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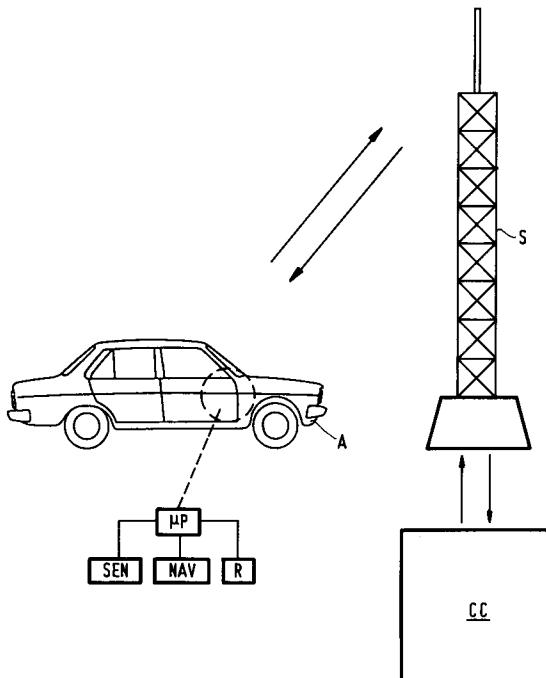
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㉓ Method of collecting traffic information, and system for performing the method.

㉔ Via a cellular radio communication system, measured values are transmitted from vehicles to a computer. The measured values are chosen so that they can be used to determine Origin-Destination matrices without infringing upon the privacy of the users.



**FIG. 4**

The invention relates to a method of collecting traffic information by receiving measured values, transmitted from at least one vehicle, in respect of location and movement of the relevant vehicle.

The invention also relates to a system for performing the method.

A method of this kind is known from the article "Ali-Scout - A universal guidance and information system for road traffic", R. von Tomkewitsch, Second International Conference on Road Traffic Control, 15-18 April 1986. The cited article describes a traffic guidance system in which vehicles comprise a navigation device which guides the user to a preselected destination by means of a position-finding device and data concerning the local road network and current traffic situation as generated by a central computer and transmitted by guidance beacons. For traffic-dependent guidance it is necessary for the central computer to have available current traffic information which is provided by the vehicles themselves, the vehicles transmitting measured values (such as travel times and waiting times on route segments determined by the guidance beacons) to the guidance beacons which transmit this data to the central computer for processing.

It is a drawback of such a method that it requires a complex and expensive network of guidance beacons with infrared transmitters and receivers in the vehicles as well as in the beacons.

It is *inter alia* an object of the invention to provide a less expensive and more efficient method.

To achieve this, a method in accordance with the invention is characterized in that said measured values are defined relative to virtual reference positions and are transmitted in a cellular radio communication system *via* the communication mechanism of an actual cell. A cellular radio communication system, for example as introduced in Europe in 1991, offers an extensive mobile and portable communication network enabling vehicles or other users to transmit and receive digitized data *via* a radio link. The use of radio channels in this system and the definition of the data relative to virtual reference positions renders the network of guidance beacons superfluous. For more detailed information regarding this so-called GSM, reference is made to the article "Implementing the Pan-European Cellular System", J.R. Easteal, Pan-European Mobile Communications, Winter 1989/90, IBC Technical Services Ltd, pp. 101-104.

A preferred version of a method in accordance with the invention is characterized in that per vehicle the transmitted measured values contain, for each intersection passed, indications in respect of a route segment travelled by the vehicle so as to reach the intersection as well as in respect of a

route segment travelled by the vehicle beyond the intersection. This offers a special advantage in that these measured values can be used to determine the so-called Origin-Destination (O-D) matrix for each intersection, and hence the O-D matrix of an entire area, without infringing upon the privacy of the user. For a given set of origins and destinations such an O-D matrix provides the frequencies at which vehicles depart from a given origin to a given destination. This enables authorities not only to improve the traffic infrastructure (for example by readjustment of traffic lights), but also to generate short-term traffic guidance recommendations to stimulate the flow of traffic. The data necessary for determining O-D matrices is customarily collected by means of video cameras monitoring the traffic flows at each intersection. This is a cumbersome and expensive approach, notably when the measurements are often repeated in order to update the data. The measured values transmitted in the cited Ali-Scout traffic guidance system are not suitable for calculating O-D matrices. An obvious solution to this problem would be the additional transmission by the vehicles of their destination; however, this has a major drawback in that the privacy of the users is then seriously affected. The method in accordance with the invention offers sufficient data for the determination of the O-D matrices, it nevertheless being impossible to trace individual users even in the case of low traffic densities. It is to be noted that this preferred version of the method can in principle also be used without a cellular radio communication system; however, in that case facilities must be provided at each intersection for the transmission of the data which is, of course a drawback.

