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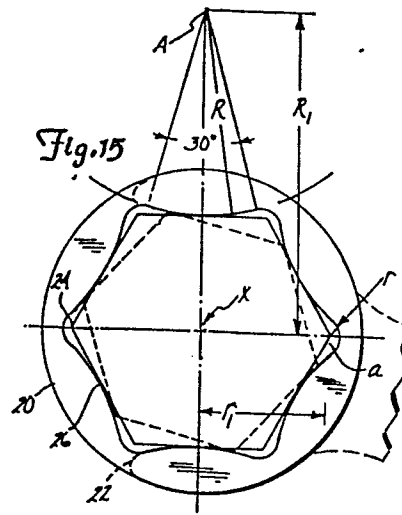
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(54) Wrenching tool.

(57) Rotary wrenching tools are sized, in one embodiment, to strongly and adequately receive heads of fastening members of two or more nominal sizes having maximum size ratios in the approximate size ranges of 1.0053-1.1430 for square heads and 1.0053-1.0600 for hexagonal heads. Visible indicia of the sizes of at least two different fastener head sizes are carried adjacent each opening.



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ROTARY WRENCHING TOOL

FIELD OF THE INVENTION

This invention relates to rotary tools of the type used in rotating or "wrenching" fasteners such as bolts and screws having polygonal (e.g., square or hexagonal) heads. The invention particularly relates to tools capable of wrenching fastener heads designed, sized or marked in various measuring systems such as the metric system, the English or inch system such as the American fractional system (AF and SAE), and the British systems such as BA, BS and Whitworth (W).

BACKGROUND OF THE INVENTION

Many countries have adopted the metric measuring system for the manufacture of bolts, screws, nuts and wrenches. Such countries as France, Germany, Italy, Japan, Czechoslovakia and Russia today almost exclusively utilize the metric system for such manufactures. The United States, Canada, England, Australia, New Zealand and the like, use measuring



systems based upon both the English (inch) and metric measuring systems.

National standards or specifications have been adopted by many technically developed countries for sockets and other wrenches. These standards, which differ at least in part from one another, include SAE, ASTM, MIL, GGG-W, BS, FS, DIN, JS, CSN, JUS, and GOST. No uniform international standard has yet been accepted, although more than fifteen years have been devoted to the effort to reach a standard acceptable to all technically developed countries. Great Britain, for example, presently uses up to six different systems for marking spanners, sockets and other wrenches. The United States predominantly uses the English (inch) system (AF, ANSI, MIL and SAE) and, to some extent, the metric system (millimeters). The diversity in such standards has limited the development of new types of bolts, nuts and wrenching tools. Periodic reviews and revisions of such standards have not produced the necessary changes to cover rapid development of a new type of wrenches, and the issuance of new, updated standards often takes over fifteen years. Consequently, a vast number of different wrenching tools of various designs, openings and tolerances are manufactured throughout the world. A user is subjected to a never-ending inventory of wrenching tools to accommodate all of the sizes and measuring systems in existence today. This is costly and inconvenient for individuals and for industry in general.

One attempt to simplify this situation is found in U.S. Patent 4,100,824 which describes a wrench with a non-uniform interior configuration having one set of grooves sized in the English system and another set of

grooves sized in the metric system. This patent does not address the problems created through the use of various additional measuring systems. Care needs to be taken with this system to insert the bolt or nut head in the correct set of grooves, and this wrenching system moreover generally is not suitable for use in impact or power sockets or in open end wrenches and British sized spanners and sockets.

U.S. Patent 3,027,790 discloses a wrench having several moving parts as adaptors and does not appear to represent a practical solution to the problem, since professionals and serious amateurs appear to prefer solid one-piece wrenching tools with no extraneous parts.

It would be desirable to provide simplified rotary wrenching tools having the ability to drive one or more and, desirably, up to six different sizes of fasteners, and wrenches having better performance in bearing action in tightening or loosening fasteners without damage to either the tool or the fastener.

SUMMARY OF THE INVENTION

The invention in one embodiment provides simple, single piece rotary wrenching tools having uniform interior configurations and no moving parts and which are specifically sized for turning fasteners (nuts, screws, bolts, etc.) having square, hexagonal or other polygonal heads such that one tool size is capable of strongly and adequately fitting polygonal heads nominally sized in at least two and up to six different nominal sizes and up to seven different system markings. By "rotary tool", "spanner" or "wrench", as used herein, reference is made to tools



having openings which completely or partially encircle or encompass the polygonal heads of threaded fasteners such as bolts and screws to rotate the fasteners. Thus, such tools may be of the socket variety in which the rotary tool opening completely encircles the head of the threaded member and is moved into such position axially of the threaded member, or may be of the spanner or open-end wrench variety in which the rotary tool opening only partially encircles the head of the threaded member and may be moved into its wrenching position in a direction generally normal to the axis of the threaded member. Rotary tools include such tools as may commonly be referred to as socket wrenches, box-end spanners, ratcheting box-end, open end, nut drivers, flare-nut, lug-nut, crowfoot and combination wrenches, impact and power socket wrenches, flex-head wrenches, etc.

In this first mentioned embodiment, wrenching tools which are adapted for use with threaded members having square heads are so sized as to accommodate maximum and minimum sized square-headed members such that the maximum ratio of the nominal distance across opposing flats of such maximum and minimum square-headed members ranges from about 1.0053 to about 1.1430. Similarly, in this first-mentioned embodiment, wrenching tools which are adapted for use with threaded members having hexagonal heads are so sized as to accommodate maximum and minimum sized hexagonal headed members such that the maximum ratio of the nominal distance across opposing flats about of such maximum and minimum sized members ranges from about 1.0053 to about 1.0600. Further, such wrenching tools desirably have inner, head-confronting surfaces contoured to provide recesses positioned opposite corners

of the fastener heads so as to avoid contact between the tool and the head corners. Visible indicia are carried adjacent each wrench opening, such indicia comprising at least two and preferably three or more specific but different nominal sizes in at least two different sizing systems.

In a second embodiment, a rotary wrenching tool of the invention is provided with a uniquely configured opening for receiving a polygonal head of a threaded member. The opening may have an axis of rotation and an inner surface comprising a series of spaced arcuate first surfaces concave to the axis of the opening, each such first surface being defined generally as the locus of points falling a given radial distance r from a first axis itself spaced a distance r_1 from, but parallel to, the axis of the opening, and a series of arcuate second surfaces convex to the axis of the opening and spaced about the circumference of the opening, each such second surface being defined generally as the locus points falling a radial distance R from a second axis spaced itself a distance R_1 from, but parallel to, the axis of the opening. Each surface that forms a portion of the inner surface and that is contiguous to an arcuate surface preferably tangentially merges into that arcuate surface. Desirably, the relationship of r and R is such that if r equals R , the wrench includes surface means providing flat surfaces between and tangentially intersecting the first and second surfaces. R_1 desirably is larger than r_1 , and in the case where each second axis is angularly spaced from at least one next adjacent second axis by 60° , the ratio R_1/r_1 desirably exceeds 1.5 and preferably exceeds

2.0. In this case also, R is desirably equal to or greater than r , and the ratio R/r preferably exceeds about 5.0. Also in this embodiment in which each second axis is angularly spaced by 60° from at least one next adjacent second axis, the adjacent arcuate surfaces preferably merge tangentially into one another.

The second axes of the embodiments described above may, if desired, be spaced from one another by 45° or by 90° to thereby provide an opening accommodating square heads of threaded members. The wrench opening may be provided with a plurality of circumferentially extending surface portions that may intersect at sharp angles, e.g., approximately at right angles, with the inwardly convex arcuate surfaces. Further, inwardly convex arcuate surfaces of different sizes may be interspersed with one another.

The rotary wrenching tools of this second embodiment preferably have head-contacting interiors sized to strongly and adequately grip polygonal fastener heads sized in two, preferably three, and up to six different nominal sizes. The ratio (determined as described above) for tools of this second embodiment accepting square heads ranges from 1.0001 to about 1.1430 and for tools accepting hexagonal heads ranges from 1.0001 to about 1.0600. Also, as the wrench opening sizes are varied (Figures 8, 9, 14, 17, 18, 19, 20, 21), the included angle between adjacent flats preferably is also varied to better accommodate fastener heads sized in different sizing systems.

DESCRIPTION OF THE DRAWING

Figure 1 is a broken-away plan view of a conventional two-contact point drive wrench, the wrench

flats making contact with corners of a square or hexagonal bolt head as shown in phantom lines;

Figure 2 is a broken-away plan view of a conventional three-contact point drive wrench similar to that of Figure 1;

Figure 3 is a broken-away plan view of a conventional four-contact point drive wrench similar to that of Figures 1 and 2;

Figure 4 is a broken-away plan view of a conventional wrench similar to that of Figure 1 but having internal wrench flats designed for turning square bolt heads;

Figure 5 is a broken-away plan view of a conventional six-driving point wrench described in British Patent 508,761 for use with hexagonal bolt heads and which avoids contact with corners of a bolt head, and which can be sized in accordance with the present invention;

Figure 6 is a broken-away plan view of a conventional twelve-contact point drive wrench for turning hexagonal headed bolts;

Figure 7 is a broken-away plan view of a twelve-contact point wrench designed to contact hexagonal bolt heads without corner contact, of the type described in U.S. Patent 3,125,910, which wrench can be sized in accordance with the present invention;

Figure 8 is a broken-away plan view of a twelve-point drive wrench which does not contact corners of a hexagonal bolt, one type of which is shown in U.S. Patents 3,272,430 and 3,495,485, which wrench can be sized in accordance with the present invention.

