Title (en)
GLOVE FOR FOOD HANDLING

Title (de)
HANDSCHUH ZUR HANDHABUNG VON NAHRUNGSMITTELN

Title (fr)
GANT POUR LA MANIPULATION D'ALIMENTS

Publication
EP 3342297 A1 20180704 (EN)

Application
EP 16207279 A 20161229

Priority
EP 16207279 A 20161229

Abstract (en)
A glove (10) for food handling is provided by which, even if the glove (10) for food handling is broken and a broken piece thereof mixes in food, the broken piece can be easily found, and further, workability can be improved. The glove main body (10) for food handling is kneaded with a luminescent material that, even if a broken piece K of the glove for food handling mixes in food F, makes the broken piece K emit light in response to ultraviolet rays S by irradiating the food F with the ultraviolet rays S by using an ultraviolet light source L such as a black light. The luminescent material is kneaded throughout the entire area of the glove main body (10) for food handling. Further, on a palm surface of the glove (10) for food handling, a plurality of fine first projections (110a) and a plurality of fine second projections (110b) formed on each of the first projections are formed.

IPC 8 full level
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CPC (source: EP)
A41D 19/0062 (2013.01); A41D 19/0082 (2013.01); A41D 19/0157 (2013.01); A41D 31/32 (2019.01); A41D 2500/50 (2013.01); A41D 2600/20 (2013.01)

Citation (applicant)
JP 2002317320 A 20021031 - WHITE MAX KK

Citation (search report)
- [A] JP 2016113717 A 20160623 - HARADA SANGYO KK
- [A] US 2011090050 A1 20110421 - MACFARLAND HECTOR GOMEZ [US]
- [A] US 2015020727 A1 20150122 - HULL JAMES L [US]
- [A] WO 2010089904 A1 20100812 - ARAM CORP [JP], et al
- [A] JP 2009120974 A 20090604 - OZU SANGYO KK

Designated contracting state (EPC)
AL AT BE BG CH CY CZ DE DK EE ES FI FR GB GR HR HU IE IS IT LI LT LU LV MC MK MT NL NO PL PT RO RS SE SI SK SM TR

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BA ME

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