

(12)

**EUROPEAN PATENT APPLICATION**

(21) Application number: **85108916.9**

(51) Int. Cl.<sup>4</sup>: **G 21 C 17/00**

(22) Date of filing: **16.07.85**

(30) Priority: **30.07.84 US 635853**

(43) Date of publication of application:  
**19.02.86 Bulletin 86/8**

(84) Designated Contracting States:  
**BE DE FR NL SE**

(71) Applicant: **COMBUSTION ENGINEERING, INC.**  
**1000 Prospect Hill Road Box 500**  
**Windsor Connecticut 06095(US)**

(72) Inventor: **Wentzell, Timothy H.**  
**630 Governor's Highway**  
**South Windsor Connecticut 06074(US)**

(74) Representative: **Mehl, Ernst, Dipl.-Ing. et al,**  
**Postfach 22 01 76**  
**D-8000 München 22(DE)**

(54) **Tool for scanning the inner surface of a large pipe.**

(57) A tool (100) for scanning the inner surface (110) of a pipe (106), comprising a scanning section (112) interacting with a centering section (114). The scanning section includes an axle member (128) having strut members (130) rigidly connected thereto and projecting diametrically outwardly for urging inspection probe sleds (126) against the pipe surface. The centering section (114) includes a slide cylinder (124) coaxially disposed about the axle member (128), and having rigidly connected actuating members (120) projecting diametrically outward for contacting the pipe inner wall with sufficient force to center and support the tool within the pipe. Locking means (146) are provided within the actuating member (120) for selectively engaging the axle member (128) to lock the longitudinal position of the strut member (130) relative to the actuating member (120). A positioning device (102) is connected to the axle member (128) whereby in a first mode of operation the scanning section (112) can be rotated or moved longitudinally relative to the supporting base provided by the centering section (114). In a second mode of operation, the actuating members (120) are disengaged from the pipe surface (110) and the axle member (128) is locked to the slide cylinder (124) by means of a piston (140), and locking rod (142, 146). In the lock mode, the tool (100) can be relocated within the pipe (106). The tool provides centering and support even in pipe elbows, such that the probe sleds can traverse and closely follow the entire contoured pipe surface (110).

./...

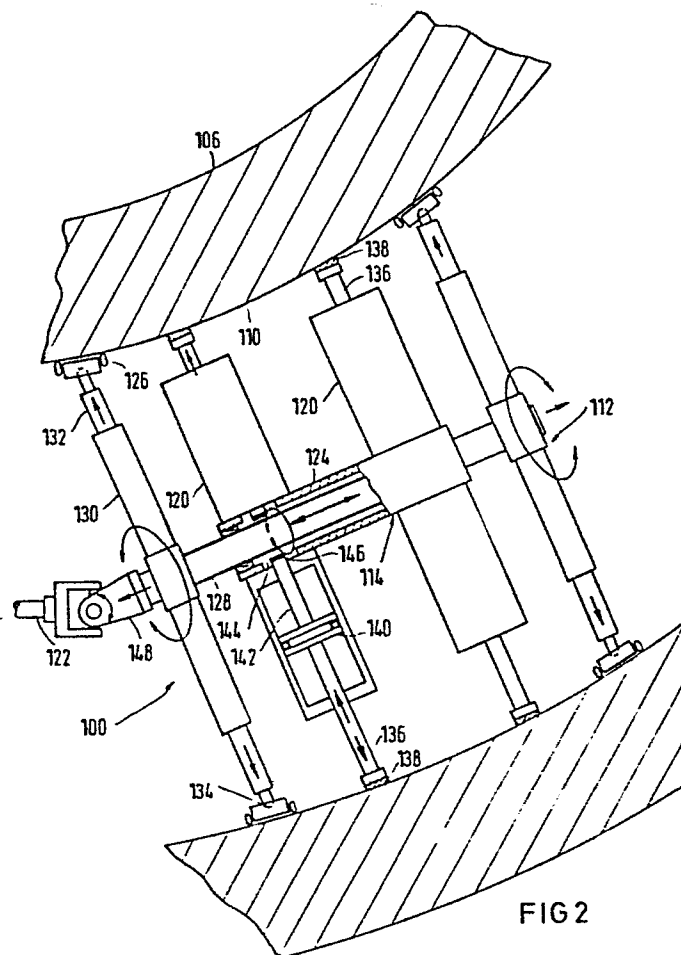


FIG 2

TOOL FOR SCANNING THE INNER SURFACE  
OF A LARGE PIPE

BACKGROUND OF THE INVENTION

This invention relates to remotely controlled tools  
5 for use in relatively inaccessible areas, and more particularly  
to a tool for internally inspecting elbows in large pipes.

