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Method to bind packages of metallic mesh and apparatus which employs the method.

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Description

This invention concerns a method and an apparatus to bind packages of superimposed stacked metallic mesh. To be more exact, the invention concerns a method suitable for the automatic binding of packages of mesh by insertion of a straight measured segment of metallic wire into the package and by the bending and twisting of that wire thereafter.

The invention is applied downstream of plants which produce and stack metallic meshes of any type.

The invention can also be applied to the binding with metallic wire of other materials packaged in various forms, such as, for instance, wound bodies such as rolls, bundles, etc.

The state of the art covers many methods and devices for the automatic binding of materials by means of metallic elements such as thin tapes, wires, etc.

Such known methods and devices include production steps and forms of embodiment of various kinds but all of them can be derived essentially from one single working principle, according to which the binding element is arranged peripherally about the material to be bound and is tightened thereafter about that material, and the ends of the binding element are tied together.

The binding element is normally fed continuously to the position or positions where the various tying operations are carried out and arrives at that position or positions from an appropriate supply store.

Suitable shearing means shear the binding element when the latter is positioned around the material to be bound; thereafter a twisting device or another device suitable to, make a joint acts on the sheared ends.

The joint is made after the binding element has been suitably drawn and tightened around the body of the material to be bound.

The positioning of the binding element around the material to be bound takes place by means of and within guides which, at the moment when the binding element has to be tightened about the material to be bound and has to be tied together thereafter, enable the binding element to emerge quickly.

Thus these guides too have to be arranged about the material to be bound and therefore have considerable overall dimensions together with great constructional complexity owing to the functions which they have to perform.

Moreover, where the materials to be bound are such as packages of metallic meshes, to which we shall refer in the description that follows, further problems arise.

In fact the packages have to be tied by passing the binding element through the outer links of the meshes of the package and then outside the package for the binding to be carried out.

The system with the guides of the state of the art is badly adapted to this kind of operation and indeed cannot be used in many cases with its meshes of tight links and lateral projections.

Furthermore, the packages of mesh in the areas provided for the binding can travel substantially only at floor level and therefore any employment of the systems of the state of the art presupposes the making of foundation works below the floor level so as to make space for the passage of the guides.

Besides, the employment of the known devices with packages of mesh presupposes the technical necessity of tying together the ends of the binding element above or below the package but in any case at the point of insertion of the binding element into the links of the meshes.

This entails the presence of several segments of the binding element protruding above or below each package, thus forming a serious obstacle to the stacking of a plurality of packages of mesh, the stacking being required for more economical handling of the packages within or without the production units.

A partial attempt to overcome the problems of the state of the art provided embodiments whereby binding elements of a suitable length are pre-formed with a "U" shape and thereafter are inserted astride the links where the binding operation is to be carried out.

In these cases too the ties are made with the ends of the U-shaped elements protruding from the upper or lower face of the package, and this leads to the drawbacks described above.

The present applicant has studied, tested and brought about a method and an apparatus suitable to overcome all the problems of the state of the art.

The invention is set forth in the main claims, while the dependent claims describe various features of the invention.

The method according to the invention provides the vertical insertion of straight segments of a binding element, for instance metallic wire to which we shall refer in the description that follows, through the lateral links of the package within which the binding operation is to take place.

The binding wire is fed continuously in preset and predeterminable lengths which are substantially twice the height of the package plus the superimposed segments of wire used for the union of the package.

In fact, the binding wire passes freely through the circumscribed spaces of the meshes, from above downwards for instance, and then, as it emerges from the lower surface of the package, is suitably bent towards

the outside edge of the package so as to be able to ascend by a required value.

The feed of the wire is stopped when the length required for the binding has been reached, namely when the segment above the package on the side of the feed of the wire has such a length that with a successive downward bend it is superimposed on the segment of wire previously bent upwards from below.

The length of the segment bent upwards from below is preferably constant with packages of any height; to take that height into account and to keep unchanged the position at which the wire is tied, the length of the segment bent downward from above is altered accordingly.

The wire is then sheared and the upper segment of wire is bent outwards from the package and downwards.

By means of the method of the invention no guide of the type used for the wire in the state of the art is required.

The binding wire passes freely inside and outside the package of mesh, and the area of union of the wire is in a position outside the package and perfectly accessible for the means provided to make the twist.

When required and depending on special properties of the binding wire and on the height of the package, a partial guide for insertion of the wire may be provided at the upper surface of the package.

The package can be moved substantially at ground level and it is not necessary to carry out any foundation works for the means that insert the binding wire in the links of the mesh, as are required instead in the state of the art. Merely a simple means to bend and direct the wire is provided at ground level.

Moreover, the operation of drawing the wire to tighten it closely to the links is obviated, thereby entailing a further saving of specific equipment together with a reduction in the overall size of the machine owing to the smaller length of wire required for each binding operation.

Furthermore, the twist of the wire ends is always performed at the lateral sides of the package, thereby providing no obstacle if packages of mesh are to be stacked.

The binding can be carried out on packages of any type of mesh and can be performed on any position of the links.

The apparatus to carry out the method according to a preferred embodiment of the invention comprises a stationary support structure for a vertically movable unit able to position itself in correspondence with the package of mesh to be bound.

The movable unit in turn bears a vertically movable assembly which determines the length of the binding wire according to height of the package to be bound. This movable assembly comprises means to feed and shear the wire and means to perform the upper bending of the wire thus sheared.

A plurality of stationary support structures may be comprised together with their relative movable units, depending on the number of binding operations to be carried out at the same time on a single package to be bound.

According to a preferred embodiment the structure to support the movable unit can be traversed in relation to the package of mesh so that it can perform binding operations at different places.

According to another embodiment it is the movable unit which can be traversed horizontally in relation to the package of mesh so as to perform binding operations at different places.

The apparatus according to the invention comprises at least one tying unit positioned in correspondence with the lateral faces of the package; this tying unit twists the ends of the binding element.

A further part of the apparatus according to the invention is a lower assembly to bend the binding wire.

These and other special features of the invention will be made clearer by the description that follows.

The attached figures, which are given as a non-restrictive example, show the following:-

Fig.1 is a diagram of the main working assemblies of the apparatus to bind packages according to the invention;

Fig.2 shows a side view of a movable unit with a trolley and a movable head assembly of the apparatus shown in Fig.1;

Fig.3 is a view of Fig.2 from above;

Fig.4 is a front view of the movable head assembly;

Fig.5 is a side view of the head assembly of Fig.4;

Fig.6 is a side view of a bending assembly to bend the wire;

Fig.7 is a plan view of the bending assembly of Fig.6;

Fig.8 gives a side view of a detail of the bending assembly of Fig.6;

Fig.9 shows a lengthwise section of the detail of Fig. 8 along the line A-A;

Fig.10 is a side view of an assembly that ties the wire;

Fig.11 is a plan view of the tying assembly of Fig.10;

Fig.12 is a plan view of a gripper belonging to the tying assembly of Fig.10;

Fig.13 is a lengthwise section of the gripper of Fig.12 along the line B-B;

Fig.14 is a plan view of a twisting element belonging to the tying assembly of Fig.10;

Fig.15 is a lengthwise section of the twisting element of Fig.14 along the line C-C;

Fig.16 is a plan view of a guide assembly for the binding wire;

5 Fig.17 is a front view of the guide assembly of Fig.16.

The diagram of Fig.1 shows an apparatus 10 for binding packages of metallic mesh 11 according to the invention. In this example the package 11 is fed on a roller conveyor 12 in a direction orthogonal to the plane of Fig.1; the roller conveyor 12 can be positioned substantially at ground level 13.

10 Obviously, the position of the package 11 in relation to the ground 13 may be different, depending on the equipment located upstream of the apparatus 10 of the invention.

The apparatus 10 comprises a support structure 14 for a trolley 15, which can move vertically in relation to the structure 14 according to arrows 16.

The trolley 15 in turn supports a head assembly 17 which can move vertically according to the arrows 18 in relation to the trolley 15.

15 In this case the movable head assembly 17 is equipped with means 19 positioned orthogonally to each other and carrying out straightening of a binding wire element 20 arriving from a suitable supply according to the arrow 21.

The movable head assembly 17 is also equipped with feeding means 22 and shearing means 23.

20 Upper bending means 24 are solidly fixed to the movable trolley unit 15 and consist of a bending element 25 and an abutment pin 26, which is advantageously retractable.

An assembly 27 to unite the binding wire element 20 is included in a lateral position generally at the side of the package 11 and outside the same 11 in the area where the binding wire 20 is united.

This assembly 27 bears a twisting means 28 and a pair of clamping grippers 29 positioned immediately above and below the twisting means 28.

25 The grippers 29 and twisting means 28 can be moved momentarily in the directions of arrows 30 to cooperate with the wire 20 in the area where the wire 20 is tied together.

While the twisting means 28 is twisting the wire 20, the grippers 29 can be displaced in a direction according to arrows 31, while still engaging the wire 20, so as to compensate the shortening of the ends of the wire during the tying operation.

30 Guide means 31 are also located in the area of union of the wire 20 so as to guide the ends of the wire 20 previously bent and can be removed momentarily while the twisting means 28 is at work.

A lower bending means 32 analogous to the upper bending means 24 is positioned in correspondence with the lower surface of the package 11 at the point of emergence of the wire 20 from the links of the mesh.

35 A plurality of apparatuses 10 of the type described according to the invention may be included, depending on the numbers of ties to be made at the same time on each package 11.

The apparatuses 10 are normally positioned at the lateral sides of the package 11 and have to twist the wire 20 in correspondence with the outer lateral links of the meshes.

40 The apparatuses 10 located at one side of the package 11 are advantageously stationary transversely in relation to the direction of feed of the package 11, whereas the apparatuses 10 located at the opposite side of the package 11 can be made transversely movable so as to be adapted to the various widths of the packages 11 to be processed.

Adaptation of the height of the package 11 being processed is carried out by the trolley 15 and the head assembly 17, which determines the length of the segment of wire 20 to be sheared for the binding of the package 11.

45 According to a variant one or more apparatuses 10 can be traversed horizontally to make a plurality of ties of wire in succession at different areas.

The structure 14 alone together with means connected thereto may be capable of being traversed, whereas a plurality of wire twisting assemblies 27 and lower bending means 32 may be stationary positioned at points where the wire 20 is to be tied together.

50 According to a further embodiment the movable trolley 15 alone will be traversed in relation to the support structure 14 to make a plurality of ties of wire in succession at different areas.

The working steps performed by the apparatus 10 may follow the sequence described below after the processing parameters have been decided according to the height and width of the package 11:

- the halting of a package 11 arriving on the roller conveyor 12 by means of a link counter, for instance;
- the positioning of abutment pins 26 of the upper 24 and lower 32 bending means;
- the descent of the movable trolley 15 until it comes into contact with the upper surface of the package 11, and its halting in position by a suitable end-of-travel signalling means;
- the feed of the binding wire 20 according to arrow 21 and the stopping of the wire at a required length;
- the positioning of the guide means 31 in its working step;

- the making of the lower bend in the wire 20;
- the shearing and making of the upper bend in the wire 20;
- movement of the grippers 29 in the direction 30 and the clamping in position of the two ends of the binding wire 20 in the guide means 31;
- retraction of the abutment pins 26 and guide means 31;
- advance of the twisting means 28 according to direction 30 and accomplishment of the twist of the wire 20 with the displacement of the grippers 29 according to direction 75 at the same time;
- the opening of the grippers 29 to release the tensions induced in the wire 20 during the union thereof, and the return of the twisting means 28 to its inactive position;
- the return of the grippers 29 to their inactive position;
- the ascent of the movable trolley 15 and preparation for a new binding operation;
- removal of the bound package 11.