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Figure 9 is a broken-away plan view of a twelve-contact point wrenching system of the type shown in U.S. Patent 3,079,819 which can be sized in accordance with the present invention;

Figure 10 is a broken-away plan view of a two-contact point wrench driving square and hexagonal nuts, and which can be sized in accordance with the instant invention;

Figure 11 is a broken-away plan view of a four-contact point wrench similar to that of Figure 10 and which can be sized in accordance with the present invention;

Figure 12 is a broken-away plan view of a three-contact point wrench of the type described in U.S. Patent 3,695,124, used for hexagonal bolt heads and, which does not contact the corners of the heads, in a manner similar to that shown in Figures 10 and 11, and which wrench can be sized in accordance with the present invention;

Figure 13 is a broken-away plan view of a six-contact point drive wrench used for hexagonal bolt heads and which does not contact the corners of the heads, which wrench can be sized in accordance with the present invention;

Figure 14 is a broken-away plan view of a twelve-point "spline" drive wrench of the type shown in U.S. Patent 3,675,516, used for turning splined members and also hexagonal bolt heads, which wrench can be sized in accordance with the present invention;

Figure 15 is a broken-away plan view of a novel six-contact point wrenching system;

Figure 16 is a broken-away plan view of a novel six-contact point wrenching system;

Figure 17 is a broken-away plan view of a novel four-contact point drive wrench for turning square bolt heads;

Figure 18 is a broken-away plan view of a novel eight-contact point drive wrench for use with square bolt heads;

Figure 19 is a broken-away plan view of a novel eight-contact point drive wrench utilizing a combination of wrenching elements;

Figure 20 is a broken-away plan view of a novel six-contact point drive wrenching system;

Figure 21 is a broken-away plan view of a novel twelve-contact point wrenching system for hexagonal bolt heads;

Figure 22 is a broken-away plan view of a novel eighteen-contact point drive wrenching system for turning hexagonal bolt heads;

Figure 23 is a broken-away plan view of a novel twenty-four-contact point drive wrench;

Figure 24 is a broken-away plan view of a novel twelve-contact point drive, preferably open-end wrench for hexagonal bolt heads;

Figure 25 is a broken-away plan view of a novel wrench having six contact points sized in one measuring system and six contact points sized in another; and

Figure 26 is a broken-away plan view of a novel eighteen-contact point drive wrench.

DESCRIPTION OF PREFERRED EMBODIMENTS

To aid in understanding the concept of rotary wrenching tools in general, a brief explanation is desirable of the contact that occurs between the working surfaces of a rotary wrenching tool and a nut or

bolt head. With reference to Figure 1, for example, the wrench (10) has wrench flats (11), (12) which are spaced apart a sufficient distance to loosely accommodate the confronting flat surfaces (13), (14) of a hexagonal bolt, shown in phantom lines. If the wrench is turned in the direction of arrow A, it will be understood that the wrench flats bear against the corners of the bolt head, rather than upon the flat surfaces of the bolt head; this is referred to as "corner contact", and use of wrenches of this type can readily score and round the corners of bolt heads, particularly hexagonal bolt heads. With wrenches of the type shown in Figure 7, on the other hand, the interior surface of the wrench opening makes contact not with the corners of the bolt head but rather at points (actually, lines) along the length of the flat bolt head edges. The rounded lobes (15) of the wrench (16) initially make line contact with the bolt head, but as pressure is applied, the bolt head edges are deformed slightly so that contact between the lobes and the bolt head occurs over a broader surface. Although certain wrench configurations, such as that depicted in Figure 8, have been advertised as providing "flat-to-flat" surface contact with hexagonal bolt heads, it will be understood that tolerances in the manufacture of both the wrench and the bolt heads prevent such contact from in fact being along the full surface of the wrench flats, such contact being in fact a line contact until the bolt head is suitably deformed by sharp edges of the wrench. Note that the wrench of Figure 8, in a manner similar to that shown in Figure 5, employs recessed portions to accommodate

corners edges of fastener heads to thereby avoid corner contact with the heads.

With reference to the tools exemplified in the drawing (except figure 25), such tools are characterized as having uniform interior configuration. That is, similarly configured interior surface elements (e.g., lobes) are radially spaced the same distance from the axis of the wrenching tool opening. For example, the lobes (15) depicted in Figure 7 are equally radially spaced from the axis X. In contrast, the circumferential surface portions (48) shown in Figure 25 are spaced unequally radially from the axis X, as will be described more fully below.

With reference to one embodiment of the invention, rotary wrenching tools are provided which have no moving parts and which are specifically sized for turning fasteners such as nuts, screws and bolts that have square, hexagonal or other polygonal heads. These wrenching tools are characterized by being capable of strongly and adequately fitting polygonal heads nominally sized in at least two different systems such as, for example, the American Fractional standard ("AF") and the British Standards ("BS", for example), and of carrying at least two and preferably three or more suitable size markings in different size systems. That is, the rotary wrenching tools of the invention fit polygonal fastener heads such that scoring or rounding of the heads does not occur even when substantial wrenching torque is applied thereto. Such strong and adequate fitting of the tool to the head of the fastener is such that the application of excessive substantial wrenching torque is more apt to cause physical breakage of the fastener head from the



threaded stem of the fastener, or simply cause the deformation ("stripping") of the stem threads. Of particular importance to this embodiment of the invention are those wrenches which have head-confronting surfaces that are contoured to provide recesses opposite corners of the heads to thereby avoid contact with the head corners. Most preferably, the head-confronting surfaces of the rotary tool are provided with inwardly protruding, rounded lobes positioned to encounter the head of a fastening member along flat surfaces of the head, rather than at its corners, the lobe, upon the application of substantial torque, tending to slightly deform the flat surfaces of the head to provide surface-to-surface contact between the wrench and head.

The driving heads of bolts and similar fastening members can be sized in the metric system (e.g., mm) and also in inches using American Fractional ("AF") standards (SAE, MIL, etc.) and British standards such as "BS", "BA" and "W" (Whitworth) measurements. The wrenches of this embodiment of the invention are sized so as strongly and adequately accommodate fastener heads of at least two different nominal sizes such that the ratio of the nominal distances across opposing head surfaces falls, in the case of square heads, within the range of about 1.0053 to about 1.1430, and, in the case of hexagonal heads, with the range of about 1.0053 to about 1.0600.

Table I set out below provides a non-inclusive, exemplary list of nominal head openings and size combinations for square and hexagonal head fasteners. Referring, for ease of explanation, to the first entry in the table, this entry describes a wrench which will

fully and adequately engage the polygonal head of a threaded fastener that has the nominal dimensions of 1.5mm & 1/16 (AF, U.S. standard) & 16 BA (British standard). As shown in the table, 1/16 inches converts to 1.5875 millimeters. 16 BA, in the British standard, corresponds to 1.4224mm. 1.5mm, in the metric system, is, of course, 1.5mm. The maximum ratio of the maximum nominal distance across flats (1.5875) to the minimum nominal distance across flats (1.4224) is 1.1161, and this is recorded in the final column of the table. As further explanation, the last entry in the table refers to a fastener head having a nominal distance across opposing flats of 220mm. The wrench of the invention, suitably sized, also fully and adequately fits fastener heads sized in the U.S. American Fractional system as 8 5/8" & 8 3/4". The latter nominal values correspond to 219.0731mm and 222.2481mm, respectively. The maximum ratio of the maximum nominal size to the minimum nominal size hence is 222.2481/219.0731, or 1.0145. The ratios thus referred to are calculated according to the following formula:

$$\text{Ratio} = \frac{\text{maximum nominal head size in millimeters}}{\text{minimum nominal head size in millimeters}}$$

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TABLE I (Continued)
 WRENCH MARKINGS AND SIZE COMBINATIONS FOR
 SQUARE AND HEXAGONAL NUTS AND BOLTS AND SCREW HEADS

Nominal Head Dimensions and Size Combinations					Nominal Size			RATIO maximum
METRIC	in MM.	in INCHES			W & BS			
		ENGLISH		Standard				
		US Standard	British Standard					
		AF & SAE	BA	BS	AF & SAE	BA	in MM	
3.2 &	3 &	1/8	-	-	3.1750	-	-	1.0667
3.2 &	-	1/8 &	9BA	-	3.1750	3.3274	-	1.0480
3.2 &	-	1/8	-	-	3.1750	-	-	1.0079
3.2 &	-	-	9BA	-	-	3.3274	-	1.0398
-	-	1/8 &	9BA	-	3.1750	3.3274	-	1.0480
3.5 &	-	9/64 &	9BA	-	3.5718	3.3274	-	1.0735
3.5 &	-	9/64	-	-	3.5718	-	-	1.0205
3.5 &	-	-	9BA	-	-	3.3274	-	1.0519
-	-	9/64 &	9BA	-	3.5718	3.3274	-	1.0735
4 &	-	5/32 &	8BA	-	3.9687	3.8608	-	1.0363
4 &	-	5/32	-	-	3.9687	-	-	1.0079
4 &	-	-	8BA	-	-	3.8608	-	1.0363
-	-	5/32 &	8BA	-	3.9687	3.8608	-	1.0282
4.5 &	-	3/16 &	7BA	-	4.7625	4.3688	-	1.0898
4.5 &	-	3/16	-	-	4.7625	-	-	1.0583
4.5 &	-	-	7BA	-	-	4.3688	-	1.0297
-	-	3/16 &	7BA	-	4.7625	4.3688	-	1.0898
4.8 &	-	3/16 &	6BA	-	4.7625	4.9021	-	1.0290
4.8 &	-	3/16	-	-	4.7625	-	-	1.0079
4.8 &	-	-	6BA	-	-	4.9021	-	1.0213
-	-	3/16 &	6BA	-	4.7625	4.9021	-	1.0289
5 &	-	3/16 &	6BA	-	4.7625	4.9021	-	1.0499
5 &	-	3/16	-	-	4.7625	-	-	1.0499
-	-	3/16 &	6BA	-	4.7625	4.9021	-	1.0289
5 &	-	3/16	-	-	4.7625	-	-	1.0289
5 &	-	-	6BA	-	-	4.9021	-	1.0529
-	-	13/64 &	6BA	-	5.1593	4.9021	-	1.0319
5 &	-	13/64	-	-	5.1593	-	-	1.0319
-	-	13/64 &	-	-	5.1593	-	-	1.0529
-	-	13/64	6BA	-	-	-	-	-