The invention will be described in detail hereinafter with reference to the following Figures; therein:

Fig. 1 illustrates the cellular structure of the radio communication system;  
 Fig. 2 shows a intersection with traffic flows;  
 Fig. 3 shows an O-D matrix associated with the intersection, and  
 Fig. 4 shows a device in accordance with the invention.

Fig. 1 shows a number of cells of a radio communication system. In this case they have a circular shape with adequate overlap for full coverage of a region. Other cell shapes, of course, are also feasible. A cell of this kind corresponds to a geographic sub-region of a larger geographic region. Within the cell there is situated a transmitter/receiver station S whereto vehicles within the relevant cell can transmit data *via* a radio link. Each cell has its own radio frequency or radio channel and the range of the transmitter/receiver station is decisive as regards the dimensions of the

relevant cell. The vehicles comprise a number of sensors (for example, magnetic sensors for direction finding and wheel sensors for determining the distance travelled) which, on the basis of their measurements, enable accurate determination of the location and the direction of movement of the vehicle by a navigation device (for example, the CARIN system) aboard the vehicle. To this end, the navigation device has available a digitized map of the area (for example, on CD-ROM) which contains all roads, composed of route segments, of the relevant region. Hereinafter, the term "intersection" or "junction" is to be understood to mean: any point of the road network where a vehicle can make a choice as regards continuation of its travel (*i.e.* three-forked roads, intersections, roundabouts and the like). Each segment of the road network between two intersections will be referred to hereinafter as a "route segment". Thus, a vehicle can determine at any instant its position on the map, *i.e.* which route segment is being followed at that instant. The digitized map forms a reference framework consisting of virtual reference positions. The measured values transmitted to the transmitter/receiver station S of a cell by a vehicle are defined in relation to these reference positions (for example, representations on the map of intersections or fuel stations along a highway); for example, a transmitted travelling time relates to the complete route completed between two given intersections. Therefore, the reference positions need not be represented by physical units such as beacons. The transmitter/receiver station S of each cell communicates with a central computer which collects and analyses the transmitted measured values. On the basis of the analysis of the traffic situation by the central computer, it can generate traffic guidance recommendations for transmission to the vehicles. The drivers of the vehicles can thus be informed about congestions caused by accidents, back-ups and the like. The flow of traffic is thus improved.

Fig. 2 shows an intersection of roads. The traffic arrives from the directions or route segments numbered from 1 to 4. At this intersection each vehicle has the choice from three route segments for continuing its travel. Therefore, there are 12 traffic flows which are represented by arrows in the Figure. In a preferred embodiment of the invention, after passage of an intersection the following information is transmitted to the transmitter/receiver station S by each vehicle: an indication of the route segment followed by the vehicle so as to reach the relevant intersection and an indication of the route segment followed by the vehicle beyond the intersection. For example, a vehicle coming from the route segment *via* and continuing on the route segment 4 will transmit, after the right-hand turn at

the intersection, the combination of the route segment 1 followed by the route segment 4 to the transmitter/receiver station S. Should a given vehicle temporarily not have the opportunity to transmit the data (for example, because the channel is busy), the indications of the route segments followed can be saved for a plurality of intersections until transmission of the data thus saved is possible. In such a case traffic will be rather busy, so that the privacy of the relevant user will not be affected, despite the transmission of the route indications relating to successive intersections.

Fig. 3 shows an Origin-Destination matrix associated with the intersection of Fig. 2. The 12 traffic flows of the intersection have been counted during a given time interval. Evidently, this is possible only by way of the described transmission of the measured values in accordance with the invention. It can be seen from Fig. 3, for example that during the time interval of the measurement 89 vehicles originating from the route segment 1 continued their travel *via* the route segment 4. Such an O-D matrix can also be translated (by simple normalization) into a percentual O-D matrix; the sum of the values of each row of the matrix is then 100. In a non-normalized O-D matrix, the sum of the values of each row represents the inflow *via* the relevant route segment and the sum of the values of each column represents the outflow *via* the relevant route segment. On the basis of this data, the authorities (the central computer) can optimize, for example the setting of traffic lights at the intersection. It is also possible to combine O-D matrices of neighbouring intersections, provided of course that they relate to the same time interval. Thus, for a given region an O-D matrix can also be determined from the O-D matrices of the constituent intersections of the relevant region. On the basis thereof the authorities can supply the users with traffic guidance recommendations *via* the cellular radio communication system. A major advantage of the collection of the traffic information in accordance with the invention consists in that the determination of the O-D matrices (or other measurements) can be simply repeated and hence continuously updated. The central computer can thus generate recommendations which fully correspond to the current traffic situation. The known step of making each vehicle transmit also its travelling time for its last route segment travelled thus also has a synergistic effect: in combination with the derived O-D matrices, even more accurate traffic guidance is possible. Another major advantage of the method in accordance with the invention consists in that the users need not make their final destination known. As a result of the transmission of the relevant route segments per intersection, the data required can be virtually anonymously collected. This is because

it is impossible to track a given vehicle along its route through the cell, even in the case of low traffic density. The privacy of the drivers is thus ensured.