The above working steps are repeated automatically in each binding operation until action is taken to preset new processing conditions.

Figs.2 and 3 show a form of embodiment of the structure 14 which supports the movable unit 15, in this case a trolley, and the movable assembly 17, in this instance a head.

The trolley 15 can run vertically in the direction 16 on wheels 35 and is actuated by a threaded shaft 33 suitably driven by a motor 34.

A frame 36 is integrally fixed to the trolley 15 and bears the movable head assembly 17, which can run along the frame 36 on wheels 38 in guide tracks 37.

Figs.4 and 5 show the movable head assembly 17 in detail. It is possible to see in succession from the top downwards a first straightener assembly 119 to straighten wire 20, a second straightener assembly 219 orthogonal to the first 119, a feeding assembly 22 and a shearing assembly 23.

The feeding assembly 22 in this case consists of a pair of feed rolls 39 driven by their own drive unit, such as a gearmotor 40. To enable the wire 20 to be inserted, one of the feed rolls 39 can be displaced sideways by a lever system 41 actuated by a drive means 42 and kept in position by a clamping means 43.

Figs.6 and 7 show, in a scale enlarged as compared to the preceding figures, a 180° bending means which is adapted for being mounted to the movable trolley 15 or to the floor 13 or at different position, can be either the upper bending means 24 or lower bending means 32.

In this example the bending means is connected to the trolley 15 and is the upper bending means 24. It comprises a bending element 25, a movable arm for instance, which is actuated by a jack 45 so as to swing about a pivot 46. During its oscillation the arm 25 engages the wire 20 by means of its grooved roll 47 and takes the wire to be bent U-shaped around the abutment pin 26.

Figs.8 and 9 show an embodiment of the retractable abutment pin 26 which cooperates with the movable arm 25 in bending the wire 20. The pin 26 is solidly fixed to an articulated system 44 actuated by a jack 48 and, together with its relative actuators, can form part advantageously of the upper 24 and lower bending means 24-32.

Figs.10 and 11 show an assembly 27 to twist the wire, the assembly 27 comprising a pair of grippers 29 and a twisting means 28.

The pair of grippers 29 are integrally fixed to a slider 76 able to be moved on guides 77 by a jack 78; the slider 76 obtains the temporary displacement of the grippers 29 in the direction 30 during the twist of the wire 20.

Each gripper 29 can move freely in the direction 75 during the twisting step, as we said above, orthogonally to its own movement in the direction 30 so as to compensate the shortening of the wire 20. For this purpose each gripper 29 can run in relation to the other gripper 29 along a pair of guide shafts 79 by overcoming a resilient contrast force applied, for instance, by a spring 80.

The twisting means 28 is housed in a casing 56 able to be moved on guides 81 in the direction 30 by a jack 82.

Figs.12 and 13 show in a larger scale than Figs.10 and 11 a gripper 29 of the assembly 27 that unites the wire 20; the gripper 29 consists of a pair of double levers 49 and 50 respectively, both of which are pivoted on a pivot 51.

The levers 49 are also pivoted at 52 on a support 53 of the grippers 29 of the assembly 27 that twists the wire 20; whereas the levers 50 are pivoted at 54 by means of such as a jack 55.

Movement of the pivot 54 towards the right as shown in the lower half of Fig. 12 entails closure of the levers 49 on the two ends of the wire 20 positioned for the union of the wire.

The upper half of Fig.12 shows, instead, the position corresponding to the opening of the levers 49.

The support 53 of the gripper 29 is capable of traversing motion in the direction 30 so as to reach the tying area, the support 53 being integrally fixed to the slider 76.

A block 74 forms an abutment element for the united wire 20 during return of the twisting means 28 to its inactive position from the area of union of the wire.

5 Figs.14 and 15 show in a larger scale than Figs.10 and 11 the twisting means 28, which forms part of the assembly 27 twisting the wire 20 and consists of a casing 56 able to move in the direction 30 on guides 81 so as to reach the twisting area of the wire.

The twisting means 28 is actuated by its own actuator 58 and comprises an assembly of gearwheels 57-157-257-357 to drive a twisting roll 59, which, as in the state of the art, includes a radial notch 60 in which the ends of the wire 20 to be united are inserted.

10 Figs.16 and 17 show guide means 31 to hold the ends of the wire 20 in position in the tying area during the wire bending steps. These guide means 31 can be retracted temporarily or be rotated to leave their position free of the wire twisting means 28.

The grippers 29 are positioned momentarily above and below the guide means 31 before the twisting means 28 takes action.

15 The guide means 31 consists of a pair of sidewalls 61 formed with two parts, namely an inclined portion 62 to form a lead-in 63 for the wire 20 and a straight portion 64 with bent ends 65. The inclined portion 62 is integrally attached to a movable arm 66, to which the straight portion 64 is also attached but can rotate about a pivot 67. This rotation is made possible by a jack 68 which is also fixed to the movable arm 66.

20 The movable arm 66 consists of a base portion 71, an upright portion 70 and an upper wing 69 to which the sidewalls 61 are connected. By means of a pivot 72 the base portion 71 cooperates with a jack 73 able to rotate the arm 66 by a desired angle, for instance 90° in Fig.16 according to the position of the arm 66 shown with lines of dashes, so as to make possible the temporary access of the twisting means 28 to the area where the wire is united, namely the position normally occupied by the guide means 31 when inactive.

25 Claims

1. Method to bind packages of superimposed stacked metallic mesh, the binding operation being carried out by the insertion of binding elements into lateral links of the meshes and being completed by the reciprocal twisting of the ends of the binding elements, the method being characterized by the following steps:

- the positioning of the package of metallic mesh at a binding station,
- the insertion of straight segments of a predetermined length of a binding element (20) into preselected links of the package (11), such that the ends of said segments protude from the opposite bottom and top sides of the package,
- 35 - the bending of such ends of the binding elements (20) towards a lateral side of the package (11) and in opposite directions along said lateral side so as to provide an overlapping portion of the binding element ends (20) on said lateral side of the package,
- the guiding and clamping of the overlapping segment ends,
- 40 - the twisting of said overlapping segment ends,
- the unclamping of said overlapping segment ends so as to release the tension induced in the binding element during the twisting step, and
- removal of the package (11) thus bound,

45 these working steps being capable of being carried out at a plurality of binding locations of the package, at the same time or in succession, the length of the inserted segment of the binding element being selected in accordance to the height of the package to be bound.

2. Method as claimed in Claim 1, characterized in that the length of the binding element is substantially twice the height of the package plus the overlapping ends of said binding element.

50 3. Method as claimed in Claim 1 or 2, characterized in that the feed of the binding element is aligned with the open space circumscribed by the links of the meshes of the package into which the binding element is inserted.

55 4. Method as claimed in any claim hereinbefore, in which the binding element is sheared when the selected length has been reached.

5. Method as claimed in any claim hereinbefore, characterized in that one of the bent segments of the binding element (20) has a constant length irrespective of the height of the package (11).

6. Method as claimed in any claim hereinbefore, characterized in that the bent ends of the binding element (20) are guided in the area of the twisting station during the bending step.
- 5 7. Method as claimed in any claim hereinbefore, characterized in that the segments of the binding element (20) during the twisting step are kept clamped while compensating the shorting of the ends of the binding element during the twisting operation.
8. Method as claimed in any claim hereinbefore, characterized in that the package (11) can move substantially at floor level.
- 10 9. Method as claimed in any claim hereinbefore, characterized in that the twisting station is stationary positioned at the lateral sides of the package of the mesh (11).
- 15 10. Apparatus (10) to bind packages (11) of superimposed stacked metallic mesh apparatus comprising means (17) for inserting a predetermined length of a straight binding element (20) into the lateral links of the meshes and means for twisting (28) the ends of the binding elements (20), characterized by
 - a structure (14) to support a trolley unit (15) able to move in relation to the package (11),
 - an assembly (17) which, in a vertical direction, is movably mounted on and with respect to said movable trolley unit (15) and bearing means to straighten (19), feed (22) and shear (23) the binding element (20), into predetermined lengths,
 - 20 - means (24-32) to bend the ends of the binding element, protruding from the opposite top and bottom sides of the package,
 - guide means (31) to guide said bent ends along a lateral side of the package to provide an overlapping portion of said binding element (20), and
 - 25 - an assembly (27) including movable gripper means (29) and movable twisting means (28).
11. Apparatus (10) as claimed in Claim 10, characterized in that the support structure (14) is stationary.
12. Apparatus (10) as claimed in Claim 10, characterized in that the support structure (14) is movable.
- 30 13. Apparatus (10) as claimed in any of Claims 10 to 12 characterized in that the movable trolley (15) is traversable according to at least one cartesian axis.
14. Apparatus (10) as claimed in any of Claims 10 to 13 characterized in that the movable assembly (17) is traversable according to at least one cartesian axis.
- 35 15. Apparatus (10) as claimed in any of Claims 10 to 14 characterized in that the bending means (24-32) consist of oscillatory levers (25) and abutment pins (26).
- 40 16. Apparatus (10) as claimed in any of Claims 10 to 15 characterized in that the abutment pins (26) are retractable.
17. Apparatus (10) as claimed in any of Claims 10 to 16 characterized in that the upper bending means (24-32) is connected to the movable trolley unit (15).
- 45 18. Apparatus (10) as claimed in any of Claims 10 to 17 characterized in that the lower bending means (32) is located at floor level (13).
19. Apparatus (10) as claimed in any of Claims 10 to 18 characterized in that the guide means (31) consist of retractable sidewalls (61).
- 50 20. Apparatus (10) as claimed in any of Claims 10 to 19 characterized in that the movable gripper means consists of an upper and lower pair of grippers (29) able to be positioned on planes above and below, respectively, the guide means (31).
- 55 21. Apparatus (10) as claimed in any of Claims 10 to 20 characterized in that the movable twisting means (28) consists of a cascade of gearwheels (57-157-257-357) which actuate a twisting roll (59).
22. Apparatus (10) as claimed in any of Claims 10 to 21 characterized in that the movable twisting means (28) are positioned in the assembly (27) that twists the ends of the binding element (20) at an intermediate

position between the pair of grippers (29).

23. Apparatus (10) as claimed in any of Claims 10 to 22 characterized in that each pair of grippers (29) comprises a block (74) to abut against the end of the binding element (20).
24. Apparatus (10) as claimed in any of Claims 10 to 23 characterized in that the pair of grippers (29) are solidly fixed to a slider (76) which is movable mounted in guides (77).
25. Apparatus (10) as claimed in any of Claims 10 to 24 characterized in that guide element (79) with return springs (80) are interposed between the pair of grippers (29).
26. Apparatus (10) as claimed in any of Claims 10 to 25 characterized in that the cascade of gearwheels (57-157-257-357) is housed in a casing (56), which can move on guides (81) and is equipped with its own actuation means (58).

