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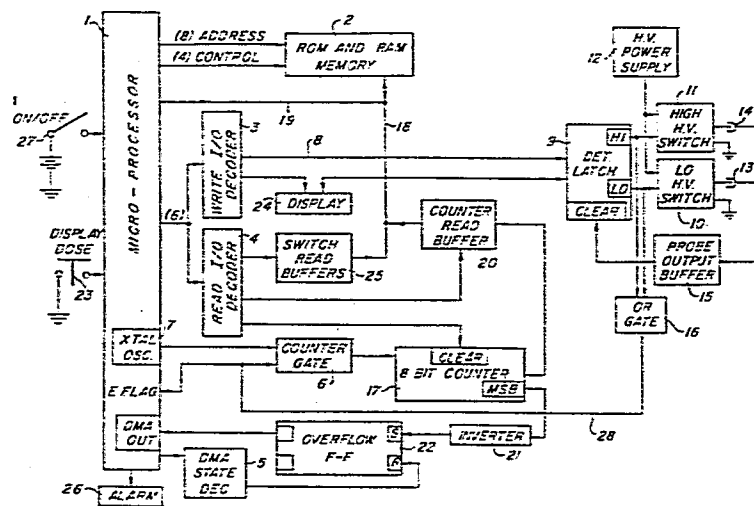
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⑤④ **Radiation measuring apparatus and method.**

⑤⑦ An apparatus and method for measuring radiation field strength uses a pulse enabled G-M detector tube (13 or 14) and is based on the equation $R=K/t$, where r is the radiation field strength, t is the time till first strike, and K is a proportionality constant for the given apparatus. The G-M tube (13 or 14) is enabled by pulsing the bias voltage across the tube up into its active region and then measuring the elapsed time interval to the incident of first strike. Since the reciprocal of this time is proportional to the radiation field strength, all information necessary to determine the field strength has been obtained. A constant wait time is employed after each strike to ensure that the G-M tube full recovery time has expired, and the G-M tube is then enabled and the process repeated. Because of the random nature of radiation phenomena the confidence level that any given measurement is an accurate representation of the true average field strength is low. Many measurements are taken and averaged for high confidence factors. For low fields, the lost time due to the deliberate "wait after strike" is a small percentage of the total time, so is of little consequence. In high fields, the "time to strike" is short, so many measurements can be made, again rendering the lost time of little significance.



RADIATION MEASURING APPARATUS AND METHOD

1 This invention relates to the field of nuclear
radiation measurement. Nuclear source strength is defined
in terms of the number of atom disintegrations per unit of
time. Typically, these disintegrations result in alpha (α),
5 beta (β), gamma (γ), or neutron radiation fields. Detection
and measurement of these field strengths has been the objective
of radiation measurement apparatus, and detectors to sense and
measure these fields traditionally have employed the inter-
action or absorption of energy from these fields. This inven-
10 tion describes apparatus for, and a method of, using a Geiger-
Mueller tube (G-M) detector over a wide range of field strengths
while circumventing the limitations traditionally encountered
in the use of such devices at the high field regions of interest.

15 Detectors for sensing radiation fields have included
ion chambers, proportional counters, Geiger Mueller tubes,
scintillation crystals and solid-state semiconductors. Each
has advantages and disadvantages, and selection of a detector
has been affected by the particular application. A single
20 measurement apparatus for measuring radiation fields from
very low intensity to extremely high intensity is highly
desirable, but has been difficult to achieve due to the
limiting physics phenomena of the various detectors at either
the high or low regions of interest.

25 G-M tubes have served as simple, rugged, dependable
detectors. Traditionally, G-M tubes are biased with a high
voltage to create a high field strength between the anode
and cathode electrodes, which field strength is chosen to be
below that which causes self-ignition, but high enough so
30 that the interaction with a nuclear particle/wave is
sufficient to result in a discharge within the tube. This
discharge pulse is sensed and counted with appropriate sup-
port electronics. After the discharge, the electric field
is restored and subsequent events can occur and similarly

1 be counted. The rate of discharges is measured (counted)
and used as a measure of the nuclear field strength.