WRENCH MARKINGS AND SIZE COMBINATIONS FOR
SQUARE AND HEXAGONAL NUTS AND BOLT AND SCREW HEADS

Nominal Head Dimensions and Size Combinations				Nominal Size				
METRIC	in MM	in INCHES		BS	AF & SAE	British	in MM	RATIO Maximum
		ENGLISH						
		US Standard	BA					
5.5 &	-	7/32 &	5BA	-	5.5562	5.5888	-	1.0164
5.5 &	-	7/32 &	5BA	-	5.5562	-	-	1.0102
5.5 &	-	-	5BA	-	-	5.5888	-	1.0164
-	-	7/32	5BA	-	5.5562	5.5888	-	1.0061
6 &	-	1/4	-	-	6.3499	-	-	1.0583
6 &	-	1/4 &	4BA	-	6.3499	6.2991	-	1.0583
6 &	-	9/32	-	-	7.1437	-	-	1.0205
7 &	-	9/32 &	3BA	-	7.1437	7.1627	7.5437	1.0777
7 &	-	5/16	-	-	7.9374	-	-	1.0079
8 &	-	5/16 &	2BA	-	7.9374	8.2295	-	1.0368
8 &	-	11/32	-	-	8.7312	-	-	1.0308
9 &	-	-	-	-	-	-	8.6359	1.0422
9 &	-	3/8 &	1BA	-	9.5249	9.2709	-	1.0583
9 &	-	3/8	-	-	9.5249	-	-	1.0583
10 &	-	3/8 &	-	-	9.5249	-	-	1.0499
10 &	-	13/32 &	OBA	-	10.3187	10.4901	10.4901	1.0490
11 &	-	7/16	-	-	11.1124	-	-	1.0102
11 &	-	7/16 &	OBA	-	11.1124	10.4901	-	1.0593
11 &	-	7/16	-	-	11.1124	-	-	1.0275
12 &	-	15/32	-	-	11.9061	-	11.3029	1.0079
13 &	-	1/2	-	-	12.6999	-	-	1.0236
13 &	-	1/2 &	-	-	12.6999	13.3349	13.3349	1.0500
14 &	-	9/16	-	-	14.2874	13.3349	-	1.0714
14 &	-	9/16 &	-	-	14.2874	-	-	1.0205
15 &	-	19/32	-	-	15.0811	-	-	1.0054
15 &	-	19/32 &	-	-	15.0811	-	15.2399	1.0160
16 &	15 & 14 &	9/16 &	-	-	14.2874	-	15.2399	1.1429
16 &	-	5/8 &	-	-	15.8749	15.2399	-	1.0499

TABLE I (Continued)
 WRENCH MARKINGS AND SIZE COMBINATIONS FOR
 SQUARE AND HEXAGONAL NUTS AND BOLT AND SCREW HEADS

Nominal Head Dimensions and Size Combinations										
METRIC	in MM	ENGLISH				Nominal Size				RATIO Maximum
		US Standard		in INCHES		US Standard		in MM		
		AF & SAE	BA	W Whitworth	BS	AF & SAE	BA	W & BS		
17 &	- 16	11/16 &	-	-	-	17.4623	-	-	1.0272	
17 &	- 16	-	-	-	-	-	-	-	1.0625	
18 &	- 17	-	-	-	-	-	-	-	1.0588	
18 &	- 18	23/32 &	-	-	7/16BS	18.2561	-	-	1.0142	
19 &	-	-	-	-	-	-	-	-	1.0556	
19 &	-	3/4 &	-	-	7/16BS	19.0498	-	18.0338	1.0563	
20 &	- 19	25/32 &	-	-	1/2BS	19.8436	-	20.8278	1.0496	
20 &	- 19	-	-	-	-	-	-	-	1.0526	
20 &	- 19 &	3/4	-	-	-	19.0498	-	-	1.0526	
21 &	- 20	13/16	-	-	-	20.6373	-	-	1.0500	
21 &	-	13/16 &	-	-	1/2 BS	20.6373	-	20.8278	1.0176	
22 &	- 21	-	-	-	-	-	-	-	1.0476	
22 &	-	7/8 &	-	-	-	22.2248	-	-	1.0102	
23 &	-	7/8	-	-	9/16BS	22.2248	-	23.3678	1.0514	
23 &	-	7/8	-	-	-	22.2248	-	-	1.0349	
23 &	- 22 &	7/8	-	-	-	22.2248	-	-	1.0455	
24 &	-	15/16	-	-	-	23.8123	-	-	1.0079	
24 &	-	15/16 &	-	-	9/16BS	23.8123	-	23.3678	1.0271	
24 &	- 23 &	15/16	-	-	9/16BS	23.8123	-	23.3678	1.0435	
25 &	-	1	-	-	-	25.3998	-	-	1.0160	
25 &	-	1	-	-	5/8BS	25.3998	-	25.6538	1.0262	
25 &	-	15/16 &	-	-	5/8BS	23.8123	-	25.6538	1.0773	
26 &	- 25	1 1/32	1	-	5/8BS	26.1935	-	25.6538	1.0477	
27 &	-	1 1/16	-	-	1 1/6BS	26.9873	-	27.9398	1.0353	
27 &	- 26 &	1 1/16 &	-	-	-	26.9873	-	-	1.0385	
27 &	-	1 1/16	-	-	-	26.1935	-	-	1.0005	
28 &	-	1 1/8	-	-	-	26.9873	-	-	1.0205	
28 &	- 27	-	-	-	-	28.5748	-	-	1.0370	
28 &	- 27 &	1 1/8 &	1 1/16 &	-	1 1/6BS	28.5748	-	27.9398	1.0588	

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TABLE I (Continued)
WRENCH MARKINGS AND SIZE COMBINATIONS FOR
SQUARE AND HEXAGONAL NUTS AND BOLT AND SCREW HEADS

Nominal Head Dimensions and Size Combinations										RATIO Maximum
METRIC	in MM	in INCHES				Nominal Size				
		ENGLISH		British Standard		US Standard		in MM		
		US Standard	AF & SAE	BA	W Whitworth	BS	AF & SAE	BA	W & BS	
47	&	1 7/8	-	-	-	-	47.6246	-	-	1.0133
48	&	1 7/8	-	-	-	-	47.6246	-	-	1.0079
49	&	1 15/16	-	-	-	-	49.2121	-	-	1.0043
50	&	2	-	-	-	-	50.7996	-	-	1.0160
50	&	1 15/16	-	-	-	-	49.2121	-	-	1.0160
55	&	2 3/16 &	-	-	1 3/8W &	1 1/2BS	55.5620	-	56.3875	1.0252
60	&	2 3/8 &	2 7/16	-	1 1/2W &	1 5/8BS	60.3245	-	61.2135	1.0319
65	&	2 9/16 &	2 5/8	-	1 5/8W &	1 3/4BS	65.0863	-	65.5314	1.0258
70	&	2 3/4 &	-	-	1 3/4W &	2BS	66.6744	-	70.1034	1.0036
75	&	3	-	-	-	-	69.8494	-	-	1.0160
75	&	3 &	2 15/16	-	-	-	76.1993	-	-	1.0213
80	&	3 1/8 &	-	-	2W &	2 1/4BS	74.6119	-	80.0093	1.0080
85	&	3 3/8	-	-	-	-	79.3743	-	-	1.0085
90	&	3 1/2	-	-	2 1/4W &	2 1/2BS	85.7243	-	90.1692	1.0143
95	&	3 7/8 &	3 3/4 &	-	2 1/2W &	2 3/4BS	88.8992	-	98.8051	1.0360
			3 13/16				95.2492			
100	&	3 7/8 &	-	-	2 1/2W &	2 3/4BS	96.8367	-	98.8051	1.0160
105	&	4 3/16 &	4 1/8 &	-	2 3/4W &	3BS	98.4241	-	106.1711	1.0152
110	&	4 3/8	-	-	-	-	104.7741	-	-	1.0102
115	&	4 1/2 &	4 5/8	-	3W &	3 1/4BS	106.3616	-	115.0610	1.0278
120	&	4 3/4 &	4 7/8	-	3 1/4W &	3 1/2BS	111.1240	-	123.1889	1.0319
125	&	4 7/8	-	-	3 1/4W &	3 1/2BS	117.4740	-	123.8239	1.0147
130	&	5 &	5 1/8 &	-	3 1/2W &	3 3/4BS	114.2990	-	131.5709	1.0500
			5 1/4				120.6489			
							123.8239			
							126.9989			
							130.1739			
							133.3488			

TABLE I (Continued)
WRENCH MARKINGS AND SIZE COMBINATIONS FOR
SQUARE AND HEXAGONAL NUTS AND BOLTS AND SCREW HEADS

Nominal Head Dimensions and Size Combinations						Nominal Size				
METRIC	in MM*	ENGLISH		in INCHES		in MM			RATIO Maximum	
		US Standard	AF & SAE	British Standard	BA	W & BS				
135 &	-	5 3/8 &	5 1/4 &	-	3 1/2W &	3 3/4BS	136.5238 133.3488	-	131.5709	1.0376
140 &	-	5 1/2 &	5 5/8 &	-	3 3/4W &	4BS	139.6988 142.8738	-	140.9688	1.0227
145 &	-	5 5/8 &	5 3/4	-	-	-	142.8738 146.0487	-	-	1.0222
150 &	-	5 7/8	-	-	-	-	149.2237	-	-	1.0052
155 &	-	6 1/8	-	-	-	-	155.5737	-	-	1.0037
160 &	-	6 1/4	-	-	-	-	158.7486	-	-	1.0079
165 &	-	6 1/2 &	6 3/8	-	-	-	165.0986 161.9236	-	-	1.0196
170 &	-	6 5/8 &	6 3/4	-	-	-	168.2735	-	-	1.0189
175 &	-	6 7/8	-	-	-	-	171.4485	-	-	1.0022
180 &	-	7 &	7 1/8	-	-	-	174.6235 177.7985	-	-	1.0178
185 &	-	7 1/4 &	7 3/8	-	-	-	180.9734 184.1484	-	-	1.0172
190 &	-	7 1/2 &	7 3/8	-	-	-	187.3234 190.4983	-	-	1.0169
190 &	-	7 5/8 &	-	-	-	-	187.3234 193.6733	-	-	1.0193
195 &	-	7 3/4	-	-	-	-	196.8483	-	-	1.0095
200 &	-	7 7/8 &	8	-	-	-	208.0233 203.1983	-	-	1.0160
210 &	-	8 1/4 &	8 3/4	-	-	-	209.5482 212.7232	-	-	1.0152
220 &	-	8 5/8 &	8 3/4	-	-	-	219.0731 222.2481	-	-	1.0145

The rotary wrenching tools of this embodiment of the invention will bear visually readable markings indicating the at least two and preferably three different head sizes for which they were designed. For example, the first wrench appearing in Table I may be marked "1.5 mm & 1/16in. & 16 BA". The table has been computed using international (ISO) and many national standards and specifications from the United States (SAE, ANSI, MIL, ASTM), British (BS), German (DIN), France (FS), Yugoslavia (JUS), Japan (JS) and specifications from various manufacturers in the United States, England, France, Germany, Canada, Japan, Italy, Sweden, Spain, Czechoslovakia, Yugoslavia, Taiwan, China, Brazil, etc.

