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(54) **A sheet binder.**

(57) A sheet material binding apparatus for binding sheet materials with a cover material by a heat-adhesive bonding agent includes a heating plate on which a bottom of the covering material having the bonding agent is placed, the heating plate heats the bonding agent; a guide for supporting the covering material and the sheet materials vertically on the heating plate; a guide driver for moving the guide in a direction of a thickness of a set of the sheet materials to facilitate setting and removing of the covering material and the sheet materials; and a controller for controlling the guide driver.

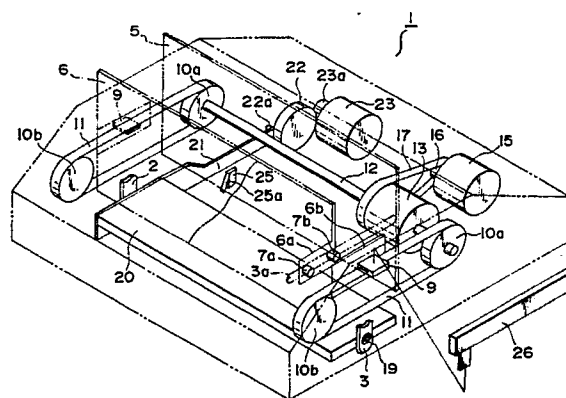


FIG. 2

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A SHEET BINDER

FIELD OF THE INVENTION AND RELATED ART

The present invention relates to a sheet binder, more particularly to a sheet binder for binding edges of sheet materials and a spine of a covering material with a bonding agent.

Referring to Figure 1, conventional sheet binder will first be described. The binder includes a main assembly 51 in which a heater 52 is fixed extending in a horizontal plane. It further includes guide plates 53 and 55 extending vertically above the heater 52, projections 53a and 55a extending in a horizontal plane substantially at the center of the guiding plates, pins 56 and 57 fixed on the projections, and horizontal elongated slot 59 for horizontally guiding the pins 56 and 57, the elongated slots 59 being formed in front and rear plates of the main assembly 51. A horizontal plate 60 is extended from the guide plate 53 toward the center of the apparatus, and a horizontal plate is extended from the guide plate 55 in a horizontal plane and in parallel with the plate 60. The opposing surfaces of the plates 60 and 61 are formed into racks 60a and 61a adjacent an end. A pinion 62 is meshed with the racks 60a and 61a. A front side shaft of the pinion 62 is journaled in the front plate of the main assembly 51, and an end of the shaft is equipped with a knob 65.

In operation, a thickness of the set of the sheet materials 33 to be bound is measured by a separate measuring device, and a heating period is determined in accordance with the thickness. Then, the sheet materials 33 are sandwiched in a folded covering material 32 having a bonding agent 63 at the folded bottom portion. Subsequently, the knob 65 is rotated in the direction indicated by a broken line to expand the interval between the guides plate 53 and 55. Then, the covering material sandwiching the sheet materials 33 is inserted between the guide plates 53 and 55 to place it on the heater 52. Thereafter, the knob 65 is rotated in the direction of the solid line arrow until the sheet materials 33 are sandwiched by the guide plate 53 and 55. The heating period determined above is set in the apparatus, and then, the heater 52 is actuated, by which the heater 52 fuses the bonding agent 63 to adhere the edges of the sheet materials 33 to the covering material 32.

When the heater 52 is deactuated (completion of the binding operation), the operator is notified of the completion by buzzer or the like. Then, the operator rotates the knob 65 in the broken line arrow direction to expand the interval between the guide plates 53 and 55, and takes the sheet materials 33 bound with the covering material 32 are

taken out. Then, the sheet materials 33 and the covering material 32 are cooled by a separate cooling stand. The binding operation ends when the binding agent is solidified.

The conventional apparatus involves a drawback that the knob 65 has to be operated often to open and close the interval between the guiding plates 53 and 55. If, the confining force to the sheet material 33 is too strong, the binding strength becomes not sufficient between the bonding agent 63 and the sheet materials 33. If it is too weak, the covering material 32 and the sheet materials are tilted, or become rhombus. Those are particularly remarkable when the thickness of the sheet materials 33 is large.

SUMMARY OF THE INVENTION

Accordingly, it is a principal object of the present invention to provide a sheet material binding apparatus in which the sheet material binding operation is simple and easy.

According to an aspect of the present invention, there is provided a sheet material binding apparatus wherein back edges of sheet materials and a bottom of a covering material are bound by heat-adhesive bonding agent, comprising heating means for heating the bonding agent, a pair of guiding members for confining the covering material and the sheet materials, and means for moving the guide member or members in a direction of the thickness of the sheet materials.

According to the present invention, the pair of guide members for confining and retaining the covering member is moved by a moving means, and therefore, there is no need for the operator to manipulate the knob for the opening and closing operation for the guide members, therefore, the labor for the binding can be saved.

These and other objects, features and advantages of the present invention will become more apparent upon a consideration of the following description of the preferred embodiments of the present invention taken in conjunction with the accompanying drawings.

BRIEF DESCRIPTION OF THE DRAWINGS

Figure 1 is a side view of a conventional binding apparatus.

Figure 2 is a perspective view of a binding apparatus according to an embodiment of the present invention.

Figure 3A is a side view of the apparatus wherein the heater is horizontal.

Figure 3B is a side view wherein the heater is jogged (intermediate position).

Figure 4A is a side view of guide plates which are opened.

Figure 4B is a side view of the guide plates wherein they are closed with a predetermined pressure.

Figure 4C is a side view of the guide plates wherein the guide plates are opened for a short period of time to provide a clearance.

Figure 5 is a block diagram for a control system of the binding apparatus.

Figure 6A is a graph showing a relation between a thickness of a set of sheet materials and proper heating period.

Figure 6B is a graph showing a relation between the thickness of a set of the sheet materials and a jogging period.

Figure 6C is a graph showing a relation between the thickness of a set of the sheet materials and proper clearance formation time.

Figure 7 is a time chart showing timing of operations of various elements.

Figure 8 is a perspective view of a binding apparatus according to another embodiment of the present invention.

Figures 9A, 9B, 9C and 9D are perspective views illustrating operation of the apparatus.

Figure 10 is a perspective view illustrating swinging movement of the heater plate.

Figures 11A and 11B are front views illustrating movement of the heater plate and the sheet materials.

Figure 12A, 12B, 12C, 12D and 12E are side views illustrating movement of the sheet materials.

Figure 13 is a perspective view of a binding apparatus according to a further embodiment of the present invention.

Figure 14 is a front view of the apparatus.

Figure 15 is a side view showing a jogging mechanism.

Figure 16 is a block diagram illustrating the control operation of the apparatus.

DESCRIPTION OF THE PREFERRED EMBODIMENTS

The preferred embodiments of the present invention will be described in conjunction with the accompanying drawings.

Referring to Figure 2, there is shown a sheet material binding apparatus 1. The binding apparatus 1 comprises side plates 2 and 3, to which a fixed guide plate 5 is mounted substantially vertically. The apparatus further comprises movable guide 6 from which tongues 6a and 6b are ex-

tended horizontally. The tongue 6a is provided with pins 7a and 7b projecting outwardly. The tongue 6b is provided with an outwardly and horizontally projecting portion 9. The pins 7a and 7b are guided along an elongated horizontal slot 3a formed in the side plate 3 (the side plate 2 has the same structure, although not shown in the Figure). To the insides of the side plates 2 and 3, a driving pulley 10a and a follower pulley 10b are mounted, around which a belt 11 is stretched. To the top travel portion of the belt 11, the above described horizontal projection 9 is mounted. The driving pulley 12a is fixedly mounted at each of the opposite longitudinal ends of the shaft 12. At a position between the opposite ends, a torque limiter 13 is mounted. A timing belt 17 is stretched around the torque limiter 13 and a pulley 16 fixed on an output shaft of a guide plate driving motor 15 fixed on the apparatus 1.

A heater 20 is supported by pins 19 in the side plates 2 and 3 at central portions at the longitudinal end surfaces thereof. As shown in Figure 3, an eccentric pin 22a of a cam gear 22 rotatably mounted on the apparatus 1 is inserted into an elongated slot 21a in an arm 21 extended from one end of the heater. The cam gear 22 is meshed with a gear 23a mounted on a heater jogging motor 23 fixed on the apparatus 1. The heater 20 is disposed below and close to the guide plates 5 and 6. A sensor 25 is mounted on the fixed guide plate 5, and a sensing element 25a of the sensor 25 is mounted on an inside of the guide plate 5 to detect the material inserted. To the horizontal projection 9, a slide volume 26 is mounted above the belt 11 in parallel therewith. As shown in Figure 3, a heater position sensor 27 is disposed close to the cam gear 22 above the center thereof. A flange 22b is provided on a half circumference of the cam gear, the circular flange 22b has a center coincident with the rotational center of the cam gear 22. By an end of the flange 22b, the sensor 27 is actuated or deactivated.

As shown in Figure 5, a control system 29 receives output signals from the sensor 25 for detecting the presence or absence of the sheet materials, the thickness detection sensor 26 constituted by the slide volume 26 and the heater position sensor 27. The control system 29, responsive thereto, supplies the drivers for the heater 20, the guide plate moving motor 15, the heater jogging motor 23, a display 30 and the buzzer 31, so that these elements are driven. The apparatus is further controlled by an unshown sensor for the heater 20, a timer in the control system 29 and memory means thereof.

In operation, the power supply to the sheet material binding apparatus 1 is started, then a covering member 32 having a heat-adhesive bond-

ing agent at the bottom thereof is inserted together with the sheet materials to be bound with the covering material, sandwiched by the covering material 32. By the actuation of the power switch of the apparatus 1, the heater 20 is supplied with electric power, and when the heater 20 reaches a pre-heating temperature, permission of the covering member 32 setting is displayed on the display 30 as shown in Figure 5.

Then, the covering member 32 together with the sheet materials 33 sandwiched thereby is inserted between the guides 5 and 6.

When the covering member 32 is detected by the sensor, the guide moving motor 15 is actuated with a time delay t_0 determined by an unshown timer. This moves the movable guide plate 6 the period of the movement is such that it is sufficient to sandwich the covering material 32 together with the sheet material, and therefore, when the thickness of the set of the sheet materials 33 is large, the torque limiter 13 slides for a long period, whereas when it is thin, the sliding period is short. Thus, a predetermined pressure is applied to the sheet materials 33 by the guide plate moving motor 15 due to the provision of the torque limiter 13.