Patentansprüche

1. Verfahren zum Binden von Packungen übereinandergelegter, gestapelter Metallgitter, wobei der Bindevorgang durch Einführen von Bindeelementen in seitliche Maschen der Gitter durchgeführt und durch gegenseitiges Verdrillen der Enden der Bindeelemente vollendet wird, und das Verfahren durch die folgenden Schritte gekennzeichnet ist:
 - Anordnen der Packung aus Metallgittern an einer Bindestation,
 - Einführen gerader Abschnitte vorbestimmter Länge eines Bindeelementes (20) in vorgewählte Maschen der Packung (11) so, daß die Enden der Abschnitte von den einander gegenüberliegenden Unter- bzw. Oberseiten der Packung vorstehen,
 - Umbiegen der Enden der Bindeelemente (20) in Richtung einer Seite der Packung (11) und längs dieser Seite in entgegengesetzte Richtungen, um so einen überlappenden Abschnitt der Enden der Bindeelemente (20) an der Seite der Packung zu schaffen,
 - Führen und Erfassen dieser einander überlappenden Endabschnitte,
 - Verdrillen der einander überlappenden Endabschnitte,
 - Loslassen der einander überlappenden Endabschnitte, um die in das Bindeelement während des Verdrillungsschrittes eingebrachte Spannung freizugeben, und
 - Entfernen der solchermaßen gebundenen Packung (11)wobei diese Arbeitsschritte an einer Mehrzahl von Bindestellen der Packung gleichzeitig oder hintereinander durchführbar sind und die Länge des eingeführten Abschnittes des Bindeelementes entsprechend der Höhe des zu bindenden Paketes gewählt wird.
2. Verfahren nach Anspruch 1, dadurch gekennzeichnet, daß die Länge des Bindeelementes im wesentlichen der doppelten Höhe der Packung, vermehrt um die einander überlappenden Enden des Bindeelementes entspricht.
3. Verfahren nach Anspruch 1 oder 2, dadurch gekennzeichnet, daß das Zuführen des Bindeelementes mit dem offenen Raum ausgerichtet ist, der von den Maschen der Siebe der Packung, in welche das Bindeelement eingeführt wird, umschrieben ist.
4. Verfahren nach einem der vorgehenden Ansprüche, bei welchem das Bindeelement abgeschnitten wird, sobald die gewählte Länge erreicht wurde.
5. Verfahren nach einem der vorgehenden Ansprüche, dadurch gekennzeichnet, daß einer der umgebogenen Abschnitte des Bindeelementes (20) unabhängig von der Höhe der Packung (11) eine konstante Länge aufweist.
6. Verfahren nach einem der vorgehenden Ansprüche, dadurch gekennzeichnet, daß die umgebogenen Enden des Bindeelementes (20) während des Biegeschrittes im Bereich der Verdrillungsstation geführt sind.
7. Verfahren nach einem der vorgehenden Ansprüche, dadurch gekennzeichnet, daß die Abschnitte des Bindeelementes (20) während des Verdrillungsschrittes festgehalten werden, wobei die Verkürzung der Enden während des Verdrillungsvorganges kompensiert werden.

8. Verfahren nach einem der vorgehenden Ansprüche, dadurch gekennzeichnet, daß die Packung (11) sich im wesentlichen auf Bodenniveau bewegen kann.
- 5 9. Verfahren nach einem der vorgehenden Ansprüche, dadurch gekennzeichnet, daß die Verdrillungsstation an den Seiten der Packung (11) der Gitter stationär angeordnet ist.
- 10 10. Vorrichtung (10) zum Binden von Packungen (11) übereinandergelegter, gestapelter Metallgitter, wobei die Vorrichtung Mittel (17) zum Einführen einer vorsbestimmten Länge eines geraden Bindeelementes (20) in die seitlichen Maschen der Gitter und Mittel zum Verdrillen (28) der Enden der Bindeelemente (20) aufweist und gekennzeichnet ist durch:
 - ein Abstützgestell (14) einer Wageneinheit (15), die sich bezüglich der Packung (11) bewegen kann,
 - einen Aufbau (17), der auf der Wageneinheit (15) bezüglich derselben in vertikaler Richtung beweglich montiert ist, und Tragemittel zum Ausrichten (19), Zuführen (22) und Abschneiden (23) des Bindeelementes (20) in vorbestimmte Längen,
 - 15 - Mittel (24-32) zum Biegen der Enden der Bindeelemente, die von den gegenüberliegenden Ober- bzw. Unterseiten der Packung vorstehen, und
 - eine Einheit (27) mit bewegbaren Greifermitteln (29) und bewegbaren Verdrillmitteln (28).
- 20 11. Vorrichtung (10) nach Anspruch 10, dadurch gekennzeichnet, daß das Abstützgestell (14) stationär ist.
12. Vorrichtung (10) nach Anspruch 10, dadurch gekennzeichnet, daß das Abstützgestell (14) bewegbar ist.
13. Vorrichtung (10) nach einem der Ansprüche 10 bis 12, dadurch gekennzeichnet, daß der bewegbare Wagen (15) bezüglich zumindest einer kartesischen Achse verfahrbar ist.
- 25 14. Vorrichtung (10) nach einem der Ansprüche 10 bis 13, dadurch gekennzeichnet, daß der bewegbare Aufbau (17) bezüglich zumindest einer kartesischen Achse verfahrbar ist.
15. Vorrichtung (10) nach einem der Ansprüche 10 bis 14, dadurch gekennzeichnet, daß die Mittel zum Biegen (24-32) aus Schwinghebeln (25) und Anschlagzapfen (26) bestehen.
- 30 16. Vorrichtung (10) nach einem der Ansprüche 10 bis 15, dadurch gekennzeichnet, daß die Anschlagzapfen (26) zurückziehbar sind.
- 35 17. Vorrichtung (10) nach einem der Ansprüche 10 bis 16, dadurch gekennzeichnet, daß das obere Biegemittel (24-32) an die bewegbare Wageneinheit (15) angeschlossen ist.
18. Vorrichtung (10) nach einem der Ansprüche 10 bis 17, dadurch gekennzeichnet, daß das untere Biegemittel (32) auf Bodenniveau (13) angeordnet ist.
- 40 19. Vorrichtung (10) nach einem der Ansprüche 10 bis 18, dadurch gekennzeichnet, daß das Führungsmittel (31) aus zurückziehbaren Seitenwänden (61) besteht.
20. Vorrichtung (10) nach einem der Ansprüche 10 bis 19, dadurch gekennzeichnet, daß das bewegbare Greifermittel aus einem oberen und einem unteren Paar von Greifern (29) besteht, welche auf Ebenen oberhalb bzw. unterhalb des Führungsmittels (31) positioniert werden können.
- 45 21. Vorrichtung (10) nach einem der Ansprüche 10 bis 20, dadurch gekennzeichnet, daß das bewegbare Verdrillmittel (28) aus einer Folge von Zahnrädern (57-157-257-357) besteht, welche eine Verdrillrolle (59) antreiben.
- 50 22. Vorrichtung (10) nach einem der Ansprüche 10 bis 21, dadurch gekennzeichnet, daß das bewegbare Verdrillmittel (28) in der Einheit (27) angeordnet ist, welche die Enden des Bindeelementes (20) an einer Zwischenposition zwischen dem Greiferpaar (29) verdrillt.
- 55 23. Vorrichtung (10) nach einem der Ansprüche 10 bis 22, dadurch gekennzeichnet, daß jedes Greiferpaar (29) einen gegen das Ende des Bindeelementes (20) stoßenden Block (74) besitzt.
24. Vorrichtung (10) nach einem der Ansprüche 10 bis 23, dadurch gekennzeichnet, daß das Greiferpaar (29) fest an einem Gleitstück (76) befestigt ist, welches in Führungen (77) beweglich montiert ist.

25. Vorrichtung (10) nach einem der Ansprüche 10 bis 24, dadurch gekennzeichnet, daß zwischen dem Greifpaar (29) Führungselemente (79) mit Rückstellfedern (80) angeordnet sind.

5 26. Vorrichtung (10) nach einem der Ansprüche 10 bis 25, dadurch gekennzeichnet, daß die Folge von Zahnrädern (57-157-257-357) in einem Gehäuse (56) untergebracht ist, welches sich auf Führungen (81) bewegen kann und mit einem eigenen Antriebsmittel (58) ausgestattet ist.

10 Revendications

1. Procédé pour lier des paquets de treillis métalliques empilés en superposition, l'opération de liaison étant effectuée par l'insertion d'éléments de liaison dans les raccords latéraux des treillis et étant réalisée par le torsadage réciproque des extrémités des éléments de liaison, le procédé étant caractérisé par les étapes ci-dessous:

- positionnement du paquet de treillis métallique dans un poste de liaison,
- insertion de segments rectilignes d'une longueur prédéterminée d'un élément de liaison (20) dans des mailles présélectionnées du paquet (11), de sorte que les extrémités desdits segments débordent des côtés opposés de base et de sommet du paquet,
- pliage de ces extrémités des éléments de liaison (20) en direction d'un côté latéral du paquet (11) et dans des directions opposées le long dudit côté latéral, de manière à réaliser une partie en superposition des extrémités de l'élément de liaison (20) sur ledit côté latéral du paquet,
- guidage et serrage des extrémités superposées du segment,
- torsadage desdites extrémités superposées du segment,
- desserrage desdites extrémités superposées du segment de manière à relâcher la tension induite dans l'élément de liaison au cours de l'étape de torsadage, et
- enlèvement du paquet (11) ainsi lié,

ces étapes de travail étant susceptibles d'être effectuées simultanément ou successivement en plusieurs emplacements de liaison du paquet, la longueur du segment inséré de l'élément de liaison étant sélectionnée en fonction de la hauteur du paquet à lier.

2. Procédé selon la revendication 1, caractérisé en ce que la longueur de l'élément de liaison vaut essentiellement le double de la hauteur du paquet, plus les extrémités superposées dudit élément de liaison.

3. Procédé selon la revendication 1 ou 2, caractérisé en ce que l'alimentation en l'élément de liaison est alignée sur l'espace ouvert circonscrit des mailles des treillis du paquet dans lequel l'élément de liaison est inséré.

4. Procédé selon l'une quelconque des revendications ci-dessus, dans lequel l'élément de liaison est cisailé lorsque la longueur sélectionnée a été atteinte.

5. Procédé selon l'une quelconque des revendications ci-dessus, caractérisé en ce qu'un des segments repliés de l'élément de liaison (20) possède une longueur constante, quelle que soit la hauteur du paquet (11).

6. Procédé selon l'une quelconque des revendications ci-dessus, caractérisé en ce que les extrémités repliées de l'élément de liaison (20) sont guidées dans la zone du poste de torsadage au cours de l'opération de pliage.

7. Procédé selon l'une quelconque des revendications ci-dessus, caractérisé en ce que les segments de l'élément de liaison (20) sont maintenus serrés pendant l'étape de torsadage, tout en compensant le raccourcissement des extrémités de l'élément de liaison pendant l'opération de torsadage.

8. Procédé selon l'une quelconque des revendications ci-dessus, caractérisé en ce que le paquet (11) peut se déplacer essentiellement au niveau du sol.

9. Procédé selon l'une quelconque des revendications ci-dessus, caractérisé en ce que le poste de torsadage est maintenu stationnaire sur les côtés latéraux du paquet de treillis (11).