With reference to Figures 3-26, each figure shows positions of a bolt head within the gripping opening of a rotary wrenching tool, the bolt head positions shown in phantom lines referring to the smallest bolt head that can be fully and adequately gripped by the tool. Certain of the Figures also show a wrenching tool in both a socket form (wherein a full circle in either solid or dotted lines appears about the bolt head) or in open-ended wrench form. In Figure 3, for example, a socket is shown in dotted lines as (17), the open-ended wrenching tool version being shown in solid lines as (18). In Figures 4, 5, 7, 9-11, 13-19, 22 and 23, similarly, the socket embodiment is shown in solid lines as (20) and the open-ended embodiment is shown in phantom lines as (22). Further, alternate positions for the ends of the open-ended embodiments may be varied, and several positions are shown, for example, in Figures 14, 24, 25 and 26.



The following non-limiting examples will serve to more clearly illustrate various further embodiments of the invention.

Example I

With reference to the embodiment shown in Figure 16, socket and open-end rotary wrenching tools shown generally at (20) and (22) are sized so as to strongly and adequately grip the hexagonal heads of threaded fasteners sized 4 mm & 5/32" & 8 BA, giving a ratio of 1.0363. The wrench of Figure 16, as shown from the drawing, has an axis of rotation X that extends normal to the plane of the paper and has an opening for receiving the polygonal head of a threaded member, in this case, a hexagonal head shown as "H". The opening has an inner, head-confronting surface comprising a series of arcuate first surfaces (24) concave to the axis of the opening and spaced about the circumference of the opening. Each such first surface is defined generally as the locus of points falling a given radial distance r from a first axis "a" that is itself spaced a distance r_1 from, but parallel to, the axis X of the opening. Between the arcuate first surfaces (24) are positioned a series of arcuate second surfaces (26) which are convex to the axis of the opening and are spaced about its circumference, each such second arcuate surface being defined general as the locus of points falling a radial distance R from a second axis A which is itself spaced a distance R_1 from, but parallel to, the axis X of the opening. Each surface that forms the opening and that is contiguous to an arcuate surface tangentially merges into that arcuate surface. R_1 preferably is larger than r_1 , and the ratio R_1/r_1

desirably exceeds 1.5 and preferably exceeds 2.0. The arcuate second surfaces (26), it will be noted, form "lobes" having rounded surfaces for making contact with the flats of a hexagonal head of a threaded member. One such member, designated "h," is shown in operative contact with the lobes. Each second axis A is angularly spaced from at least one next adjacent second axis A by 60°.

With further reference to Figure 16, rotary wrenching tools of this general configuration may be manufactured as socket, box-end, open-end, flare nut, nut driver and crowfoot wrenches, sized for receiving hexagonal fastener heads nominally sized as follows:

- 10 mm & 3/8" (AF) (ratio of 1.0499);
- 11 mm & 7/16" (AF) & 3/16 W (Whitworth) & 1/4 BS (ratio of 1.0275);
- 19 mm & 3/4" (AF) & 3/8 W & 7/16 BS (ratio of 1.0563).

Similarly, rotary wrenching tools configured as shown in Figure 16 may be designed as socket, box-end and crowfoot wrenches, sized to accommodate hexagonal fastener heads nominally sized as 28 mm & 27 mm & 1 1/16" (AF) & 1 1/8" (AF) & 5/8 W & 11/16 BS, the wrench having a ratio, as defined above, of 1.0588. Other wrenching tools configured as shown in Figure 16 may be provided as socket and box-end tools sized to receive hexagonal fastener heads nominally sized as 32 mm & 33 mm & 1 5/16" (AF) & 1 1/4" (AF) & 3/4 W & 7/8 BS, the wrench having a ratio of 1.0500. Yet another wrench configured as shown in Figure 16 may be provided as a socket wrench sized to receive hexagonal fastener heads nominally sized as 220 mm & 8 5/8" (AF) & 8 3/4" (AF), the ratio of which is 1.0145.

If the ratio R/r is substantially greater than 1.0, preferably exceeding about 5.0, and if R_1 is substantially larger than r_1 , the particularly desirable configuration of the wrench shown in Figure 15 is obtained. This embodiment makes use of large, gently rounded, inwardly projecting lobes (26) separated by rounded recessed arcuate portions (24), the latter providing room to accommodate corners of the head of a threaded member without coming into corner contact therewith. Again, each surface forming the opening that is contiguous to an arcuate surface tangentially merges into that surface.

Example II

Socket and Box-End rotary wrenching tools configured as shown in Figure 15 are sized to receive hexagonal heads of threaded members nominally sized 35 mm & 34 mm & 1 3/8" (AF) & 1 5/16" (AF) & 13/16W & 15/16 BS, the tool having a ratio, as defined above, of 1.0591. Similarly, socket wrenches may be designed in accordance with Figure 15 and sized to receive hexagonal heads of threaded fasteners nominally sized as follows:

- a) 105 mm & 4 3/16" (AF) & 4 1/8" (AF) & 2 3/4 W & 3 BS, the ratio being 1.0152;
- b) 140 mm & 5 5/8" (AF) & 5 1/2" (AF) & 3 3/4 W & 4 BS, the ratio of which wrench is 1.0227.
- c) 200 mm & 7 7/8" (AF) & 8" (AF), with a ratio of 1.0160.

If the wrenching tool shown in Figure 16 in which R is approximately equal to r is modified so that R_1 is approximately equal to r_1 , then tools

of the general type shown in Figures 18, 22 and 23 are obtained. Referring to Figure 18, eight contact points or lobes (26) are provided. This wrenching tool is particularly adapted for receiving square heads of threaded fasteners. The inner surface of the tool includes portions designated (30) which are generally flat surfaces and that extend between the arcuate first and second surfaces. Such flat surfaces (30) may be oriented so as to come into generally surface-to-surface contact with the flats of a threaded member head, as shown in Figure 18, the angular dimensions appearing in Figure 18 being adapted to promote such surface-to-surface contact. Figure 22 and 23 show tools somewhat similar to that shown in Figure 18, except that the tool of Figure 22 has its lobes angularly spaced 20° apart and the tool of Figure 23 has its lobes spaced angularly 15° apart. Note is made that the spacing between adjacent second axes A of the embodiments of Figures 18, 22 and 23 are generally less than $3R$ in which R is as described above in connection with Figure 16.

Example III

Socket and box-end rotary wrenching tools may be designed and manufactured in the configuration shown in Figure 18 and specifically sized in accordance with the invention to receive square heads of threaded fasteners nominally sized 13 mm & $1/2"$ (AF) & $1/4$ W & $5/16$ BS, and having a ratio of 1.0500. Similarly, socket, box-end and open-end wrenching tools may be designed and manufactured in accordance with the configuration of Figure 18 and sized for receiving square-headed fasteners nominally sized 16 mm & $5/8"$, and having a ratio of 1.0079. The same

socket and box-end tools may be designed and manufactured in accordance with the configurations of Figures 22 and 23 and sized to receive hexagonal fastener heads nominally sized 16 mm & 5/8" (AF), the tools having a ratio of 1.0079.

Using the nomenclature described above in connection with Figure 16, the rotary wrenching tool of Figure 20 is provided with inwardly convex lobes (26) formed generally on radii R swung about axes A, the latter axes being angularly spaced about the axis of rotation X by 60°. Inwardly concave surfaces (24) are formed on radii r swung about axes a and positioned such that two spaced inwardly concave arcuate surfaces are positioned between each of the inwardly convex surfaces (26) forming lobes of the wrench. Generally flat surface portions (30) extend between adjacent inwardly concave and convex surfaces (24) and (26), the inwardly concave surfaces being joined by a surface (32) that is formed on a radius about the axis of rotation X. Again, each surface that forms the wrench opening and that is contiguous to an arcuate surface tangentially merges into that arcuate surface. The wrenching tools of Figures 19, 20 and 21 each have head-receiving openings configured to provide combinations of line, surface and flat-to-flat contact with differently sized fastener heads.

Example IV

A socket wrenching tool designed and manufactured to have the configuration shown in Figure 20 is specifically sized to receive hexagonal head fasteners nominally sized at 5 mm & 3/16" (AF) & 6 BA, the tool having a ratio of 1.0499. A similar tool is sized to receive hexagonal fastener nuts nominally

sized 100 mm & 3 7/8" (AF) & 2 1/2 W & 2 3/4 BS, the tool having a ratio of 1.0160. Similarly, a wrenching tool fabricated in accordance with the configuration of Figure 20 may be specifically sized to receive hexagonal head fasteners nominally sized at 14 mm & 9/16" (AF), the tool having a ratio of 1.0205. Socket and box-end wrenching tools configured as in Figure 20 may be sized to specifically receive hexagonal fastener heads nominally sized 75 mm & 3" (AF) & 2 15/16" (AF), and having a ratio of 1.0213.