Another example for this function is that the output of the motor 15 is properly selected, and the motor 15 is locked when the pressure exceeds a predetermined pressure level, by which the constant pressure can be provided without use of the torque limiter 13. At this time, the stop position of the movable guide plate 6 is detected by the slide volume 26, by which the thickness of the set of the sheet materials 33 is detected. The detection signal is transmitted to the control system 29, which determines the heating period t_1 (approximately 30 sec for the thickness of 10 mm), and actuates the heater 20 (approximately 150 °C), so that the covering material is heated for the period t_1 . The determined heating period t_1 is displayed on the display 30 (the remaining period may be displayed to notify the operator of the remaining period for the operators convenience).

After the start of the heating, the guide moving motor 15 is rotated in the opposite direction to add a small clearance (1 mm - 2 mm approximately) to the interval between the guide plates 5 and 6 after a small reverse period t_2 , by which the impregnation of the bonding agent is improved (by increasing the reverse period t_2 with increase of the thickness of the set of sheet materials 33, by which the impregnation of the bonding agent is further improved). After the heating period t_1 elapses, the control system 29 determines a jogging period t_3 - (approximately 10 sec), and the heater jogging motor 23 rotates for the period t_3 . This improves the alignment of the sheet materials 33 and increases the impregnation of the bonding agent

liquefied by the heat into between the adjacent sheet materials 33 (the period t_3 may be increased with the thickness of the set of the sheet materials 33 to improve the alignment and impregnation). As shown in Figure 7 by chain lines, the heating may be continued during the jogging operation.

After the completion of the jogging operation for the period t_3 , the buzzer 31 is actuated to notify the operator of the finishing (simultaneously, a display to that effect may be made), and simultaneously, the guide moving motor 15 is rotated reversely to expand the interval between the guide plates 5 and 6 to be prepared for the next binding operation. The heater 20 is stopped when it takes the horizontal position, that is, the position convenient for the next operation, by stopping the motor 23 actuation, deactuation of the heater position detecting sensor 27, or at the instance of the switching between the off-state and the on-state thereof.

Then, the sheet materials 33 and the covering material 32 now having the bonding agent properly adhered, are taken out together from between the opened guide plates 5 and 6, and is set in a cooling stand (not shown) to cool and solidify the bonding agent. The sheet binding operation is completed upon solidification of the bonding agent.

Referring to Figure 6A, between the thickness $S1$ of the set of the sheet materials 33 and the proper heating period t_1 of the heater 20, there is a substantially linearly increasing relation. As shown in Figure 6B, between the thickness $S1$ of the set of sheet materials 33 and the jogging period t_3 there is the same relationship. As shown in Figure 6C, the same applies to between the thickness $S1$ of the set of sheet materials 33 and the short reversing period t_2 . The change may be stepwise rather than continuous.

Figure 7 shows the above operation in a time sequential order.

In place of the contact sensor 25, a transparent type sensor may be used to detect the presence or absence of the sheet materials.

In this embodiment, only the movable guide plate 6 is moved, but it is possible that the guide plate 5 which is fixed in this embodiment may be made movable.

In this embodiment, the thickness is detected by the slide volume 26, and the short reverse period t_2 and the jogging period t_3 are controlled. However, those controls are not inevitable to the present invention, and therefore, they may be omitted.

In place of the heating period t_1 , the heating temperature may be changed in accordance with the thickness of the set of sheet materials, more particularly, the heating temperature is increased with increase of the thickness.

In the embodiment, after the completion of the heating operation, the guide plate 5 and 6 are opened automatically. However, this is not limiting, and the guide plates 5 and 6 are not opened upon the completion of the heating operation, but they may be opened when the operator takes the bound sheet materials out.

Referring Figures 8 - 12, a second embodiment of the present invention will be described.

Figure 8 is a perspective view of a binding apparatus (thermal binder) according to this embodiment. The apparatus comprises a fixed guide plate 101, a movable guide plate 102, a swingably vibratable heater plate 103 and a side cover 104. The inside surface of the side cover 104 functions as a lateral guide. The guides 101 and 102 may be folded to be overlapped to each other to facilitate to carry it around that is, the top of the apparatus becomes substantially flat.

The operation will be described.

Figures 9A, 9B, 9C and 9D are perspective views illustrating operation of the binder.

(1) The start button is actuated to start power supply (Figure 9A). The power lamp L is flickered, and the heater plate starts to be heated (pre-heating).

(2) The power lamp becomes continuously on-state upon completion of the pre-heating (30 sec, 60 °C).

(3) A cover 106 is selected in accordance with the thickness of the set of sheet materials 105 to be bound, and the sheet materials 105 are sandwiched by the cover 106. A heat-fusible bonding layer 113 is applied on an inside of the spine 106 of the cover 106. On the layer 113, the edges of the sheet materials 105 to be bound is set (Figure 9B).

The cover 106 sandwiching the sheet materials 105 is inserted into between the guide plates 101 and 102, and is placed on the heater plate 103.

(4) When the insertion of the sheet materials is detected by a switch SW in the apparatus, the movable guide plate 102 moves in the direction indicated by an arrow A to sandwich the sheet materials and the cover 106 between the movable guide plate 102 and the fixed guide plate 101. Thereafter, the movable guide plate 102 is reversely moved (approximately 2 mm), to relatively loosely sandwich the cover 106 and the sheet materials. At this time, even if the guide plate 102 is reversed, the cover 106 expands by its elasticity, so that the cover 106 is supported by the guide plates 101 and 102. Simultaneously, the heater plate 103 starts to be heated. The heating period is 60 sec, in which the temperature thereof reaches 130 °C. After the bonding agent layer 113 starts to fuse by the heat (48 sec after the heating), the swinging vibration of the heater plate 103 starts its

swinging vibration and continues for 12 sec. The remaining period is displayed by a lamp which is counted down (Figure 9C).

(5) After the predetermined heating period (60 sec) elapses, the vibration ends, and the ending is notified to the operator by buzzer (Figure 9D).

(6) The set of sheet materials and the cover now bound are taken out together. When they are taken out, the movable guide plate 102 is moved away from the other guide plate (in the direction B) to its home position (Figure 9A). The sheet materials are placed on a cooling table on which the sheet materials are placed vertically with the bound portion 106a at the bottom by being sandwiched by proper means.

The heater plate will be described in detail.

Figure 10 is a perspective view for swinging the heater plate 103.

The heater plate 103 is swingably supported (direction C) by a shaft 108 substantially at the center of the heater plate.

The shaft 108 is planted on a holding means 107 fixed on the apparatus. A forked plate 102 is fixed to an end of the heater plate 103. The forked portion is engaged with an eccentric cam 112 rotatably supported on the apparatus. Therefore, when the eccentric cam 112 rotates by the motor 110 through a gear train 111, the heater plate 103 reciprocally swings about the shaft 108 in the direction C.

The swinging movement of the heater plate will be described.

As shown in Figure 11A, the swinging movement of the heater plate occurs between the horizontal plate a and the inclined state by the angle θ . The angle θ is approximately 1 degree in this embodiment. The frequency is 3 reciprocations per 1 sec. The operator sets the sheet materials at the solid line position in Figure 11A. By the first lowering swing of the heater plate, the end edges 105b of the sheet materials makes an arcuate movement with the lateral guide 104 fixed, and therefore, end edges 105b of the sheet materials are pushed to the lateral guide 104, so that they are pushed back to the chain line position through a distance 1.

With continuance of the swinging vibration, the end edges 105b of the sheet materials are softly abutted to the lateral guide 104 in each of the reciprocations. The right end of the heater plate does not move upwardly beyond the horizontal line A. Therefore, when the heater plate 3 moves upwardly, the sheet materials are elevated while the distance 1 is being kept, and therefore, they do not displace (Figure 11B).

The reason why the heater plate is swung will be described.

In this embodiment, the sheet materials are

vibrated by the swinging movement of the heater plate, by which the bonding agent is impregnated into between adjacent sheet materials. The principle thereof will be described. As shown in Figures 12B and 12C, when the cover 106 lowers and instantaneously stopped, the sheet materials encroaches into the bonding agent layer 13. When the cover 106 is elevated as shown in Figure 12D, the bonding agent layer 113 is elevated against the weight of the sheet materials 105, and therefore, the sheet materials further encroaches into the bonding material layer 113. By the repetition of the upward and downward vibration, the sheet materials encroach into the bonding layer 113.

Referring to Figures 13 - 16, a third embodiment will be described, wherein the heating plate which swings as described with Figure 11 is incorporated into the apparatus of Figure 2. The same reference numerals as in Figures 2 and 10 are assigned to the elements having the corresponding functions, and the detailed description thereof are omitted for simplicity.

Substantially a longitudinal center of the heater 103 is rotatably supported on a pin 108 threaded in a heater fixing plate. As shown in Figures 14 and 15, a fork portion 109a of the arm 109 extended from one end of the heater 103 is engaged with an eccentric cam 112 of an eccentric cam gear 12 rotatably mounted on the apparatus 1. The eccentric cam gear 22 is meshed with a gear 23a mounted on a shaft of the heater jogging motor 23 fixed on the apparatus 1. The heater 103 is disposed below and close to the guide plates 5 and 6. The sensor 25 (corresponding to SW of Figure 9) is mounted on the fixed guide plate 5, and a sensing element 25a of the sensor 25 is mounted on the inside of the guide plate 5, and the sensor 25 detects the material inserted. The slide volume 26 is mounted on the horizontal projection 9 above and in parallel with the belt 11.

As shown in Figure 16, the control system 29 receives outputs from the sensor 25 for detecting presence and absence of the sheet materials, the thickness detecting sensor 26' constituted by the slide volume 26. The control system 29, responsive to these signals, transmits signals to the drivers of the heater 103, the guide moving motor 15, the heater jogging motor 23, the display 30 and the buzzer 31 so as to drive them. It further controls the operation of the apparatus 1 using an unshown sensor for the heater 3, a timer of the control system and memory means of the control system.

In operation, the power is supplied to the sheet material binding apparatus 1. Then, the sheet materials 105 to be bound is sandwiched by a cover material 106 having a heat-fusible bonding agent at the bottom thereof. When the heater 103 reaches a preheated state, it is notified in the

display 30 that the covering material 106 can be set in the apparatus, on the display 30 shown in Figure 16.

The covering material 106 sandwiching the sheet materials 105 is inserted between the guide plates 5 and 6 until it is abutted to a side guide 104.