10. Equipement (10) pour lier des paquets (11) de treillis métalliques empilés en superposition, l'équipement

comprenant des moyens (17) pour insérer une longueur prédéterminée d'un élément rectiligne de liaison (20) dans les mailles latérales des treillis, et des moyens (28) pour torsader les extrémités des éléments de liaison (20), caractérisé par:

- 5 - une structure (14) pour soutenir une unité de chariot (15) capable de se déplacer par rapport au paquet (11) qui est monté à déplacement dans une direction verticale et par rapport à ladite unité mobile de chariot (15), et des moyens de support en vue de redresser (19), alimenter (22) et cisailer (23) l'élément de liaison (20) dans des longueurs prédéterminées,
- 10 - des moyens (24, 32) pour plier les extrémités de l'élément de liaison qui débordent des côtés opposés du sommet et du fond du paquet,
- des moyens de guidage (31), pour guider lesdites extrémités repliées le long d'un côté latéral du paquet, pour fournir une partie superposée dudit élément de liaison (20), et
- un mécanisme (27) comprenant des moyens mobiles d'accrochage (29) et des moyens mobiles de torsadage (28).
- 15 11. Equipement (10) selon la revendication 10, caractérisé en ce que la structure de soutien (14) est stationnaire.
- 12. Equipement (10) selon la revendication 10, caractérisé en ce que la structure de soutien (14) est mobile.
- 20 13. Equipement (10) selon l'une quelconque des revendications 10 à 12, caractérisé en ce que le chariot mobile (15) peut être déplacé transversalement suivant au moins un axe cartésien.
- 14. Equipement (10) selon l'une quelconque des revendications 10 à 13, caractérisé en ce que le mécanisme mobile (17) peut être déplacé transversalement suivant au moins un axe cartésien.
- 25 15. Equipement (10) selon l'une quelconque des revendications 10 à 14, caractérisé en ce que les moyens de pliage (24, 32) sont constitués de leviers oscillants (25) et de goujons de butée (26).
- 30 16. Equipement (10) selon l'une quelconque des revendications 10 à 15, caractérisé en ce que les goujons de butée (26) sont rétractables.
- 17. Equipement (10) selon l'une quelconque des revendications 10 à 16, caractérisé en ce que les moyens de pliage supérieurs (24) sont reliés à l'unité mobile de chariot (15).
- 35 18. Equipement (10) selon l'une quelconque des revendications 10 à 17, caractérisé en ce que les moyens de pliage inférieurs (32) sont situés au niveau du sol (13).
- 19. Equipement (10) selon l'une quelconque des revendications 10 à 18, caractérisé en ce que les moyens de guidage (31) sont constitués de parois latérales rétractables (61).
- 40 20. Equipement (10) selon l'une quelconque des revendications 10 à 19, caractérisé en ce que les moyens mobiles d'accrochage sont constitués d'une paire supérieure et d'une paire inférieure de dispositifs d'accrochage (29) susceptibles d'être positionnés sur des plans situés respectivement au-dessus et en dessous des moyens de guidage (31).
- 45 21. Equipement (10) selon l'une quelconque des revendications 10 à 20, caractérisé en ce que les moyens mobiles de torsadage (28) sont constitués d'une cascade de roues dentées (57, 157, 257, 357) qui actionnent un rouleau de torsadage (59).
- 50 22. Equipement (10) selon l'une quelconque des revendications 10 à 21, caractérisé en ce que les moyens mobiles de torsadage (28) sont positionnés dans le mécanisme (27) qui torsade de l'élément de liaison (20) en une position intermédiaire entre les éléments de la paire de dispositifs d'accrochage (29).
- 23. Equipement (10) selon l'une quelconque des revendications 10 à 22, caractérisé en ce que chaque paire de dispositifs d'accrochage (29) comprend un bloc (74) pour venir buter contre l'extrémité de l'élément de liaison (20).
- 55 24. Equipement (10) selon l'une quelconque des revendications 10 à 23, caractérisé en ce que la paire de dispositifs d'accrochage (29) est solidaire d'un traîneau (76) qui est monté à déplacement dans des guides (77).

25. Equipement (10) selon l'une quelconque des revendications 10 à 24, caractérisé en ce que des éléments de guidage (79) avec ressorts de renvoi (80) sont interposés entre les éléments de la paire de dispositif d'accrochage (29).

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26. Equipement (10) selon l'une quelconque des revendications 10 à 25, caractérisé en ce que la cascade de roues dentées (57, 157, 257, 357) est logée dans un boîtier (56) qui peut se déplacer sur des guides (81) et est équipé de ses propres moyens d'actionnement (58).

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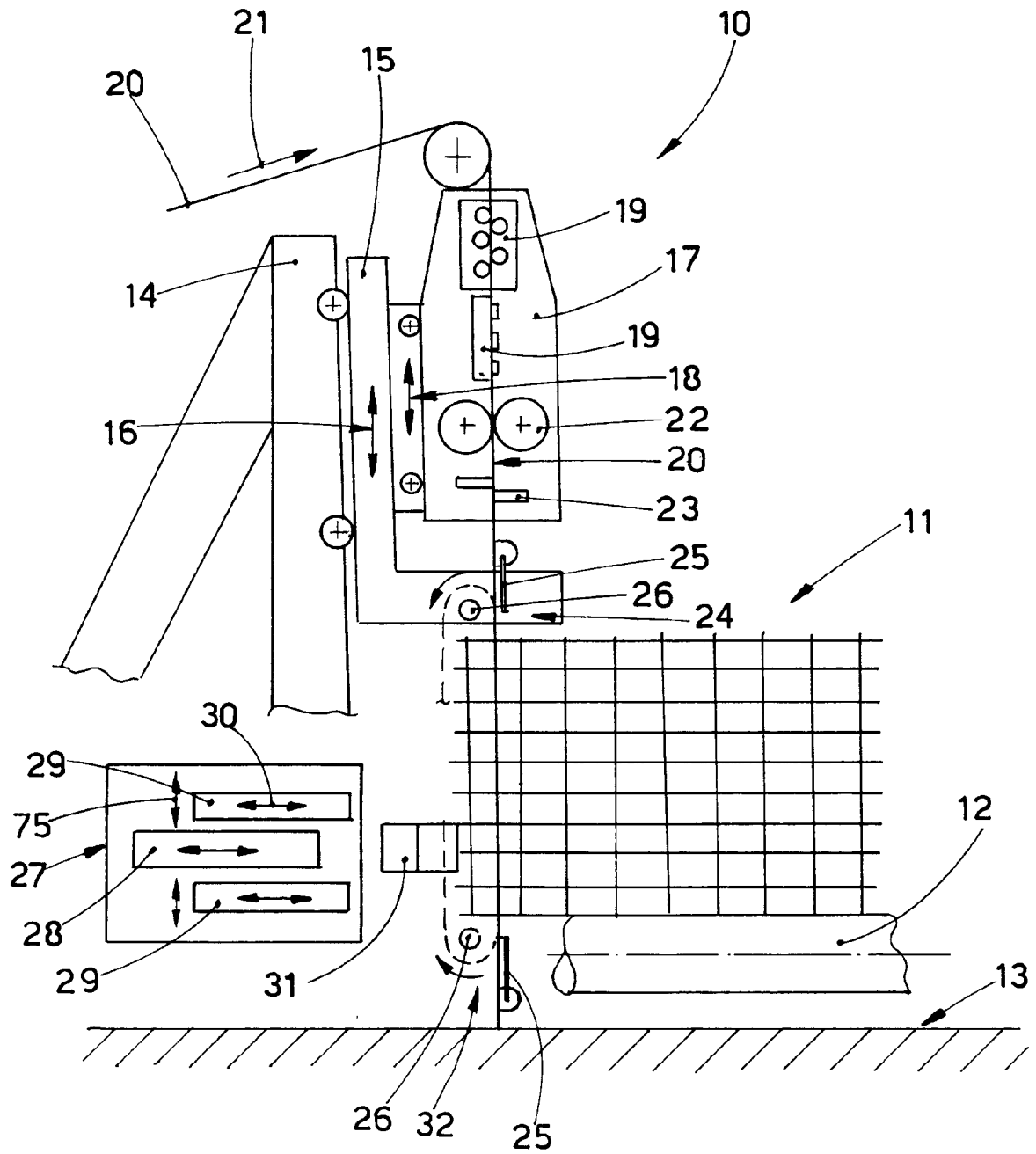