Limitations occur at high fields since the G-M tube
exhibits an inactive or dead time just following a discharge.
5 This dead time limitation is further complicated by the fact
that its extent is a function of the field strength. This
phenomenon can actually result in complete crippling of the
ability of a G-M tube to function at high fields. Dead time
correction via electronics is a difficult task due to its
10 non-linear character.

Because of their simplicity, ruggedness and dependa-
bility, G-M tubes are highly desirable as radiation detectors.
The useful life of G-M detectors can be expressed as a total
15 number of discharges (e.g. 10^{10} to 10^{12}). This results in
short detector life when used conventionally in high radia-
tion fields, that is, by counting discharges. The method
according to the invention limits the number of discharges
in high radiation fields by the insertion of a fixed wait
20 time between discharges. Even though the time to discharge
is short, the time interval between discharges becomes do-
minated by the wait time. This has the effect of signifi-
cantly increasing the detector life.

Another drawback of using G-M detectors in high
25 radiation fields in the previously known modes of use is
the occurrence of partial amplitude discharges resulting
from incomplete recovery of the G-M detector from a previous
discharge. Since the amplitude of these pulses varies, the
counting apparatus normally used to count discharges displays
30 erratic counting. The apparatus according to the invention
eliminates this problem. Additionally, at very high radia-
tion fields, the G-M detector becomes totally saturated and
therefore crippled. This crippling results in an erroneous
low or zero reading even though a high field exists. As a
35 result of the fixed wait time between discharges utilized
in the present invention the G-M detector is operable at
arbitrarily high radiation fields.

Moreover, the known types of devices do not in general present a linear meter scale and require the generation of a closely controlled, narrow high voltage pulse. While both the linearization of the readout and the generation of the high voltage pulse can be accomplished, the techniques required add to the component count, overall equipment complexity, and necessity of scale-changing for each decade covered. The apparatus and method according to the invention enables an inherently precise linear readout over many decades of operation with only one ranging operation required.

This invention describes apparatus for and a method of measuring nuclear field strength which uses a pulse enabled detector (e.g. G-M tube) and is based on the equation $R = \frac{K}{t}$, where R is the radiation field strength, t is the time till first strike, and K is a proportionality constant for the given apparatus. The G-M detector is enabled by pulsing the bias voltage across the detector up into its active region and then measuring the elapsed time interval to the incident of first strike. Since the reciprocal of this time is proportional to the radiation field strength, all information necessary to determine the field strength has been obtained. A constant wait time is employed after each strike to assure that the G-M tube has fully recovered, and the G-M tube is then enabled and the process repeated.

Because of the random nature of nuclear phenomena, even though each timed interval to strike contains all the necessary information to calculate the radiation field strength, the confidence level that any given measurement is an accurate representation of the true average field strength is low. Many measurements are, therefore, taken and combined for high confidence factors. For low fields, the lost time due to the deliberate "wait after strike" is a small percentage of the total time, so is of little consequence. In high fields, the "time to strike" is short, so many measurements can be made, again rendering the lost time of little significance. The fineness to which the time can be measured and the minimum time measurable limits the accuracy and maximum

1 radiation field that can be measured. The non-linearity and
lack of repeatability that is normally encountered as a re-
sult of G-M tube dead time no longer is present.

Accordingly it is a primary object of the invention
5 to provide novel detector apparatus for and a method of
measuring radiation fields by counting the time which elapses
between the enabling of a detector device to record an inter-
action with a radiation particle or wave and the first actual
interaction which thereafter occurs.

10 Another object of the invention is to provide a novel
apparatus and method of measuring radiation fields as afore-
said wherein upon occurrence of the first interaction the de-
tector apparatus is disabled for a predetermined time and is
then again enabled and the time counting process repeated
15 until the next interaction occurs, the enabling and disabling
sequences being continued and the time counts being averaged
to provide a measurement of the radiation field.

