

Title (en)
ROBOT AND METHOD FOR CONTROLLING A ROBOT

Title (de)
ROBOTER UND VERFAHREN ZUR STEUERUNG EINES ROBOTERS

Title (fr)
ROBOT ET PROCÉDÉ DE COMMANDE D'UN ROBOT

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Application
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Abstract (en)
[origin: WO2018197295A1] The invention relates to a robot having a robot manipulator (101) with an effector, wherein the robot manipulator (101) is designed and constructed for picking up, handling and releasing an object and is controlled/regulated in accordance with a control program by a control unit (103), comprising a first sensor means (105), which is designed and constructed to determine a persisting adherence of the object to the effector after a release of the object by the effector in accordance with the control program, and where such adherence persists to generate a signal S, wherein the control unit (103) is designed and constructed to execute the following control program: where a signal S is present, control the robot manipulator (101) in such a manner that it executes a predefined movement in which the effector with the persistently adhering object is passed by a wiping object (104) in such a manner that the adhering object is wiped off on the surface of the wiping object (104). (Fig. 1)

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