

Title (en)

POLARIZATION-BASED MAPPING AND PERCEPTION METHOD AND SYSTEM

Title (de)

VERFAHREN ZUR POLARISATIONSBASIERTEN KARTIERUNG UND WAHRNEHMUNG

Title (fr)

PROCÉDÉ ET SYSTÈME DE MAPPAGE ET DE PERCEPTION BASÉS SUR LA POLARISATION

Publication

EP 3186606 A2 20170705 (EN)

Application

EP 15859072 A 20150826

Priority

- US 201462041778 P 20140826
- US 201514602823 A 20150122
- US 2015047008 W 20150826

Abstract (en)

[origin: AU2015347259A1] A method using Long Wave Infrared Imaging Polarimetry for improved mapping and perception of a roadway or path and for perceiving or detecting obstacles comprises recording raw image data using a polarimeter to obtain polarized images of the roadway or area. The images are then corrected for non-uniformity, optical distortion, and registration. IR and polarization data products are computed, and the resultant data products are converted to a multi-dimensional data set for exploitation. Contrast enhancement algorithms are applied to the multi-dimensional imagery to form enhanced object images. The enhanced object images may then be displayed to a user, and/or an annunciator may announce the presence of an object. Further, the vehicle may take evasive action based upon the presence of an object in the roadway.

IPC 8 full level

G01J 4/00 (2006.01); **G01J 4/04** (2006.01); **G06V 10/147** (2022.01)

CPC (source: EP US)

B60W 30/00 (2013.01 - EP); **G01C 21/26** (2013.01 - EP US); **G06T 5/80** (2024.01 - EP); **G06T 5/92** (2024.01 - EP);
G06V 10/147 (2022.01 - EP US); **G06V 20/58** (2022.01 - EP US); **G06T 2207/10048** (2013.01 - EP); **G06T 2207/30252** (2013.01 - EP)

Cited by

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AL AT BE BG CH CY CZ DE DK EE ES FI FR GB GR HR HU IE IS IT LI LT LU LV MC MK MT NL NO PL PT RO RS SE SI SK SM TR

Designated extension state (EPC)

BA ME

DOCDB simple family (publication)

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