A further object of the invention is to provide a
novel apparatus according to the method of the invention as
20 aforesaid which utilizes a Geiger-Mueller tube in the detector
apparatus, and in which the time between disabling the de-
tector and subsequently enabling the detector is longer than
the full recovery time of the Geiger-Mueller tube.

Yet another object of the invention is to provide a
25 novel radiation measuring apparatus which provides a precise
linear readout over many decades of operation with only a
single ranging change required, which demonstrates signifi-
cantly increased detector life with high accuracy and stabil-
ity, and has the ability to function accurately in very high
30 radiation fields.

The foregoing and other objects of the invention will
become clear from a reading of the following specification in
conjunction with an examination of the appended drawing which
is a functional block diagram of the novel apparatus accord-
35 ing to the invention which carries out the novel method of
the invention.

The apparatus and method according to the invention,

1 as previously stated, is based upon the equation $R = \frac{K}{t}$,
 where R is the radiation field strength, t is the time till
 the first strike after the G-M tube is enabled, and K is a
 proportionality constant. This equation is derived from the
 5 proven mathematical expression

$$\% \text{ Coincidences} = 1 - e^{-nRt}$$

which relates the expected count rate in terms of the probability of obtaining a count (% coincidence) to the radiation field R in milli-Roentgens, the detector sensitivity n in
 10 counts per second per mr per hour, and t, the observation time in seconds.

Since, if one waits long enough there will always occur a count, if even from background radiation, the probability of getting a count is certain, and the % coincidence can be written as a constant. Thus, the above equation
 15 becomes

$$K_1 = 1 - e^{-nRt}$$

Since n = the G-M tube sensitivity and is a constant based on the tube size and construction, the equation then reduces
 20 to

$$K_1 = 1 - e^{-K_2Rt}$$

where R = radiation field strength (mr/hr)
 and t = observation time (seconds)

Since two of the three terms in the equation are constants,
 25 the third must also be a constant, and therefore

$$e^{-K_2Rt} = K_3 = \text{a constant}$$

Thus, it can be seen that if e^{-K_2Rt} is a constant, the exponent of e must also be a constant and we may write:

$$-K_2Rt = K_4$$

$$30 \quad \text{or } Rt = \frac{K_4}{-K_2} = K_5 = K$$

$$\text{and, } R = \frac{K}{t}$$

where R = radiation field strength and

t = time to obtain a G-M count,

or the radiation field intensity is proportional to the reciprocal of the time required to obtain a G-M count.
 35

pulse may extend to as much as a second or more depending on the actual field level and the G-M tube sensitivity. However, it can be seen that by simply counting time for whatever period is required, the G-M tube can be used over many decades without range changing, the limitation being the ability to measure extremely short time intervals reliably.

It is also evident that since the detector is permitted to count at the same rate as in D.C. operation, the number of counts per second increases as the field increases, and, as distinguished from the prior use modes of pulsed operation of G-M tubes, the counting rate is not limited by a controlling repetition rate of applied high voltage pulses to the G-M tube. In this approach, the G-M tube is essentially allowed to "free run", that is, count as rapidly as the radiation field dictates with the only limit being the imposed recovery time occurring after the receipt of each G-M pulse. Therefore, the statistics associated with any radiation field readings are maximized.

Turning now to a consideration of the functional block diagram of a radiation measuring apparatus which embodies the invention there is seen a Micro-processor 1 which controls all of the operations of the apparatus through the other components, which include a ROM and RAM Memory 2, a Write I/O Decoder 3, a Read I/O Decoder 4, a DMA State Decoder 5, and a Counter Gate 6. The eight Address lines to the Memory 2 are multiplexed to function as sixteen lines. The Write I/O Decoder 3 tells the Detector Latch 9 and the Display 24 when to read data from the Data Bus 18. The Read I/O Decoder 4 selects when count data is read onto the Data Bus, and also clears the Counter 17 at the appropriate times. The Memory EPROMs contain the Program and the RAM is used for transient data. A crystal oscillator 7 provides one microsecond timing clock pulses to the Micro-processor 1 and to the Counter gate 6 for respectively timing the operations of the apparatus and the "time to strike". The oscillator circuitry is internal in the Micro-processor although the crystal is external.