When the covering material 106 is detected by the sensor 25, the guide moving motor 15 starts to rotate with a time delay t_0 determined by an unshown timer, by which the movable guide plate 26 moves for a time period which is sufficient to sandwich the sheet materials 105 through the covering material 106 by the movable and fixed guide plates. When the thickness of the set of sheet materials 105 is large, the torque limiter 13 slides for a long period, whereas when the set of sheet materials 105 has a small thickness, the sliding period of the torque limiter 13 is short. Thus, the sheet materials 105 receive a constant pressure from the guide plate moving motor 15 due to the provision of the torque limiter 13. As an alternative, the output of the motor 35 may be properly selected so that when the pressure increases beyond a predetermined level, the motor 15 is locked, by which the constant pressure can be maintained without the torque limiter 13. At this time, the sheet material set thickness detection sensor 26' constituted with the slide volume 26 detects the thickness of the set of materials 105. The detection signal is supplied to the control system 9, which then determines the heating period t_1 - (approximately 30 sec for 10 mm thickness) as shown in Figure 6A and which brings the heater 103 into a heating state (approximately 150 °C). The heating is continued for the period t_1 . The heating period t_1 is displayed on the display 30. The rest of the period may be displayed to facilitate the operation.

After the start of the heating operation, the guide moving motor 15 reverses its rotation to add a small clearance (1 mm - 2 mm approximately) between the interval between the guide plates 5 and 6 after a short reversing period t_2 to improve the impregnation of the bonding agent. The short reversing period t_2 may be increased with the increase of the thickness of the set of sheet materials 105, as shown in Figure 6C, to further improve the impregnation of the bonding agent.

When the heating period t_1 ends, the controlling system 29 determines the jogging period t_3 - (approximately 10 sec), as shown in Figure 6B. Then, the jogging motor 10 rotates for the period t_3 , by which the heater 103 is swingingly vibrated for the period t_3 to improve the impregnation of the bonding agent heated and fused into between the adjacent sheet materials 105. Simultaneously, the deviation of the sheet material 105 are prevented

by an abutting plate 4. At this time, if the vertical swinging angle at the abutting plate side is large below the horizontal plate, the effect of moving toward the abutting plate is provided. The jogging period t_3 may be increased with increase of the thickness of the set of sheet materials to increase the sheet aligning effects and the impregnation of the bonding agent between the sheet materials 105.

When the jogging period (t_3) ends, the buzzer 51 is actuated to notify the operator of the end, and simultaneously, the guide moving motor 35 is reversely rotated to expand the interval between the guide plates 1 and 2 to be prepared for the next binding operation. The interval between the guides 5 and 6 may be expanded after the sheet materials are taken out.

In the embodiment, the jogging period t_3 is controlled in accordance with the thickness of the set of sheet materials 105, but the number of vibrations and/or amplitude of the vibration of the heater may be changed.

While the invention has been described with reference to the structures disclosed herein, it is not confined to the details set forth and this application is intended to cover such modifications or changes as may come within the purposes of the improvements or the scope of the following claims.

A sheet material binding apparatus for binding sheet materials with a cover material by a heat-adhesive bonding agent includes a heating plate on which a bottom of the covering material having the bonding agent is placed, the heating plate heats the bonding agent; a guide for supporting the covering material and the sheet materials vertically on the heating plate; a guide driver for moving the guide in a direction of a thickness of a set of the sheet materials to facilitate setting and removing of the covering material and the sheet materials; and a controller for controlling the guide driver.

Claims

1. A sheet material binding apparatus for binding sheet materials with a cover material by a heat-adhesive bonding agent, comprising:
a heating plate on which a bottom of the covering material having the bonding agent is placed, said heating plate heats the bonding agent;
guiding means for supporting the covering material and the sheet materials vertically on the heating plate;
guide driving means for moving said guiding means in a direction of a thickness of a set of the sheet materials to facilitate setting and removing of the covering material and the sheet materials; and
control means for controlling said guide driving

means.

2. An apparatus according to Claim 1, further comprising means for detecting the setting of the covering material, and wherein said guide driving means is operated in response to the setting of the covering materials in a direction of sandwiching the covering material.

3. An apparatus according to Claim 1, wherein said guide driving means includes a torque limiter which operates when the guiding means moves in a direction sandwiching the covering material.

4. An apparatus according to Claim 1, further comprising means for detecting a thickness of the set of sheet materials in interrelation with movement of said guiding means in a direction of sandwiching the covering material.

5. An apparatus according to Claim 1, wherein said heating plate is supported for jogging movement.

6. An apparatus according to Claim 5, wherein said heating plate is swingably supported on a shaft extending in a direction of the thickness of the set of sheet materials.

7. An apparatus according to Claim 5, wherein said heating plate is swingably supported on a shaft perpendicular to a direction of a thickness of the set of sheet materials.

8. An apparatus according to Claim 1, further comprising detecting means for detecting setting of the covering material, wherein said guide driving means is operated in response to an output of said detecting means to move said guiding means so as to sandwich the covering material thereby, and thereafter, said guide driving means is operated in a reverse direction to lightly sandwich the covering material.

9. An apparatus according to Claim 8, wherein said guiding means is controlled by said control means so that it is slightly moved back after said guiding means sandwiches the covering material.

10. An apparatus according to Claim 8, wherein said guiding means is controlled by said control means so that said guide means moves back slightly after start of heating operation of said heating plate.

11. An apparatus according to Claim 4, further comprising heating means for controlling a heating condition of said heating plate in accordance with a thickness of the set of sheet materials.

12. A sheet material binding apparatus for binding sheet materials with a cover material by a heat-adhesive bonding agent, comprising:
a heating plate on which a bottom of the covering material having the bonding agent is placed, said heating plate heats the bonding agent;
guiding means for supporting the covering material and the sheet materials vertically on the heating plate;

guide driving means for moving said guiding means in a direction of a thickness of a set of the sheet materials to facilitate setting and removing of the covering material and the sheet materials;
 control means for controlling said guide driving means;
 means for detecting a thickness of the set of sheet materials; and
 second control means for determining a heating condition of said heating plate in accordance with an output of said detecting means.

13. A sheet material binding apparatus for binding sheet materials with a cover material by a heat-adhesive bonding agent, comprising:
 a heating plate on which a bottom of the covering material having the bonding agent is placed, said heating plate heats the bonding agent;
 guiding means for supporting the covering material and the sheet materials vertically on the heating plate;
 guide driving means for moving said guiding means in a direction of a thickness of a set of the sheet materials to facilitate setting and removing of the covering material and the sheet materials;
 detecting means for detecting insertion of the covering material between said guiding means;
 control means, responsive to said detecting means, for closing said guiding means by said guide driving means, and thereafter, opening slightly said guiding means;
 detecting means for detecting a thickness of the set of sheet materials in interrelation with the closing operation of said guide means;
 second control means for determining a heating condition of said heating plate in accordance with an output of said thickness detecting means.

14. An apparatus according to Claim 13, further comprising means for displaying a time period required for binding the covering material and the sheet materials, the time is being counted down.

15. An apparatus according to Claim 14, wherein said display means includes a lamp.

16. A sheet material binding apparatus for binding sheet materials with a cover material by a heat-adhesive bonding agent, comprising:
 a heating plate on which a bottom of the covering material having the bonding agent is placed, said heating plate heats the bonding agent;
 guiding means for supporting the covering material and the sheet materials vertically on the heating plate;
 guide driving means for moving said guiding means in a direction of a thickness of a set of the sheet materials to facilitate setting and removing of the covering material and the sheet materials;
 detecting means for detecting insertion of the covering material between said guiding means;
 control means, responsive to said detecting means,

for closing said guiding means by said guide driving means, and thereafter slightly opening said guiding means;

means for swingably supporting said heating plate having a shaft extending in a direction of a thickness of the set of sheet materials; and
 swinging drive means for swinging said heating plate after heating operation.

17. An apparatus according to Claim 16, further comprising means for guiding edges of the sheet materials perpendicular to a surface of the covering material, wherein the edges of the sheet materials are abutted to said edge guiding means by swinging movement of said heating plate.

18. An apparatus according to Claim 17, wherein said heating plate swings between a substantially horizontal state and an inclined state in which the edges of the sheet materials are lowered.

19. A sheet material binding apparatus for binding sheet materials with a cover material by a heat-adhesive bonding agent, comprising:
 a heating plate on which a bottom of the covering material having the bonding agent is placed, said heating plate heats the bonding agent;
 guiding means for supporting the covering material and the sheet materials vertically on the heating plate;
 guide driving means for moving said guiding means in a direction of a thickness of a set of the sheet materials to facilitate setting and removing of the covering material and the sheet materials;
 control means for driving said guide driving means;
 supporting means extending in a direction of a thickness of the set of sheet materials to swingably support said heating plate;
 heating plate driving means for swinging said heating plate.

20. A sheet material binding apparatus wherein edges of sheet materials are placed on a heat-adhesive binding agent, and they are placed on a supporting table, where the bonding agent is heated to bind the sheet materials, comprising:
 a supporting member for supporting the supporting table, said supporting member being extended in a direction of a thickness of a set of the sheet materials; and
 means for swinging said supporting member.

21. An apparatus according to Claim 20, further comprising an abutment member for confining edges of the sheet materials.

22. An apparatus according to Claim 21, wherein said supporting table swings downwardly from a horizontal plate at a side where the abutment member is provided.