Fig. 4 shows a device in accordance with the invention. Vehicle A comprises sensors SEN (for example, magnetic sensors for direction finding and wheel sensors for determining the distance travelled), a navigation device NAV with a digitized map of the geographic region which contains virtual reference positions, a radio unit R for transmitting and receiving data in a cellular radio communication system, and a microprocessor  $\mu$ P. The microprocessor is programmed to apply the measured values from the sensors to the navigation device which utilizes this data for accurate determination of the location and the direction of movement of the vehicle relative to virtual reference positions on the map. The microprocessor is also programmed to transmit measured values, such as indications of the route segment travelled to a passed intersection and of the route segment travelled beyond the intersection, *via* the radio unit R, to the transmitter/receiver station S which communicates with the central computer CC. The transmitter/receiver station S and the radio unit R form part of a cellular radio communication system, for example GSM. The central computer CC receives measured values from a number of vehicles *via* several transmitter/receiver stations and processes this information so as to form, for example traffic guidance recommendations which can be transmitted to the vehicles *via* the transmitter/receiver stations. The microprocessor  $\mu$ P in the vehicles applies this data to the navigation device which applies it to the driver of the vehicle. This can be realised in a visual manner, *via* a display screen, or audibly by means of a speech synthesizer.

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values contain, for each intersection passed, indications in respect of a route segment travelled by the vehicle so as to reach the intersection as well as in respect of a route segment travelled by the vehicle beyond the intersection.

4. A method as claimed in Claim 3, characterized in that the transmitted measured values per vehicle also comprise the travelling time for the last segment travelled.
5. A system for performing a method as claimed in any one of the Claims 1 to 4, comprising a central computer, at least one transmitter/receiver station for radio communication between the central computer and at least one vehicle, and a microprocessor aboard said at least one vehicle which is programmed to select measured values and to apply these values to a radio unit aboard the at least one vehicle for transmission.
6. A vehicle comprising a radio unit and a microprocessor and suitable for use in a system as claimed in Claim 5.

## Claims

1. A method of collecting traffic information by receiving measured values, from at least one vehicle, in respect of location and movement of the relevant vehicle, characterized in that said measured values are defined relative to virtual reference positions and are transmitted in a cellular radio communication system *via* the communication mechanism of an actual cell.
2. A method as claimed in Claim 1, characterized in that the virtual reference positions comprise representations of road junctions.
3. A method as claimed in Claim 2, characterized in that per vehicle the transmitted measured