1 The Micro-Processor, through Write I/O Decoder 3,
line 8, Detector Latch 9 and the Data Bus 18, selects which
of the High Voltage switches 10 or 11 will be closed to
apply voltage from Power Supply 12 through a capacitor to
5 pulse bias G-M tube 13 or 14 for operation. The strikes
detected by the G-M tubes are shaped by the Probe Output
Buffer 15 and passed to the CLEAR input of the Detector
Latch 9 to clear the Latch and drive the HI and LO outputs
low to disable the active G-M tube by discharging it through
10 the Switch. A pair of transistor switches provide the bias
and discharge functions within each High Voltage Switch 10
and 11. When either of the HI or LO latch outputs is up, a
signal is routed through OR Gate 16 to open the Counter Gate
6. When both HI and LO Latch outputs are down, the Counter
15 Gate is closed. Accordingly, a strike closes the Counter
Gate 6 and stops the count in the Counter 17. The Counter
17 receives and counts timing clock pulses through the
Counter Gate 6 when the latter is open.

 The eight line Data Bus 18, under control of the
20 Micro-Processor 1, carries "count" information to the Memory
2, the count information also being routed via line 19 di-
rectly to the Micro-processor as it is being transmitted
through Counter Read Buffer 20, and also routes information
to Display 24 and to Detector Latch 9 which directs the Latch
25 to enable or disable the High and/or LO High Voltage Switches.
The Counter 17 via the Inverter 21 and Overflow Flip-flop 22
is used to signal the DMA (direct memory access) in the
Micro-Processor upon the RESET of the most significant bit
(MSB) in the 8 Bit Counter 17, a count of 256. After this
30 information is dealt with internally in the Micro-Processor,
a signal from the latter resets the Overflow Flip-flop 22
via the DMA State Decoder 5. This permits a 16 bit extension
of the Counter 17 within the Micro-Processor without inter-
rupting the Micro-Processor programming.

35 Two kinds of count information are displayable under
control of the Micro-processor, namely, the radiation level
being measured and the accumulated dose. When display Dose

1 switch 23 is actuated it causes the Micro-Processor to signal
Write I/O Decoder 3 to enable the Display 24 to decode the
accumulated dose information when it is read out of the Memory
2 onto Data Bus 18, the decoded dose data passing into the
5 Display 24, for visible display. When the Dose switch 23 is
not actuated, the Write I/O Decoder 3 signals the Display 24
to decode the currently measured radiation level when that
information is on the Data Bus from the Memory. The Switch
Read Buffers 25 at the appropriate times, under control of
10 the Micro-Processor via Read I/O Decoder 4, place onto the
Data Bus 18 scale factors corresponding to the HI and LO
ranges and a correction factor to correct for circuit delay
time. Alarm conditions are indicated by the Alarm 26, and
the entire equipment is turned on and off by switch 27.

15 The Micro-Processor operates on a defined time period,
as for example two seconds, which is divided into a data pro-
cessing time of for example 0.3 seconds followed by a data
collection time of the remaining part of the two second cycle,
or about 1.7 seconds. After power is turned on and the system
20 is initialized, data collection begins. The Micro-Processor 1
via Write I/O Decoder 3 and Detector Latch 9 generates a LO
enable signal to the LO High Voltage Switch 10 which closes
the switch and applies 550 volts D.C. from the H.V. Power
Supply 12 to pulse bias the Low Range G-M Detector tube 13
25 to detect radiation. The LO enable is passed through OR Gate
16 to open the Counter Gate 6 via line 28 and pass the clock
pulses to be counted in the Counter 17 which has been cleared
by a pulse from the Read I/O Decoder 4 as directed by the
Micro-Processor. This counting continues until the Detector
30 Latch 9 is cleared either by a pulse from the Probe Output
Buffer 15 which is generated by a radiation incident or by a
signal from the Micro-Processor after the two second Micro-
Processor defined time period expires. The clearing of the
Detector Latch removes the LO enable output which sends a
35 signal to the Micro-Processor E flag input and also closes
Counter Gate 6 terminating the transmission of clock pulses
to the Counter 17.