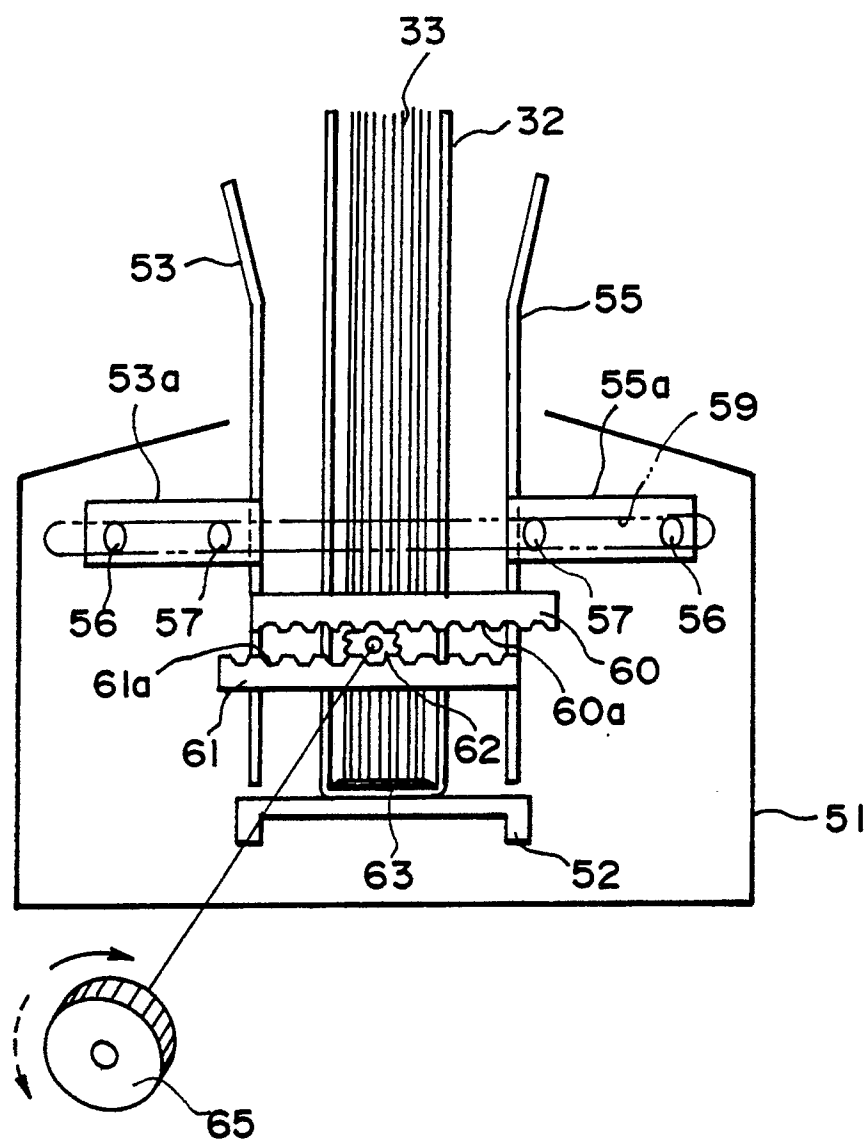


FIG. 1

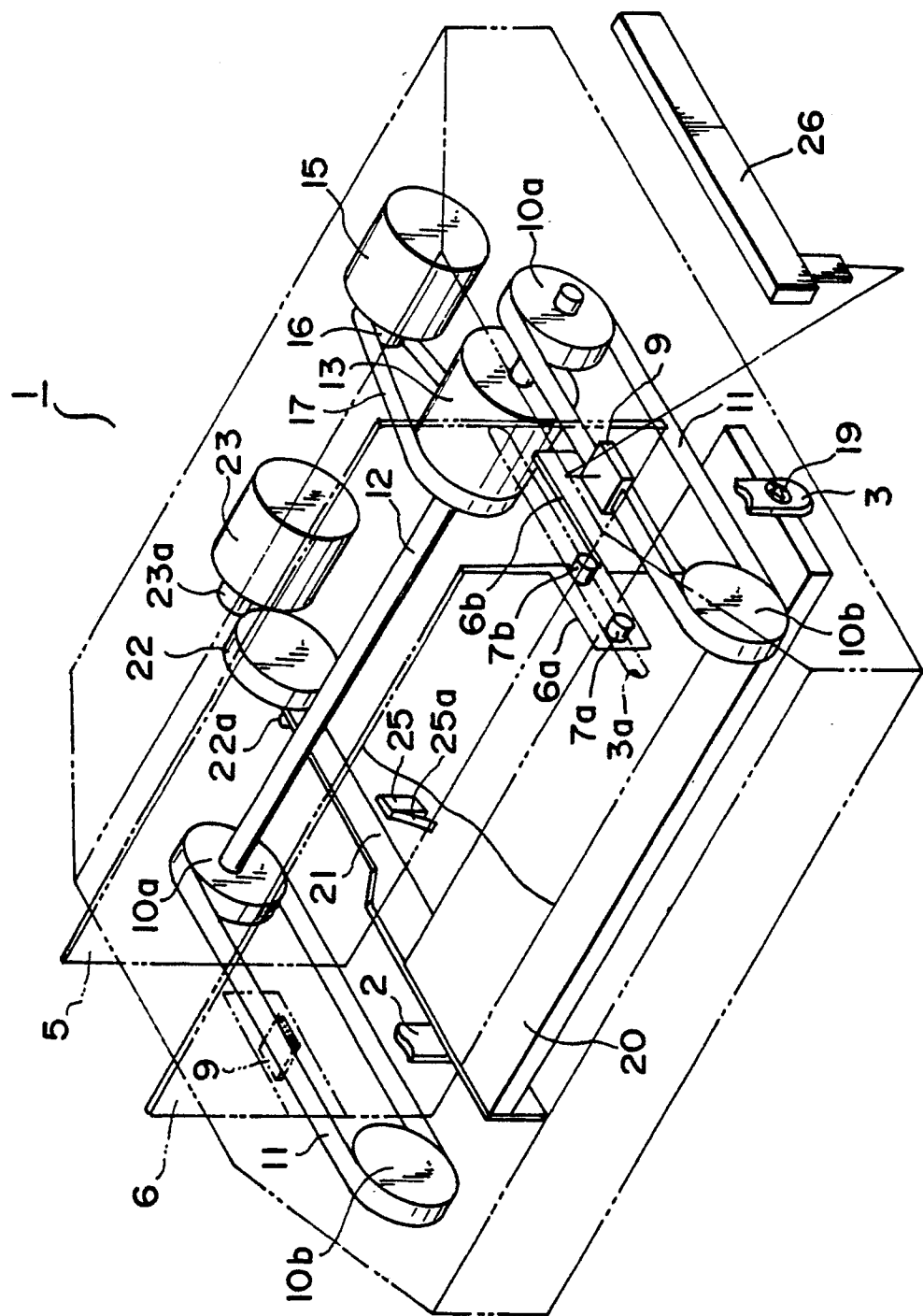


FIG. 2

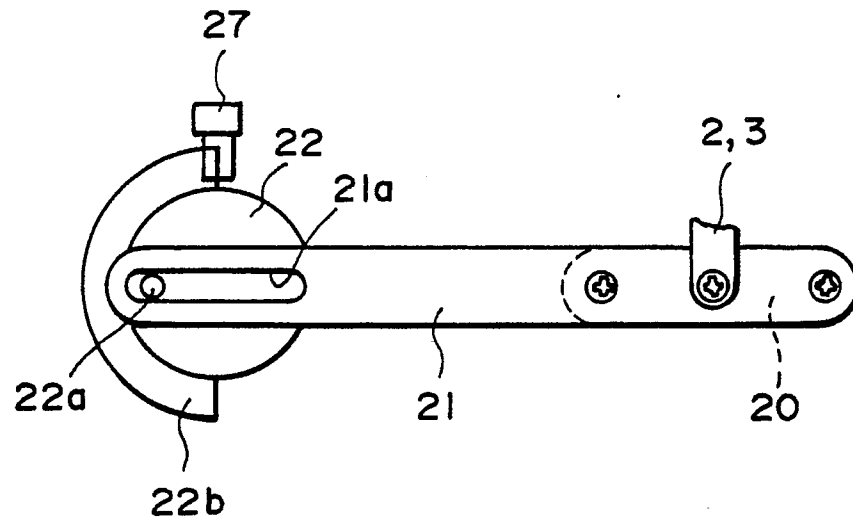


FIG. 3A

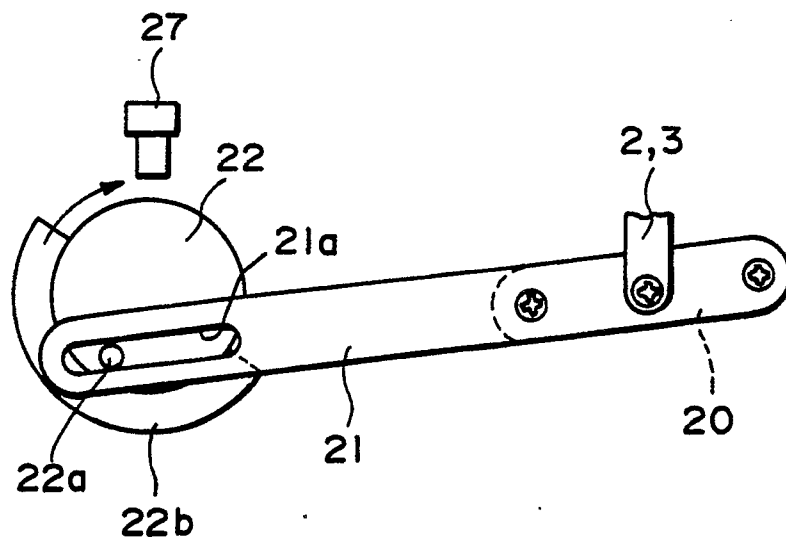


FIG. 3B

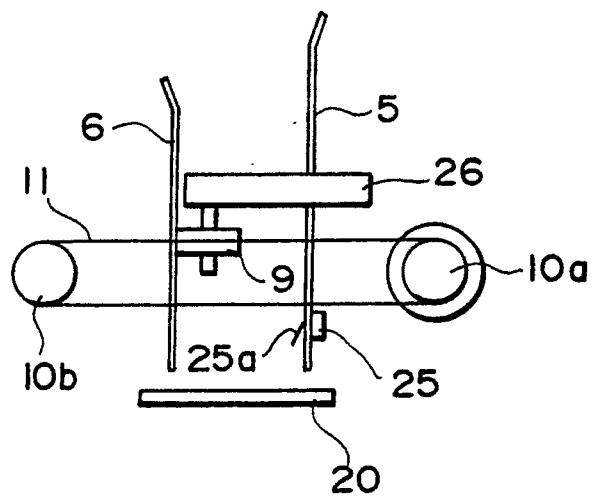


FIG. 4A

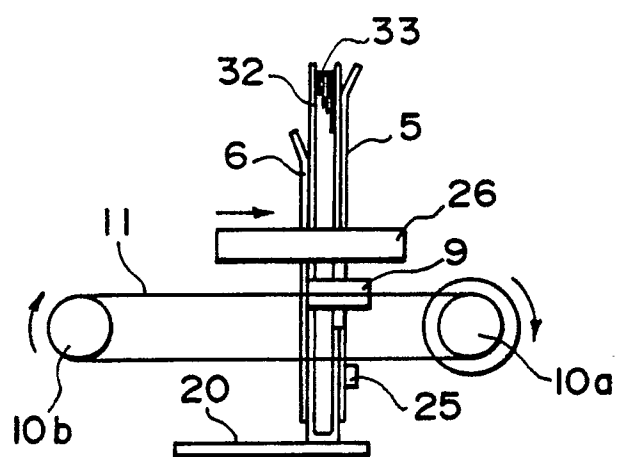


