

Title (en)

SURGICAL ROBOT, AND GRAPHICAL CONTROL DEVICE AND GRAPHIC DISPLAY METHOD THEREFOR

Title (de)

CHIRURGISCHER ROBOTER UND GRAFISCHE STEUERUNGSVORRICHTUNG UND GRAFISCHES ANZEIGEVERFAHREN DAFÜR

Title (fr)

ROBOT CHIRURGICAL, ET DISPOSITIF DE COMMANDE GRAPHIQUE ET PROCÉDÉ D'AFFICHAGE GRAPHIQUE ASSOCIÉS

Publication

EP 4218652 A1 20230802 (EN)

Application

EP 20956605 A 20201203

Priority

- CN 202011068091 A 20201008
- CN 2020133490 W 20201203

Abstract (en)

A surgical robot, and a graphical control device and graphic display method therefor. The surgical robot includes: an input portion; a display (22); an operating arm (31) having a feature point sequence consisting of feature points arranged orderly, the feature points representing joints; and a controller. The controller is coupled to the input portion, the display (22) and sensors, and configured to: obtain the feature point sequence of the operating arm (31) and a corresponding kinematic model thereof (S11); obtain joint variables sensed by the sensors (S12), and obtain a virtual camera selected by the input portion(S13); determine a projection point of each feature point in the feature point sequence on a projection plane of the virtual camera according to the kinematic model and the joint variables (S14); orderly fit and connect each projection point to generate a projected image of the operating arm (3 1)(S15); and display the projected image on the display (22)(S16). The surgical robot helps a doctor in observing a motion state of the operating arm (31) in all orientations.

IPC 8 full level

A61B 34/37 (2016.01); **A61B 34/30** (2016.01)

CPC (source: CN EP US)

A61B 34/25 (2013.01 - CN US); **A61B 34/37** (2016.02 - CN EP US); **A61B 90/361** (2013.01 - EP); **G06T 5/80** (2024.01 - US);
G06T 7/0012 (2013.01 - US); **G06T 7/64** (2017.01 - US); **G06T 7/75** (2017.01 - US); **G06T 11/00** (2013.01 - US); **G06T 13/00** (2013.01 - US);
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Designated contracting state (EPC)

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Designated extension state (EPC)

BA ME

Designated validation state (EPC)

KH MA MD TN

DOCDB simple family (publication)

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