

Title (en)

AUTONOMOUS LOADING VEHICLE CONTROLLER

Title (de)

STEUERGERÄT FÜR AUTONOMES LADEFAHRZEUG

Title (fr)

DISPOSITIF DE COMMANDE DE VÉHICULE À CHARGEMENT AUTONOME

Publication

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Application

EP 15740514 A 20150123

Priority

- US 201461931243 P 20140124
- US 201462033904 P 20140806
- CA 2015000044 W 20150123

Abstract (en)

[origin: WO2015109392A1] Provided are dig controller and dig control method embodiments for an autonomous loading vehicle (ALV) used in applications such as mining, construction, and exploration. Embodiments may comprise at least one controller that controls a bucket and/or the ALV in accordance with at least one sensor signal, wherein the at least one sensor signal is representative of interaction between the bucket and the rock pile during a dig. Some embodiments include at least one admittance controller and optionally at least one iterative learning controller (ILC) that uses feedback from at least one previous dig to modify the at least one sensor signal provided to the at least one controller.

IPC 8 full level

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CPC (source: EP RU)

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Citation (examination)

US 2012330463 A1 20121227 - SCHREIBER GUNTER [DE], et al

Cited by

EP4219844A4

Designated contracting state (EPC)

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DOCDB simple family (publication)

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