FIG. 4B

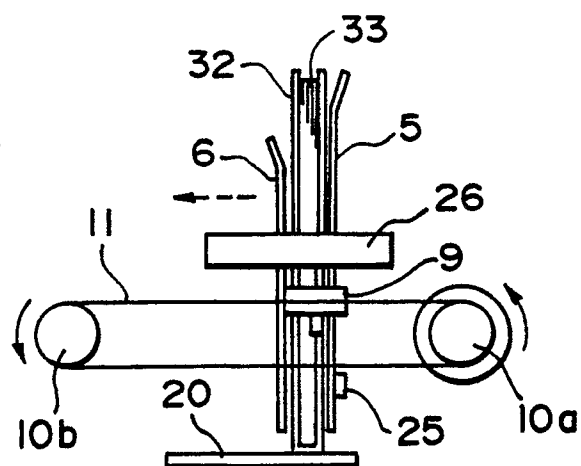


FIG. 4C

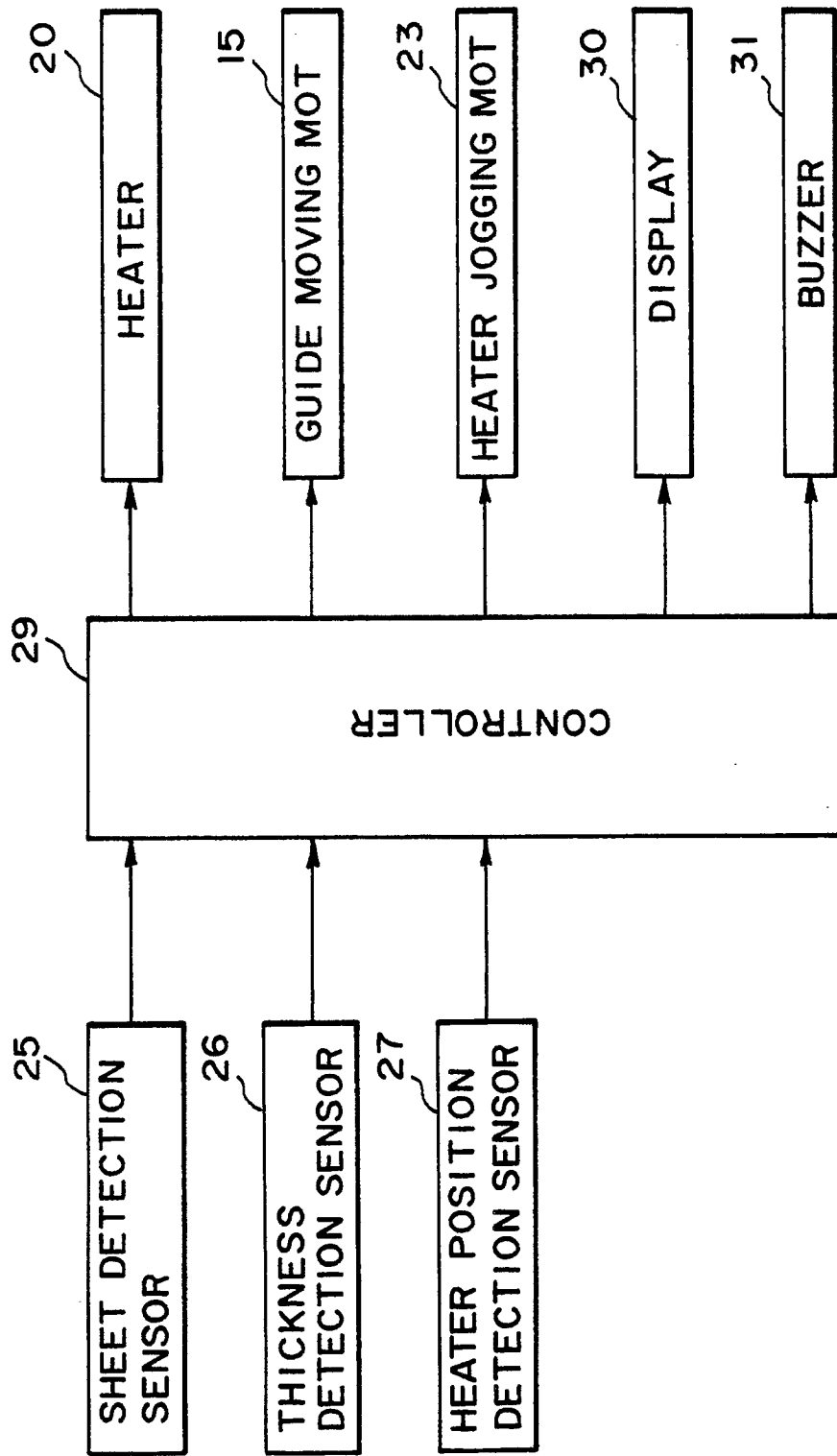


FIG. 5

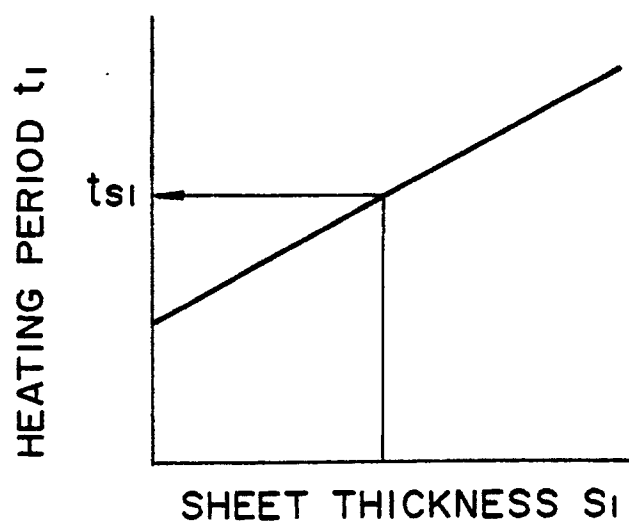


FIG. 6A

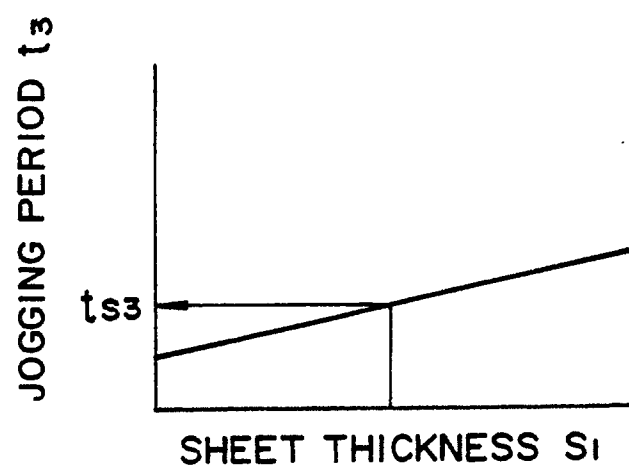


FIG. 6B

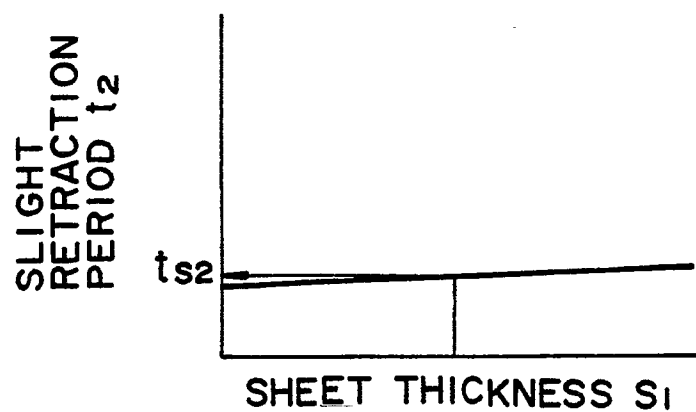


FIG. 6C

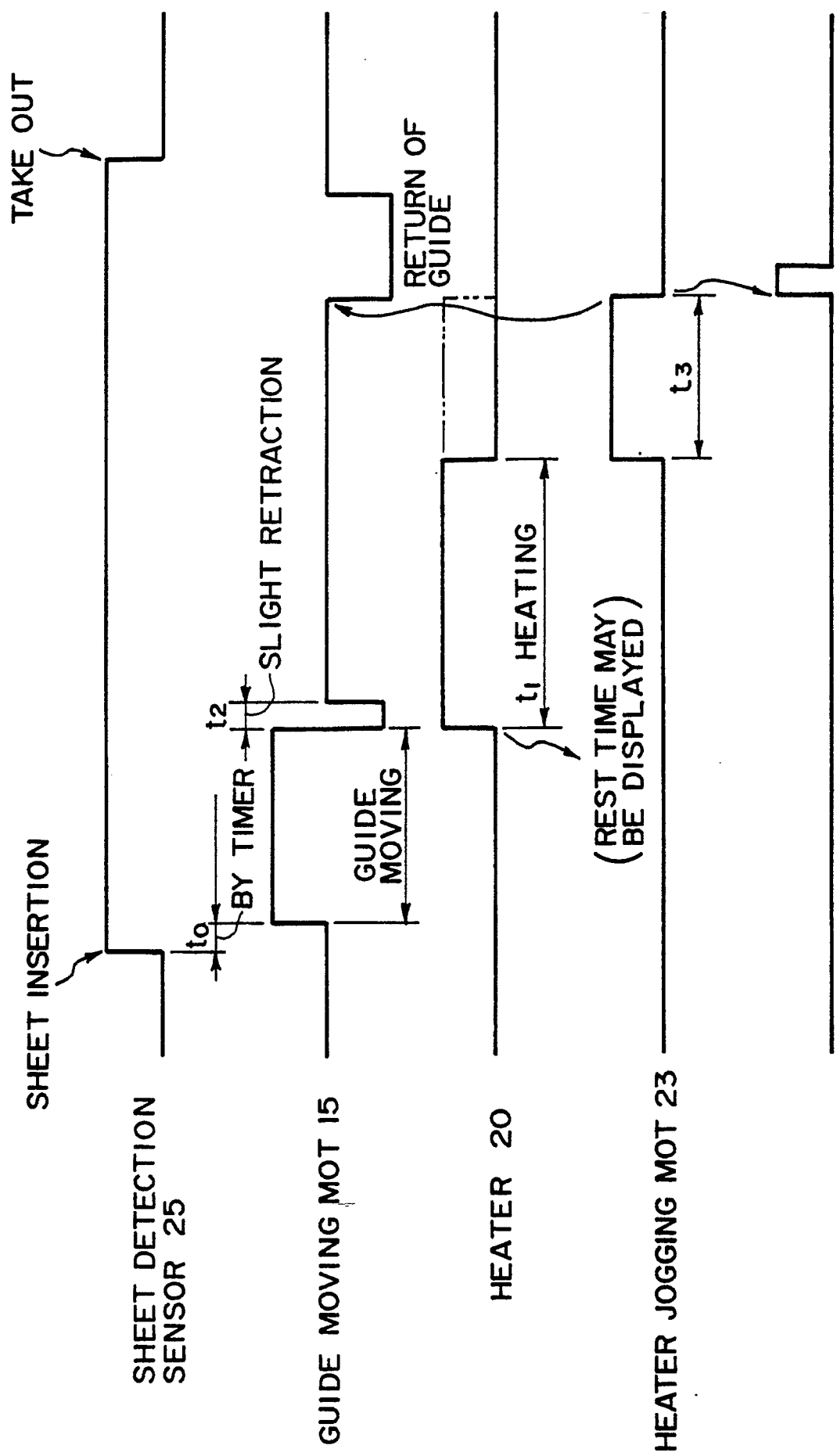


