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(54) **Cassette for mosaics from tiles**

(57) A cassette of the type for receiving and storing
articles in stack form comprises a generally elongated
tubular member having a first end and an opposite sec-
ond end and having an interior confine disposed there-
between. One of the first and second ends is provided
with a means for releasably connecting the cassette to
a tile piece delivery apparatus, and the interior confine
of said tubular member is compatibly shaped and sized
to receive a plurality of tile pieces in a stacked arrange-
ment.

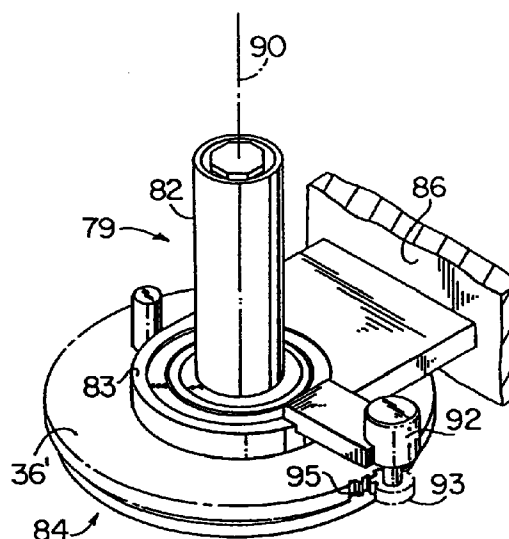


FIG. 7

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Description

BACKGROUND OF THE INVENTION

The present invention relates to a system and related method for creating art work using tile pieces and deals more particularly with an automated tiling system whereby tilings are arranged in an ordered collection of plates in accordance with numeric data representing a pattern to be followed by the tile pieces such that the ordered collection of plates once bonded to a substrate surface depict the pattern initially prescribed by the input data.

Hitherto, the creation of tile plates, that is, the pre-made assembly of the tile pieces and the material backing on which they are attached, were manufactured for the most part by hand. This involved the time consuming process of hiring people to pick and place individual tile pieces in a given arrangement on the plate material. The manual arrangement of tilings on a backing material has without doubt many problems associated with it, and among these problems is that the complexity of the design to be carried out is limited by the skill of the worker. Attempts have been made to simplify the creation of designs.

One such attempt is disclosed in U.S. Patent 2,715,289 wherein fabrication of repetitive or nonrepetitive designs is accomplished using plates having a repeating pattern baked in them. The design is created by varying the orientation of the individual plates relative to one another. A mosaic is thus created by the juxtaposition of each plate with the other. However, the tile pieces used are all of the same shape and size so that there is no aesthetic enhancement through shape and size variances. Also, there is no point-by-point color variation capability with this system, thus making it virtually impossible to portray different designs outside of those which are provided for by the system.

With the advancement of new scanning technology, the ability to take an image and transpose it into digital form for use in a computer is readily available. The availability of such scanning technology presents countless possibilities for decorating interiors and exteriors of an environment. In addition, surfaces on commonly found items, such as plazas, walkways, pool areas, coffee tables, dining tables, counter tops, mantle pieces and wall hangings, could all be decorated in tile with exquisite beauty using the data representing the design which is to be represented by the tile pieces. In digital form, a desired design could be projected electronically in a simulation of an environment in which it is to be used. That is, data representing a graphic in digitized form quite easily lends itself to being displayed on a screen, or printed by a multicolored laser jet printer on paper in the case where a hard copy is desired. However, while it is very possible to create and maintain such graphic representations of a given design electronically in a computer, implementing this data to drive

numerically controlled machinery to create a simulated mosaic involves correlating the rules of tiling mathematics with the numeric control logic of the implementing machines.

Additionally, the capability of computers taken from a stand point of storing and executing complex equations and matrices, such as, equations involving the laws of tessellism or pointillism which govern tiling pattern design, is made virtually automatic through the use of such technology. The placement of the basic geometric shapes often used in creating a mosaic, such as squares, hexagons or triangles, while hitherto primarily arranged in a monohedral relationship, can be integrated with one another by using appropriate software. Examples of such are prototiles in which equilateral triangles, squares and regular hexagons can be arranged in a myriad of different formations by execution of the appropriate algorithm in the computer. The laying out of individual tiles to physically determine whether or not they fit within a given confine, as is presently done by hand, can further be simplified by an overall algorithm for automatically creating a tiling by computer.

Accordingly, it is an object of the present invention to provide a system wherein a computer is employed mathematically to arrange tile pieces on plates in accordance with data representing a pattern to be depicted by the tile pieces and wherein data is used by the system for controlling a handling device which places individual tile pieces onto a plate material at predetermined locations to create the desired tile arrangement, and/or to provide a system of the aforementioned type wherein a design which is to cover a contiguous environment is capable of being projected in a portrayal of that environment prior to the actual assembling of tiles pieces onto plates, and/or to provide a system of the aforementioned type whereby a simulated mosaic can be bonded to a surface using an ordered arrangement of plates which are coded to correspond to a designated area of the surface to be covered by the plates, and/or to provide improvements generally.

SUMMARY OF THE INVENTION

The invention resides in a method and related apparatus for creating a desired pattern design wherein tile pieces are arranged on individual plates in accordance with a general panoramic scheme for which each of the plates has a designated position in the overall layout. The system includes, for this purpose, a base support surface for providing a surface upon which a material is supported and onto which material tile pieces are deposited. A delivery means is disposed in a spatial relationship proximate the base support surface for applying tile pieces onto the material supported by the base support surface at predetermined locations thereon. A drive means controllably positions the base support surface and the delivery means relative to one another such that the delivery means is positioned rela-

tive to the base support surface at the predetermined locations. A supply means communicates with the delivery means for providing a supply of tile pieces to be deposited on the base support surface through the delivery means. Control means connects the drive means and the delivery means to controllably position the delivery means relative to the base support surface at the predetermined locations and for causing the delivery means to discharge a tile piece at one of the predetermined locations. The predetermined locations are defined for each tile piece discharged by control data used by the control means to effect positioning by the delivery means and the support surface relative to one another and to effect discharge of the tile pieces by the delivery means at the predetermined locations onto the material supported by the base support surface.

The invention further resides in a method of creating a simulated mosaic whereby an ordered collection of plates is provided and on each of which plates is disposed a plurality of tile pieces in a given arrangement such that the plates collectively, when affixed to a decorated surface as an ordered collection, present a desired artistic effect.

BRIEF DESCRIPTION OF THE DRAWINGS

Fig. 1 is a schematic of the control system of the invention.

Figs. 2 and 2a show respectively a perspective and top view of a drum dispenser type tile applicator.

Fig. 2b illustrates in detail a sleeve of the applicator of Fig. 2 with a tile piece disposed within its confines.

Fig. 3 is a partially fragmentary vertical sectional view of a tile delivery device.

Figs. 4a and 4b illustrate possible routes that may be taken to place tiles on a plate.

Fig. 5a, 5b, and 5c illustrate monohedral tilings made up of regular polygons.

Fig. 6 is a perspective view of a second embodiment of a tile applicator in the form of a cassette dispenser.

Fig. 7 is a perspective view of the dispensing unit shown apart from the device of Fig. 6.

Fig. 7a is a partially fragmentary vertical sectional view through the unit of Fig. 7.

Fig. 8 is a perspective view of a pick and place device used for loading a cassette.

Fig. 9 is a vertical section through a bin illustrating the loading of tiles into a cassette.

Figs. 10 and 11 illustrate the relationship between a path taken to deposit the tile pieces and the corresponding manner in which the cassette is loaded.

Fig. 12a illustrates a mosaic made by regular polygons to create a desired design using a skewing feature.

Fig. 12b illustrates a mosaic made by the randomized placing feature of the invention.

Figs. 13a, 13b, and 13c show alternative designs

capable of being created by the apparatus of the invention.

Fig. 14a shows a quasiperiodic mosaic made from the two shapes of Fig. 14b.

Fig. 15 is a flowchart illustrating the process by which tile pieces are arranged.

Figs. 16a and 16b illustrate tile laying out processes in accordance with the flowchart of Fig. 15.

Figs. 17a, 17b, and 17c illustrate an embodiment of a tile holding plate.

Figs. 18a and 18b illustrate an alternative embodiment of a tile holding plate.

Fig. 19 illustrates a method for bonding tile pieces with the plate material associated with it.

Fig. 20 is a perspective view of an alternative method for applying tiles to the plate.

Fig. 21 illustrates in perspective view a spray jet usable with the delivery means.

Fig. 22 illustrates a simulated mosaic colored by the spray jet of Fig. 20.

DETAILED DESCRIPTION OF THE PREFERRED EMBODIMENT

Referring to the drawings, and first to Fig. 1, a system embodying the invention is there shown schematically and referred to generally by reference numeral 2. The system includes a controller 4, associated input and output peripheral devices 14 and 16 linked to the controller for data input purposes and for projecting data to the user in visual form, and handling means 18 driven by the controller in conjunction with the data input through the devices 14 for causing tile pieces to be placed onto a support surface in a manner which will hereinafter become apparent.