An embodiment similar to that described above in connection with Figure 20 is shown in Figure 17, this rotary tool having internally projecting lobes (26) spaced 90° from one another and having a pair of inwardly concave arcuate surfaces (24) formed between each pair of inwardly projecting lobes (26). Generally flat interior surfaces (30) extend between the arcuate surfaces and merge tangentially into such arcuate surfaces.

Example V

Socket, box-end and open-end wrenching tools may be manufactured in accordance with the configuration shown in Figure 17 and sized to receive square heads of threaded fasteners nominally sized as follows:

- a) 11 mm & 7/16" (AF) & 0 BA (ratio of 1.0593)
- b) 14 mm & 9/16" (AF) & 1/4 W & 5/16 BS (ratio of 1.0714)
- c) 16 mm & 15 mm & 14 mm & 9/16" (AF) & 5/8" (AF) & 5/16 W & 3/8 BS (ratio of 1.1429).

Figure 19 shows a wrenching tool having an opening adapted to receive hexagonal heads H of

threaded members. The tool has an axis of rotation X, and the inner, head-confronting surface of the wrenching tool opening comprises three equiangularly spaced, inwardly convex arcuate first surfaces (40) and, forming a portion of the inner surface between said arcuate first surfaces, inwardly convex arcuate second surfaces (42). The inner surface additionally includes at least one outwardly divergent pair of flat inner surface portions (44) that tangentially merge into each arcuate second surface (42). The head confronting inner surface of the tool additionally includes circumferential surface portions that extend between the flat inner surface portions and the arcuate first surfaces, the arcuate first surface portions (40) and second surface portions (42) being so arranged as to come into contact with the flats of a hexagonal head H. The first arcuate surfaces (40) are spaced angularly from one another by 120° , and the second arcuate surfaces are spaced from each other by 120° also, each first arcuate member being angularly spaced from an adjacent second arcuate member by 60° . Preferably, the pair of flats (44) diverge at an angle of 140° therebetween.

Example VI

Socket and box-end wrenches are manufactured in accordance with the configuration of Figure 19 and are specifically sized to receive hexagonal fastener heads nominally sized 8 mm & 5/16" (AF) & 2 BA, the wrench having a ratio of 1.0368. Socket, box-end, open-end, flare nut, nut driver and crowfoot wrenches may be manufactured in the configuration shown in Figure 19 and specifically sized to receive hexagonal heads of fasteners having the following nominal sizes:

- a) 11 mm & 7/16" (AF) & 0 BA (1.0593 ratio)
- b) 16 mm & 5/8" (AF) & 5/16 W & 3/8 BS (1.0499 ratio)

Referring now to the rotary wrenching tool of Figure 21, and utilizing the nomenclature referred to above in connection with Figure 16, the tool includes an opening for receiving a hexagonal head of a threaded member and has an axis of rotation X. The tool includes an inner surface comprising a series of spaced, arcuate first surfaces (24) concave to the axis of rotation of the opening and angularly spaced from one another by an angle of 30°. A series of spaced, arcuate second surfaces (26) that are convex to the axis of rotation X of the opening are spaced about the opening between the first arcuate surfaces and are angularly spaced from one another by 30°. The inner surface of the opening includes flat surfaces (30) which extend between neighboring first and second arcuate surfaces. The flat surfaces (30) merge tangentially into the second arcuate surfaces (26), as shown, but intersect at approximately right angles the first arcuate surfaces. The first arcuate surfaces, as will now be understood, define recesses which serve to receive the corners of a hexagonal head H of a threaded member.

Example VII

Socket, box-end, open-end, flare nut, nut driver and crowfoot wrenching tools may be manufactured in accordance with the configuration of Figure 21 and sized for receiving hexagonal fastener heads nominally sized 17 mm & 11/16" (AF) (1.0272

ratio), and also 21 mm & 13/16" (AF) & 7/16 W & 1/2 BS (1.0176 ratio).

Socket, box-end and nut driver wrenching tools may be manufactured in accordance with the configuration of Figure 21 and sized to receive hexagonal fastener heads nominally sized as 24 mm & 15/16" (AF) & 1/2 W & 9/16 BS (1.0271 ratio). Socket, box-end and crowfoot wrenching tools may be manufactured in accordance with the configuration of Figure 21 and sized to receive hexagonal fastener heads nominally sized as 32 mm & 1 1/4" (AF) & 3/4 W & 7/8 BS (1.0400 ratio). A socket wrench may be manufactured in accordance with the configuration of Figure 21 and sized to receive hexagonal fastener heads nominally sized as 95 mm & 3 7/8" (AF) & 3 3/4" (AF) & 3 13/16" (AF) & 2 1/2 W & 2 3/4 BS (1.0360 ratio).

Referring to Figure 24, a wrenching tool for receiving a polygonal head is shown with its inner surface comprising a series of arcuate first surfaces (46) that are convex to the axis of rotation of the head-receiving opening and are spaced equiangularly about the opening, each arcuate surface being defined generally as the locus of points falling a given radial distance R from an axis A parallel to but spaced from the axis of rotation X of the tool and each such axis A being angularly spaced from the next adjacent axis by an angle of 20° (Figure 26) or 30° (Figures 24 and 25). The inner surface of the wrench opening includes circumferential surface portions (48) which intersect the arcuate surfaces at approximately right angles. In Figure 24 and 26, the circumferential surface sections (48) are equally spaced from the axis of rotation X, whereas in Figure 25, each second circumferential surface section (48) spaced

from the axis of rotation of the wrench opening by a given distance S_1 and each circumferential section therebetween is spaced from the axis of rotation of the wrench by a distance S_2 , S_1 being greater than S_2 . In Figure 26, at Section "A", it can be seen that the circumferential surface portions can be replaced by inwardly concave arcuate portions which merge tangentially into the inwardly convex portions (46).

Example VIII

Socket, box-end and open end wrenches may be manufactured in accordance with the configurations of Figures 24 and 25, and sized for receiving hexagonal fastener heads nominally sized at 70 mm & 2 3/4" (AF) & 1 3/4 W & 2 BS (1.0036 ratio). Further, socket, box-end and open-end wrenches may be manufactured in accordance with the configuration of Figure 25 and sized to specifically receive hexagonal fastener heads nominally sized at 75 mm & 3" (1.0160 ratio).

Preferably, the wrenching tools exemplified in Figures 15-26 likewise carry markings adjacent each tool opening identifying at least two and preferably three or more different fastener head sizes that the opening will strongly and adequately engage. Exemplary markings are shown in Figure 16, the markings (4 mm & 5/32 AF & 8 BA) being stamped, in this example, onto or into the handle of the tool. Rotary wrenching tools in the form of sockets would normally have markings on the outer socket surfaces.

While a preferred embodiment of the present invention has been described, it should be understood that various changes, adaptations and modifications may be made therein without departing from the spirit of the invention and the scope of the appended claims.

1. A rotary wrenching tool having an opening for receiving a polygonal head of a threaded member, the opening having an axis of rotation and having an inner surface comprising a series of arcuate first surfaces concave to the axis of the opening and spaced about the circumference of the opening, each such first surface being defined generally as the locus of points falling a given radial distance " r " from a first axis " a " itself spaced a distance " r_1 " from, but parallel to, the axis of the opening, and a series of arcuate second surfaces convex to the axis of the opening and spaced about the circumference of the opening, each such second surface being defined generally as the locus of points falling a radial distance R from a second axis spaced itself a distance R_1 from but parallel to the axis of the opening, each surface forming the opening and that is contiguous to an arcuate surface tangentially merging into that arcuate surface, the relationship of r and R being such that if r is equal to R , the wrench includes means providing flat surfaces between and tangentially intersecting the first and second surfaces.

2. A rotary wrenching tool having an opening for receiving a polygonal head of a threaded member, the opening having an axis of rotation and having an inner surface comprising a series of spaced, arcuate first surfaces concave to the axis of rotation of the opening, each such first surface being defined generally as the locus of points falling a given radial distance " r " from a first axis itself spaced a

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distance r_1 from, but parallel to, the axis of rotation of the opening, and a series of spaced arcuate second surfaces convex to the axis of rotation of the opening, each such second surface being defined generally as the locus of points falling a given radial distance R from a second axis itself spaced a distance R_1 from the axis of rotation, each second axis being angularly spaced from at least one next adjacent second axis by 60° , and each surface forming the inner surface of the opening and that is contiguous to an arcuate surface tangentially merging into that arcuate surface.

3. The tool of Claim 2 wherein R_1 is larger than r_1 .

4. The tool of Claim 2 wherein the ratio R_1/r_1 exceeds 1.5.

5. The tool of Claim 2 wherein R is equal to or greater than r .

6. The tool of Claim 2 wherein the ratio R/r exceeds 5.0.

7. The tool of Claim 2 wherein adjacent arcuate first and second surfaces merge tangentially into one another.

8. A rotary wrenching tool having an opening with a uniform interior configuration for receiving a polygonal square or hexagonal head of a threaded member, the opening having an axis of rotation and having an inner surface spaced from the axis and providing a series of surfaces configured and arranged to contact the flats of a threaded member

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head to apply torque to a threaded member, the tool being sized to receive strongly and adequately the heads of threaded members that are sized in at least two different nominal sizes such that the maximum ratio of the nominal distances across opposing flats of such nominally sized heads ranges from about 1.0053 to about 1.1430 for square heads and from about 1.0053 to about 1.0600 for hexagonal heads, said tool carrying, adjacent said opening, visible markings identifying said at least two nominal sizes.

9. The tool of Claim 8 wherein such wrench includes an inner surface contoured to provide recesses opposite corners of the heads of the threaded members so as to avoid contact with said corners.

