

Title (en)  
ROBOT COMPRISING A MOBILE SUPPORT AND A MANIPULATOR

Title (de)  
ROBOTER MIT MOBILEM TRÄGER UND MANIPULATOR

Title (fr)  
ROBOT À SUPPORT MOBILE ET MANIPULATEUR

Publication  
**EP 3448631 A1 20190306 (DE)**

Application  
**EP 17720001 A 20170420**

Priority  
• DE 102016005029 A 20160426  
• EP 2017000510 W 20170420

Abstract (en)  
[origin: WO2017186345A1] Disclosed is a method for controlling a robot comprising a mobile support (20) equipped with a propulsion system (21), a manipulator (10) that is arranged on the support and is equipped with an actuator system (q1 - q7), and a controller (30), said method involving the step of controlling (S20) the actuator system and the propulsion system such that a desired movement of a reference point (TCP) fixed in relation to the manipulator is carried out.

IPC 8 full level  
**B25J 9/16** (2006.01)

CPC (source: EP)  
**B25J 9/162** (2013.01); **G05B 2219/40298** (2013.01); **G05B 2219/40513** (2013.01)

Citation (search report)  
See references of WO 2017186345A1

Designated contracting state (EPC)  
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Designated extension state (EPC)  
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DOCDB simple family (publication)  
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