The controller 4 includes a central processing unit 6 which is linked through an appropriate bus to a read only memory location 8 in which a tiling executing program is stored, a volatile memory location 7 for storing the digitized data taken from the input means 14, and an output display controller 10 linked to the central processing unit 6 for driving the output devices 16 to display or print an image of the desired design. The controller 4 further includes a positioning means driver 12 which is linked to the central processing unit 6 and to the handling means 18. The driver 12 is responsible for translating the theoretical coordinate locations of individual tile pieces given to it by the processing unit 6 into machine numeric control language for driving the handling means 18 to place the tilings at given locations on a support surface.

The input devices 14 are responsible for generating a desired pattern to be followed by the tile pieces. For this purpose, the design may be fashioned from one of a variety of designs stored in a library, for example, as encoded information on a disc 20. Alternatively, the design may be derived from an imaging device, such as a scanner 22. The images taken from either of these

sources are capable of being used in conjunction with an editing device 24 for the purpose of altering the image that is input to the controller. The peripheral output means 16 includes a color printer 26 and a video display 28 linked to the output display controller 10 which allow the operator to see the selected image in hard copy or in screen display, prior to the actual creation of the tile plates. Thus, the display means 16 is capable of providing either in hard copy or electronically, a portrayal of the pattern as it would look in the intended environment as will hereinafter become apparent with other aspects of the invention.

The controller 4 drives the handling means 18 to cause tile pieces to be deposited on a plate material M to create free standing tile plates in accordance with an executing program which is stored in memory at location 8. By free standing it is meant that the tile pieces are attached to the plate material so that each plate is capable of being moved and applied separately. The handling means 18 for this purpose may either include a cassette assembler 30 used in conjunction with a coordinate controlled cassette-type tile dispensing device 34, or a drum type dispensing device 32 used in lieu of the former combination. Each of the devices which makes up the handling means 18 is responsive to commands issued by the driver 12. To this end, each of the coordinate controlled dispensing devices 32,34 has appropriate X,Y control and positioning means 31a, 31b, a theta control means 33, and a delivery means controller 35, while the assembler device 30 is provided with X,Y,Z axis control means 37.

Tile pieces are arranged by the coordinate controlled handling means 18 on a support surface overlaid with the material M which ultimately constitutes a plate. The plates are themselves a depiction of separate designs which, when taken together, combine to generate the overall mosaic pattern when assembled on a substrate surface. Additionally, the plates may take many different forms as will become apparent, but, in the preferred embodiment, the material is made from a mesh or gauze type material which is capable of being easily cut into smaller blocks sized in accordance with industry standards to form the individual plates.

In Fig. 2 a drum type dispensing device 32 is shown. The material M which constitutes the plate 36 is supported on a platen 38 having an exposed upper support surface 39 and is capable of being moved in the indicated X and Y coordinate directions. In addition to the platen 38, the apparatus shown in Fig. 2 is constituted by a drum portion 42 and a delivery portion 44 juxtaposed below it. As shown in Fig. 2a, the drum portion has a plurality of sleeves 46,46 which extend along its length L and are disposed circumferentially about its periphery. In transverse cross-section, the sleeves are internally shaped and sized to receive correspondingly or otherwise compatibly shaped and sized tile pieces 48,48 in stack form. That is, as shown in Fig. 2b, the sleeves do not necessarily have to have the exact shape

of the tile piece received within it, but only a shape that is compatible, such as with the octagonal tile piece 48 and the square shaped sleeve 46. The delivery portion 44 of the apparatus, as best shown in Fig. 3, is comprised of a delivery means 51 which includes a planar holding member 50 mounted against the bottom face 45 of the drum portion 42 and is rotatable about a central axis 54. A shaft 56 is provided and is journaled for rotation on the drum portion 42 about the axis 54. The shaft is drivingly connected at its upper end to a positioning motor 58 and is fixed at its lower end to the holding member 50 at its center. The motor 58 is linked to the theta control means 33 of the handling device 32 and is thus capable of being controllably rotated in either direction.

The holding member 50 has an opening 52 formed in it sized suitably to allow a single tile piece to be ejected from the drum portion 42 at a designated location on the platen. A planar closure member 60 is fixed to and is disposed below the holding member 50 so as to partially cover the opening 52 over an area corresponding in size to that of the sleeves 46,46. This arrangement prevents tile pieces from falling directly downwardly from the sleeves and instead creates a chamber 62 in which a single tile piece is received. Juxtaposed relative to each of the sleeves 46 is a reciprocating rod 66 connected at its upper end to an actuator 67 secured to the top of the drum portion of the apparatus. Each rod is capable of being reciprocated between a retracted position wherein the lower tip T of the rod is maintained within the drum portion and an extended position wherein the tip of the rod extends beyond the lower face 45 of the drum and into the chamber 62 as illustrated in phantom line. A discharge opening 61 is formed in the closure member 60 and is sufficiently wide to permit the passage of a single tile piece through the closure member 60 when aligned with the one of the rods 66 responsible for striking the involved tile piece.

The delivery means 51 further includes a laterally moveable shuttle member 68 which is drivingly connected to an associated conventional actuator 70 which is controlled by the delivery means controller 35. The shuttle member 68 is itself moveable between an extended position in which it extends into the chamber 62 as shown in phantom line, and a retracted position wherein it is maintained out of interference with the tile pieces which drop from the sleeve disposed above it.

In operation, the holding member 50 is controllably rotated to a position as shown in Fig. 3 wherein the chamber 62 is located generally in line with a selected one of the sleeves 46,46 containing the tile pieces to be deposited. With the discharge of each tile piece, a corresponding positional movement of the platen 38 will occur to move the platen to the next predetermined location beneath the delivery means 51. In this dispensing condition, the discharge opening 61 is located slightly laterally offset from the sleeve involved in the discharge process and is thus positioned in line with the

striking rod 66. During this alignment process, the shuttle member 68 is normally in its chambered position, thus blocking the downward travel of the tile pieces. In the discharging process however, the shuttle member is retracted allowing one of the tile pieces to drop into the chamber and thereafter be moved linearly laterally by the travel of the shuttle member 68. In so doing, the involved tile piece becomes located along the line of action of the rod 66 associated with the selected sleeve and is thereafter tamped by the action of the rod down onto the platen. When a different tile shape is to be dispensed, the holding member 50 is again rotated to bring the chamber 62 beneath the next adjacent sleeve which carries the next tile shape or color to be deposited.

The controller directs the dispensing device 32 to deliver the tile pieces in the most efficient manner possible. To effect this, and depending on the type of design to be created, the dispensing device 32 will deliver all the tiles of a single sleeve onto the platen 38 at one time. The arrangement of tilings in the design of Fig. 4a is such that tile pieces of the same type and/or color extend diagonally. Thus, the platen as shown in Fig. 4b is moved along a first diagonal P1 to deposit tile pieces of the "a" type, and then follows a second delivery path P2 along which "b" type tile pieces are dispensed, followed in similar manner until all "c", "d", and "e" type tile pieces have been deposited on the platen.

The drum type dispensing device 32 shown in Fig. 2 is well suited for creating monohedral tilings comprised of regular polygons, e.g. hexagons, triangles, or squares. In the case of Fig. 5a, a monohedral mosaic comprised of hexagonal shaped tile pieces arranged in alternating colored rows are dispensed in a manner similar to that disclosed with reference to Figs. 4a and 4b to achieve this effect. In Fig. 5b, a monohedral mosaic is shown which is comprised of a plurality of identical equilateral triangles. The triangles shown in shade line are highlighted to indicate that they are angularly offset relative to those which are unshaded by forty-five degrees. Thus, in at least two of the sleeves 46,46 contained in the drum portion of the apparatus 32, two stacks of triangular tile pieces of identical size are contained, each held within the drum at angular orientations differing by forty-five degrees. The dispensing device 32 is also used where the tile pieces are squares of the same size, but carry specific designs which must be oriented in different angular orientations, e.g. at ninety degree offsets, to create a desired pattern, as shown in Fig. 5c. The tile pieces 48,48 may be ones, such as disclosed in U.S. Patent 4,546,025 entitled MULTILATERAL EDGE UNIT HAVING AN ASYMMETRICAL DESIGN THAT EXTENDS TO THE LATERAL EDGES issued on October 8, 1985, having two side edges which are complementary to one another to create a repeating or non-repeating design as determined by the user and as directed by applicable software.

Turning now to Figs. 6 through 10, and in particular to the cassette type dispensing device 34 shown

therein, it should be seen that this dispensing device employs one or more sleeves 79,79 which are carried by a Y-carriage 86 above a stationary support surface 85 traversed by an X-carriage 88 movable in the X-coordinate direction and carrying the Y-carriage 86 for movement along its length. Each sleeve 79,79 includes a cassette 82 and a tile delivery means 84 connected for communication with one another and secured to the Y-carriage 86 through the intermediary of a mounting part 83. The X and Y carriages are each driven respectively by positioning motors (not shown) linked to the associated X,Y position control means 31a, 31b of the control system.

The delivery means 84 of the device 34 operates similarly and is in essence identical componentwise to the means shown in Fig. 3 in that it is comprised of a planar holding member 36', a shuttle means and a reciprocating rod 66. This means does not however include a rotatable shaft controlling the rotation of the member 36'. Instead, the delivery means 84 includes a stepper motor 92 mounted to the Y-carriage and linked to the theta control means 33 for controlling the angular orientation of the holding member 36' about the axis 90. Rotation of the holding member 36' occurs through the intermediary of a pinion gear 93 driven by the motor 92 and positively engaging teeth 95 disposed about the outer circumference of the holding member 36'.