FIG. 7

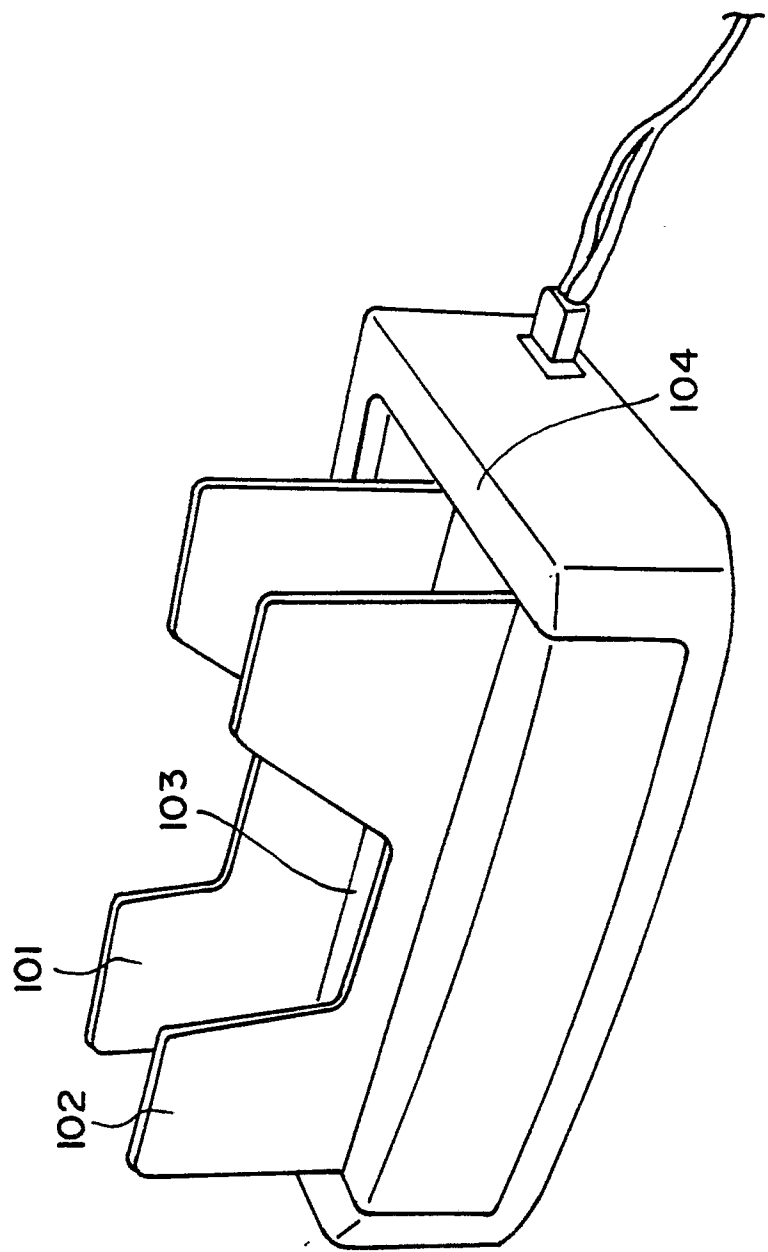


FIG. 8

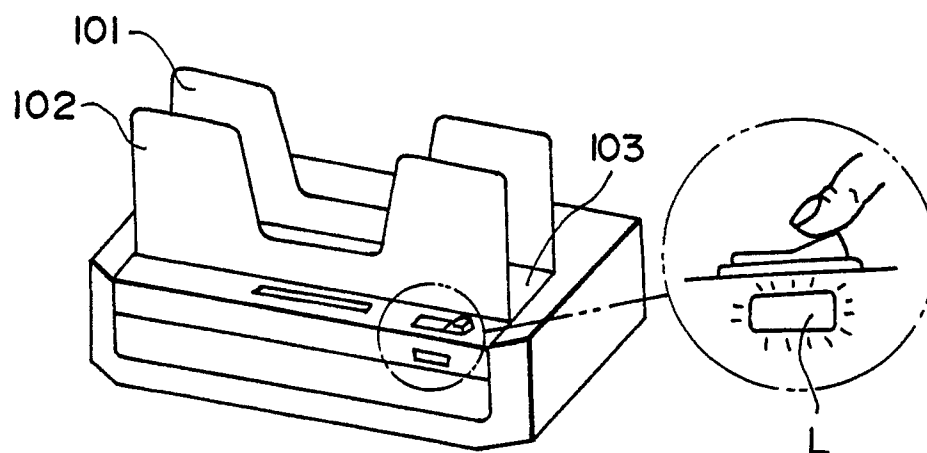


FIG. 9A

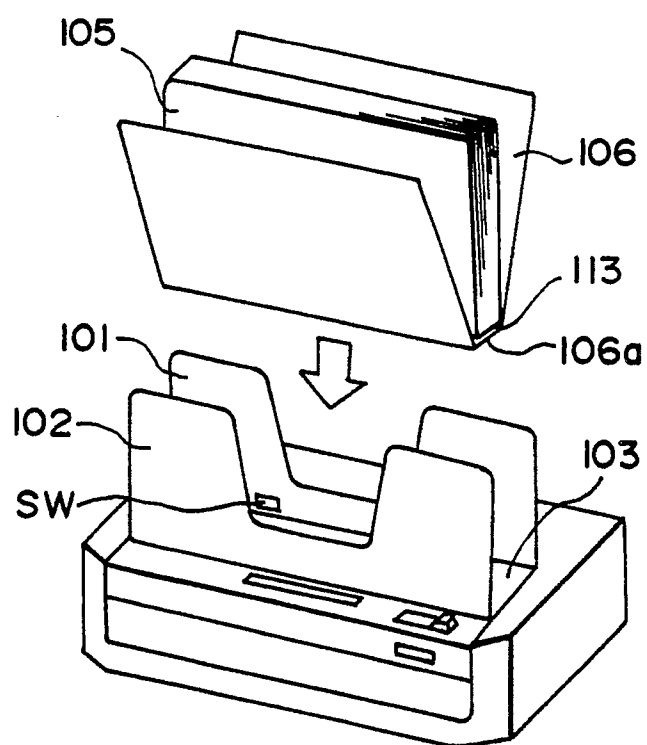


FIG. 9B

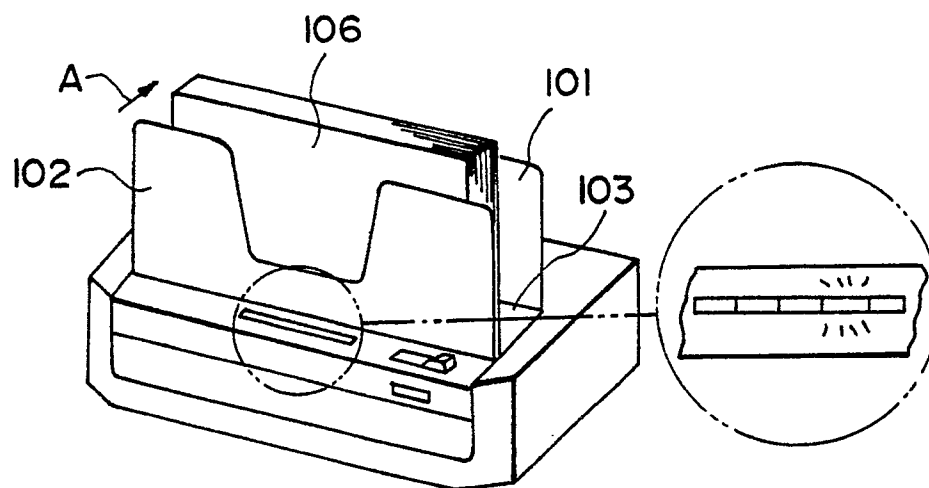


FIG. 9C

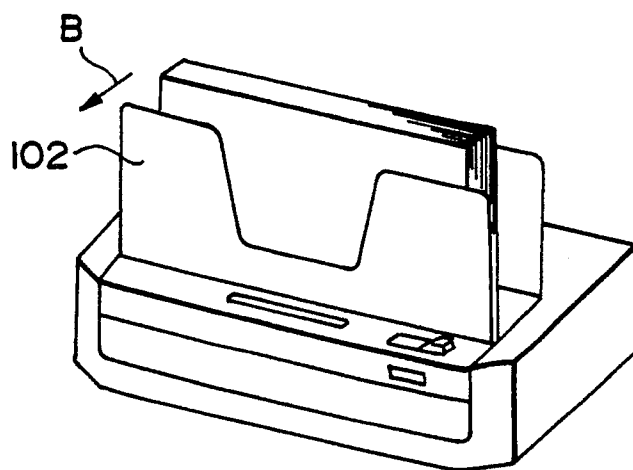


FIG. 9D

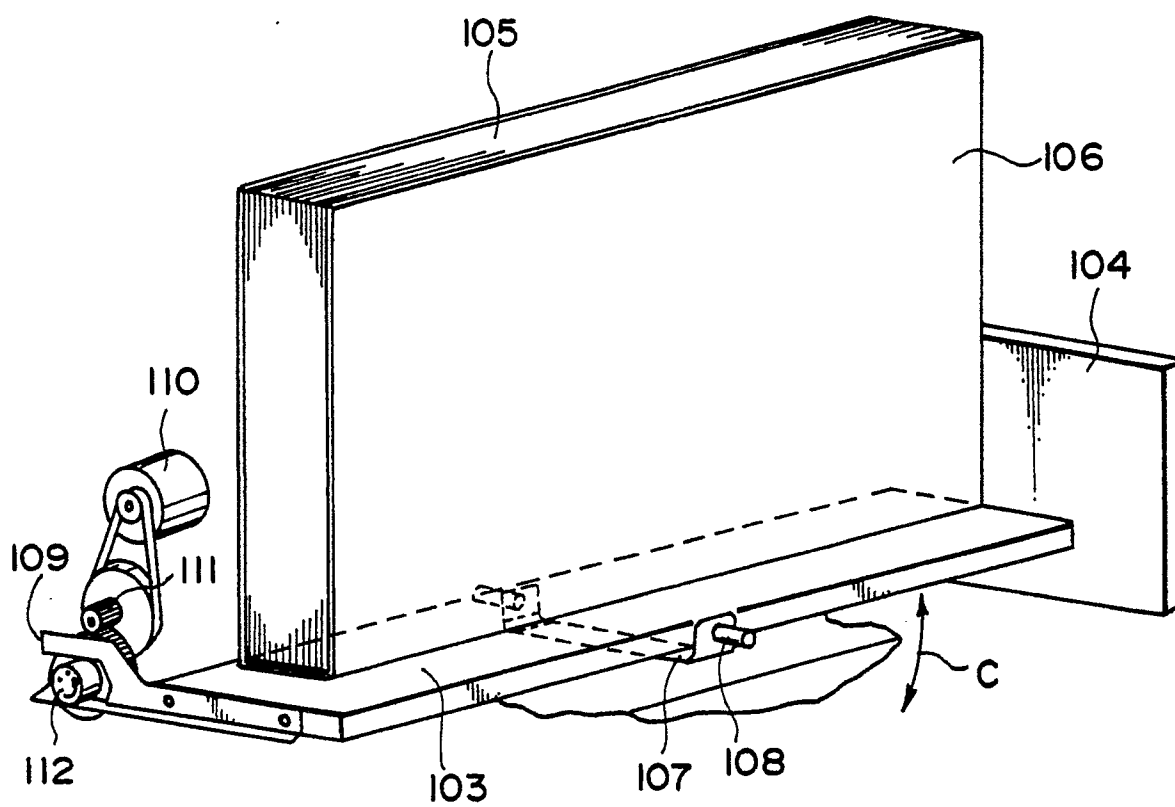


