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(71) Applicant: FUJI JUKOGYO KABUSHIKI KAISHA Tokyo (JP)

(72) Inventors:

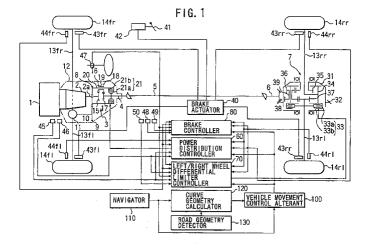
 Matsuno, Koji Mitaka-shi, Tokyo (JP)

- Matsuura, Munenori Mitaka-shi, Tokyo (JP)
- Konno, Toshihiro Shinjuku-ku, Tokyo (JP)
- Takahashi, Akira Mitaka-shi, Tokyo (JP)
- Mine, Atsushi
 Mitaka-shi, Tokyo (JP)
- (74) Representative: W.P. THOMPSON & CO. Coopers Building, Church Street Liverpool L1 3AB (GB)

(54) Vehicle dynamic control system

(57) The present invention provides a vehicle dynamic control system which alters characteristics of respective vehicle movement controllers so that they can function properly against coming and foreseeable running conditions and current running conditions, recognizing beforehand details of an emerging curve on the road to be traveled. The system comprises a vehicle movement control alterant and at least one among vehicle movement controllers, i.e., a brake controller, a left/right wheel differential limiter controller and power

distribution controller. When the vehicle is approaching the curve, the vehicle movement control alterant alters characteristics of a braking controller, the left/right wheel differential limiter controller and the power distribution controller to those favorable to turning for driving through a curve appropriately. When the vehicle is approaching the curve end, the alternate alters characteristics of the left/right differential controller to those favorable to stabilizing running so that the vehicle can pass the curve end and go into straight road appropriately.





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EP 98 30 8597

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