The mounting part 83 is provided as part of the delivery means 84 and is secured to the Y-carriage for supporting the holding member 36' for rotation about the axis 90. The holding member is adapted for connection with the cassette for communication with the delivery means 84. For this purpose, a throat portion 87 is provided and is integrally formed as part of the holding member 36' such that the mounting part is freely rotatably mounted about it. The throat portion 87 and the lower end of the cassette, as shown in Fig. 7a, are provided with releasable corresponding mating surfaces in the form of an annular groove 94 formed along the inner wall of the throat portion 87 which cooperates with a radially outwardly extending rib 98 disposed on the lower end of the cassette to create a snap fitting connection therebetween. The cassettes are made from a flexible material, i.e. plastic, to aid in this connection.

Turning next to Figs. 8 through 11, it should be seen that the cassettes 82,82 are loaded with respect to the order in which the tile pieces will be deposited along a delivery path to be followed across the support surface 85. As shown in Fig. 8, the assembler is provided and is comprised of a pick and place device 100 used in conjunction with a supply 102 of tile pieces of different colors and/or shapes, kept separately from each other in bins 104,104. The apparatus 100 includes a track means 140 and a base 121 movable in a conventional manner along the track means 140 in the illustrated X-coordinate direction. The base 121 supports a body member 115 through the intermediary of an extendable mast 117 vertically movable in the indicated Y-coordi-

nate direction. An arm 106 is attached to the body member 115 and is movable between retracted and extended positions in the indicated Z-coordinate direction through the controlled action of an actuator 107. Each of the parts of the apparatus 100 responsible for generating movement in the indicated X,Y,Z directions is linked respectively to the corresponding part of the control means 37 to effect precision movement along respective ones of the three coordinate axes.

As shown in Fig. 9, the tile pieces are arranged in rows in the bins 104,104 and are outwardly biased therefrom by conventional spring members 111. Finger means 108 are provided at the open ends of each bin and engage the outwardmost tile piece 48' for the purpose of preventing its ejection prior to its intended withdrawal from the bins. The finger means 108 are radially compliant members which are normally inwardly biased to engage the peripheral edges of the outwardmost tile piece 48' so as frictionally to keep it from being ejected. The arm 106 of the apparatus 100 in the identified embodiment is constituted by a cassette 82 such that the open end 109 of the cassette is cantilevered outwardly from the body member 115 of the apparatus and moveable into and out of engagement with the front faces of the bins 104,104 through the action of the actuator 107. In this way, the open end 109 of the cassette is moved along the Z axis into engagement with a selected one of the bins 104,104 and against the normal radially inward bias of the fingers 108 thereby causing the tile piece to be ejected into the cassette. The open end 109 of the cassette may be chamfered at 99 to effect more effective sliding of the cassette wall between the finger means 108 and the first tile piece 48'.

In Fig. 10, an example is shown of a path P taken by the cassette delivery apparatus of Fig. 6 over the support surface 85 in order to deposit tile pieces in a given arrangement onto that surface. The path so followed is generally serpentine so as to deposit the tiles in the most efficient manner possible. As is apparent from Fig. 11, the pick and place apparatus 100 loads the tile pieces into each cassette 82 in the order that these pieces will be dispensed along the predetermined path P to effect this efficiency of movement. Also, by providing a pick and place apparatus which is separate from the dispensing apparatus 34, parallel operations, i.e. tile dispensing and cassette loading, can take place, thereby further reducing the overall performance time for the system.

The simulated mosaic shown in Fig. 12a is comprised of three regular polygons, i.e. triangular 101, square 103 and hexagonal 105 shapes, which together create a desired image. Each polygon shape is respectively contained in one of three cassettes carried by the Y-carriage of the apparatus 36. As with the sleeves 46,46 of the drum type dispenser, each cassette has an interior passage correspondingly or otherwise compatibly sized and shaped to receive the tile shape and size

designated for it. Since the delivery means 84 of each sleeve is capable of being rotated about a rotational axis 90, the tile pieces can be deposited in infinite angular orientations thus leading to the creation of numerous artistic effects. Among these, as seen in Fig. 12a, is the slight skewing effect of the tile pieces off center from one another to simulate the effect of hand craftsmanship. To this end, the controller 4 is provided in memory with an appropriate program which causes the delivery means 84 to deposit the tilings in these desired angular orientations. In keeping with this aspect of the invention, and as illustrated in Fig. 12b, a randomizing program may be provided and used randomly to select the size and shape of the tile pieces and thereafter to locate them within a block 132 depicting the dimensions of the plate onto which the tilings will actually be bonded as will be discussed in greater detail with reference to Fig. 16b. This is done by designating one corner O as an origin, and thereafter breaking the block up into inclusive section 131, 131', 131'', each containing the point O as its congruent origin. Randomized selection and orienting of the shapes called for by the program are next fit into each section within certain tolerances starting from the section closest to the origin O. Each section is sized to receive the largest designated shape within the set tolerances, so that a total randomized fitting is accomplished throughout the block.

The rotatable feature of the delivery means in the apparatus 34 enables patterns, such as shown in Figs. 13a-13c which use combinations of triangular 101, square 103 and/or hexagonal 105 shapes disposed at different angular orientations, to be created as prescribed by the controlling algorithm. Also, this apparatus is particularly well suited for the creation of quasiperiodic patterns such as the one shown in Fig. 14a. The tilings used for this pattern, as shown in Fig. 14b, are two diamond-shaped pieces 113 and 113', each differing sizewise, but nevertheless having between them at least one equal side edge. These pieces are loaded into respective separate ones of the sleeves 79,79 and deposited at positions and in varying angular orientations prescribed by the rules governing quasiperiodic patterns to achieve the three dimensional effect illustrated in Fig. 14a.

Turning now to Figs. 15 and Figs. 16a, 16b, a method of laying out tile pieces in a desired pattern in accordance with the rules of pointillism is disclosed. The first step is in effect to generate an overall style or pattern to be followed by the tile pieces (Step 110). To this end, the user can generate the overall pattern using one of several different methods provided by the system. One option is to use data already stored in memory in the library 20 (Step 112) which is representative of the design to be portrayed. Alternatively, the desired design can be scanned from a photograph or other hard copy medium and subsequently translated by the imaging device 22 into digital format (Step 114). The design can alternatively be drawn using the editing device 24 to

create a desired tile pattern from scratch (Step 116). The editing device 24 may further be used in conjunction with the scanner or the library memory to alter the images that have been either scanned (Step 114) or downloaded from the library (Step 112), if change is desired (Step 118). In the case where scanning is used to initially generate a pattern, it must be determined from the graphic scanned whether or not the pattern lines to be followed by the tile pieces are discernible (Step 114). If such pattern lines are discernible, then the program returns to its main flow. However, if pattern lines are not recognizable, such as in the case of a photograph where only color or shade divisions exists, then the pattern lines to be followed by the tilings are defined in terms of color/ shade division or separation for the involved image (Step 114b). Thereafter, color or shade designations are assigned to each region of the pattern which are separated by the pattern lines (Step 114c). The assigning of color designations at this step is useful in two ways. The first may be the use of this information as a guide for the selection of precolored tilings using the pick and place system illustrated in Fig. 8, while the alternative use for this information would be to drive a tile painting machine to color regions on otherwise plain white tilings, such as shown in Fig. 21.

Next, the description of the tile pieces to be used is entered. The system assumes that all pieces are regular in shape. The user inputs the shape by the number of sides (n) of the tiling, i.e. (5) for a pentagon (4) for a square etc. The dimensions (D,d) of the shapes are also entered followed by any copy color or other designation, such as, for example material type, which may be required (Step 119). The dimensions (D,d) are controlled primarily by the sizes and shapes of the tile pieces available in inventory, and by those which are capable of being loaded into the supply sleeves of the dispensing devices. In the case where a discernible pattern is scanned, the shape (i.e. the number "n") of the tile piece is determined by a pattern recognition program while the dimensions of the tilings are calculated and scaled according to the sizes available in inventory.

Since it is ultimately the goal of the system to arrange tile pieces in a manner which fits the substrate surface intended to be covered, it is thus necessary to provide the executing program with data identifying the dimensions of that surface. The surface to be covered is assumed to be a planar. However, several such surfaces are capable of being portrayed, for example, as an interior space and oriented in three dimensions. Thus, three coordinate dimensions (X,Y,Z) for a given surface are entered (Step 120). Once the controller 4 receives the surface area dimensions input to it at (Step 120), it stores this data along with the data which represents the pattern to be portrayed input at steps 110-117 for use later.

Following this, the executing program translates the existent shapes, designs or patterns which were inputted into the computer at steps 110 through 117 into spa-

tially related tile arrangements based on the actual dimensions of the surface and the tilings to be used using known rules of pointillism or a randomizing function as discussed with reference to Fig. 12b. This process ultimately results in tile pieces each being assigned given X,Y coordinate locations on the plate material M to be covered with a tile piece. The collection of these coordinate locations reflects the creation of the overall mosaic.