10. The tool of Claim 8 specifically sized to receive heads of threaded members nominally sized in accordance with one of the entries of Table I and bearing, adjacent said opening, visible indicia identifying different nominal sizes set out in said entry.

11. The tool of Claim 9 specifically sized to strongly and adequately receive heads of threaded members nominally sized in accordance with one of the entries of Table I and bearing, adjacent said opening, visible indicia identifying different nominal sizes set out in said entry.

12. The tool of Claim 1, 2 or 3, wherein the tool opening is sized to receive strongly and adequately the heads of threaded members sized in at least two different nominal sizes such that the maximum ratio of the nominal distance across opposing flats of such at least two differently sized heads ranges from 1.0001

to about 1.1430 for square heads and from 1.0001 to about 1.0600 for hexagonal heads, the tool carrying, adjacent said opening, visible indicia identifying the at least two different nominal sizes.

13. The tool of claim 12 wherein the opening of the tool is specifically sized to strongly and adequately receive heads of threaded members nominally sized in accordance with one of the entries of Table I and bearing, adjacent said opening, visible indicia identifying different nominal sizes set out in said entry.

Fig.1

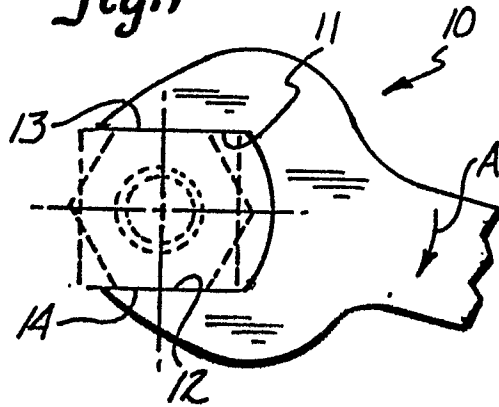


Fig.2

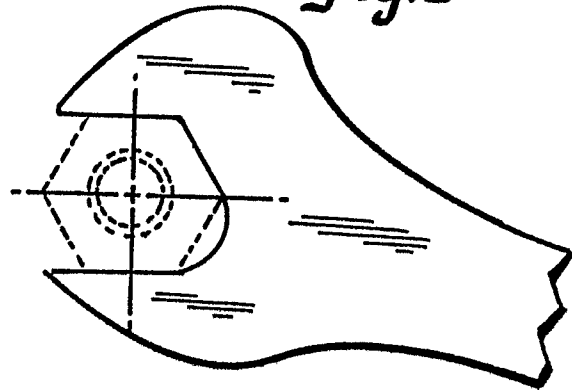


Fig.3

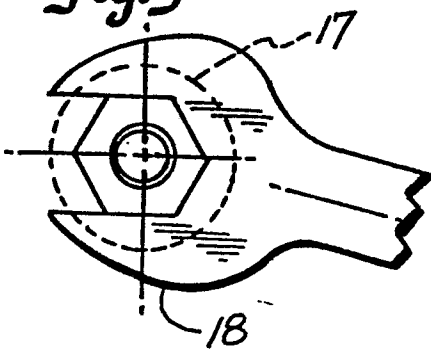


Fig.4

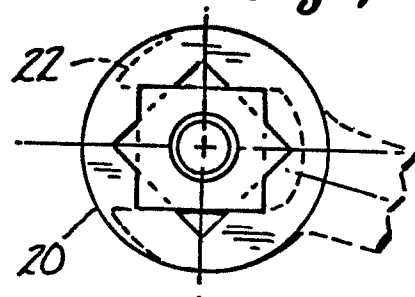


Fig.5

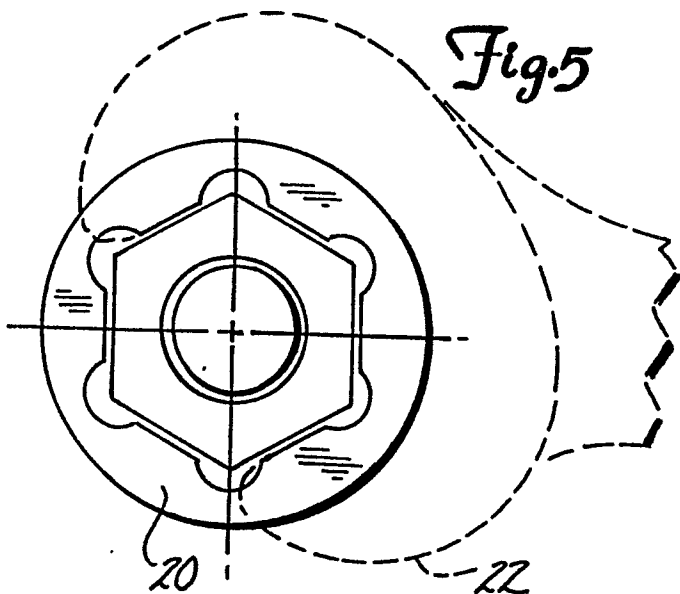
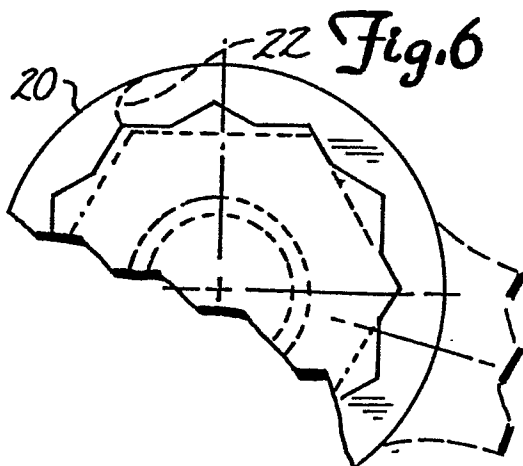


Fig.6



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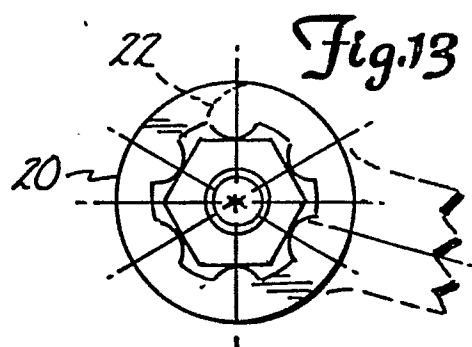
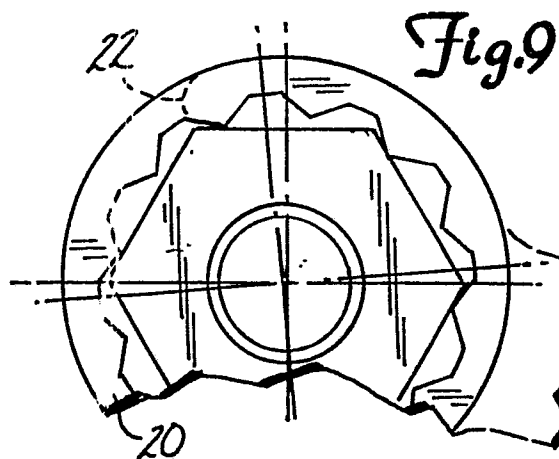
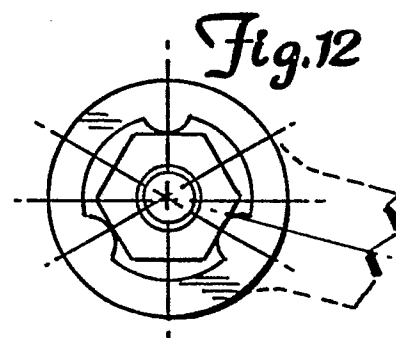
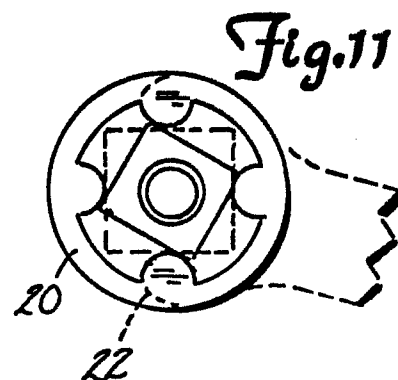
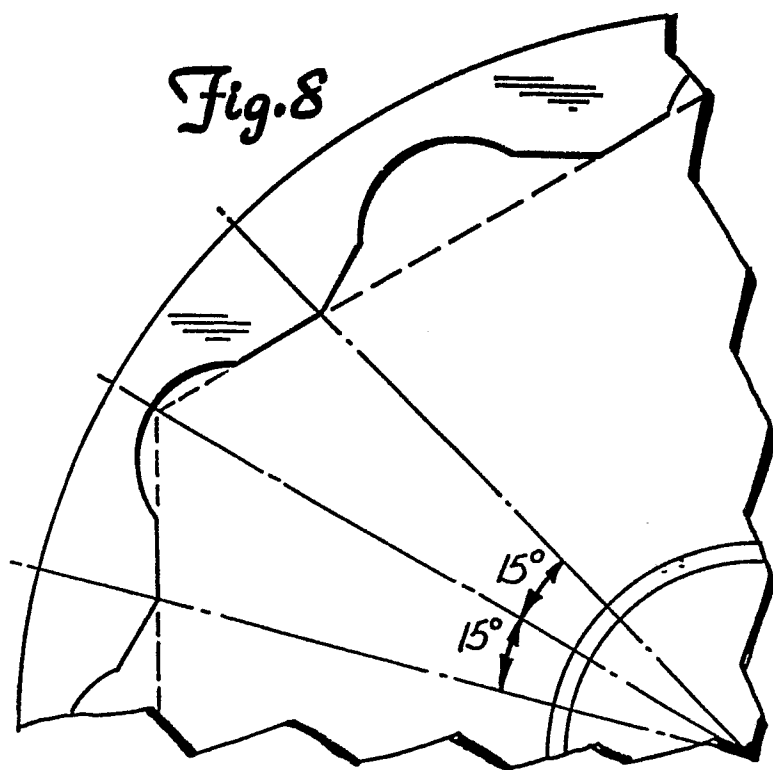
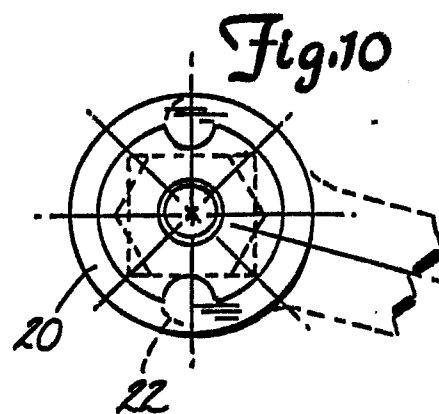
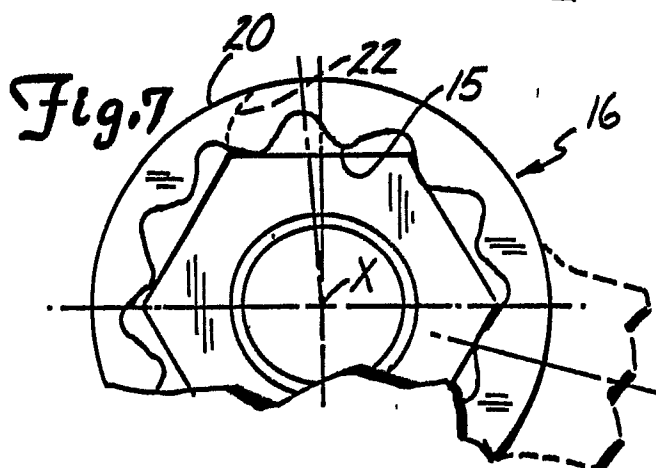