FIG. 10

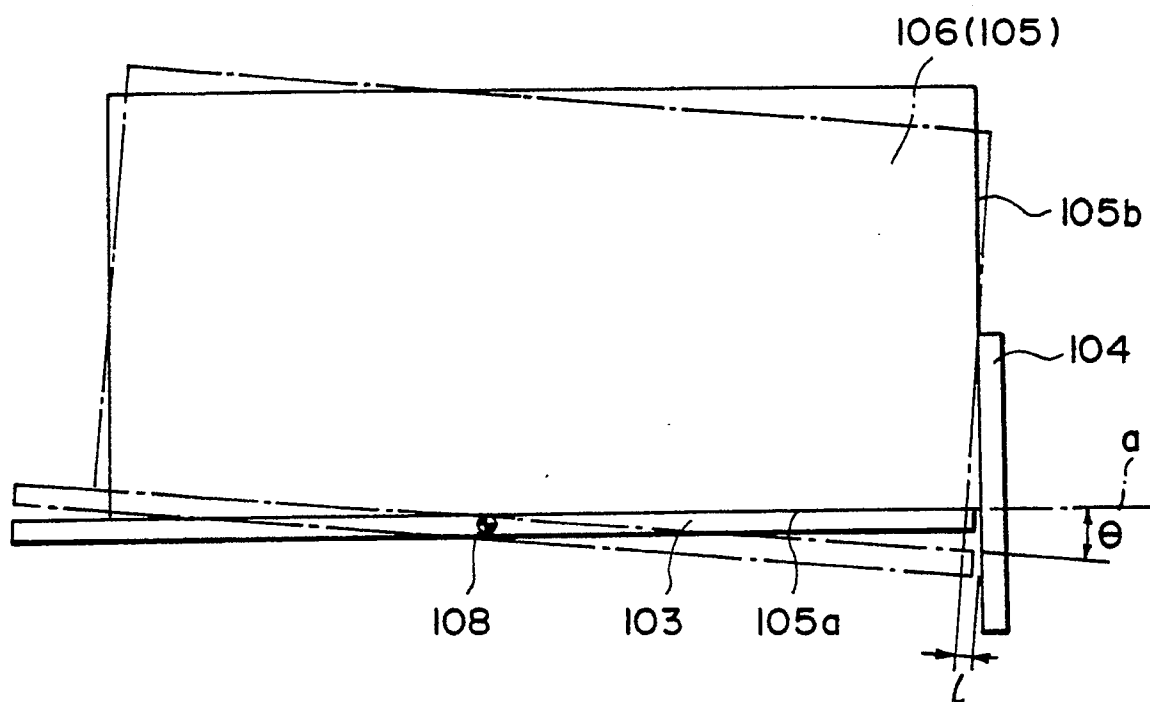


FIG. IIA

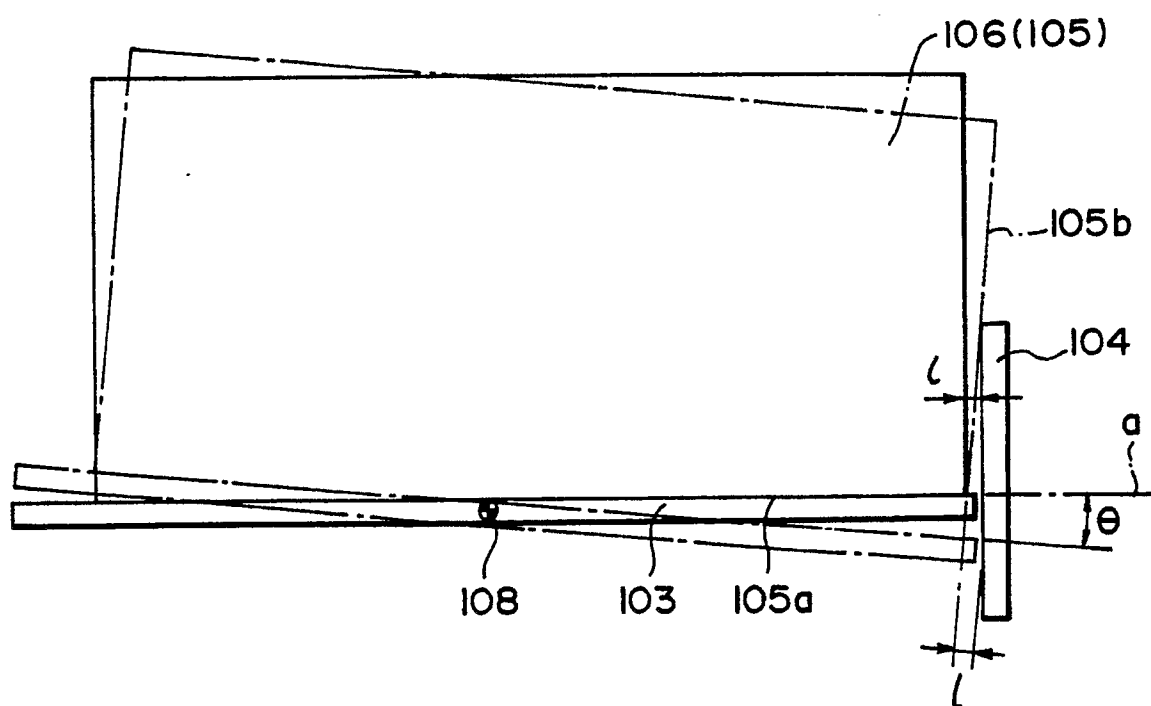


FIG. IIB

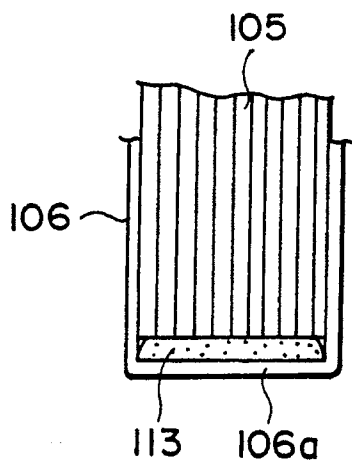


FIG. 12A

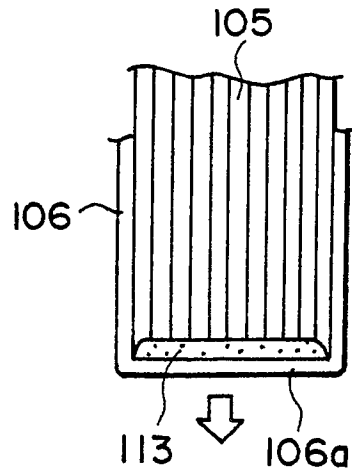


FIG. 12B

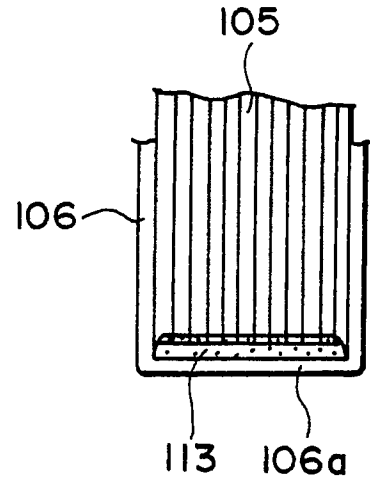


FIG. 12C