The process (Step 122) followed for spatially relating one tile piece to the next is done by determining the locations of the vertices of the tilings relative to where they will lie on the substrate surface. The vertices of a tiling, as best shown in Fig. 16a by the letter V, are the junctures of the edges of adjacently positioned tilings. As discussed with reference to step 119, regular polygon shapes are identified by the value n representative of the number of sides for each shape. A polygon having "n" sides and therefore "n" corners, is identified, for example, as (3), if a triangle, as (4), if a square, etc. Since the program assumes tilings of nonrandomized edge-to-edge construction, that is, that each side of a tile is also the side of precisely another tile, the vertices of the tilings are thus regular and can be predicted.

In dealing with polygons of a regular shape, there are 21 known types of vertices possible for any combination of regular polygonals. These known vertex types are stored in memory to be recalled on an as needed basis once the combination of tilings surrounding a given vertex is known. Each vertex type is thus identified by determining the types of polygons which are fitted around that vertex (Step 122a). For example, in Fig. 16a, vertex "Vo" would be identified as (4,8,8) corresponding to the previously determined (n) sided polygons which surround it, taken in rotation in the direction shown by arrow "A". Using this initial identifying data, the types and positions of each remaining vertex in the design are determined based on the vertex Vo being the origin (Step 122b). This is done using the initial vertex Vo as a starting point in combination with the known dimensions D,d of the polygons which surround it. Subsequent vertex locations, such as that for V1, are determined horizontally along line Rh for the width dimension of the surface area to be covered, which dimension corresponds to the value X input previously. The vertical components of the vertex locations taken in the direction Rv above base line B are established relative to this line by again using the inputted dimensions (D,d) in conjunction with the data which identifies each vertex along the base line. In the case of the polygon array shown in Fig. 16a, the vertices of this arrangement are all of the same type. Thus, once the distances between vertices have been established in the Rh and Rv directions for a given arrangement of polygons fitted around a repeated vertex type, all subsequent vertices can thus be determined by positioning them at uniform intervals from one another (Step 122d) based on the data taken about vertex Vo. There are 11 such polygonal

arrangements in which all vertices are the same. These vertices are stored in memory and can be retrieved on an as needed basis as follows:

(36), (34.6), (33.42), (32.4.3.4), (3.4.6.4), (3.6.3.6),
(3.122), (44), (4.6.12), (4.82) and (63)

In the case where vertex types are not ones of the type listed above (Step 122c), a point by point determination of the placement of each vertex must be made based on an examination of the placement and type of vertex which precedes it (Step 122e) in the previously discussed manner.

The controller 4 thus effectively creates a theoretical arrangement of the tile pieces which is the direct result of the translating operation at (Step 122). However, this arrangement as denoted by the dashed lines in Fig. 16b depicts the theoretical juxtaposition of the tiles rather than actual and does not take into account the spacing S needed for grout to be applied between the tile pieces in patterns which call for it. Thus, (Step 124) the controller causes the theoretical juxtaposition of the tilings to be altered as shown in solid line by the pieces 123 to allow for the spacing S.

Once the actual positions of the tile pieces are calculated, the controller next lays out the tilings in terms of separate plates which will actually be laid down onto the substrate surface (step 126). This is done through an appropriate algorithm which causes the tilings as arranged in memory to be divided into blocks 132 having areas which depict areas of the plates 36,36 on which each tile piece will eventually be attached. A code is assigned to each of the blocks 132 to identify to the user where the plate is to be positioned on the substrate surface relative to other such plates. Then, the tile pieces are deposited onto the support surface 85 at predetermined X,Y locations as prescribed by the foregoing algorithms (Step 128). The code is marked as indicia 134 onto the plate by a marker or labeller 130 provided on the dispensing apparatus for the purpose of providing identification of its placement in the overall design (Step 129). The marker or labeller is preferably one manufactured by Gerber Garment Technology, Inc. of Tolland, Connecticut and disclosed in U.S. Patent No. 4,764,880 entitled COMPOUND PLOTTING APPARATUS AND RELATED METHOD OF OPERATION. Further, the plate material M on which the tile pieces are laid will usually be greater in area than the area allotted for the blocks 132, i.e. two or more blocks may actually fit onto the material M as spread over the support surface 85. To this end, the dispensing apparatus shown in Figs. 2 and 6 may include a roller cutter which depends, respectively, from the holding plate 36 and the Y carriage 86 of each illustrated device, and is sized to fit within the spacing S to cut the material M along lines corresponding to the dimensions of the blocks 132,132.

In addition to its use as a marker for making the indicia 134, the marker 130 is employed to draw an

edge line on the tile pieces which make up the end row of a given plate, denoting the line along which the tile pieces must be cut to effect an edgewise fit with the edge of the surface to be covered. The line is drawn on these tile pieces based on a determination of what portion of the end tiles extends beyond the vertical and horizontal extents (i.e. X,Y dimensions) of the involved surface.

In Figs. 17-20, several different embodiments of the material used for the plates are shown, each of which includes a specific means for securing the tile pieces 48,48 to the plate material. In Figs. 17a-17c, a first embodiment of a holding plate 150 is shown in fragmentary view. This plate includes a receiving means 154 comprised of a plurality of separate compartments or chambers 152 each defined by an upstanding wall 156 which separates the plate 150 into grids for receiving tile pieces in a defined angular orientation. A web 159 is provided and is disposed at the base of the partitioning walls at the intersection between adjacent side walls. The web provides a seat against which each tile piece sits and is prevented from passing through the plate from its bottom end. Each chamber at its top end has an inwardly directed flange 160 which acts as a detent to prevent the withdrawal of the tile pieces from the chambers 152. The material which constitutes the wall 156 and the flange 160 is formed from a pliable material, such as flexible plastic. The tile piece 162 shown in Fig. 17c is ready for snap in place insertion into the chamber 152 upon application of the downward force 164 applied by the rods 66,66 in a manner discussed previously with reference to the operation of the overall delivery mechanism.

In Figs. 18a and 18b, a second embodiment of a plate is shown. The tile pieces 184,184 are configured to be received within corresponding openings 193,193 formed in the plate 186. Each of the tile pieces for this purpose is generally T-shaped having an upper portion 181 and a lower portion 183 intersecting at a shoulder 194. Each of the plurality of openings 193,193 formed in the plate 186 has an inwardly directed groove 190 disposed about its perimeter. The groove 190 is sized to receive a correspondingly shaped and sized detent 192 disposed outwardly about a lower portion 183 of the tile piece 184. The shoulder 194 coacts against the upper surface 196 of the plate 186 to add further stability to the connection and is aided to these ends by the plate 186 having a given thickness T which is sufficiently sized to receive the depending end portion 183 of the tile piece 184.

Turning now to Fig. 19 and to an embodiment of a means and method by which the tile pieces are adhered to a plate material 166, it should be seen that this means and method includes a platen 168 having a heating element 170 which causes the top surface 172 of the platen to be heated once it is activated. Upon the surface 172 is placed the plate material 166 onto which the tile pieces are deposited by the apparatus in a man-

ner discussed previously. The plate material 166 is mesh-like in texture having a polymer base which bonds to the tile pieces deposited onto the surface 172 when the heating element is activated to thus bond the tilings in place.

Referring now to Fig. 20 and to an alternative embodiment of a method and apparatus for attaching tile pieces to a plate material, it should be seen that the tile pieces 174, 174 shown therein are modified versions of the tile pieces discussed previously in that each has a lower surface 176 on which is disposed a layer of activatable adhesive 178. The activatable adhesive layer 178 may be one which includes a plurality of microcapsules 180 which, upon the application of sufficient downward pressure, are caused to burst and release the encapsulated adhesive onto the plate material 149. Alternatively, the layer 178 may be one which employs air bubbles which burst to allow contact between a substrate and an adhesive layer. Such an adhesive is sold commercially by 3M Corporation under the tradename CONTROL TACK. The plate material 149 may be formed from medium weight paper and is sheet-like in form having a plurality of perforations 182 arranged uniformly in rows and in columns. These perforations permit the cement which bonds the tilings to the substrate to pass through the paper and adhere to the undersides of the tile pieces 174.

In Fig. 21, a spray jet head 200 is therein shown connected to the controller 4 for the purpose of marking, coloring or shading tile pieces in whole or in part. The head is used in place of the marker 130 and is vertically mounted to the drum portion of the device 32 and to the Y-carriage in the case of the cassette dispenser 34 such that the spray is directed downward and onto the tile pieces situated below it. At least four jets 202 are provided in the head, each responsible for respectively spraying the three primitive colors and black. In the embodiment where the head 200 is used, there is no need to separate tile pieces by color. Rather, tilings can be arranged so as to depict certain colored regions as discussed previously with reference to steps 114a-c and thereafter sprayed on. Alternatively, as shown in Fig. 22, the tilings used may be identical in shape and arrangement, but painted on by the head 200 such that each tile piece takes on a pixel-type character with respect to the overall design 206, or the tilings may simply be sprayed on without attempting to give each tile piece a discrete color designation. This approach results in a savings in the number of sleeves, cassettes or bins otherwise dedicated to color separation between inventoried tile pieces. The sprayed tile pieces are thereafter baked in accordance with normal tile making procedure, with the understanding that the material M be sufficiently resistant to the baking temperature.