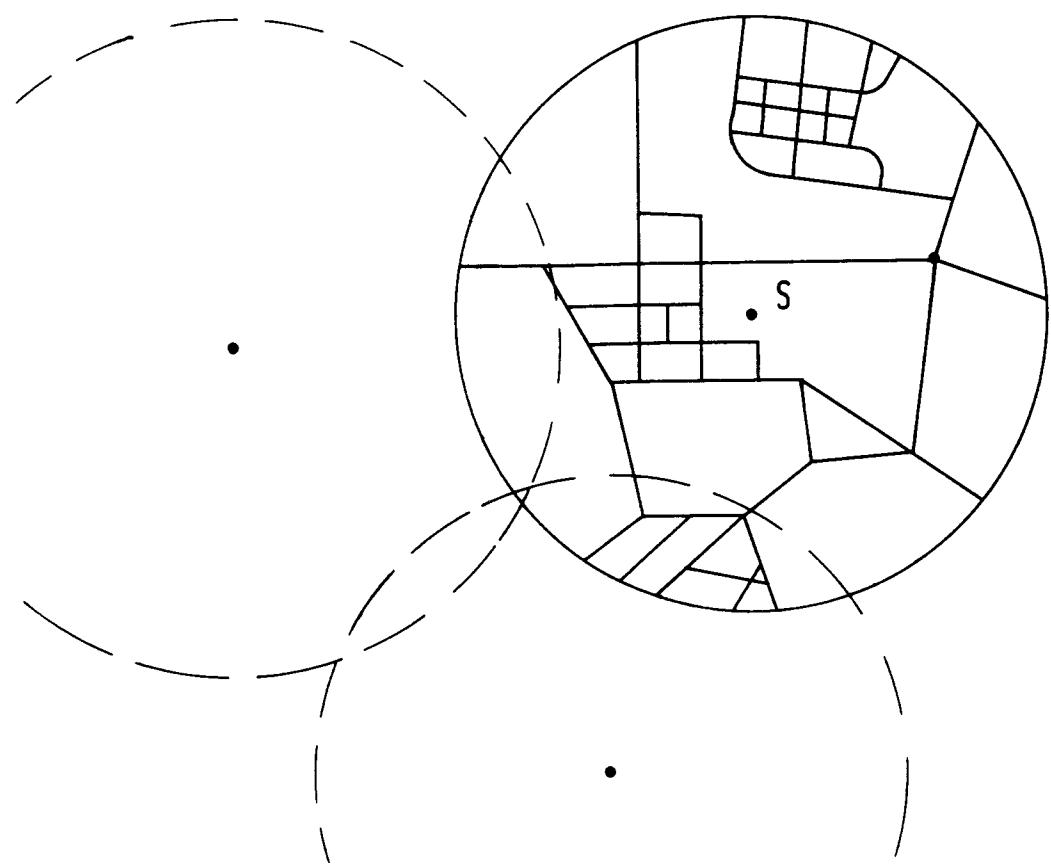


FIG.1

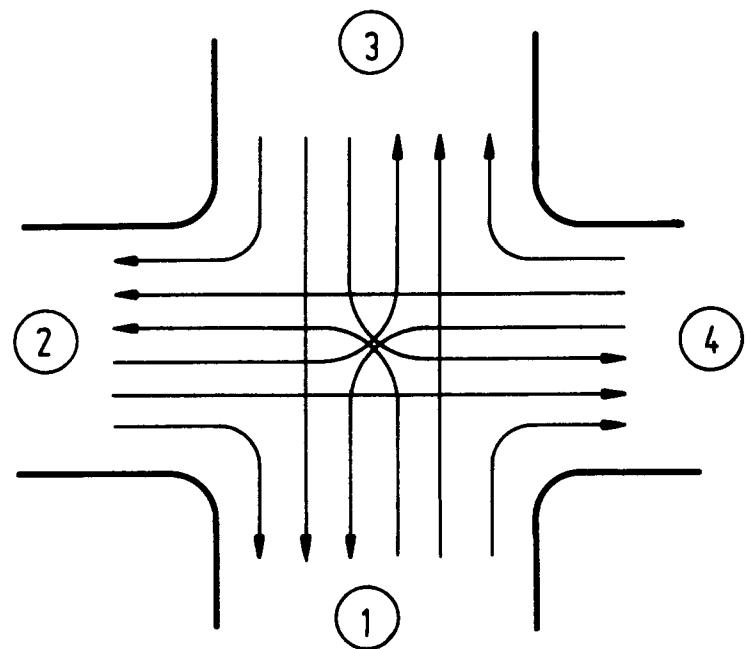


FIG. 2

$\sigma$	0	1	2	3	4
1	0	117	652	89	
2	212	0	173	974	
3	578	155	0	43	
4	67	866	52	0	

