

Title (en)  
INVENTORY MANAGEMENT METHOD AND SYSTEM

Title (de)  
INVENTARVERWALTUNGSVERFAHREN UND -SYSTEM

Title (fr)  
PROCÉDÉ ET SYSTÈME DE GESTION DES STOCKS

Publication  
**EP 4160347 A1 20230405 (EN)**

Application  
**EP 21811869 A 20210518**

Priority  
• CN 202010477658 A 20200529  
• CN 2021094416 W 20210518

Abstract (en)  
An inventory management method and system (600). The method comprising: scheduling, according to task information, a first autonomous mobile robot (102, 602) and a second autonomous mobile robot (105, 603) to travel to a same target workstation (103) to execute tasks (502); controlling the first autonomous mobile robot (102, 602) to fetch one or more inventory containers from an inventory area (201) and carry same to a first working point (1031) in the target workstation (103) (504); and controlling the second autonomous mobile robot (105, 603) to fetch one or more inventory containers from the inventory area (201) according to an instruction and carry same to a second working point (1032) in the target workstation (103) (506). The first working point (1031) and the second working point (1032) are two adjacent working points of the same station, and therefore, after a worker finishes picking from the inventory container carried by the first autonomous mobile robot (102, 602), the worker can continue picking from the inventory container carried by the second autonomous mobile robot (105, 603), thereby avoiding time waste caused in the robot switching process, and improving the working efficiency of inventory management work.

IPC 8 full level  
**G05D 1/02** (2006.01); **B66F 9/06** (2006.01)

CPC (source: CN EP US)  
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BA ME

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