

Title (en)
CONTROLLING A GROUP OF ROBOTS

Title (de)
STEUERN EINES ROBOTERVERBANDS

Title (fr)
COMMANDE D'UNE ASSOCIATION DE ROBOTS

Publication
EP 3408062 A1 20181205 (DE)

Application
EP 17701637 A 20170125

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Abstract (en)
[origin: WO2017129360A1] The invention relates to a method for controlling a group of robots, comprising a leading robot (10) and at least one following robot (20, 30), which cooperates with the leading robot and moves in accordance with the leading robot, wherein the absolute velocity (v₁₀) of the leading robot and/or the absolute velocity (v_{20abs}) of the following robot is reduced on the basis of a specified limit (v_{max}) such that a mutual relative velocity (V_{20rel}) is not exceeded and therefore a safety function is not triggered.

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Citation (search report)
See references of WO 2017129360A1

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