fig. 1

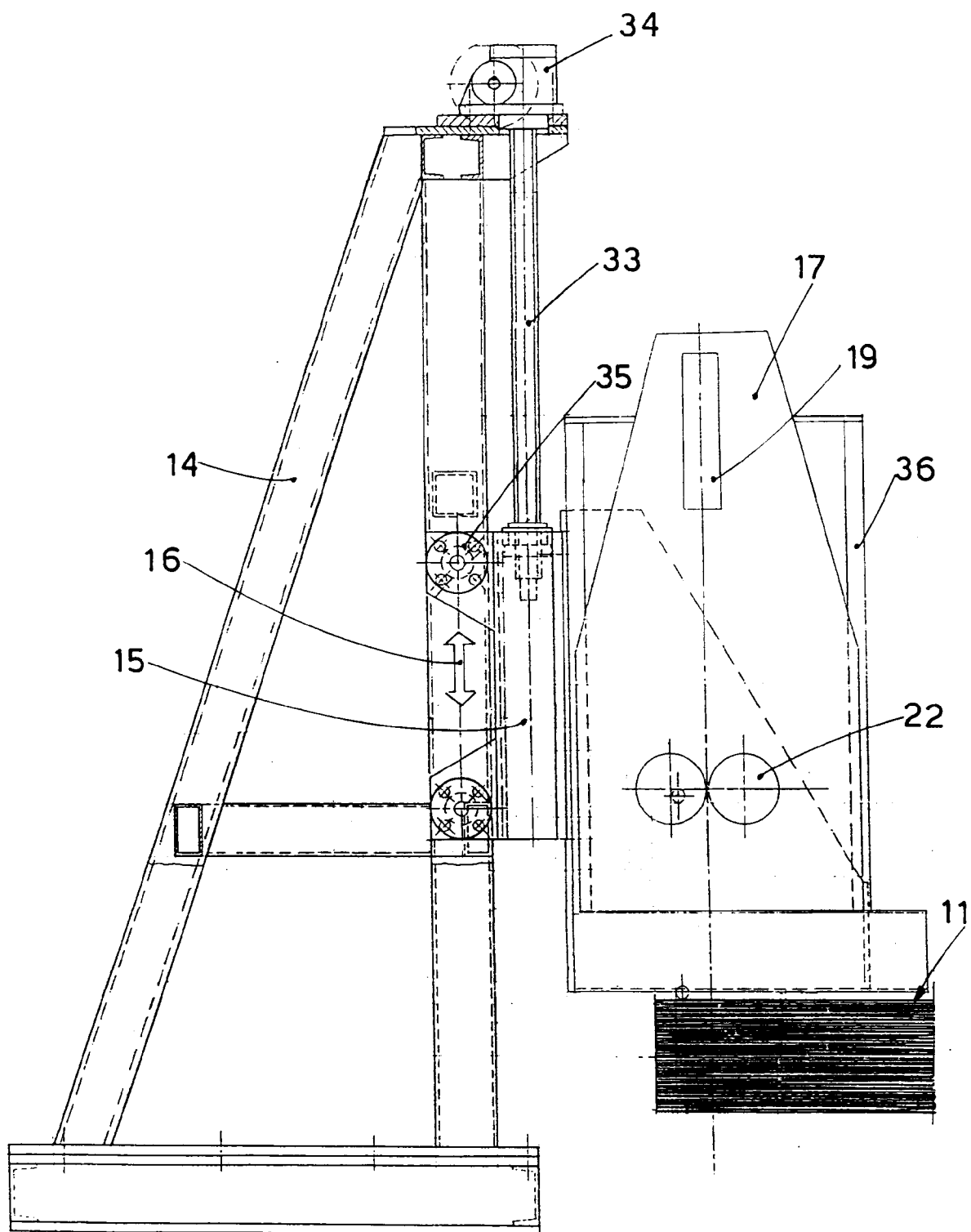


fig. 2

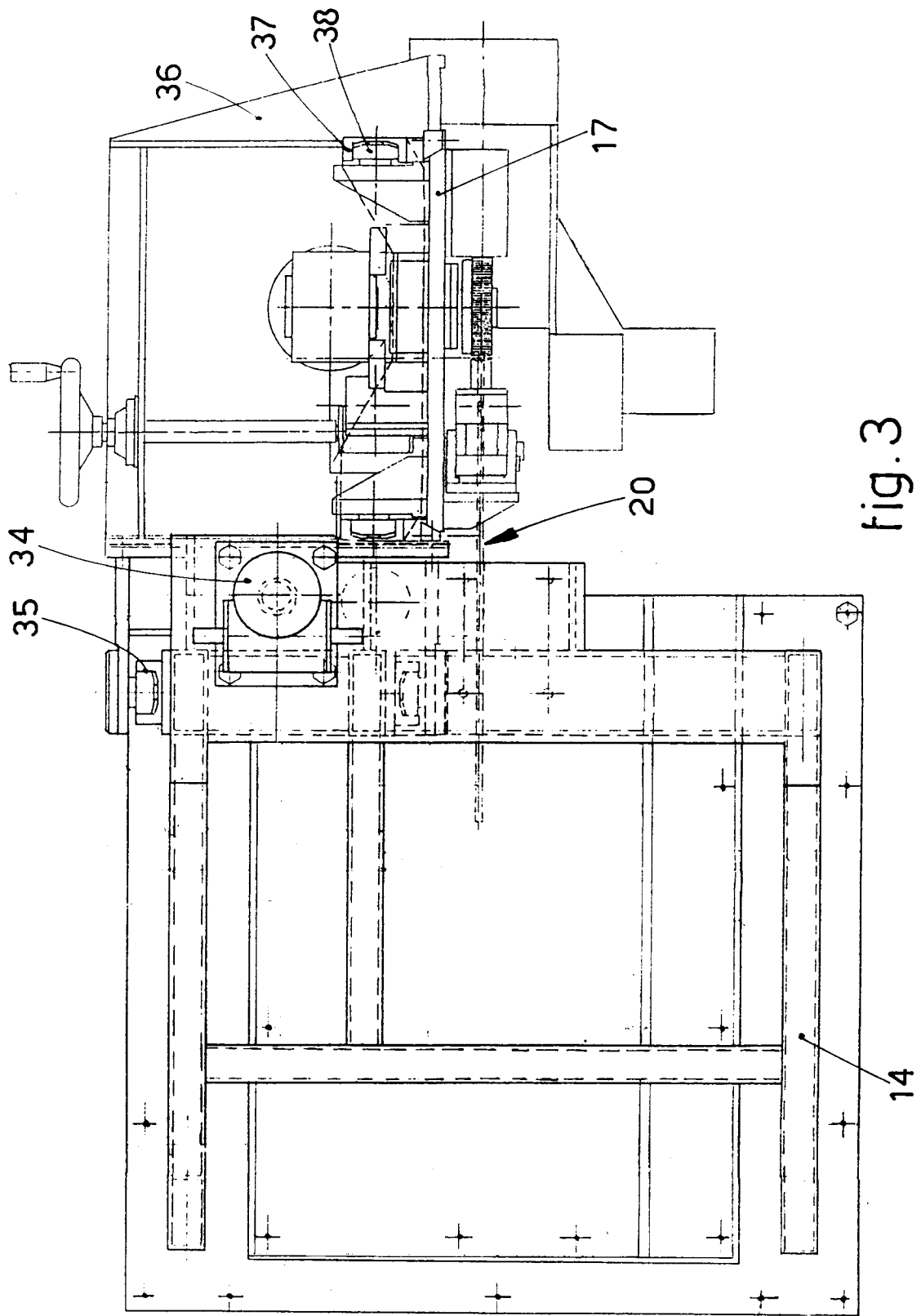


fig. 3

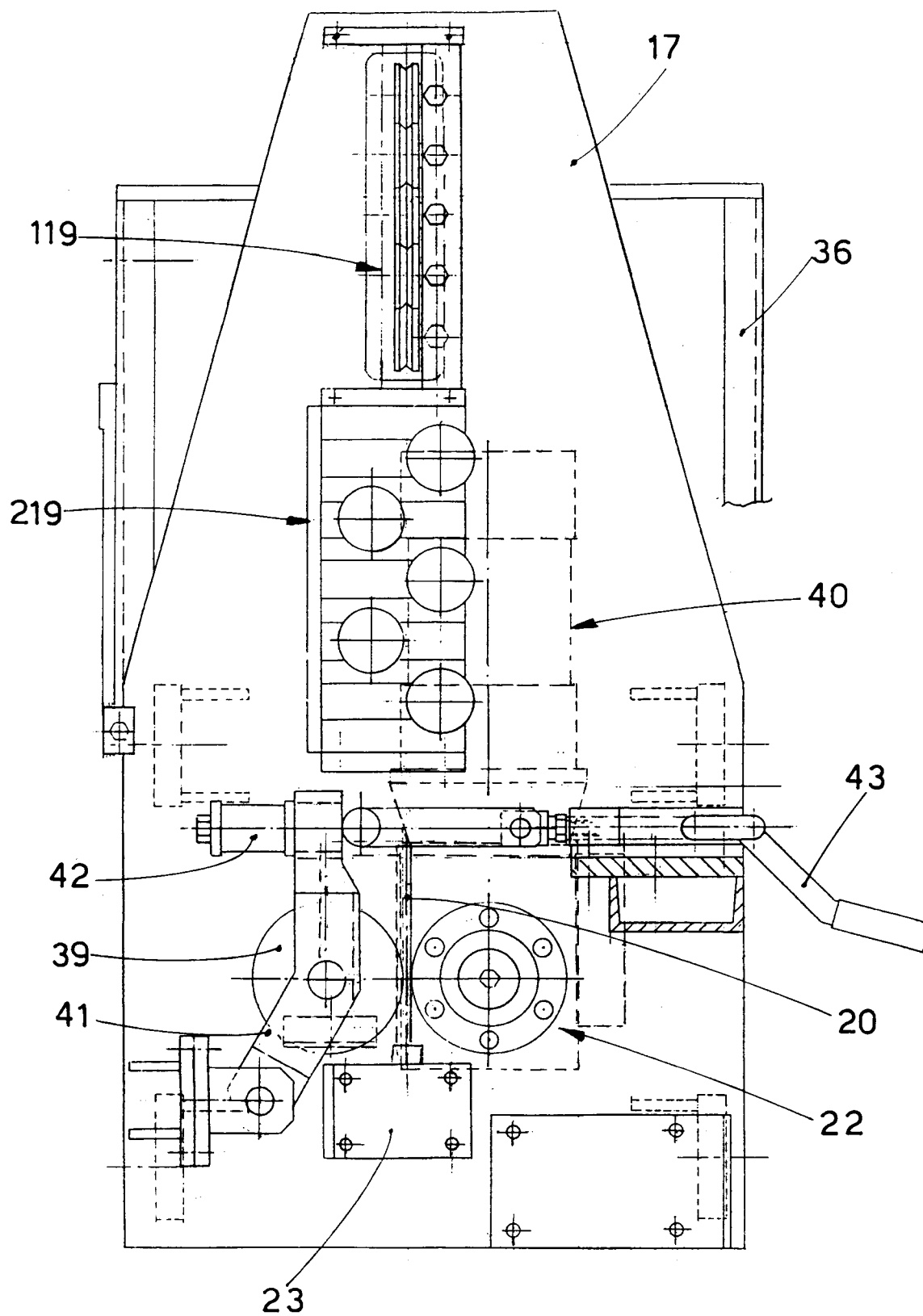


