Title (en)
ROBOT PROCESS

Title (de)
ROBOTERPROZESS

Title (fr)
PROCESSUS ROBOTISÉ

Publication
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Application
EP 21715537 A 20210324

Priority
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Abstract (en)
[origin: WO2021204544A1] The invention relates to a method for executing a process, in particular with the aid of at least one robot (10), which method has the steps of: executing (S10) a run-through of the process with a process control, in particular of the robot; detecting (S10) a value of a first process variable (x) for this execution; and detecting (S10) an assessment (E) of this executed process run-through; the following assessment learning steps, repeated multiple times: varying (S20) the process control, in particular at least one parameter of the process control, in particular of a controller (31), by an optimiser (4) to achieve a varied process control on the basis of values of a quality criterion for executed process run-throughs; executing (S20) a run-through of the process with the varied process control; detecting (S20) a value of the first process variable for this execution; and detecting an assessment (E) of this executed process run-through; wherein a first quality factor model (51) of the process, which determines a quality factor (E') of the process on the basis of the first process variable (x), is machine-learned on the basis of these detected assessments and values of the first process variable; and the following process control optimisation steps, repeated multiple times: varying (S40) the process control by the optimiser to achieve a varied process control on the basis of values of the quality criterion for executed process run-throughs; executing (S40) a run-through of the process with the varied process control; and detecting (S40) a value of the first process variable for this execution; wherein the value of the quality criterion for at least one of the process run-throughs executed with one of the altered process controls is determined on the basis of a quality factor (E') determined by the machine-learned first quality factor model on the basis of the value of the first process variable detected for this process run-through.

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