROBOTERSYSTEME

## Title (fr)

PROCÉDÉS, SYSTÈMES, ET APPAREIL DE VISION STÉRÉOSCOPIQUE MULTI-SENSORIELLE POUR LA ROBOTIQUE

## Publication

**EP 2972478 A4 20161109 (EN)**

## Application

**EP 14770009 A 20140314**

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## Abstract (en)

[origin: WO2014152254A2] Embodiments of the present invention include multi-sensory stereo vision sensors suitable for use in robotics, navigation, machine vision, manufacturing, and other applications. In some cases, a sensor includes a stereo camera that produces image data for use in generating disparity maps to determine the positions of objects in the scene and/or the position of the sensor itself. The stereo sensor may include image sensors that are fastened to a unitary frame to prevent undesired drift and a thermal pad that wicks heat away from a processor. The processor may provide an efficient means to directly compute stereo disparity maps onboard the sensor. A sensor can also include a laser rangefinder that provides range data suitable for calibrating the stereo camera and for improving its accuracy in certain environments. In some cases, the laser is coupled to a spindle, which in turn is driven by a gear-train through a slipping clutch.

## IPC 8 full level

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## Citation (search report)

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