In many industries, the need arises for inspecting  
the integrity or surface properties of large pieces of  
equipment that may operate under pressure or otherwise have  
10 potentially severe economic or safety consequences in the event  
of rupture or failure. In the nuclear power industry, the  
reactor vessel and associated nozzles and piping must be  
periodically inspected. One area that has been particularly  
difficult to inspect is the elbow area in piping connected to  
15 reactor vessel. Ultrasonic inspection of the pipe is desired  
to assure that no cracks or other weaknesses will render the  
pipe susceptible to failure.

SUMMARY OF THE INVENTION

The apparatus of the present invention solves this  
20 problem, in the form of a unique tool having two major  
sections, a scanning section and a centering section. In use,  
the inspection tool is preferably mounted on a conventional  
positioning device that is aligned with the reactor vessel  
nozzle from within the vessel. The scanning section of the  
25 tool carries sleds for supporting conventional ultrasonic  
probes, and the centering section provides a means for

centering the tool within the pipe and supporting it during longitudinal and rotational motion of the scanning section.

In more specific terms, the scanning section includes an axle member to which are rigidly connected preferably two  
5 sets of diametrically extending strut members. The strut members include outer portions which carry the sleds and have means for urging the sleds outwardly toward the internal surface of the pipe. The centering section includes a slide cylinder or sleeve coaxially disposed about the axle member and  
10 having preferably two sets of actuating members rigidly connected thereto and projecting diametrically outward. The actuating members include means for extending the outer portion of the member into contact with the pipe wall under sufficient pressure to secure the tool within the pipe. Locking means are  
15 operatively connected to the actuating member for selectively engaging the axle to lock the longitudinal position of the strut member relative to the actuating member.

When connected to the conventional remote positioner, the tool operates in essentially two modes. Once the tool has  
20 been initially positioned within the nozzle or pipe, the first mode begins when the actuating members are extended to bear upon the pipe internal surface to center and secure the tool. The axle member is free to rotate within the sleeve thereby enabling the sleds carried thereon to make a complete  
25 revolution around the inner surface of the pipe. With the centering section in place, the positioner may advance the scanning section longitudinally relative to the centering section and then rotate the scanning section to test another circumferential strip on the pipe inner surface.

30 After several such rotations, the entire tool must be advanced within the pipe, in accordance with the second mode of operation. The outward bias on the struts is relaxed and the actuating member is retracted. While retracting, the actuating member locks the axle member with respect to the sliding  
35 sleeve. When the positioner pushes on the tool, the entire tool moves further into the pipe. The locking action maintains the spatial relationship between the scanning section and the centering section.

To begin another inspection cycle, the centering section is secured to the inner surface of the pipe and the scanning section is extended to urge the inspection sleds against the pipe wall.

5           The present invention provides a tool for inspecting the curved, or elbow portion of a large pipe by uniquely coordinating of the centering and supporting function, with the inspection probe translation function. The inspection struts can be rotated to enable gimbaled sleds to maintain  
10 perpendicularity with respect their respective traversed surfaces, while the centering section provides a firm, centered base. Several scan rotations can be taken from a given base position, since the scanning and centering sections are independent during the inspection mode. The precise location  
15 of the sleds can be controlled and recorded based only on the known coordinates of the positioner, without significant uncertainties added by the inspection tool itself.