fig.4

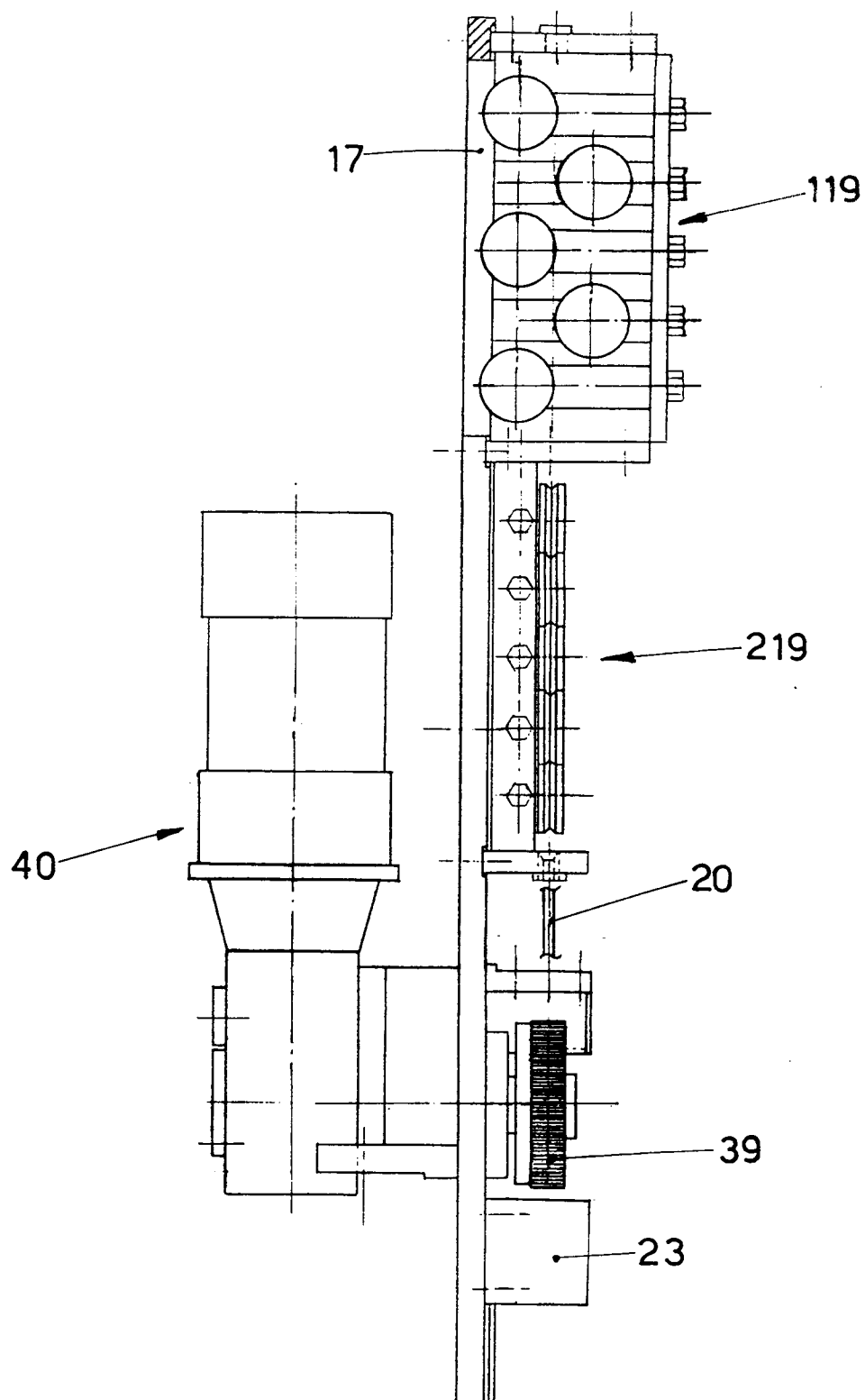
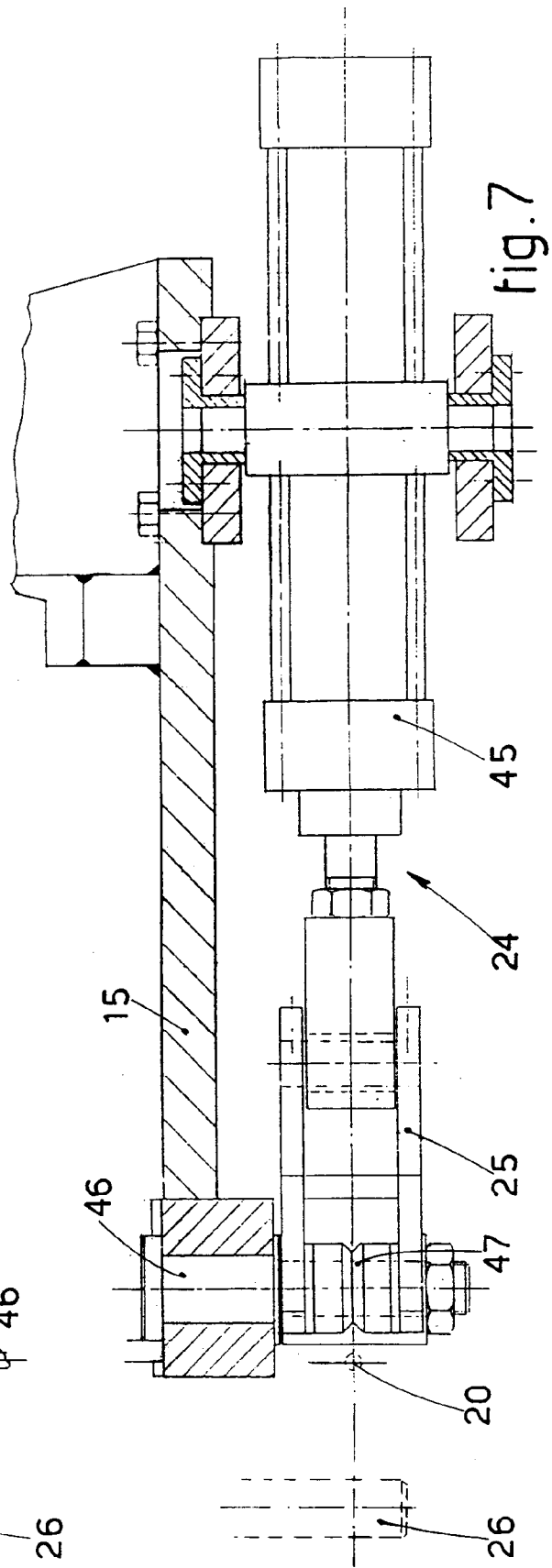
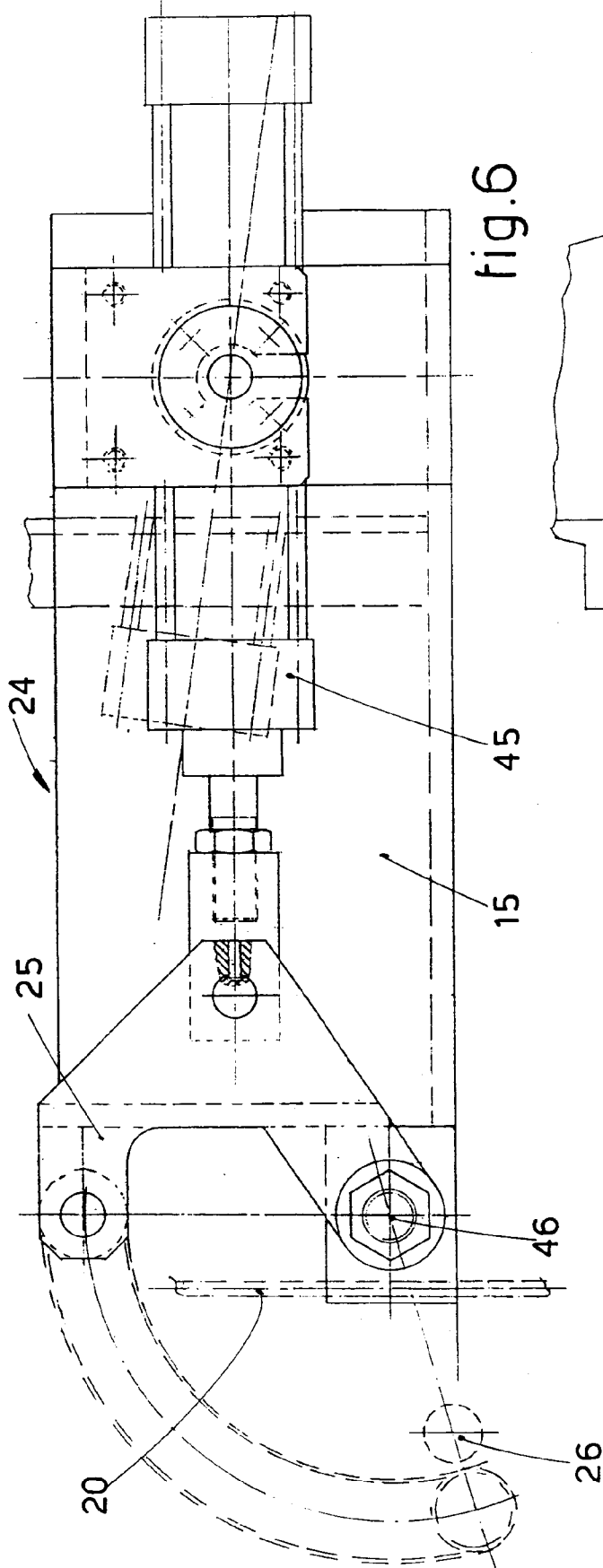