1 The signal sent to the Micro-Processor E Flag input
via line 28 tells the Micro-Processor that a "strike" has oc-
curred so that the Micro-Processor can start counting to wait
1.5 milliseconds to insure that the G-M tube full recovery
5 time has elapsed before sending another enable signal to the
High Voltage switch to again pulse bias the G-M tube. After
a data collection cycle (I.E. 1.7 seconds), the Micro-
Processor disables the G-M tube via the Write I/O Decoder 3,
the Detector Latch 9, and LO H.V. Switch, reads into Memory
10 the 24 bit Counter time and the scale factor and circuit
delay time from the Switch Read Buffers 25, and after allow-
ing processing time (I.E. 0.3 seconds) causes another signal
to be sent to the High Voltage Switch 10 via the Write I/O
Decoder 3, the Detector Latch 9 and Data Bus 18 to again
15 pulse bias the G-M tube and start another data collection
cycle.

 If the radiation field present is too strong for
counting with Low Range tube 13, the Micro-Processor applies
a pulse via the Write I/O Decoder 3 and Data Bus 18 to cause
20 the Detector Latch 9 to generate a HI enable signal to the
High Voltage Switch 11 which closes and applies 550 volts
D.C. through a capacitor to pulse bias the High Range De-
tector tube 14 and condition it for radiation detection, the
LO Range Detector tube 13 remaining inoperative. The Micro-
25 Processor determines that the field is too strong for low
range use by monitoring the Counter 17 through the Counter
Read Buffer 20 and Overflow Flip-flop 22, and determining
that the average time-to-count is less than a pre-set pro-
grammed time, as for example six microseconds which equates
30 to a level of five Roentgens per hour. It also determines
when a field is too weak for statistically reliable measure-
ment on the high range, and automatically switches to the
low range. This is done whenever the time-to-count exceeds
for example twenty five thousand (25,000) microseconds,
35 which equates to three Roentgen per hour. This switching
as described is accomplished via the Write I/O Decoder 3
and Detector Latch 9. The remaining high range sequence

1 is the same as for the Low Range Detector.

5 This counting sequence is repeated and a weighted measurement is made in the Memory 2. This measure of the radiation present is normally displayed on the Liquid Crystal Display 24 except, as previously described, when the Display Dose Switch 23 is actuated. The Display is typically up-dated every two seconds. The Micro-Processor will indicate an alarm condition through the Alarm 26 if the radiation present exceeds the alarm level programmed in Memory 2. This
10 alarm could be audible or visual.

Illustrative of the average times to count using the previously given equation and the set of G-M tubes indicated, are the following.

<u>HIGH RANGE (3G10 G-M tube)</u>	
<u>Field Intensity R/hr</u>	<u>Average Time to Count (usec)</u>
10,000	8.33
1,000	83.33
100	833.3
10	8,333
1	83,333
0.1	833,333
0.01	8,333,333
<u>LOW RANGE (18505 G-M tube)</u>	
<u>Field Intensity R/hr</u>	<u>Average Time to Count (usec)</u>
10 R/hr	3.125
1 R/hr	31.25
.1 R/hr	312.5
10 mr/hr	3,125
1 mr/hr	31,250
.1 mr/hr	312,500
0.01 mr/hr	3,125,000

From the above tables it can be seen that by simply measuring the "time to count" parameter, a significant extension of operating range without detector switching is made available.

35 This makes certain features available, if desired, that are denied in other approaches. For example, using a low range frisking probe in conjunction with the 18505 G-M tube could

1 provide a gamma-beta capability in excess of 50 R/hr with
excellent linearity and statistical reliability.