By the foregoing description, a method and related apparatus for creating an ordered collection of plates with tilings arranged thereon in a predetermined orientation has been disclosed. However, it should be appre-

ciated that numerous modifications and substitutions may be made without departing from the spirit of the invention. For example, while the shapes of the tile pieces used are assumed to be regular, in actuality, the pieces used may be irregular but will be assumed to have a regular shape based on overall geometry of the piece.

Accordingly, the invention has been described by way of illustration rather than limitation.

Claims

1. A cassette (82) of the type receiving and storing articles in stack form further characterized by: a generally elongate tubular member (82) having a first end and an opposite second end and having an interior confine disposed therebetween, one of said first and second ends being provided with a means (98, 99) for releasably connecting the cassette to a tile piece delivery apparatus, and wherein said interior confine of said tubular member being compatibly shaped and sized to receive a plurality of tile pieces therein in a stacked arrangement.
2. A cassette (82) as defined in claim 1 further characterized by said means (98) for releasably connecting the cassette to a delivery apparatus is an annularly extending projection correspondingly sized and configured to be received within a similarly sized and shaped groove in the delivery apparatus.
3. A cassette (82) as defined in claim 2 further characterized by the one of said first and second ends being provided with a means for releasably connecting the cassette to a tile piece delivery apparatus further includes an annular chamfer (99) disposed about that end.
4. An apparatus for automatically assembling tile pieces in a predetermined arrangement to create a simulated mosaic containing the tile pieces attached to a material, said apparatus being further characterized by: a support surface (39) for providing a base support surface to which a material (36) is supported and onto which material tile pieces are deposited, delivery means (18) disposed in a spatial relationship relative to said base support surface for depositing tile pieces at predetermined locations onto the material (36) supported by said base support surface, drive means (31a, 31b, 130, 92) for controllably positioning said base support surface and said delivery means relative to one another to effect positioning of said delivery means relative to said base support surface at said predetermined locations, supply means (42, 82) communicating with said delivery means for providing a supply of tile pieces to be deposited on said support

surface through the action of said delivery means, control means (12) connected to said drive means and to said delivery means for controllably positioning said delivery means relative to said base support surface at said predetermined locations and for causing said delivery means to discharge a tile piece at one of said predetermined locations, and said predetermined locations being defined by control data used by said control means to effect positioning of said delivery means and said support surface relative to one another and to effect discharge of said tile pieces onto the material by said delivery means at said predetermined locations; and optionally further characterized by said control data being provided by input means (14) connected to said control means for providing said control data with a first set of data representing a desired pattern to be presented by said tile pieces and a second set of data derived from said first data set for controlling the movements of said drive means; and/or optionally further characterized by said supply means including means (42) for holding tile pieces of at least two types differing from one another by at least size and/or shape; and/or optionally further characterized by said supply means being comprised of an apparatus having a drum portion (42) having a central axis (54) extending parallel to its length, said drum portion including a plurality of sleeves (46,46) disposed concentrically about and extending parallel to said central axis, and said sleeves being internally sized and shaped to receive correspondingly or compatibly sized and shaped ones of said tile pieces (Fig. 2b); and/or optionally further characterized by said delivery means being a unit capable of being rotated about the circumference of said drum portion, said delivery means having a single discharge opening (61) which is controllably positionable beneath said drum portion to permit the discharge of a single tile piece at one of said predetermined locations on said base support surface; and/or optionally further characterized in that said delivery means includes a planar holding member movable relative to said drum and having an off-set closure member (60) connected to it and forming a chamber (62) associated with said discharge opening, said delivery means further including an actuated shuttle member (68) moveable between a retracted position and an extended position in which extended position tile pieces are caused to be deposited on said base support surface; and/or optionally further characterized in that associated with each sleeve is a reciprocating rod (66) journaled within said drum portion so as to be capable of striking a tile piece being moved to said discharge opening (61) by said shuttle member; and/or optionally further characterized in that said base support surface is a part of a platen (38) and

said drive means is a X,Y positioning system connected to said platen for positioning it relative to said delivery means, and wherein said platen is caused to be moved in a path (Figs. 4a, 4b) whereby tile pieces from a given sleeve are first deposited along a given route followed by tiles from a second given sleeve in sequence until all of said predetermined locations on said surface are covered by a tile piece.

5. An apparatus as defined in claim 4 further characterized in that said supply means includes at least one cassette (82) in which are disposed a plurality of tile pieces, said at least one cassette having a central axis (90) and being an elongate tubular member having releasable connecting means formed at its lower end; and/or optionally further characterized in that said delivery means comprises at least one unit (84) capable of being rotated about the central axis (90) of said at least one cassette, said delivery means having a single discharge opening which is controllably positionable beneath said at least one cassette to permit the discharge of a single tile piece at said predetermined location on said base support surface; and/or optionally further characterized in that said delivery means and the cassette associated with it are carried by a first carriage (86) moveable in a first coordinate direction and said first carriage being disposed on a second carriage (88) moveable in a second coordinate direction disposed orthogonally to the first; and/or optionally further characterized in that said delivery means includes a plurality of units (Fig. 6) each respectively connected for communication with a cassette, each of said cassettes being generally tubular in form and internally sized and shaped to receive correspondingly or compatibly sized and shaped tile pieces of different types; and/or optionally further characterized by said apparatus being part of a system and said system comprising a pick and place mechanism (100) connected to said control means, said pick and place mechanism having means capable of stacking into a cassette (82) selected tile pieces; and/or optionally further characterized in that said pick and place mechanism is comprised of an arm (106), said arm being a cassette and said tile pieces which are received within said cassette are maintained in bins (102) such that individual ones of the tiles can be received within said cassette by engaging the free end thereof with one of the bins (Fig. 9); and/or optionally further characterized in that said pick and place means (100) assembles said tile pieces in a given one of said cassettes in accordance with the order (Fig. 11) in which the tile pieces will be dispensed along a path (P) to be followed by said delivery means over said support surface to deposit individual ones of said tile pieces

at said predetermined locations on said base support surface (Fig. 10).

6. An apparatus as defined in claim 4 further characterized in that said base support surface is part of a platen (168) and said base support surface is adapted to support plate material on which are deposited said tile pieces at said predetermined locations, and said platen includes a heating element (170) and said plate material is a thermally sensitive material such that upon placement of said tile pieces thereon and subsequent activation of said heating element, said tile pieces are caused to bond with said plate material; and/or optionally further characterized in that each of said tile pieces (174) includes a layer of adhesive attached to the bottom surface thereof, and wherein said layer of adhesive (178) includes a plurality of bubbles which upon the application of adequate downward pressure causes said bubbles to rupture and the adhesive to attach to said plate material; and/or optionally further characterized in that said plate material includes a sheet of paper (149) having a plurality of perforations (182) formed in it; and/or optionally further characterized in that said plate material (150) is provided with a plurality of chambers (152) each defined by intersecting upstanding walls, and wherein a web (159) is provided at the intersection between upstanding walls to provide a seat against which the bottom of a tile piece sits; and/or optionally further characterized in that said plate material (186) is comprised of a sheet having a given thickness and having a plurality of openings (193,193) formed therein, said tile pieces (184) each having upper (181) and lower (183) portions defining a shoulder engagable with said sheet, and means (190,192) provided in each of said openings and said tile pieces for connecting the tile pieces with the sheet; and/or optionally further characterized by a spray jet means (202) connected to said control means (12) and moveable relative to said base support surface for causing spraying of tile pieces once the tile pieces are assembled on said plate material.
7. A method for automatically assembling tile pieces in a given arrangement, the collection of which tile pieces creates a simulated mosaic, said method being further characterized by: providing data representing a graphic to be depicted by tile pieces when arranged in a given orientation, providing plate material (36) and supporting it relative to a delivery means for receiving said tile pieces deposited onto it by said delivery means, providing delivery means (32) for depositing tile pieces at predetermined locations to arrange the tile pieces in said given orientation, providing a supply of tile pieces (42, 82) and associating said supply with

said delivery means to supply said delivery means with tile pieces, inputting parameters corresponding to size, shape, and/or color of tile pieces to be used in creating said given orientation of said tile pieces (Step 100), using said parameters as data to create control data to drive said delivery means to controllably cause the delivery means to deposit a tile piece on the plate material (36) at one of said predetermined locations; and/or optionally further characterized in that said step of using said parameters to create control data includes the steps of assuming the shape to be used in the tile arrangements as being regular, defining the shape of the tile piece by a number (Step 119), defining at least one dimension of the tile shape, determining at least one vertice type (Vo) by establishing the defined shapes of the tile pieces which surround said at least one vertice (Vo), and calculating the spacing between vertices using the given dimension of the tile shapes and the at least one vertice type established (Fig. 16a); and/or optionally further characterized by inputting as said parameters first and second dimensions defining the surface on which the tile pieces are to be placed (Step 120), and calculating the vertice spacings along said first and second dimensions of the surface area to be covered (Steps 122a-122e); and/or optionally further characterized by using said at least one vertice (Vo) as an origin and establishing a base line from that origin, determining whether said at least one vertice type is repeating or nonrepeating, and if the vertice is a repeating one (Step 122c), uniformly spacing the remaining vertices relative to one another (Step 122d), and if the at least one vertice is nonrepeating, then determining the positions of the remaining vertices on a point by point basis (Step 122e); and/or optionally further characterized by said spacing between said vertices being taken theoretically and subsequently altering the positions of the tile pieces to allow actual spacings to exist between said tile pieces (Step 124), and marking said tiles based on the actual arrangement of tiles (Step 129); and/or optionally further characterized by determining the position of said tile pieces as they would appear on the surface to be covered after accounting for said actual spacing which may exist therebetween, and dividing the determined arrangement of tilings into blocks (Step 126) representative of the plates to be applied to the substrate, and providing means for coding said plates (Step 129) such that the plates when applied to a surface can be arranged according to the code in an orientation which depicts the overall arrangement of the tile pieces; and/or optionally further characterized by providing said delivery means with a means for dispensing onto said plate material tile pieces of different shapes and/or sizes; and/or optionally further characterized in that said delivery