fig. 5



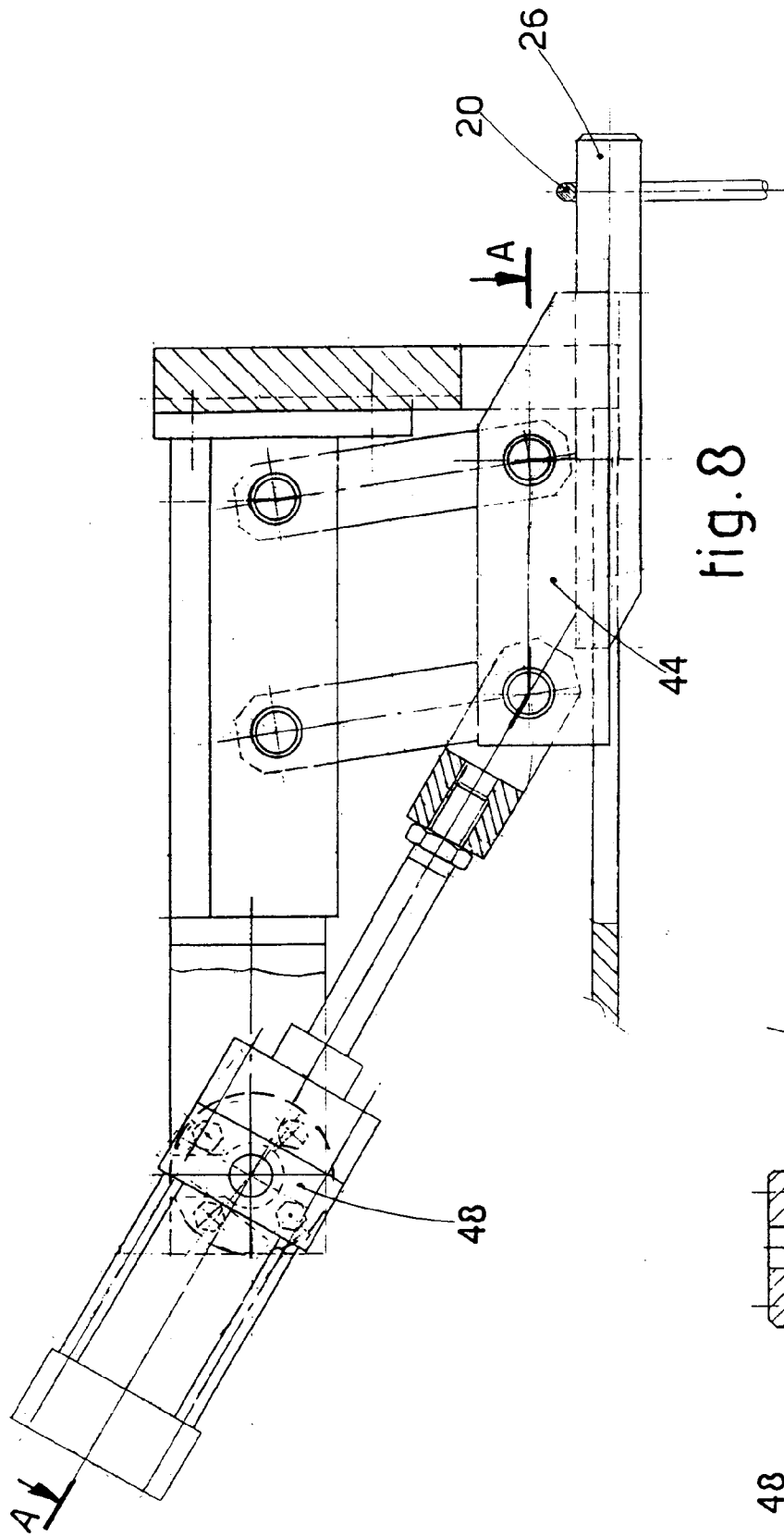


fig. 8

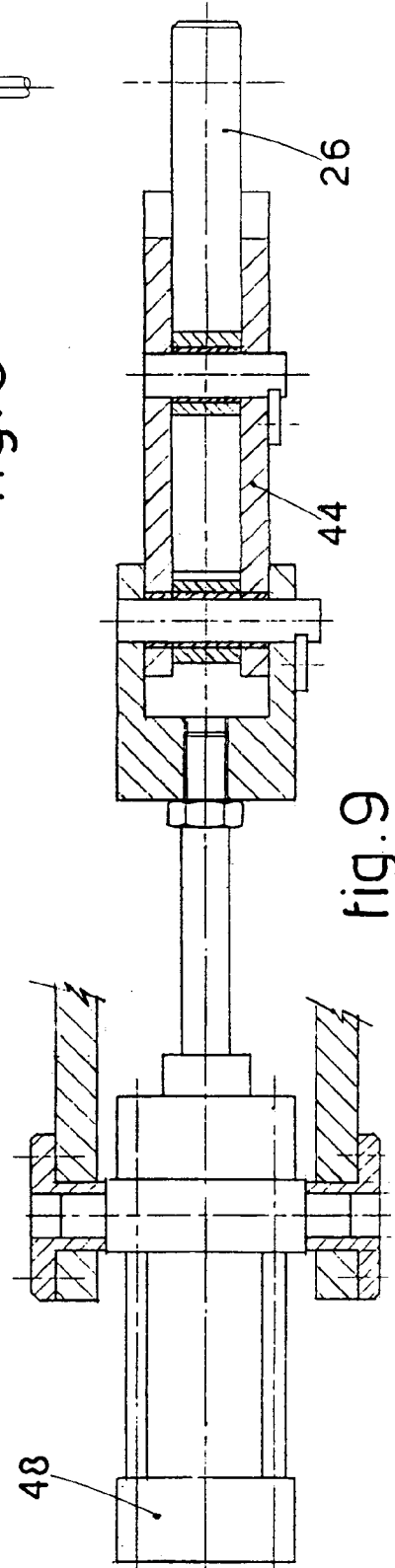
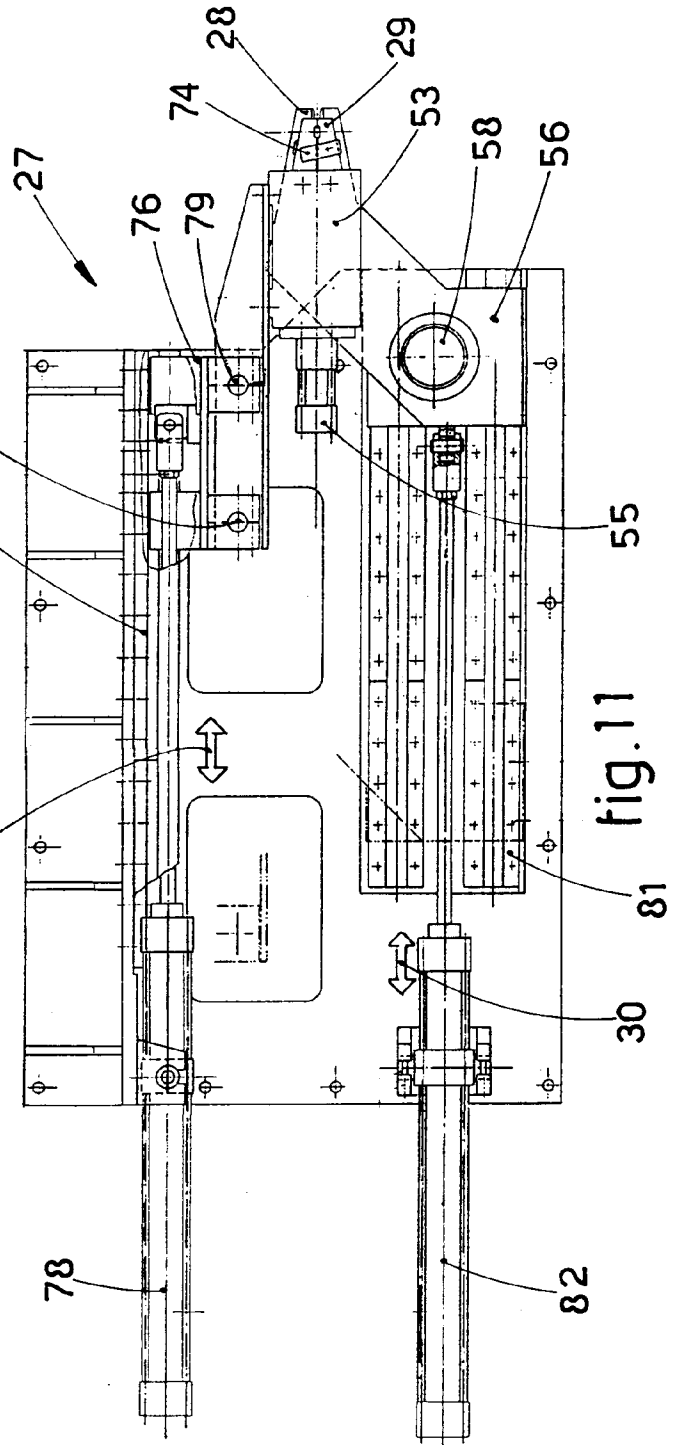
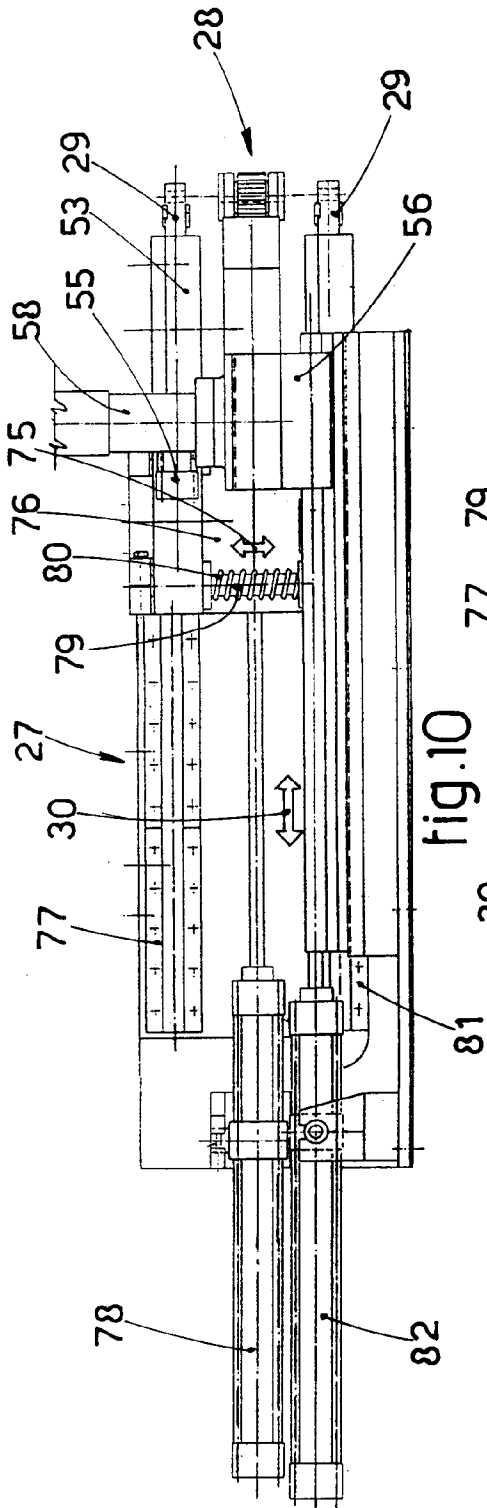


