

Title (en)
ROBOT COMPRISING A MOBILE SUPPORT AND A MANIPULATOR

Title (de)
ROBOTER MIT MOBILEM TRÄGER UND MANIPULATOR

Title (fr)
ROBOT À SUPPORT MOBILE ET MANIPULATEUR

Publication
EP 3448631 A1 20190306 (DE)

Application
EP 17720001 A 20170420

Priority
• DE 102016005029 A 20160426
• EP 2017000510 W 20170420

Abstract (en)
[origin: WO2017186345A1] Disclosed is a method for controlling a robot comprising a mobile support (20) equipped with a propulsion system (21), a manipulator (10) that is arranged on the support and is equipped with an actuator system (q1 - q7), and a controller (30), said method involving the step of controlling (S20) the actuator system and the propulsion system such that a desired movement of a reference point (TCP) fixed in relation to the manipulator is carried out.

IPC 8 full level
B25J 9/16 (2006.01)

CPC (source: EP)
B25J 9/162 (2013.01); **G05B 2219/40298** (2013.01); **G05B 2219/40513** (2013.01)

Citation (search report)
See references of WO 2017186345A1

Designated contracting state (EPC)
AL AT BE BG CH CY CZ DE DK EE ES FI FR GB GR HR HU IE IS IT LI LT LU LV MC MK MT NL NO PL PT RO RS SE SI SK SM TR

Designated extension state (EPC)
BA ME

DOCDB simple family (publication)
DE 102016005029 A1 20171026; CN 109070352 A 20181221; EP 3448631 A1 20190306; WO 2017186345 A1 20171102

DOCDB simple family (application)
DE 102016005029 A 20160426; CN 201780026000 A 20170420; EP 17720001 A 20170420; EP 2017000510 W 20170420