means includes at least one delivery sleeve (82) adapted to carry tile pieces, said delivery means associated with said sleeve being capable of rotating about 360 degrees to orient each tile piece in accordance with a predetermined orientation as set forth by the control data; and/or optionally further characterized by using said delivery means to randomly place tile pieces of different sizes and/or shapes onto said plates material in differing angular orientations (Fig. 12b); and/or optionally further characterized by the step of randomized placing of tile pieces being effected by dividing an area representing a plate into sections (131, 131', 131''), each section capable of fitting the largest shape into it, and filling one section at time with a random selection and orientation of tile pieces; and/or optionally further characterized in the by providing a plurality of sleeves each containing a diamond shaped tile piece and said control data containing instructions for depositing said diamond shaped tile pieces in orientations to replicate a quasiperiodic pattern (Fig. 14a); and/or optionally further characterized by providing a plurality of sleeves each containing three regular polygons each having equal side edges such that they are discharged onto the plate material to create a monohedral tiling (Fig. 13a); and/or optionally further characterized by providing a spray jet means (202) and separating tile pieces from one another by shape and size, and depositing the tilings onto the plate material and thereafter causing said spray jet means to spray discrete ones of the tile pieces with a predetermined color (Fig. 22); and/or further characterized by causing said delivery means to discharge the tile pieces at slightly skewed orientations relative to an otherwise off-axis orientation to generate a look of hand craftsmanship (Fig. 12a).

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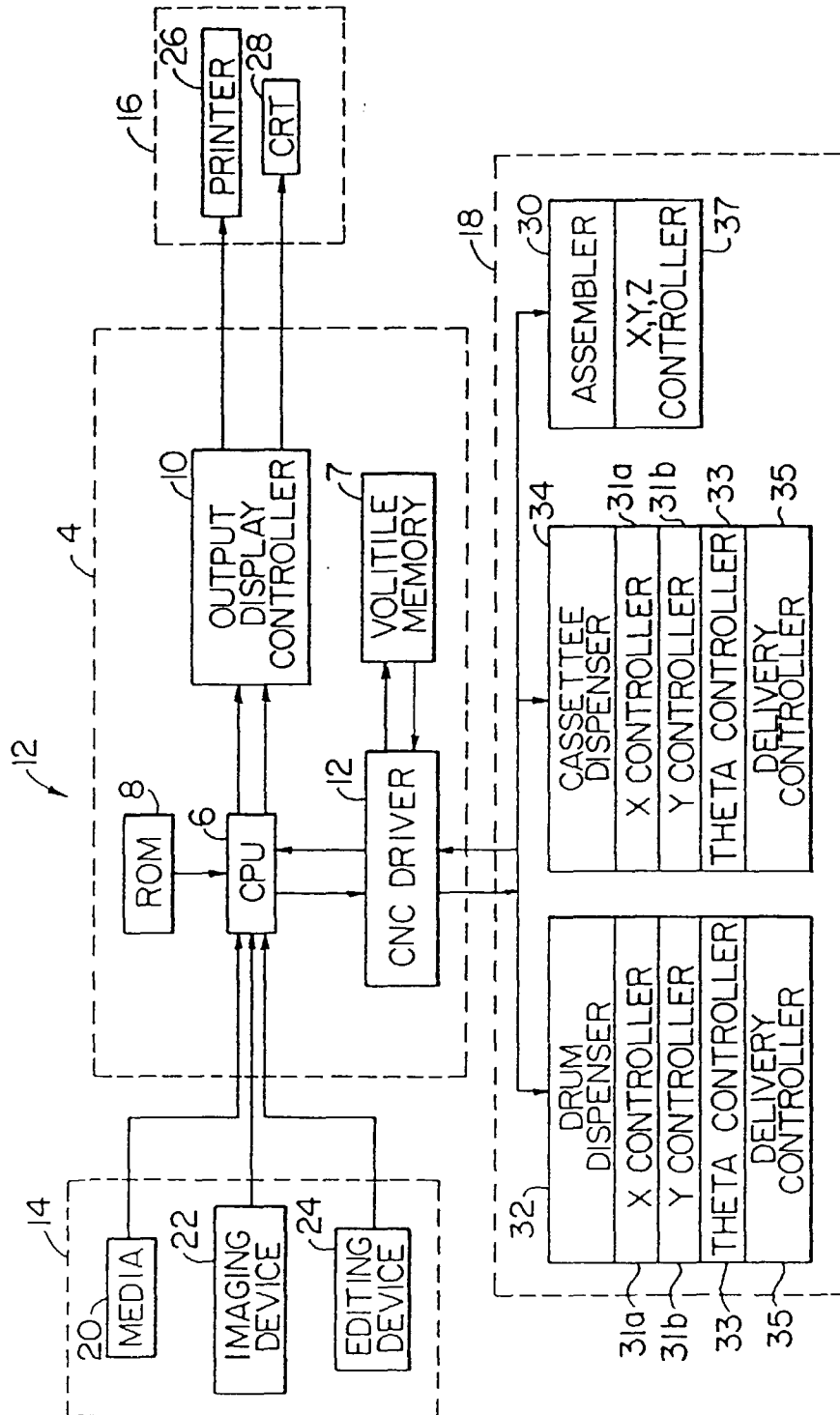
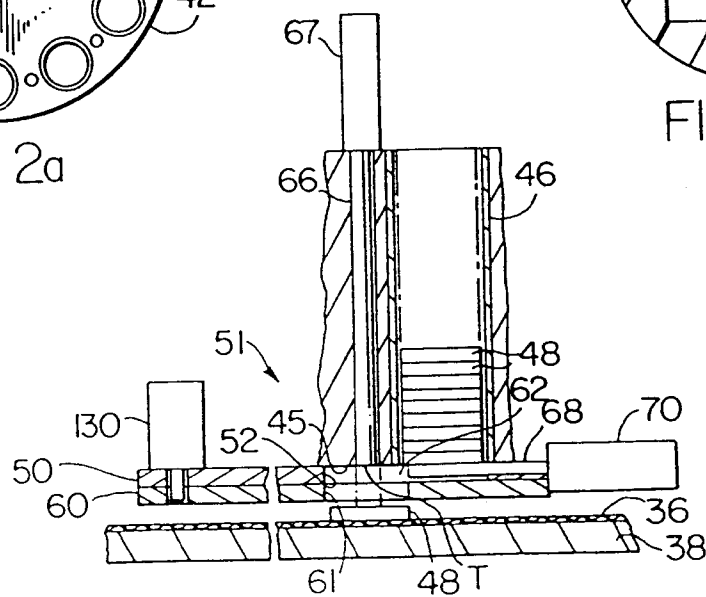
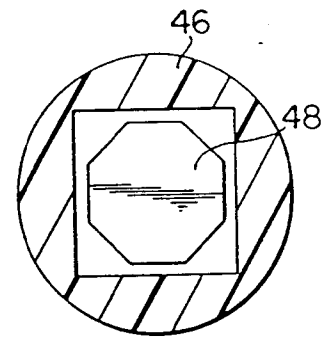
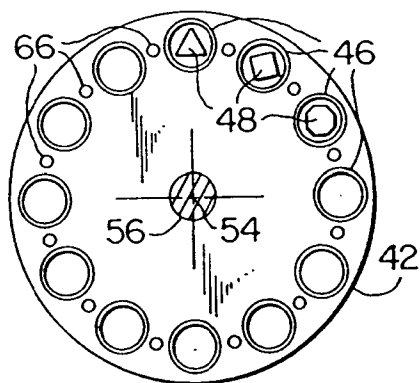
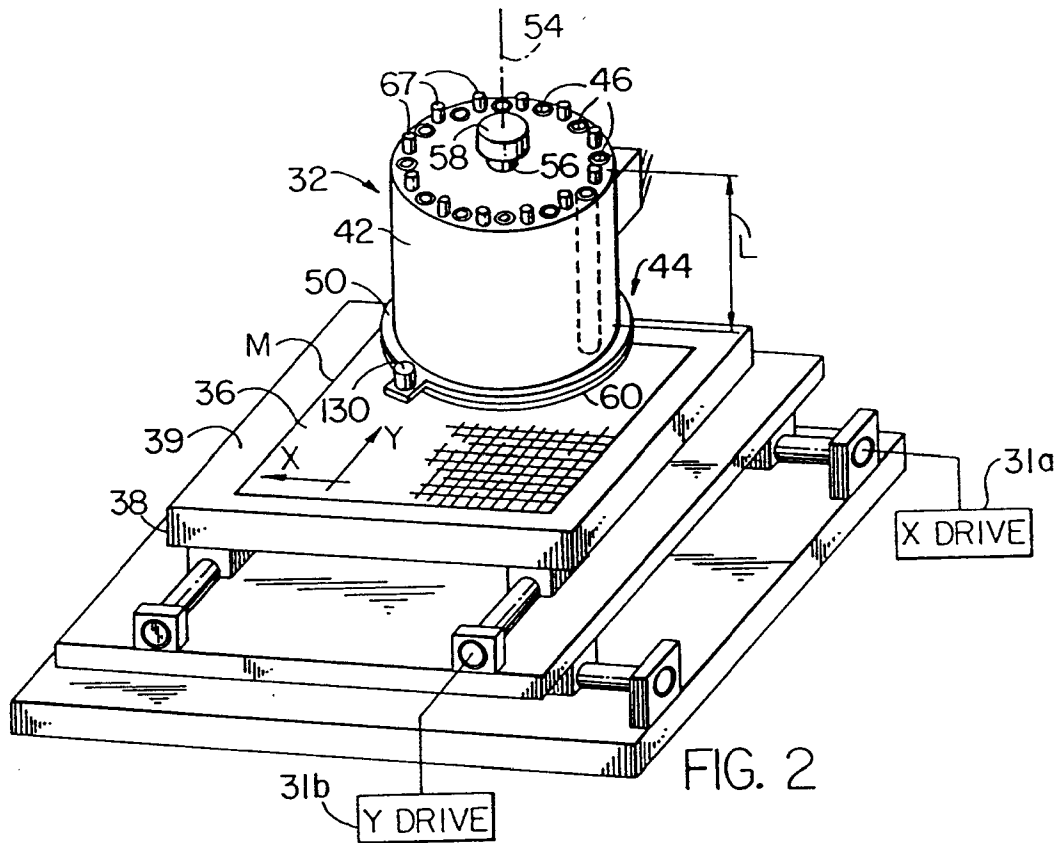