5 In general, there are a number of advantages over
other approaches to be realized through use of this new mode
of G-M tube operation. Perhaps the most important, however,
when considering long term accuracy, stability and overall
precision, is that the new method lends itself to a totally
digital system. No analog measurements are required, all
data and signals are in the form of "ons" and "offs" with
10 the one required reference being a crystal controlled oscil-
lator, a most reliable form of standard. It is to be noted
that items such as G-M starting voltage changes, G-M tube
plateau length, generation of narrow H.V. pulses or analog
variations such as charge per pulse, ion chamber current, MOS
15 FET leakage current, etc. are ameliorated by the "time to
count" method of operation. This mode of operation is analo-
gous to operating an ideal detector with zero dead time and
simply counting pulses. Operation of that type would produce
a linear reduction of the interval between pulses as the
20 field intensity is increased, whereas the method of operation
according to the invention produces a linear reduction of the
time to count" as the field intensity increases.

The effect on real time of the tube dead time is re-
moved by virtue of stopping the time measurement for 1.5
25 milliseconds when a G-M pulse is obtained. Therefore, tube
dead time and its effect, which normally produces a non-
linear readout, is removed in the new method of operation.
As previously indicated, the parameter which is proportional
to field intensity is the reciprocal of "average time to
30 count". To obtain this measurement the proposed method re-
quires the division at routine intervals, for example two
seconds, of the accumulated G-M tube counts by the total ac-
cumulated "time to count". Before this division, however,
the time data is adjusted by a calibration constant corres-
35 ponding to the circuit delay constant. This quotient is then
multiplied by a calibration constant corresponding to the G-M
tube scale factor and applied to a digital readout to provide

- 1 the radiation field intensity in mr/hr or R/hr averaged over a certain time period.

The field intensity information in the Mr/hr levels can be presented in the form of a smoothed average with a digital update appearing every two seconds. This removes the necessity of a long waiting period prior to obtaining field intensity readings or updates in low level areas. The R/hr levels can be digitally displayed every two seconds or a running average can be displayed every two seconds.

- 5
- 10 The method of using a running average is similar to the time constant employed in analog measurements except that rapid changes in field strength can be used to clear the previous dose rate information and the new level presented in the very next update display. Total dose information is obtained
- 15 from the incremental two second field intensity information. Every 2 seconds the dose rate number would be divided by 1800 and stored to provide a continuous record of dose.

An operative program for the illustrated system is as follows for a measured time period data collection cycle, as controlled by the micro-processor.

- 20 1)- Initialize for data collection by zeroing the strike count in the micro-processor.
- Reset 24 bit Hardware/software counter timer to zero.
- 25 2)- Acquire data.
- BEGIN
- a) Enable appropriate detector (HIGH or LOW range)
 - b) Wait for (b_1) GEIGER PULSE or (b_2) CALCULATION TIME out flag (interval in Micro-processor)
- 30 (b_1)- WHEN GEIGER PULSE OCCURS increment by one the strike count stored in the Micro-processor and wait out geiger tube FULL RECOVERY TIME.
- IF CALCULATION time out flag, THEN BRANCH TO data calculation (b_2)
- 35 - ELSE go back to 2a)

1 END

 (b₂)- WHEN CALCULATION time out flag:

 - Turn off active detector via detector latch (also stops timer)

5 - Read 8 bits from Counter into Micro-processor and combine with 16 bits of extended count to get ACCUMULATED TIME SUM.

 The 24 bit time count = T1 (Accumulated time 1)

 - Read and store range scale and circuit delay factors

10 3) T2 = T1- (Number of Strikes x Circuit Delay Correction factor)

 Calculate FIELD STRENGTH and UPDATE DOSE

4) Divide adjusted sums.

 RATE 1 = EVENT SUM/ACCUMULATED TIME SUM.

 (EVENT = STRIKE)

15 5) Scale RATE 1 according to HIGH or LOW range scale factors.

 RATE 2 = RATE 1 x SCALE FACTOR.

6) Update accumulated DOSE according to RATE (field strength).

 DOSE = DOSE + (RATE 2 x 1/1800)

7) Test for DOSE ALARM.

20 8) Filter rate using digital filter to smooth the display

 RATE 2 $\xrightarrow{\text{filter}}$ RATE 3

9) Test for RATE (field strength) ALARM.