#### BRIEF DESCRIPTION OF THE DRAWINGS

Additional features, benefits and advantages of the  
20 invention will be evident to those skilled in this art, from the description of the preferred embodiment set forth below and the references to the accompanying figures, in which:

Figure 1 is a partially sectioned view of a nuclear reactor vessel nozzle and pipe elbow in which are located a  
25 conventional remote positioner device to which is attached the inventive inspection tool; and

Figure 2 is an enlarged, partially sectioned view of the inspection tool, showing in partial cut-away, the relationship between the scanning section axle member and the  
30 centering section sleeve cylinder.

#### DESCRIPTION OF THE PREFERRED EMBODIMENT

Figure 1 shows the inventive inspection tool 100 connected to a conventional remote positioner 102, as would be employed for making an ultrasonic inspection of the inner  
35 surface of the nozzle 104 and pipe 106 associated with a nuclear reactor vessel 108. The positioner 102 is typically centered on the vertical axis of the vessel 108 and is extended

transversely from the vessel axis along the centerline of the nozzle inner wall 104. The invention will be described with respect to an intermediate position along the pipe 106, where a turn, or elbow 110 in the pipe prevents acceptable operation of conventional inspection tooling.

The basic operation of the tool 100 involves a scanning section 112 interacting with a centering section 114. The centering section 114 centers and supports the inspection tool 100, while the extension mechanism 116 and rotator mechanism 118 on the remote positioner 102 control the scanning section 112. Energizing the actuator or centering cylinders 120 secures the tool against the inner surface of the pipe 106. Either longitudinal or rotational motion may be imparted to the scanning section 112, even at the pipe elbow 110 through the flexibility provided by the dual universal joint 122. The scanning section 112 carries pivoted or gimbaled sleds 126 which follow the pipe contour.

Figure 2 is an enlarged view of the inspection tool 100 shown in Figure 1, with a partially cut-away view of the central portion of the tool to illustrate the relationship between the scanning section 112 and the centering section 114. The centering section 114 includes a slide cylinder 124 preferably in the form a journal bearing tube oriented generally coaxially with the center line of the pipe 106. The actuating cylinders 120 are rigidly connected to the slide cylinder and extend diametrically toward the pipe inner surface. Preferably, two sets of such actuating cylinders 120 are adjacently connected on a single slide cylinder 124.

The scanning section 112 includes a hub or axle member 128 coaxially disposed within the slide cylinder 124 and adapted to rotate and slide therewithin. A set of strut members 130 extend diametrically from the axle member 128, at preferably both ends thereof, outside the actuating cylinders 120. Inspection probe sleds 126 are located on outer strut segments 132 which are preferably outwardly biased by controlled air pressure through the axle member 128 and strut 130. The sleds 126 are preferably gimbaled 134 to allow the

sleds to maintain perpendicularity with respect to the pipe inner wall 110. Although the illustrated embodiment is directed to an ultrasonic inspection tool, it should be appreciated that other types of probes, transducers or devices could be carried by the sleds without departing from the scope of the invention.

Each actuating cylinder 120 preferably includes an outer actuator portion 136 having support pads 138 thereon for engaging the pipe walls to prevent sliding. The outer actuator portion 136 is preferably controlled by a piston 140 to which is also connected an inner rod 142 that passes through an opening 144 in the slide cylinder or sleeve 124. Locking pads 146 are adapted to engage the axle member 128 when the piston 140 moves towards the sleeve 124, thereby retracting the outer portion 136 while locking the scanning section 112 to the centering section 114. This locks the longitudinal position of the strut member 130 relative to the actuating member 120 and enables the extension mechanism 116 on the remote positioner (Figure 1) to push the entire inspection tool 100 to a new basic location deeper into the pipe 106.

Once the tool is relocated to the new basic position, the pistons 140 are actuated outwardly to disengage the locking pads 146 and to engage the support pads 138. The sleds 126 are urged outwardly into contact with the pipe wall 110, and the scanning section 112 may be rotated or moved longitudinally a short distance along the pipe relative to the fixed position of the centering section 114. Preferably, several rotations are made by the scanning section 112 for a given fixed position of the centering section 114 so that the time required to complete a pipe inspection is minimized. After several rotations the strut member 130 will nearly abut the actuating cylinder 120 and a move of the entire tool 100 to a new position would be required. Since the axle 128 is locked to the slide cylinder 124 during relocation of the tool, the relative longitudinal spacing between the scanning section 112 and centering section 114 is not altered. Thus, only the movement of the extension mechanism 116 and rotator 118 need be

monitored to accurately establish the position of the sleds 126 within the pipe 110.