FIG. 1



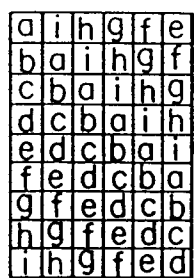


FIG. 4a

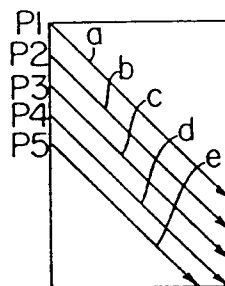


FIG. 4b

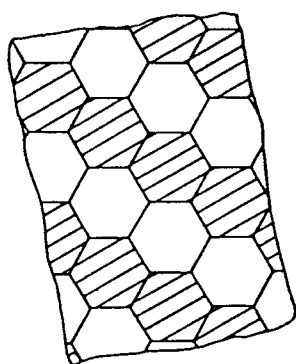


FIG. 5a

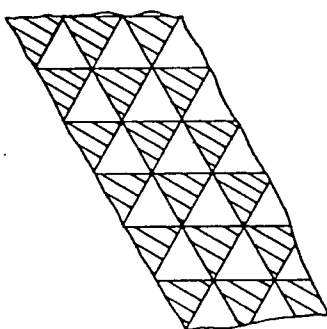


FIG. 5b

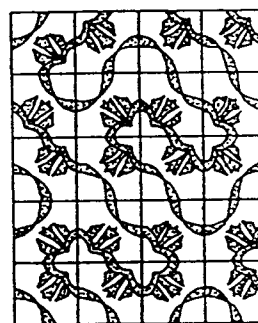


FIG. 5c

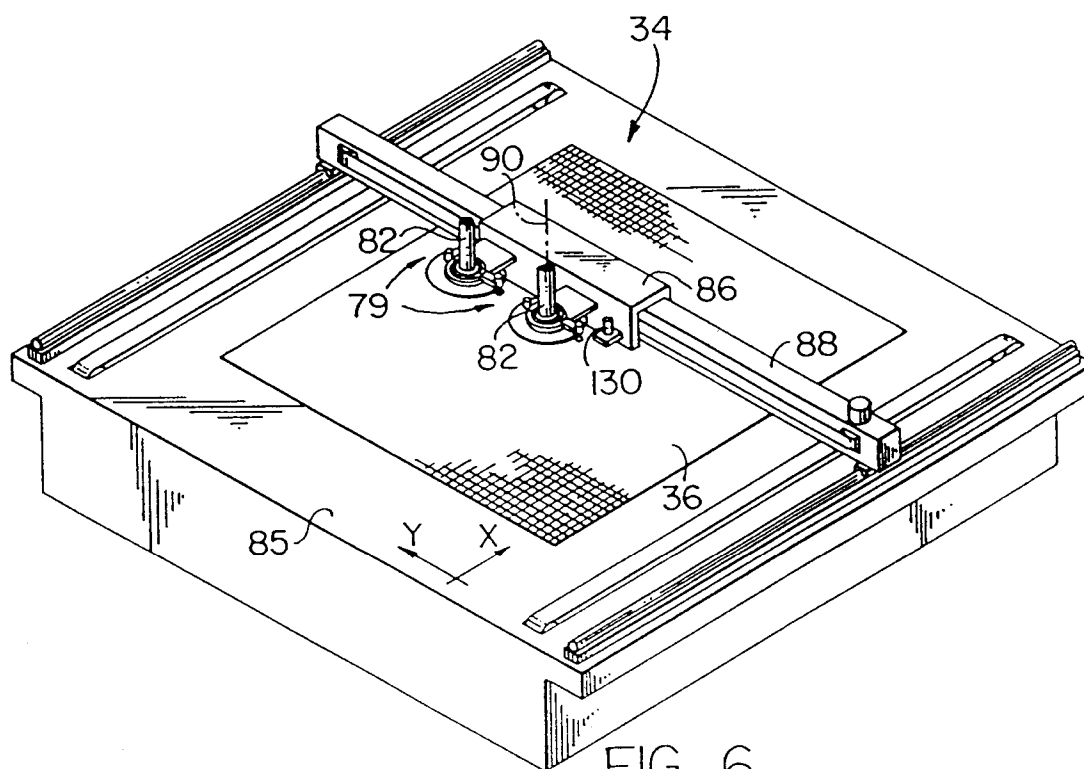


FIG. 6

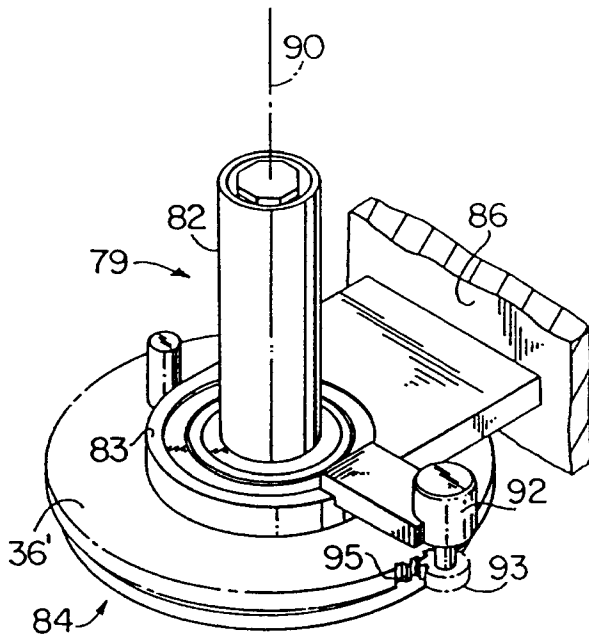


FIG. 7

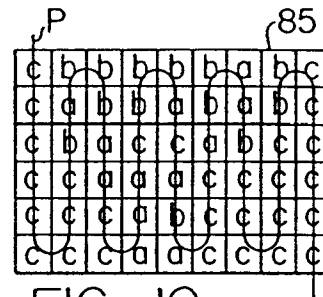


FIG. 10

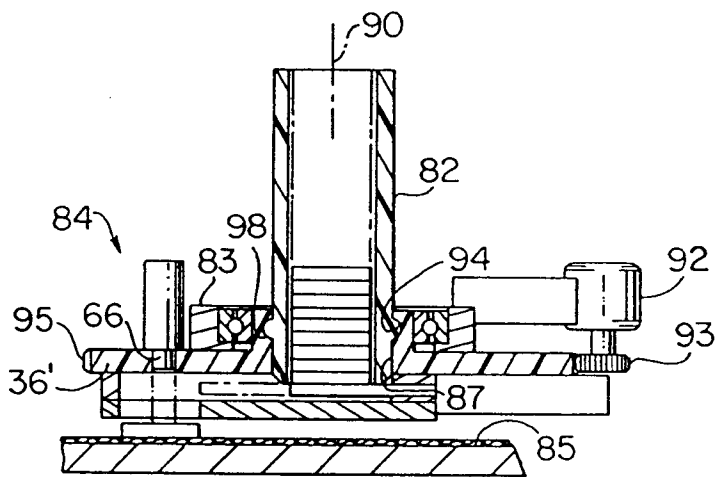


FIG. 7a

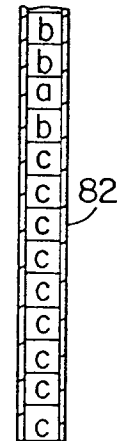