 (use RATE 3 for test)

10) Update RANGE flag for next data collection time.

25 (Select HI or LO range)

 (use RATE 3 for update)

11) Branch back to 1) and start collecting data.

Typically, the components of the block diagram could be the following

30	Micro-processor 1	GDP 1805
	Memory 2	
	Address latch	GD 40174
	Address decoder	MS 14556
	E PROMS	NMC 27C32
35	RAM	CMD 6116
	Detector Latch 9	GD 40174
	Write I/O Decoder 3	GD 4028

1	DMA State Decoder 5	MC 14556
	Read I/O Decoder 4	MM 74C42
	High voltage switches 10,11	2N5096, 2N5011
	Probe Output Buffer 22	CD 4049
5	Counter gate 6 and Alarm 26	CD 4093
	Counter 19	CD 14520
	Read Buffers 20,25	MM 74C244
	Overflow Flip-flop 22	MM 74C374
	Display 24	Hamlin LCD, MC 14543,
10		74C374

Having now described our invention in connection with a particularly illustrated embodiment thereof, variations and modifications of the invention will now naturally occur to those persons normally skilled in the art without departing from the essential scope or spirit of the invention; and accordingly it is intended to claim the same broadly as well as specifically as indicated by the appended claims.

CLAIMS

- 1 1. Apparatus for measuring radiation field strength
characterised by,
- 5 a) a biased potential radiation detector having an out-
put circuit, said detector being of the type that is
effective when biased to respond to impingement of
radiation by generating an output pulse at its output
circuit, and when not biased being ineffective to
generate an output pulse when impinged by radiation,
- 10 b) biasing means operatively coupled to said radiation
detector for selectively biasing said radiation de-
tector to generate an output pulse in response to im-
pingement by radiation,
- 15 c) time counting means including timing control means
operable to start and terminate time counting, said
radiation detector output circuit being operatively
coupled to said time counting means and being effec-
tive upon generation of an output pulse to cause said
time counting means to terminate time counting,
- 20 d) master control means operatively coupled to
(1) said biasing means to selectively cause said
biasing means to bias said radiation detector
to respond to impingement by radiation,
- 25 (2) said time counting means and effective to cause
said time counting means to start time counting
simultaneously with the operative biasing of said
radiation detector, said master control means
receiving a signal when said radiation detector
generates an output pulse.
- 30 2. Apparatus as described in claim 1 wherein said master
control means is operatively coupled to said timing control
means part of said time counting means to start time counting.
- 35 3. Apparatus as described in claim 1 wherein said master
control means receives a signal from said radiation detector
output circuit through said timing control means part of said
time counting means.

1 4. Apparatus as described in claim 1 wherein said master
control means causes said biasing means to bias said radia-
tion detector for response to radiation only when a prede-
5 terminated time has elapsed after said master control means
has received a signal in response to generation of an out-
put pulse by said radiation detector.

5 5. Apparatus as described in claim 1 wherein said master
control means causes said time counting means to start
10 counting time only when a predetermined time has elapsed
after said master control means has received a signal in
response to generation of an output pulse by said radiation
detector.

15 6. Apparatus as described in any preceding claim including
memory means operatively coupled to said master control means
and to said time counting means, said master control means
being operative to transfer time counts in said time counting
means to said memory means where the time count information
20 is translated into radiation field intensity information in
accordance with the equation $R = \frac{K}{t}$ where R is the radiation
field intensity, t is the time over which the time count is
made, and K is a constant, said radiation field intensity in-
formation being also accumulated in said memory means as cumu-
25 lative dose information.

7. Apparatus as described in claim 1 wherein said master
control means is operatively coupled to said timing control
means part of said time counting means to start time counting,
30 wherein said master control means receives a signal from
said radiation detector output circuit through said timing
control means part of said time counting means, and wherein
said master control means simultaneously causes said time
counting means to start counting time and causes said biasing
35 means to bias said radiation detector for response to radia-
tion when a predetermined time has elapsed after said master
control means has received a signal in response to generation

of an output pulse by said radiation detector.