Fig. 15

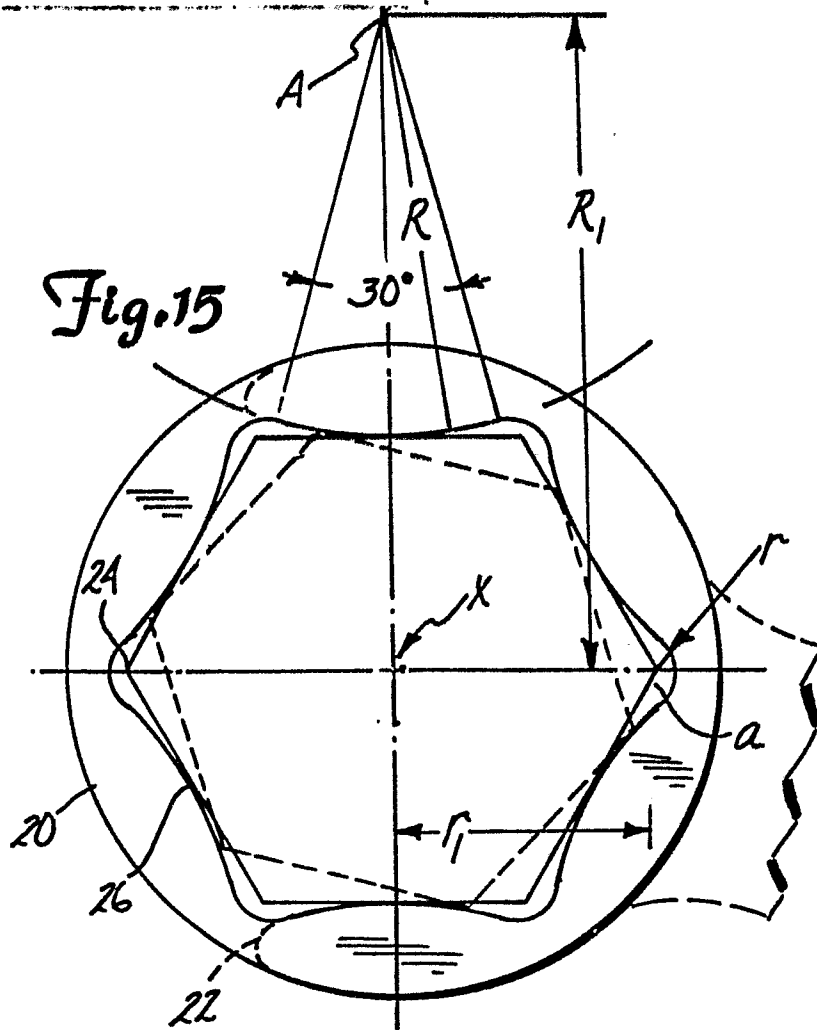
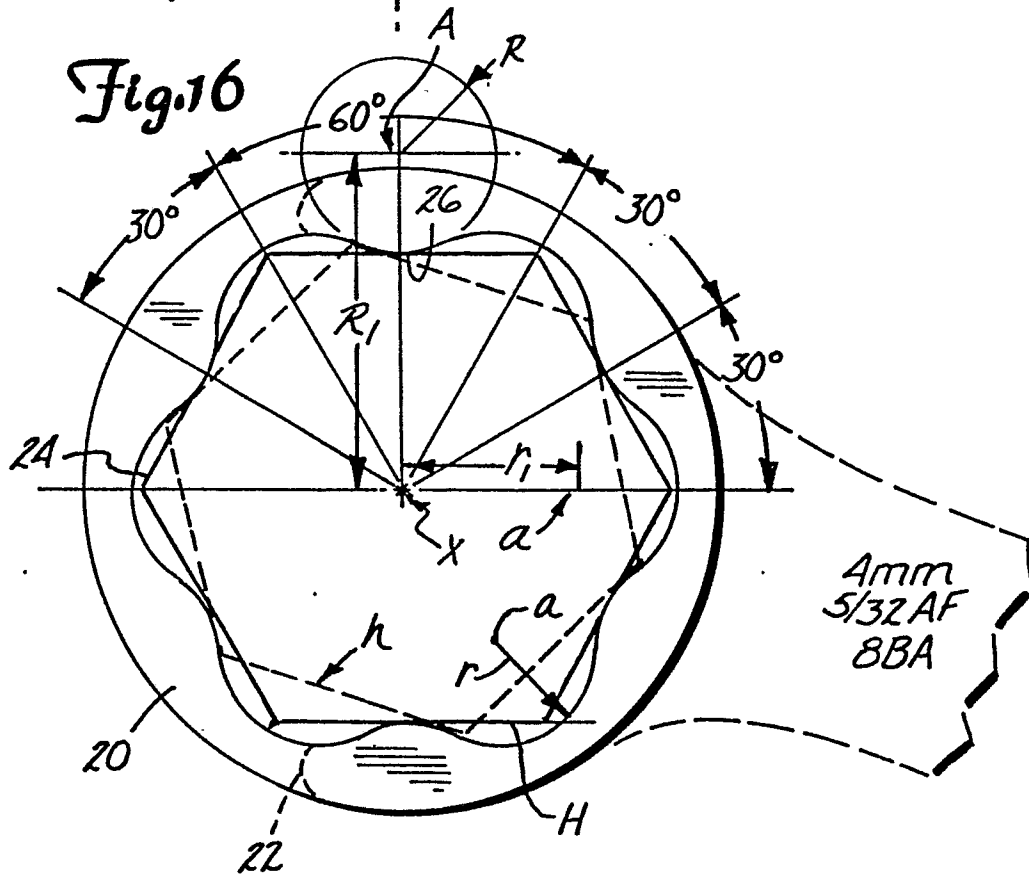


