

Title (en)
AUTOMATIC THREE-WHEELED VEHICLE

Title (de)
AUTOMATISCHES DREIRAD

Title (fr)
VÉHICULE À TROIS ROUES AUTOMATIQUE

Publication
EP 3037333 A4 20170712 (EN)

Application
EP 13887499 A 20130619

Priority
JP 2013066822 W 20130619

Abstract (en)
[origin: EP3037333A1] A motor tricycle that enables a cornering performance to be enhanced without the use of any differential gear and any active suspension is provided. The motor tricycle has a control unit for performing, when a travel speed V is not less than a predetermined speed V1, and a steering angle α is not less than a predetermined angle α_1 , addition of an additional rotation speed ratio Rd1 meeting the thus travel speed V and the thus steering angle α , to an outer-wheel necessary rotation speed ratio R0 being a rotation speed ratio obtained in accordance with the handlebar steering angle α , detected by a steering angle detecting means on the assumption that no skid occurs between each of left and right rear wheels and a road surface at the time when a vehicle body turns a curve by the turning operation of a handlebar, specifically, a rotation speed ratio to an inner wheel, more specifically, a rotation speed ratio required for an outer wheel, and then permitting the outer wheel to be driven by drive means with a rotation speed ratio R resulting from the addition.

IPC 8 full level
B62K 5/027 (2013.01); **B60L 15/20** (2006.01); **B60W 10/08** (2006.01)

CPC (source: EP US)
B60K 7/0007 (2013.01 - EP); **B60L 3/102** (2013.01 - EP); **B60L 15/2036** (2013.01 - EP); **B62J 45/412** (2020.02 - EP US);
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Y02T 10/64 (2013.01 - EP); **Y02T 10/72** (2013.01 - EP)

Citation (search report)
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• [Y] JP 2009190649 A 20090827 - VIEWTEC JAPAN CO LTD
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