

Title (en)

GRIPPING DEVICE FOR A CO-HANDLING ROBOT, AND CO-HANDLING ROBOT EQUIPPED WITH SUCH A DEVICE

Title (de)

GREIFVORRICHTUNG FÜR EINEN CO-HANDLING-ROBOTER SOWIE MIT SOLCH EINER VORRICHTUNG AUSGESTATTETER CO-HANDLING-ROBOTER

Title (fr)

DISPOSITIF DE PREHENSION POUR ROBOT CO-MANIPULATEUR ET ROBOT CO-MANIPULATEUR EQUIPE D'UN TEL DISPOSITIF

Publication

**EP 3068589 A1 20160921 (FR)**

Application

**EP 14798752 A 20141106**

Priority

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- EP 2014073897 W 20141106

Abstract (en)

[origin: WO2015071161A1] The invention relates to a gripping device (5) comprising a gripping member (10) designed to come into contact with an object to be manipulated (100) and control means for controlling a joining and a separation of the gripping member and the object to be manipulated, the control means being associated with a contact (16) able to generate a joining and/or separating control signal intended for the control means when the contact is activated. According to the invention, the gripping member is slidably mounted in the device between a non-pushed-in position and a pushed-in position, the contact being positioned in the device so as to be activated by the gripping member when the gripping member is in the pushed-in position. The invention also relates to a co-handling robot comprising such a device.

IPC 8 full level

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Citation (search report)

See references of WO 2015071161A1

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