

Title (en)
ENVIRONMENT SENSOR SYSTEM IN A TWO-WHEELED VEHICLE

Title (de)
UMFELDSSENSORIK IN EINEM ZWEIRAD

Title (fr)
SYSTÈME DE DÉTECTION D'ENVIRONNEMENT DANS UN DEUX-ROUES

Publication
EP 3548369 A1 20191009 (DE)

Application
EP 17781461 A 20171005

Priority

- DE 102016223761 A 20161130
- EP 2017075328 W 20171005

Abstract (en)
[origin: WO2018099637A1] The invention relates to an environment sensor system 5 in a two-wheeled vehicle 1, which can be coupled to the two-wheeled vehicle by means of a carrier unit, wherein the carrier unit is designed so as to be pivotable about a two-wheel axle and, in the event of a deflection of the two-wheeled vehicle about the two-wheel axle, is pivoted in the opposite direction to the deflection.

IPC 8 full level
B62J 99/00 (2009.01)

CPC (source: EP US)
B60Q 1/0023 (2013.01 - US); **B60W 40/072** (2013.01 - US); **B60W 40/11** (2013.01 - US); **B62J 6/023** (2020.02 - EP US); **B62J 6/027** (2020.02 - EP US); **B62J 45/414** (2020.02 - EP US); **B62J 45/4151** (2020.02 - EP US); **B60Q 2300/132** (2013.01 - US); **B60Q 2300/322** (2013.01 - US); **B60Y 2200/12** (2013.01 - US)

Citation (search report)
See references of WO 2018099637A1

Designated contracting state (EPC)
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DOCDB simple family (publication)
WO 2018099637 A1 20180607; CN 109982920 A 20190705; DE 102016223761 A1 20180530; EP 3548369 A1 20191009; JP 2020500766 A 20200116; US 10906450 B2 20210202; US 2019283659 A1 20190919

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EP 2017075328 W 20171005; CN 201780073858 A 20171005; DE 102016223761 A 20161130; EP 17781461 A 20171005; JP 2019528488 A 20171005; US 201716465029 A 20171005