

Title (en)

ORIENTATION OF USER-INPUT DEVICES FOR CONTROLLING SURGICAL ARMS

Title (de)

AUSRICHTUNG VON BENUTZEREINGABEVORRICHTUNGEN ZUR STEUERUNG CHIRURGISCHER ARME

Title (fr)

ORIENTATION DE DISPOSITIFS D'ENTRÉE D'UTILISATEUR POUR COMMANDER DES BRAS CHIRURGICAUX

Publication

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Application

EP 20896623 A 20201204

Priority

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Abstract (en)

[origin: WO2021111394A1] A surgical system comprises an articulated mechanical arm comprising arm segments connected serially by arm joints that flex and rotate, and first and second input-devices. The second input-device comprises a handle configurable to be oriented in any orientation in an x-y-z space, and the handle comprises segment members and joint members corresponding to the arm segments and arm joints of the arm. The arm joints can be actuatable by, and have the same degrees of freedom as, the handle joint member. A method of using the surgical system includes retroflecting the arm, transitioning control of the arm from the first input device to the second input device, and performing a surgical action, during which a displacement vector or a reorientation arc of the handle member through the x-y-z space is translated to a corresponding displacement vector or corresponding reorientation arc of the end effector in the same x-y-z space.

IPC 8 full level

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