In the illustrated embodiment, a mounting boss 148 is located on the end of the axle member closest to the positioner 5 102, for connecting the tool 100 to the means for imparting longitudinal and rotational movement to the axle member 128, or scanning section 112. Thus, the scanning section may be considered the primary component that is connected to and controlled by the positioner 102 . The centering section 114 10 is relatively slidable and selectively lockable thereto, for providing centering and support during the movement of the scanning section associated with the surface inspection operation.



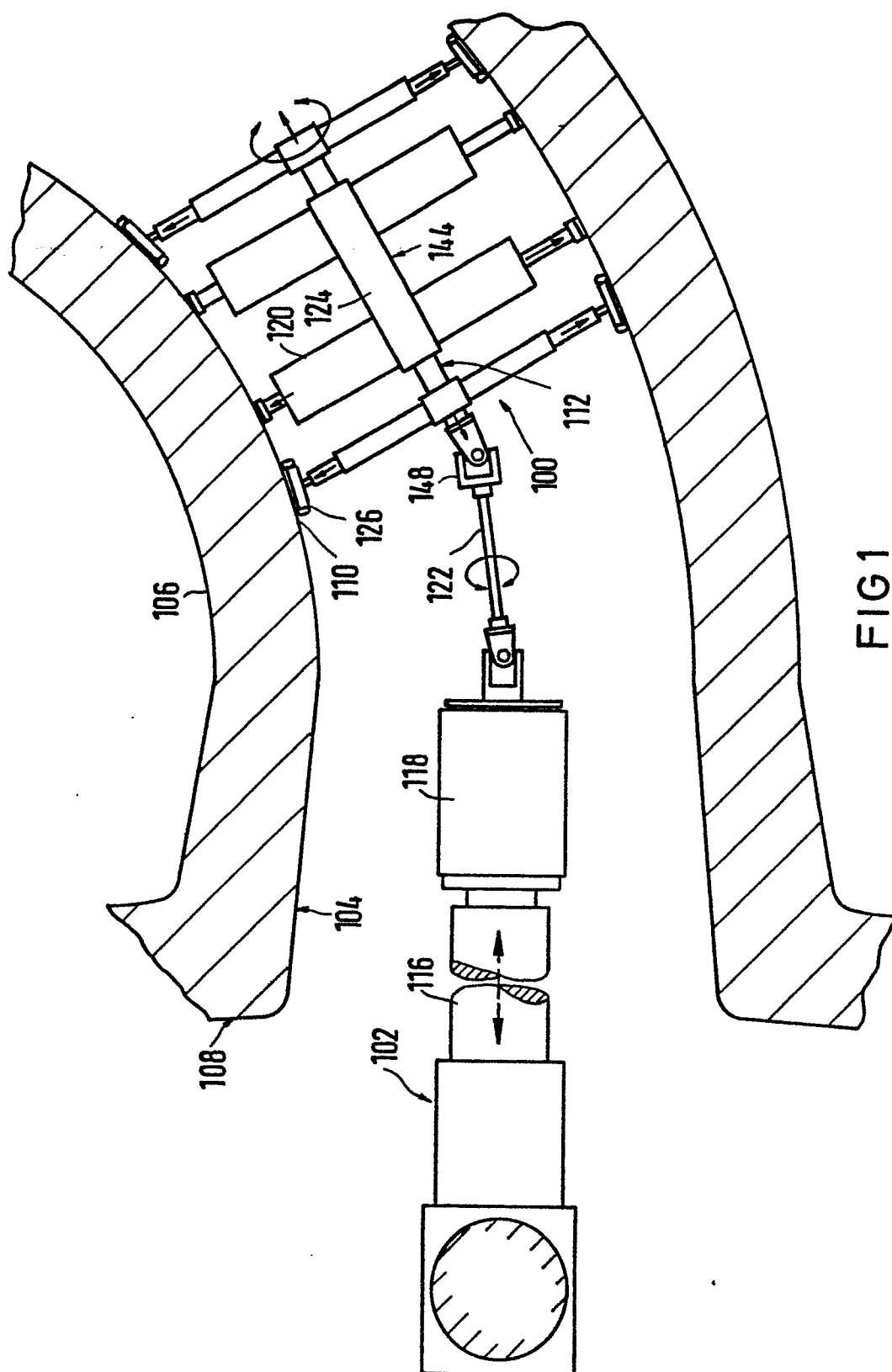
CLAIMS

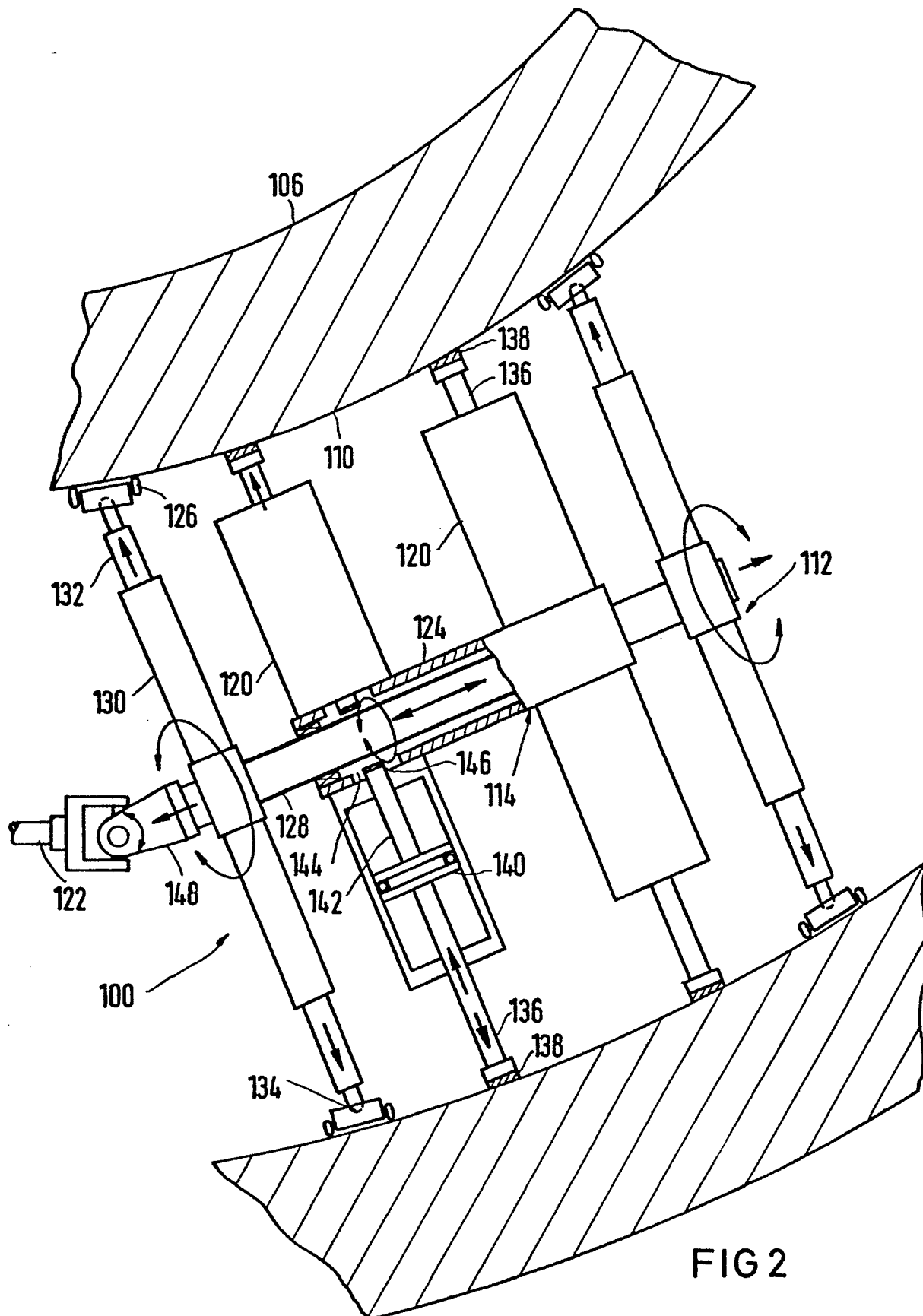
1. A tool for scanning the inner surface of a pipe,  
comprising:
  - an axle member (128) having at least one strut member
  - 5 (130) rigidly connected thereto and projecting diametrically outward therefrom, the strut member including an extendable outer portion (132) for urging sled means (126) against said surface;
  - a slide cylinder (124) coaxially disposed about said
  - 10 axle member (128) and having at least one actuating member (120) rigidly connected thereto and projecting diametrically outward therefrom, the actuating member including an outer portion (136) extendable with sufficient force to contact said surface and center and support the tool within the pipe;
  - 15 locking means (146) operatively connected to said actuating member (120) for selectively engaging the axle member (128) to lock the longitudinal position of the strut member (130) relative to the actuating member (120);
  - mounting means (148) located on one end of the axle
  - 20 member for engaging a positioner device (102) capable of imparting longitudinal and rotational motion to said axle member (128);
  - whereby in a first mode of operation the actuating member (120) can be extended to bear upon said surface and
  - 25 said strut members can be rotated or advanced longitudinally within the pipe by said positioner means (102), and in a second mode the slide cylinder (124) can be locked to said axle (128) the strut members (130) relaxed, and the actuator member (120) retracted such that the entire tool (100) may be moved
  - 30 longitudinally within the pipe.
2. The tool recited in Claim 1 wherein,
  - the slide cylinder (124) is in the form of a journal bearing tube having openings (144) the actuating members (120) and said locking means (146) pass through said openings from
  - 35 the actuating member (120) to said axle member (128).
3. The tool recited in Claim 2 wherein,
  - said actuating member (120) includes a piston member