8. Apparatus as described in claim 1 further including a second radiation detector, second biasing means operatively coupled thereto and to said master control means, and further means operatively coupling said master control means to said time counting means effective to convey time count information to said master control means, said second radiation detector being operable in radiation fields too high in intensity for said radiation detector to function in, and said master control means selectively actuating one of said radiation detector and second radiation detector in accordance with time count information conveyed to said master control means from said time counting means.

9. Apparatus as described in claim 1 wherein said master control means after a first time interval causes said time counting means to terminate time counting for a second time interval, and after termination of said second time interval said master control means causes said biasing means to again bias said radiation detector and simultaneously causes said counting means to start counting.

10. Apparatus as described in claim 1 further including memory means operatively coupled to said master control means and to said time counting means, said master control means being operative to transfer time counts in said time counting means to said memory means where the time count information is translated into radiation field intensity information in accordance with the equation $R_T = \frac{K \times \sum \text{COUNTS}}{\sum t_{ON}}$ where R_T is

the radiation field intensity over a defined time period, $\sum \text{COUNTS}$ is the sum of the counts obtained during the total time that said radiation detector is operative during said defined time period, $\sum t_{ON}$ is the total time that said radiation detector is operative during said defined time period, and K is a constant, said radiation field intensity information

14 being also accumulated in said memory means as cumulative dose information.

5 11. The method of measuring radiation field strength characterised by the steps of,

- a) activating a radiation detector in a radiation field and simultaneously activating a time counting device to count time,
- 10 b) generating a marker signal in response to radiation detection,
- c) utilizing the marker signal to deactivate the time counting device,
- d) translating the time count registered by the time counting device in accordance with the formula

15
$$R = \frac{K}{t}$$

where, R is the radiation field intensity

t is the time between activation and deactivation of the time counting device, and

K is a constant.

20

12. The method as set forth in claim 11 wherein the step of translating the time count includes the steps of,

- a) operating on the time count data to obtain the radiation field strength over a predetermined fixed time interval, and
- 25 b) operating on the just obtained radiation field strength to reduce variations in the data for display.

30 13. The method as set forth in claim 11 including the further step of disabling the radiation detector for a predetermined length of time after generation of the marker signal.

35 14. The method as set forth in claim 11 including the further step of utilizing the marker signal as a time reference to prevent activation of the radiation detector for a predetermined length of time after generation of the marker signal.

- 1 15. The method as set forth in claim 11 including the further
steps of continuously repeating the step sequence of claim 11,
and for each sequence carrying out the steps of,
- 5 a) operating on the time count data to obtain the radiation
field strength over a predetermined fixed time
interval, and
- b) operating on the just obtained radiation field strength
to reduce variations in the data for display.
- 10 16. The method as set forth in claim 11 including the further
steps of continuously repeating the step sequence of
claim 11 and for each sequence carrying out the steps of,
- 15 a) operating on the time count data to obtain the radiation
field strength over a predetermined fixed time
interval,
- b) adding the obtained radiation field strength to previously
stored accumulated dose information, and
- c) operation on the just obtained radiation field strength
to reduce variations in the data for display.
- 20 17. The method of measuring radiation field strength
characterised by the steps of,
- a) activating a radiation detector in a radiation field
and simultaneously activating a time counting device
- 25 to count time,
- b) generating a marker signal in response to radiation
detection,
- c) utilizing the marker signal to deactivate the time
counting device,
- 30 d) repeating steps a), b), and c) continuously for a
defined time period,
- e) translating the time count registered by the time
counting device in accordance with the formula

35

$$R_T = \frac{K \times \sum \text{COUNTS}}{\sum t_{ON}}$$

1 where, R_T is the radiation field intensity over the
defined time period

5 Σ COUNTS is the sum of the Counts obtained
during the total time that said radiation
detector is activated during said defined
time period

10 Σt_{ON} is the total time that said radiation de-
tector is activated during said defined time
period

K is a constant

18. The method as set forth in claim 17 further including
after each step c), the step of waiting a pre-set time in-
terval before commencing step a).