Fig. 16



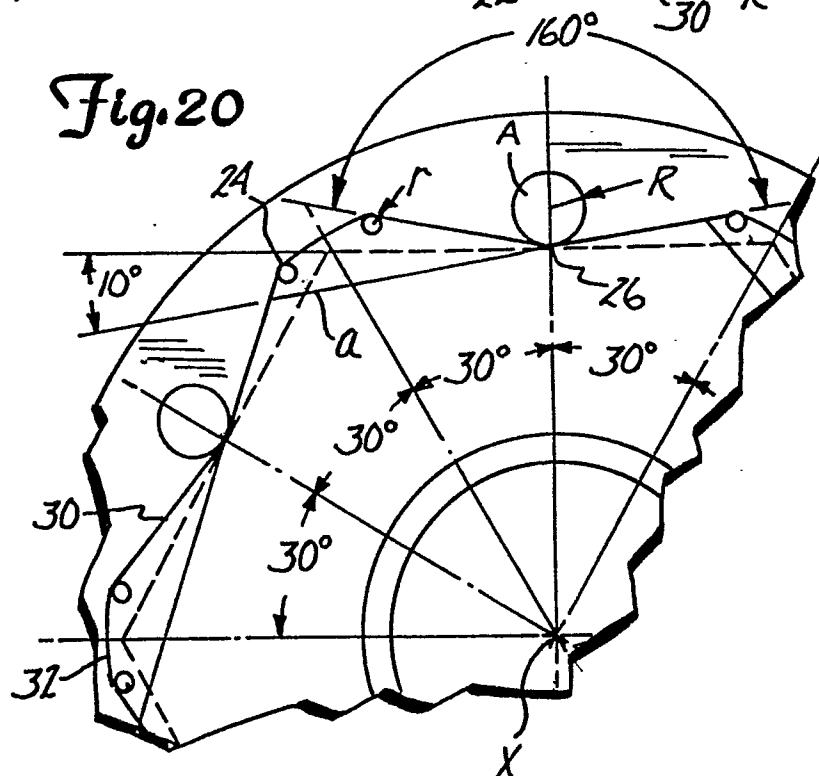
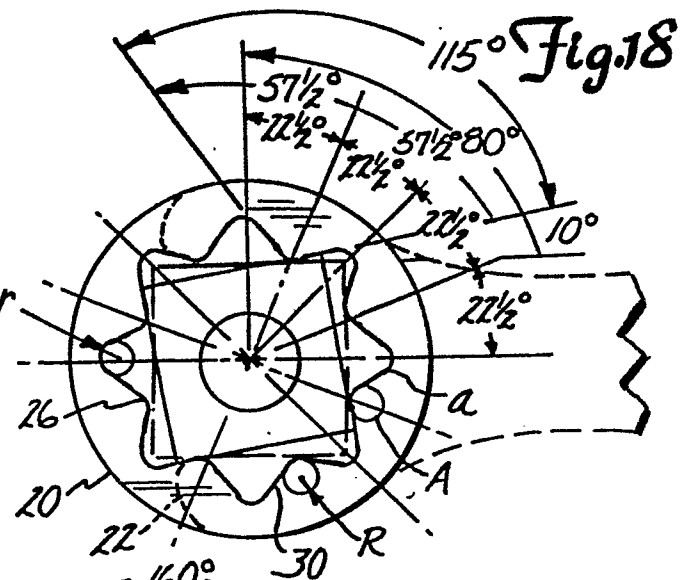
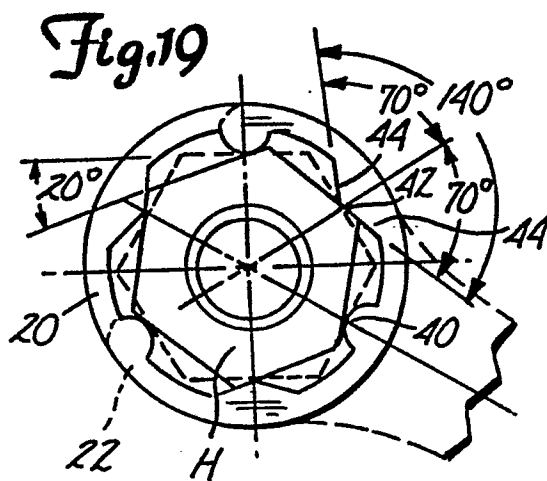
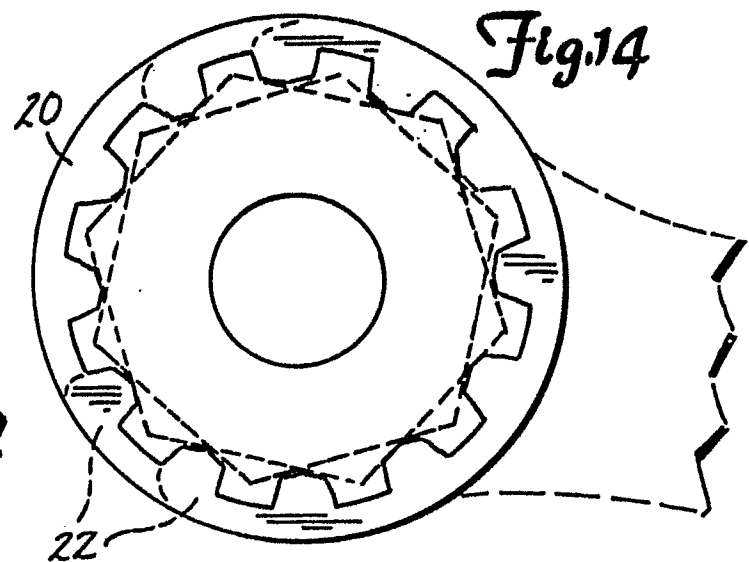
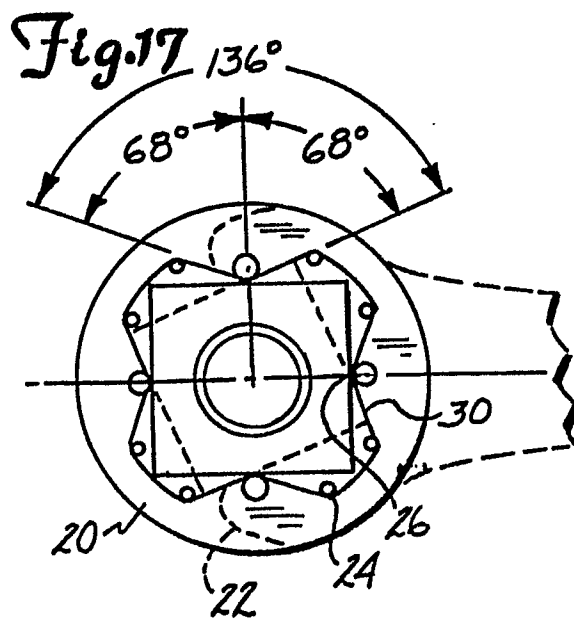


Fig. 21

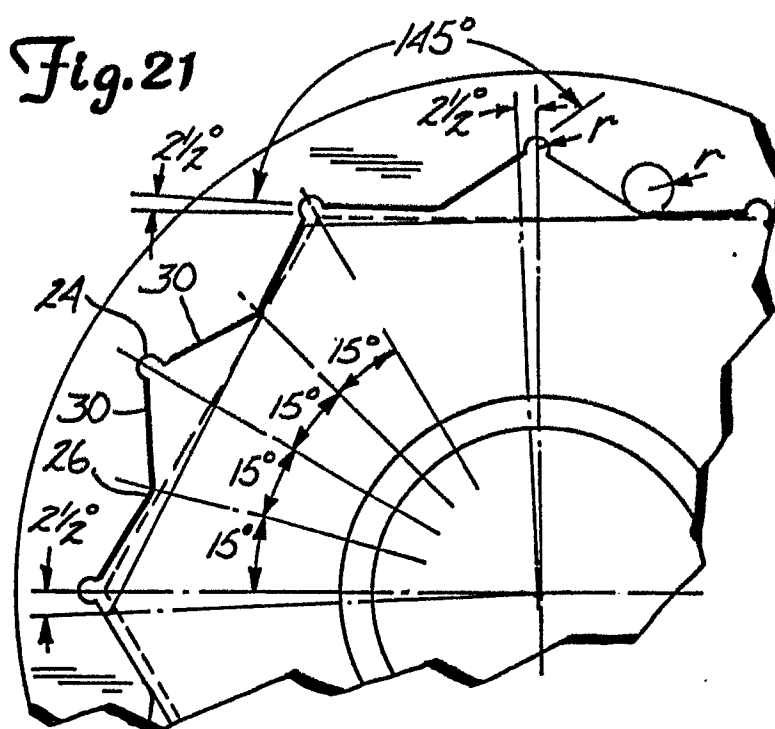


Fig. 22

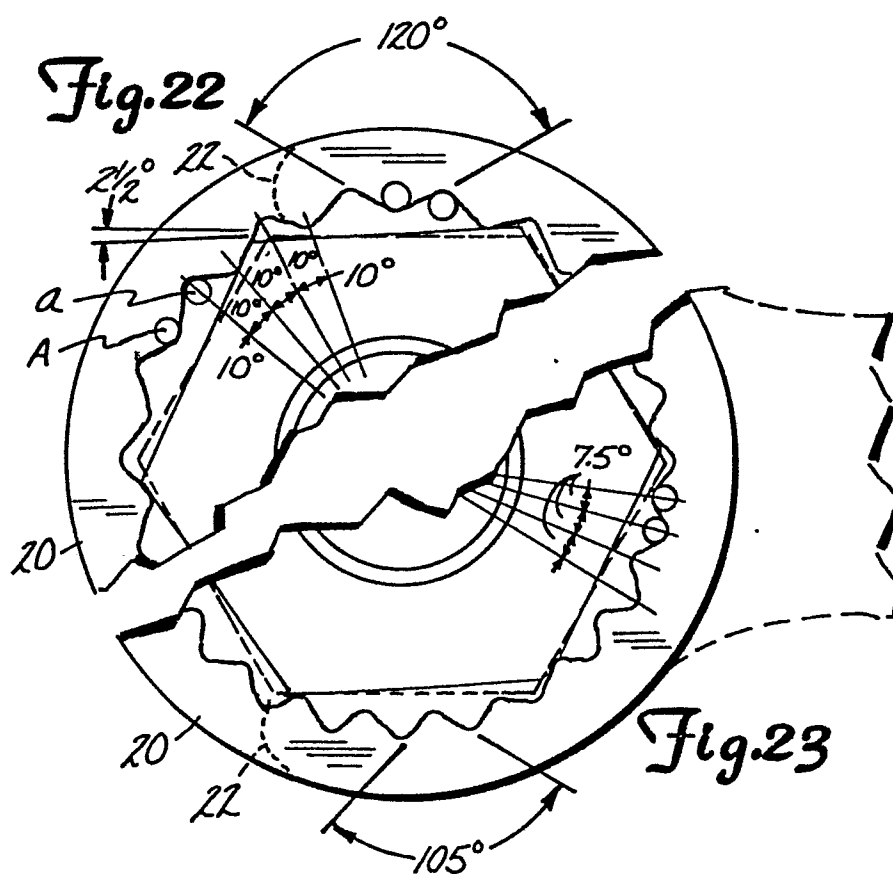


Fig. 23





DOCUMENTS CONSIDERED TO BE RELEVANT			EP 86309812.5
Category	Citation of document with indication, where appropriate, of relevant passages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. Cl. 4)
A	US - A - 4 512 220 (BARNHILL) * Fig. 3, 4 *	1, 2	B 25 B 13/06
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A	EP - A1 - 0 156 681 (DOSSIER) * Fig. 1 *	1, 2	
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D, A	US - A - 3 495 485 (R.G.KNUDSEN) * Fig. 2, 3 *	1	B 25 B 13/00
	--		
A, P	US - A - 4 598 616 (COLVIN) * Fig. 5 *	1	

The present search report has been drawn up for all claims			TECHNICAL FIELDS SEARCHED (Int. Cl. 4)
			B 25 B 13/00
Place of search VIENNA		Date of completion of the search 01-04-1987	Examiner BENCZE
CATEGORY OF CITED DOCUMENTS X : particularly relevant if taken alone Y : particularly relevant if combined with another document of the same category A : technological background O : non-written disclosure P : intermediate document T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons & : member of the same patent family, corresponding document			