(140) having an inner rod (142) adapted to pass through said opening (140) in the slide cylinder (124) and support said locking means (146).

4. The tool recited in Claim 1 wherein said sled  
5 means (126) are gimbaled (134) to remain perpendicularly oriented to the pipe wall as the strut members are rotated by the positioner.

5. A remote inspection tool comprising,  
a scanning section having a plurality of rigidly  
10 connected strut members extending outwardly from a hub member, each strut member carrying an inspection sled at its outer end;  
a centering section having a plurality of actuator members rigidly connected to and extendable outwardly from a sleeve member, said sleeve member and hub member connected  
15 together to permit relative longitudinal and rotational movement therebetween;  
means for selectively locking the hub member to the sleeve member such that the positions of the strut members relative to the actuator members do not change when the entire  
20 tool is moved from one location to another.







DOCUMENTS CONSIDERED TO BE RELEVANT			
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. Cl. 4)
A	EP-A-0 061 078 (KRAFTWERK UNION) * Page 7, lines 7-34; figures 1,5,6,11-16 * ---	1,3,5	G 21 C 17/00
A	DE-A-2 640 055 (KRAFTWERK UNION) * Page 9, lines 7-37; page 10, lines 1-17; page 12, lines 27-32; figures 1-6 * ---	1,5	
A	FR-A-2 336 681 (KRAFTWERK UNION) * Page 18, lines 5-33; figures 7,8 * ---	4	
A	EP-A-0 105 418 (HITZEL) * Abstract; figure 1 * -----	1	
			TECHNICAL FIELDS SEARCHED (Int. Cl. 4)
			G 21 C 17/00 G 01 N 27/00 G 01 N 29/00 B 08 B 9/00 E 21 B 4/00
The present search report has been drawn up for all claims			
Place of search THE HAGUE		Date of completion of the search 12-11-1985	Examiner KAVCIC D.
<p><b>CATEGORY OF CITED DOCUMENTS</b></p> <p>X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document</p> <p>T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons &amp; : member of the same patent family, corresponding document</p>			