

Title (en)

METHOD AND ROBOT SYSTEM FOR USING AN INDUSTRIAL ROBOT FOR TEST JOBS

Title (de)

VERFAHREN UND ROBOTERSYSTEM ZUR NUTZUNG EINES INDUSTRIEROBOTERS FÜR PRÜFAUFGABEN

Title (fr)

PROCÉDÉ ET SYSTÈME ROBOTIQUE D'EXPLOITATION D'UN ROBOT INDUSTRIEL POUR DES TÂCHES DE CONTRÔLE

Publication

EP 3213159 A1 20170906 (DE)

Application

EP 15787548 A 20151027

Priority

- DE 102014221798 A 20141027
- EP 2015074816 W 20151027

Abstract (en)

[origin: WO2016066616A1] The invention relates to a method and a robot system (1) for verifying the position of components (200, 201, 202, 203, 204) in an assembly process. A multi-shaft articulated-arm robot (100), the shafts (A1-An) of which are preferably equipped with torque sensors for sensing the torques acting on the shafts, is used for approaching various checkpoints (220, 221, 222, 223) on the components, and the measured signals from the torque sensors are compared with expected signals corresponding to the correct positions of the components.

IPC 8 full level

G05B 19/401 (2006.01)

CPC (source: EP)

G05B 19/401 (2013.01); **G05B 2219/37216** (2013.01); **G05B 2219/37222** (2013.01); **G05B 2219/40543** (2013.01); **G05B 2219/40566** (2013.01);
G05B 2219/40599 (2013.01); **G05B 2219/45066** (2013.01)

Citation (search report)

See references of WO 2016066616A1

Designated contracting state (EPC)

AL AT BE BG CH CY CZ DE DK EE ES FI FR GB GR HR HU IE IS IT LI LT LU LV MC MK MT NL NO PL PT RO RS SE SI SK SM TR

Designated extension state (EPC)

BA ME

DOCDB simple family (publication)

DE 102014221798 A1 20160428; EP 3213159 A1 20170906; WO 2016066616 A1 20160506

DOCDB simple family (application)

DE 102014221798 A 20141027; EP 15787548 A 20151027; EP 2015074816 W 20151027