fig. 9



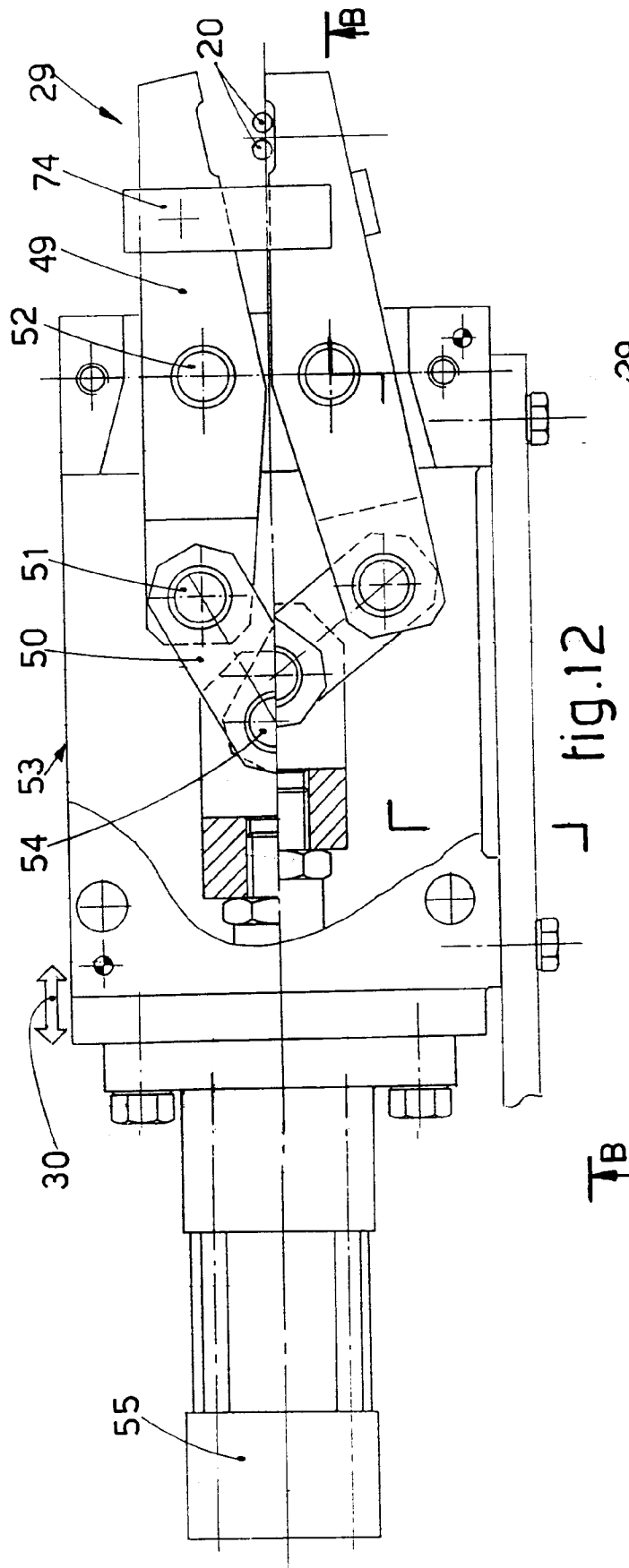


fig.12

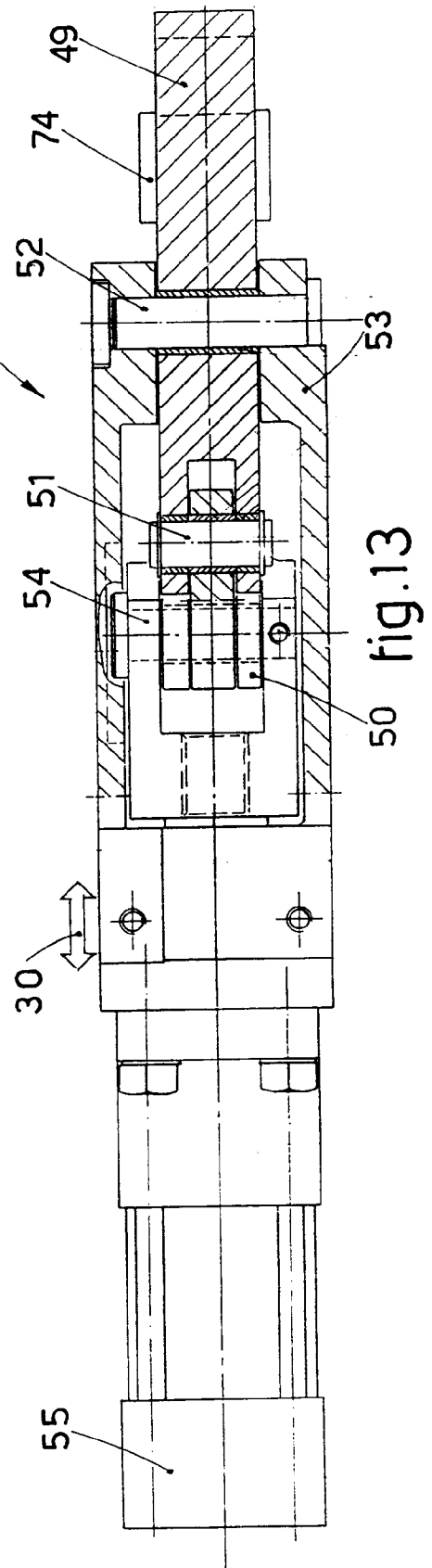


fig.13

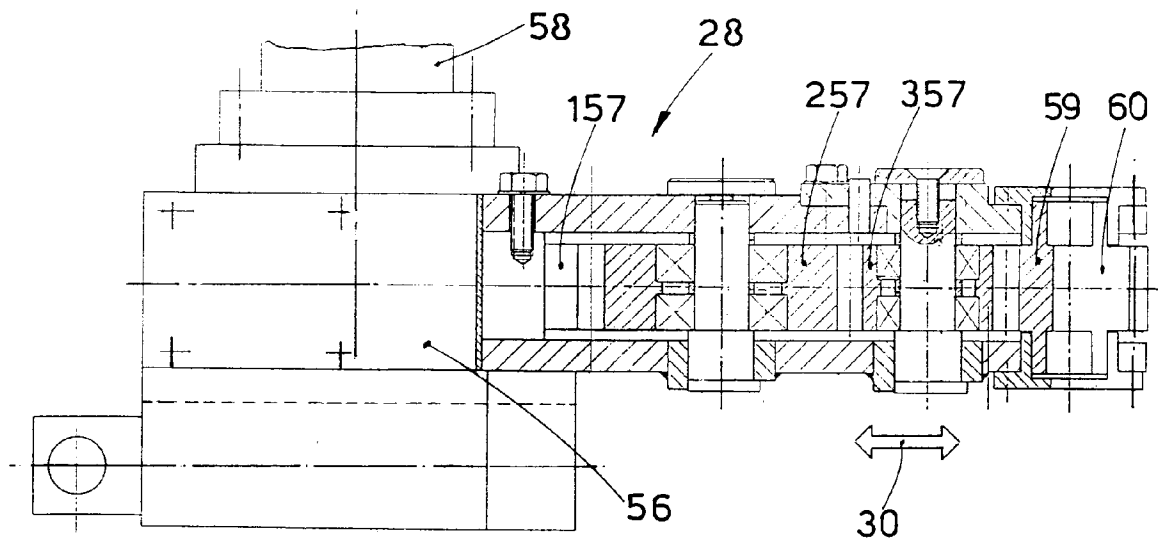


fig.15

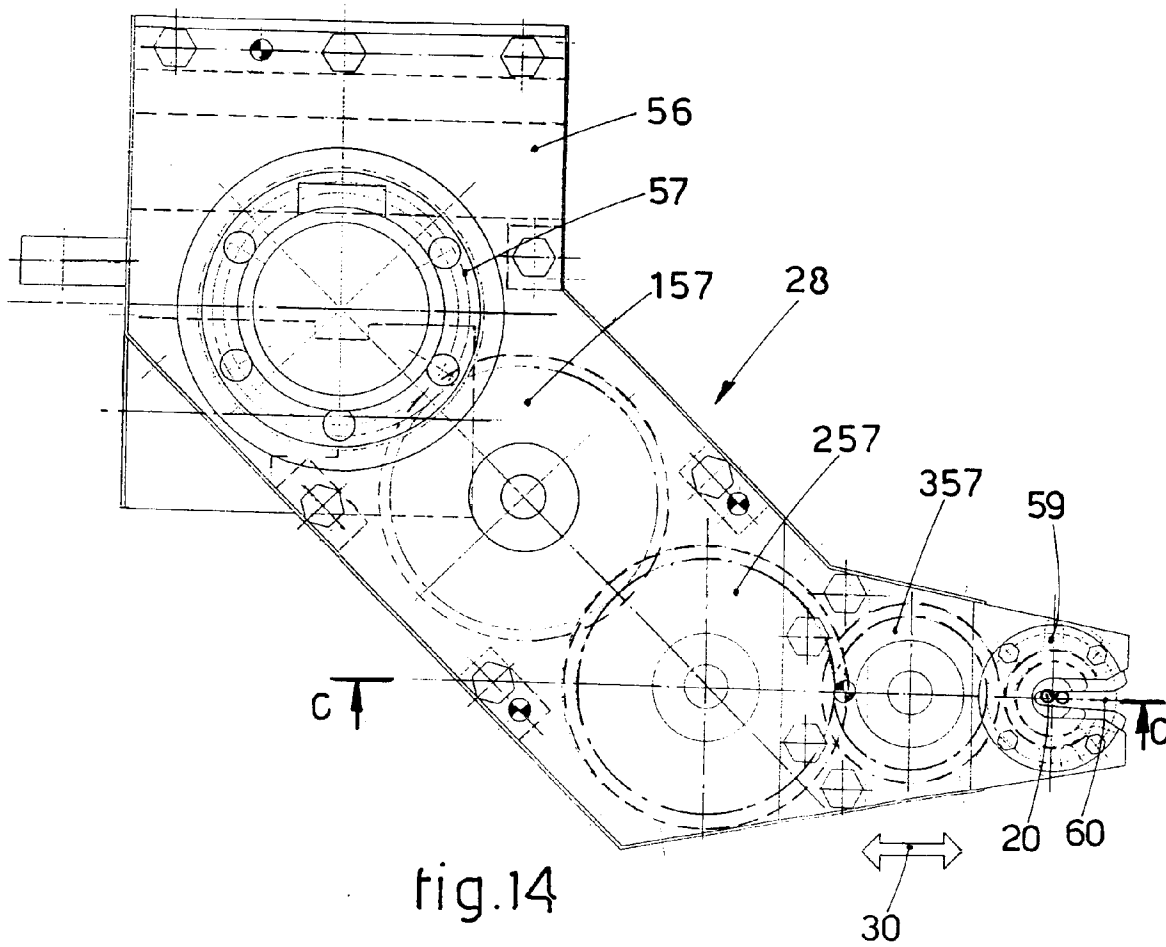
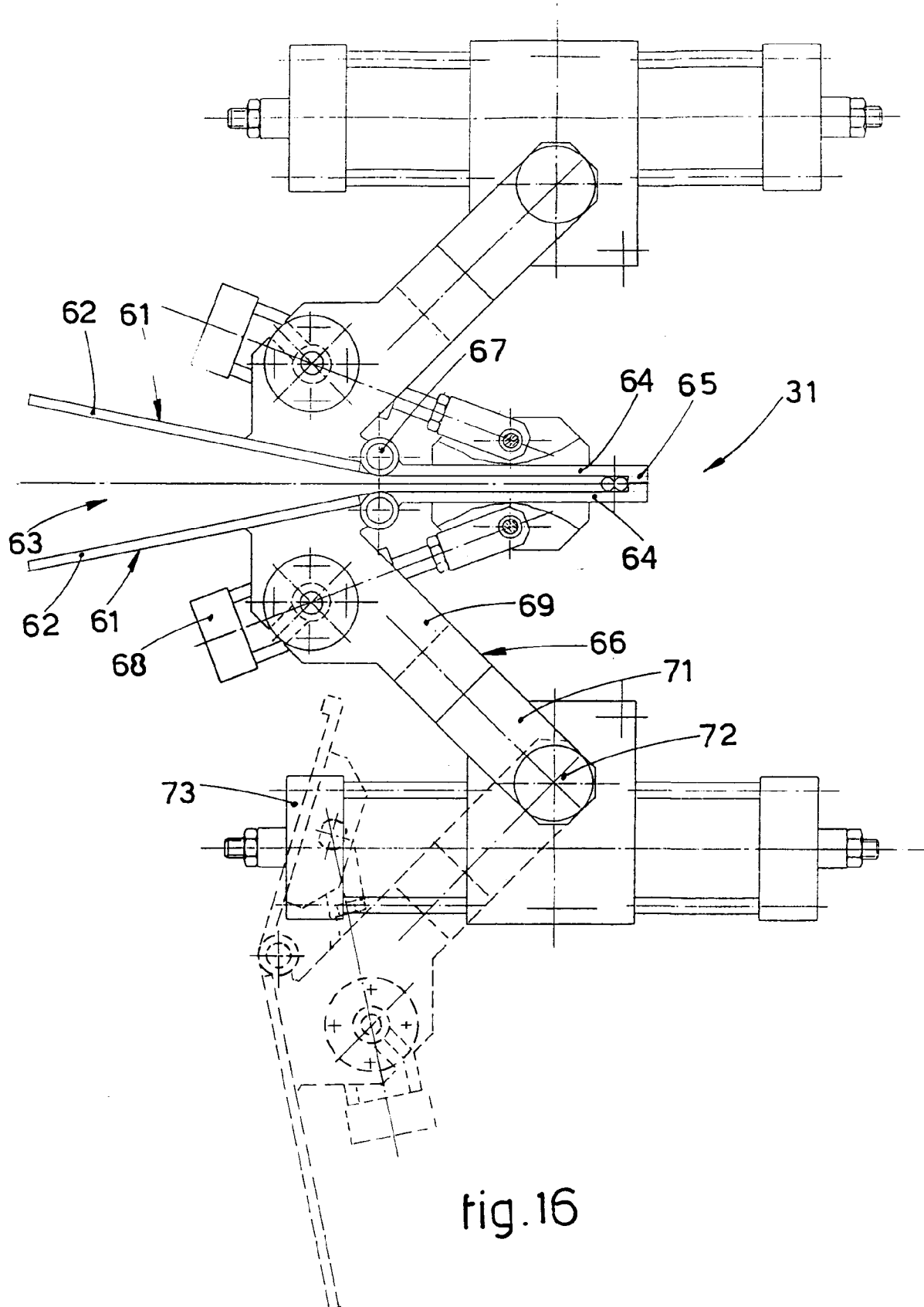


fig.14



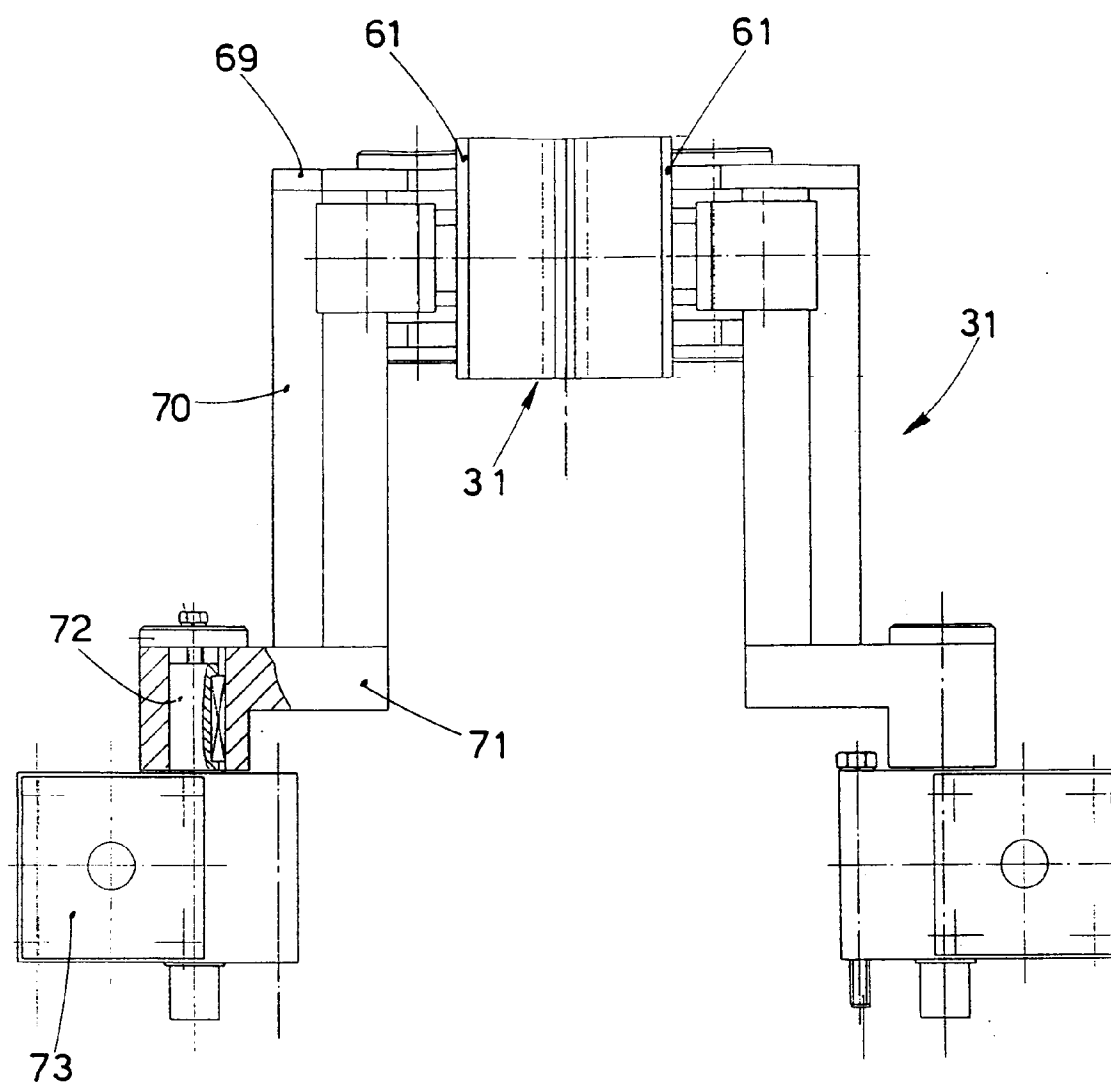


fig. 17