

Title (en)
HOLDING AND TRANSPORTING DEVICE, METHOD FOR OPERATING A HOLDING AND TRANSPORTING DEVICE, SYSTEM AND METHOD FOR PRODUCING A BOOK-TYPE IDENTIFICATION, VALUE OR SECURITY DOCUMENT

Title (de)
HALTE- UND TRANSPORTVORRICHTUNG, VERFAHREN ZUM BETRIEB EINER HALTE- UND TRANSPORTVORRICHTUNG, SYSTEM UND VERFAHREN ZUR HERSTELLUNG EINES BUCHFÖRMIGEN AUSWEIS-, WERT- ODER SICHERHEITSDOKUMENTS

Title (fr)
DISPOSITIF DE MAINTIEN ET DE TRANSPORT, PROCÉDÉ POUR FAIRE FONCTIONNER UN DISPOSITIF DE MAINTIEN ET DE TRANSPORT, SYSTÈME ET PROCÉDÉ DE FABRICATION D'UN DOCUMENT D'IDENTITÉ, DE VALEUR OU INFALSIFIABLE EN FORME DE LIVRE

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Application
EP 17769081 A 20170920

Priority
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• EP 2017073744 W 20170920

Abstract (en)
[origin: WO2018054956A1] The invention relates to a holding and transporting device (1000), in particular for producing a book-type identification, value, or security document (100), having: at least two guide units (1002), at least two holders (1006), each for an identification, value, or security document (100), a passport book blank (128), a passport book block (104), a cover (102), a data card (106) or a book half of an identification, value or security document (100), and a control unit (1022), wherein the holders (1006) can be moved in associated guide units (1002), wherein the guide units (1002) each form a closed path curve (1004), along which the holder (1006) can be moved, wherein the guide units (1002) and/or the holders (1006) can be moved between a processing position and an avoidance position, wherein in a processing position of the guide units (1002) and/or of the holders (1006) the holders (1006) can be moved along the path curve (1004) within a processing region (1018) extending along a closed processing path (1016), wherein in the avoidance position of the guide units (1002) and/or of the holders (1006) the holders (1006) can be moved outside of the processing region along the path curve (1004), wherein the control unit (1022) is configured to control the movement of the holders (1006) along the guide units (1002) and to control the movement of the guide units (1002) and/or of the holders (1006) between the processing position and the avoidance position, wherein the control unit (1022) is designed to determine a movement path (1024) of the first and the second holder (1006) and to check if a cross-over region (1026) of the movement paths (1024) is present along the movement paths (1024), wherein the guide units (1002) and/or the holders (1006) are moved between the processing position and the avoidance position in accordance with the result of the check.

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