FIG. 3

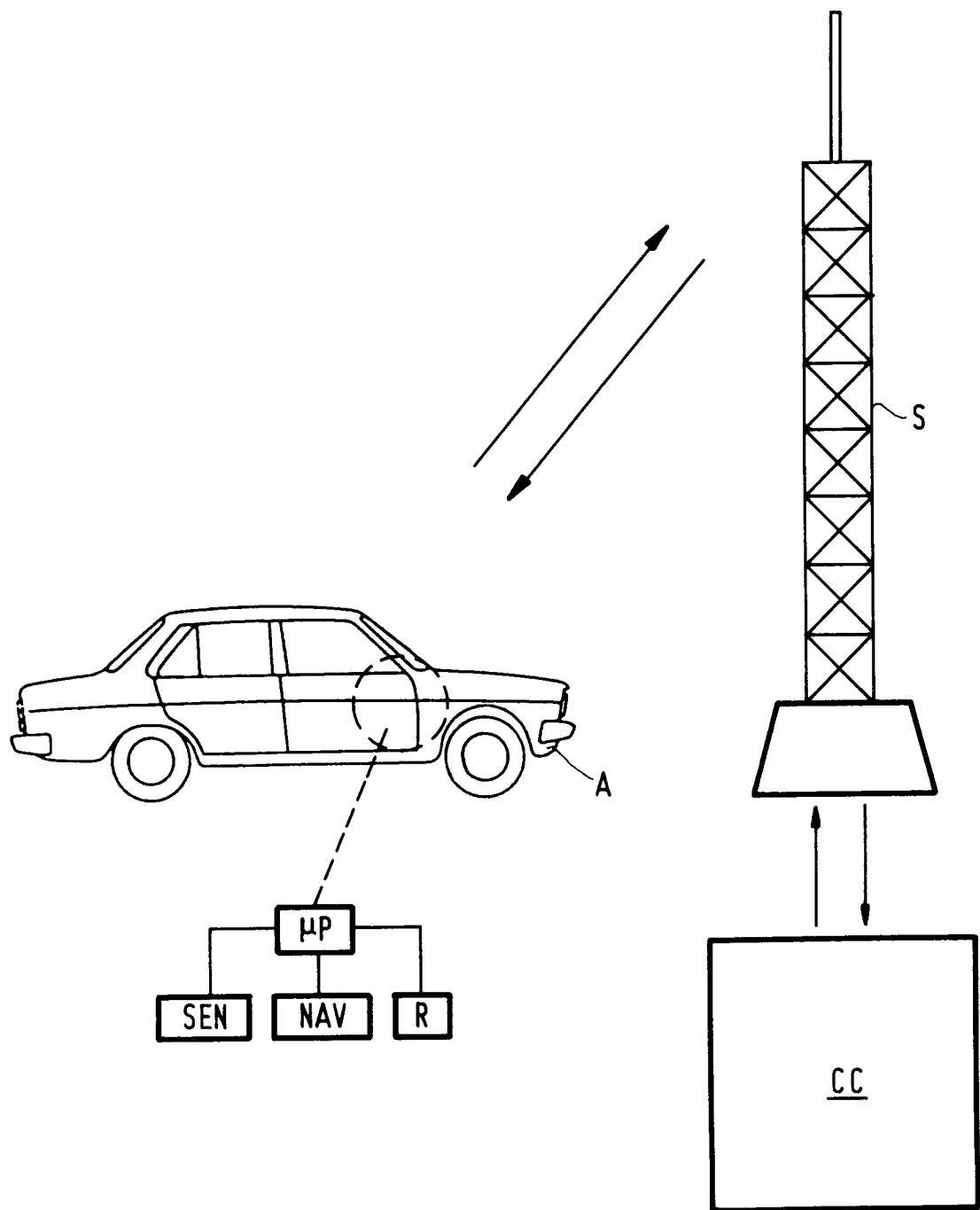


FIG. 4



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EUROPEAN SEARCH REPORT

Application Number

EP 92 20 1420

DOCUMENTS CONSIDERED TO BE RELEVANT		Relevant to claim	CLASSIFICATION OF THE APPLICATION (Int. Cl.5)
Category	Citation of document with indication, where appropriate, of relevant passages		
X	IEEE TRANSACTIONS ON VEHICULAR TECHNOLOGY, vol. 40, no. 1, February 1991, NEW YORK US pages 132 - 140; I. CATLING ET AL: 'Road Transport Informatics in Europe---Major Programs an Demonstrations'	1,5,6	G08G1/0968
Y	* page 134, paragraph B * * page 135, paragraph C -paragraph H * * page 136; figure 1 * ---	2-4	
Y	EP-A-0 292 897 (SIEMENS AKTIENGESELLSCHAFT BERLIN UND MÜNCHEN) * column 4, line 29 - column 5, line 22; figures 1,2 *	2-4	
X	VEHICLE ELECTRONICS IN THE 90,S: PROCEEDINGS OF THE INTERNATIONAL CONGRESS ON TRANSPORTATION ELECTRONICS October 1990, WARRENDALE, US pages 209 - 215; W. E. SUCHOWERSKYJ: 'Vehicle Navigation and Information Systems in Europe --- An Overview' * page 212, left column, line 1 - page 214, right column, line 24; figures 6,7 *	1,5,6	TECHNICAL FIELDS SEARCHED (Int. Cl.5)
A	EP-A-0 384 794 (URBA 2000) * claims 1-3; figures 1,2 *	1	G08G
The present search report has been drawn up for all claims			
Place of search	Date of completion of the search	Examiner	
THE HAGUE	03 SEPTEMBER 1992	WANZEELE R.J.	
CATEGORY OF CITED DOCUMENTS		T : theory or principle underlying the invention E : earlier patent document, but published on, or after the filing date D : document cited in the application L : document cited for other reasons ..... & : member of the same patent family, corresponding document	
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