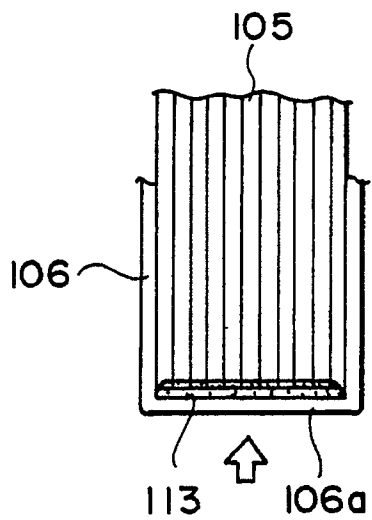


FIG. 12D

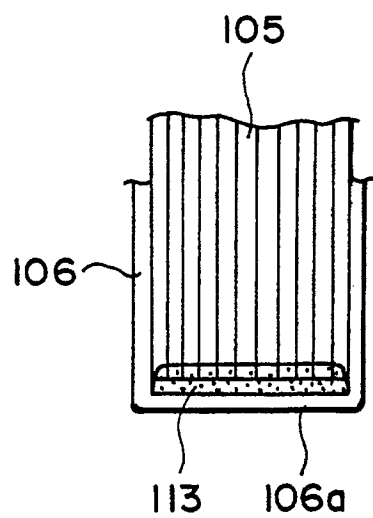


FIG. 12E

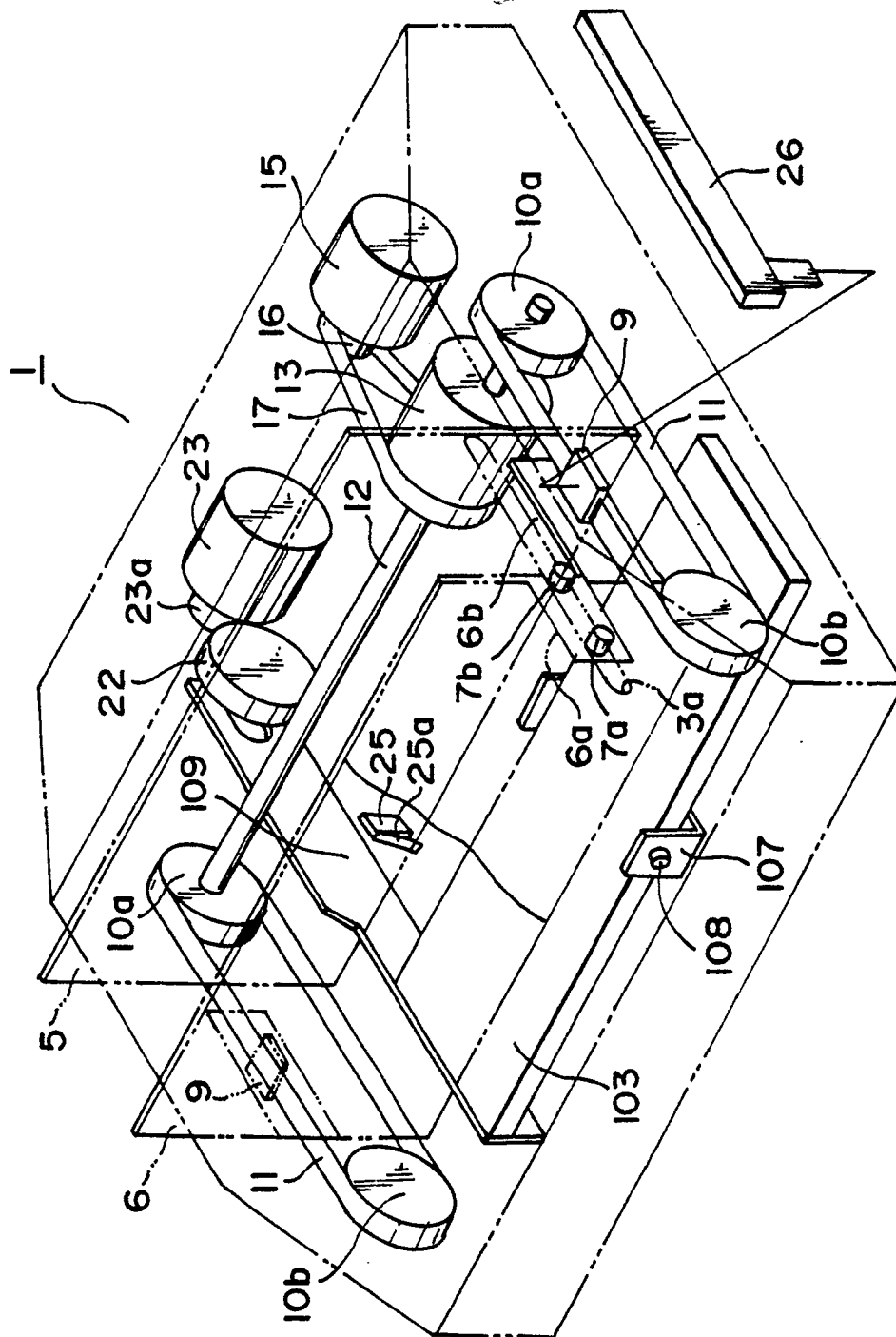


FIG. 13

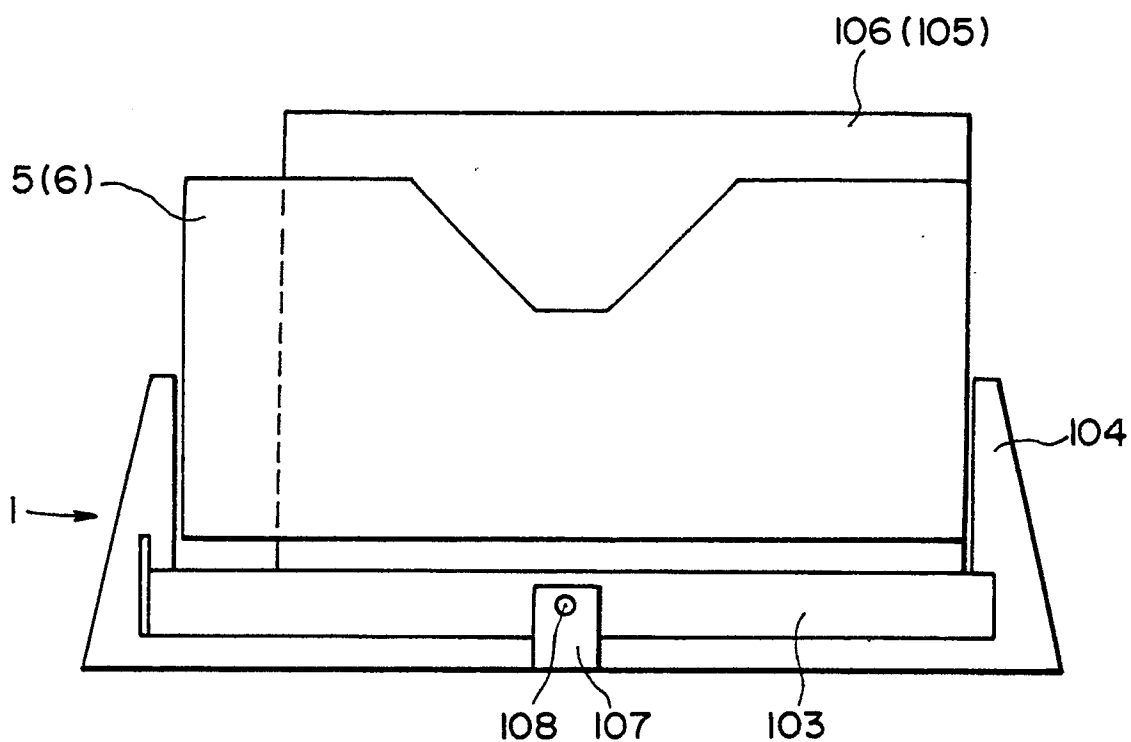


FIG. 14

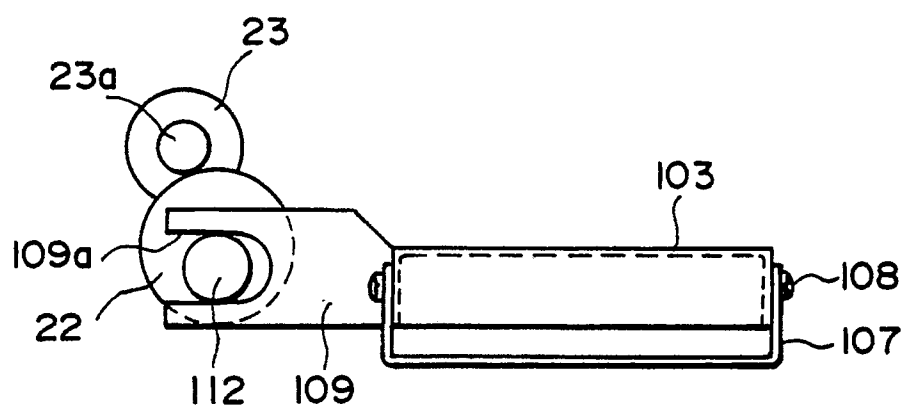


FIG. 15

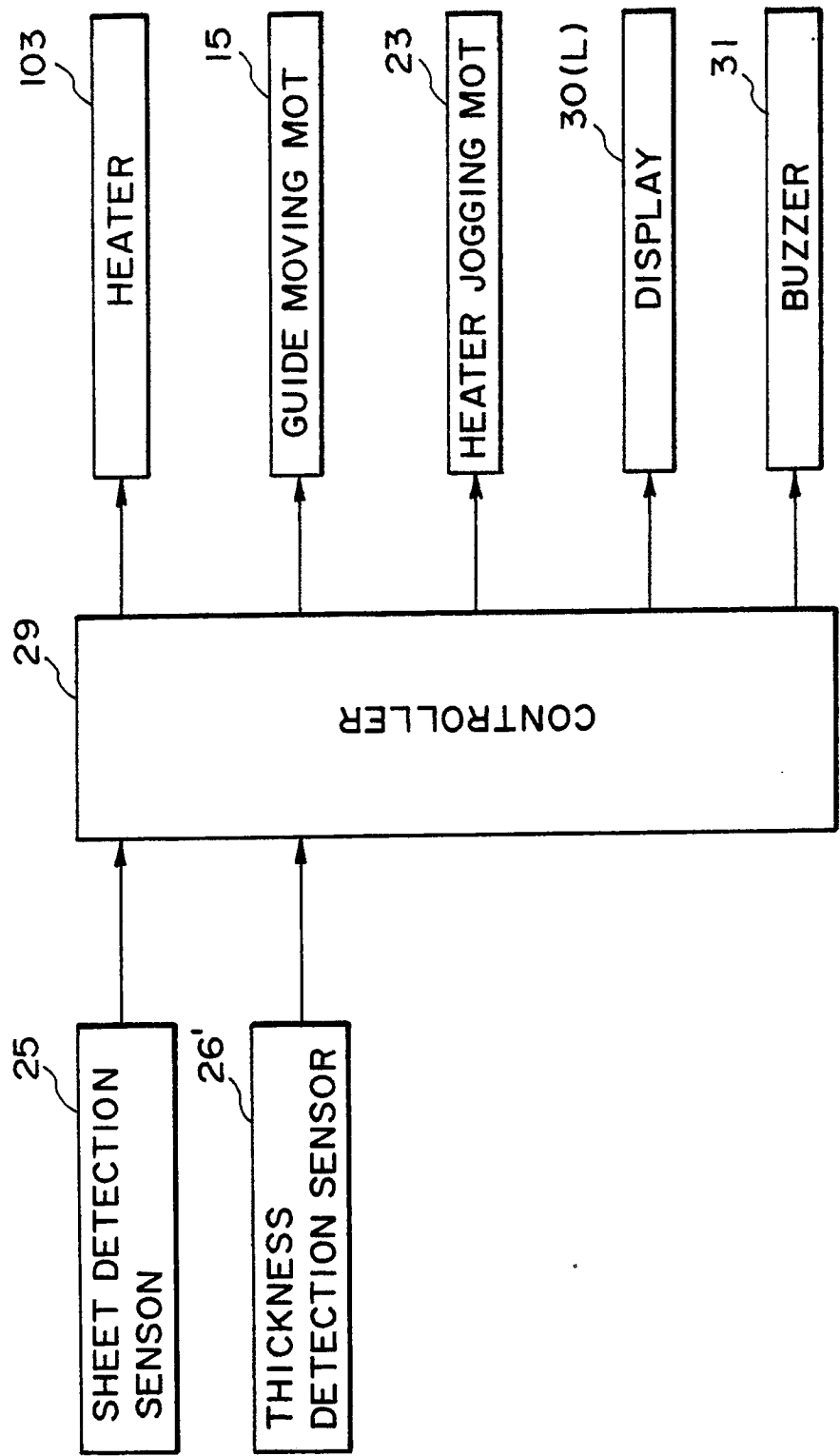


FIG. 16