FIG. 11

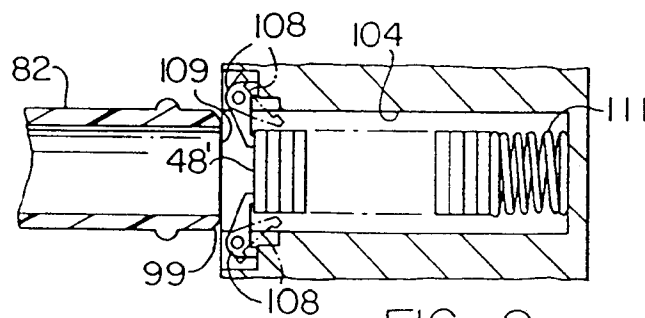
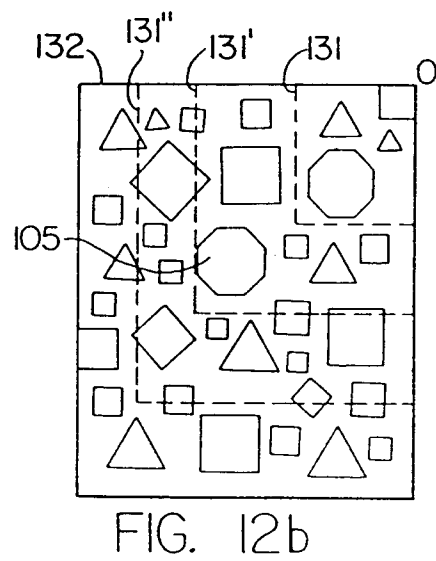
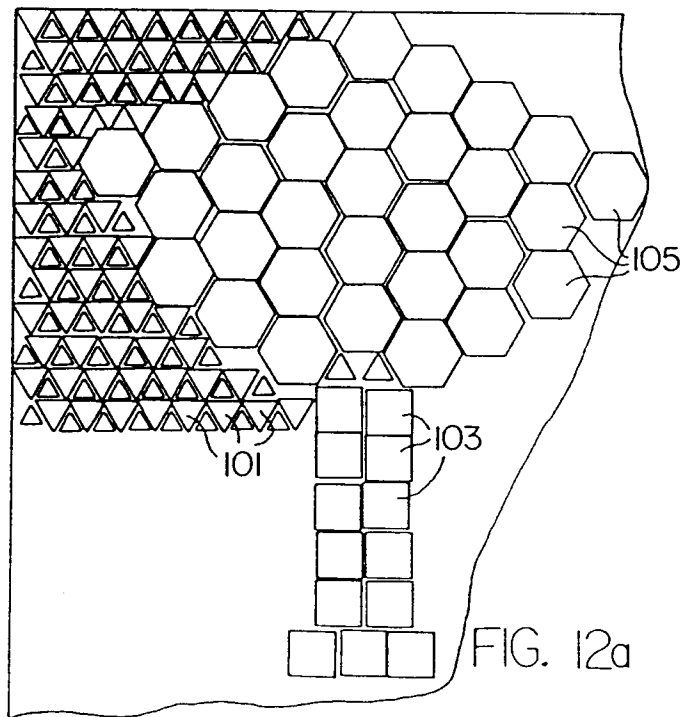
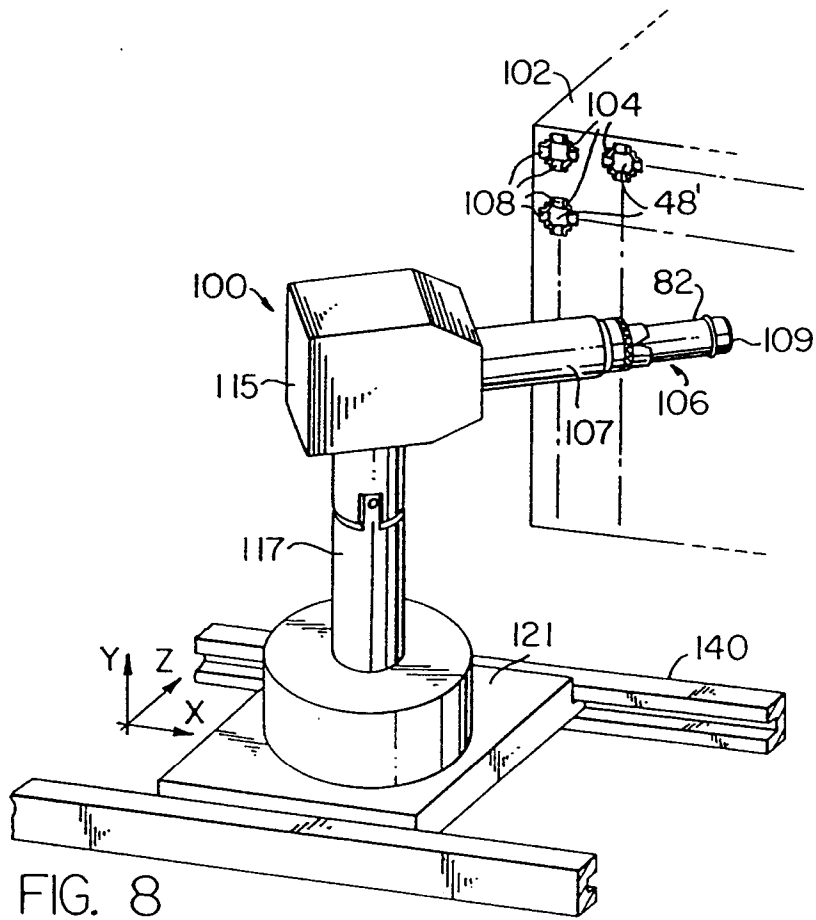


FIG. 9



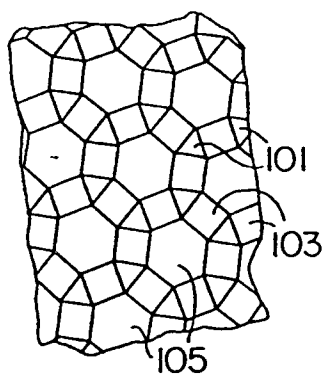


FIG. 13a

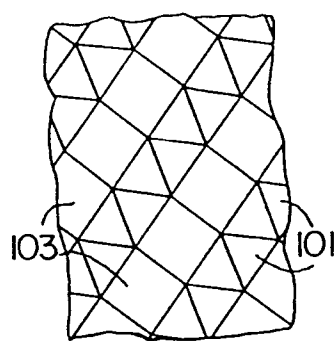


FIG. 13b

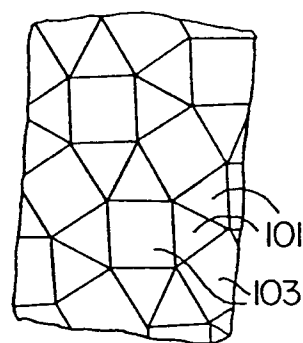


FIG. 13c

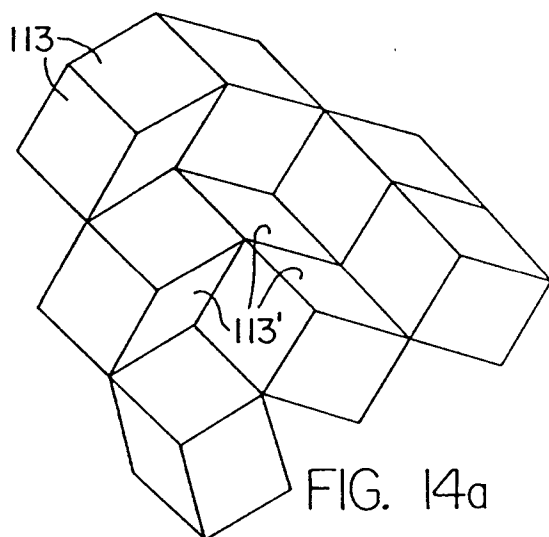


FIG. 14a

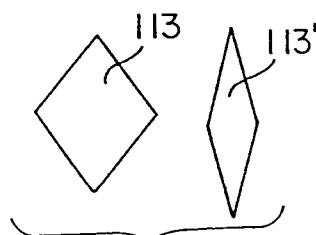


FIG. 14b

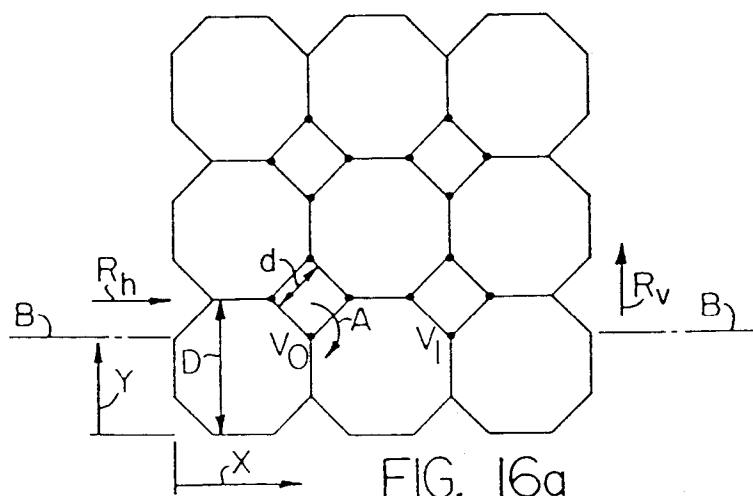
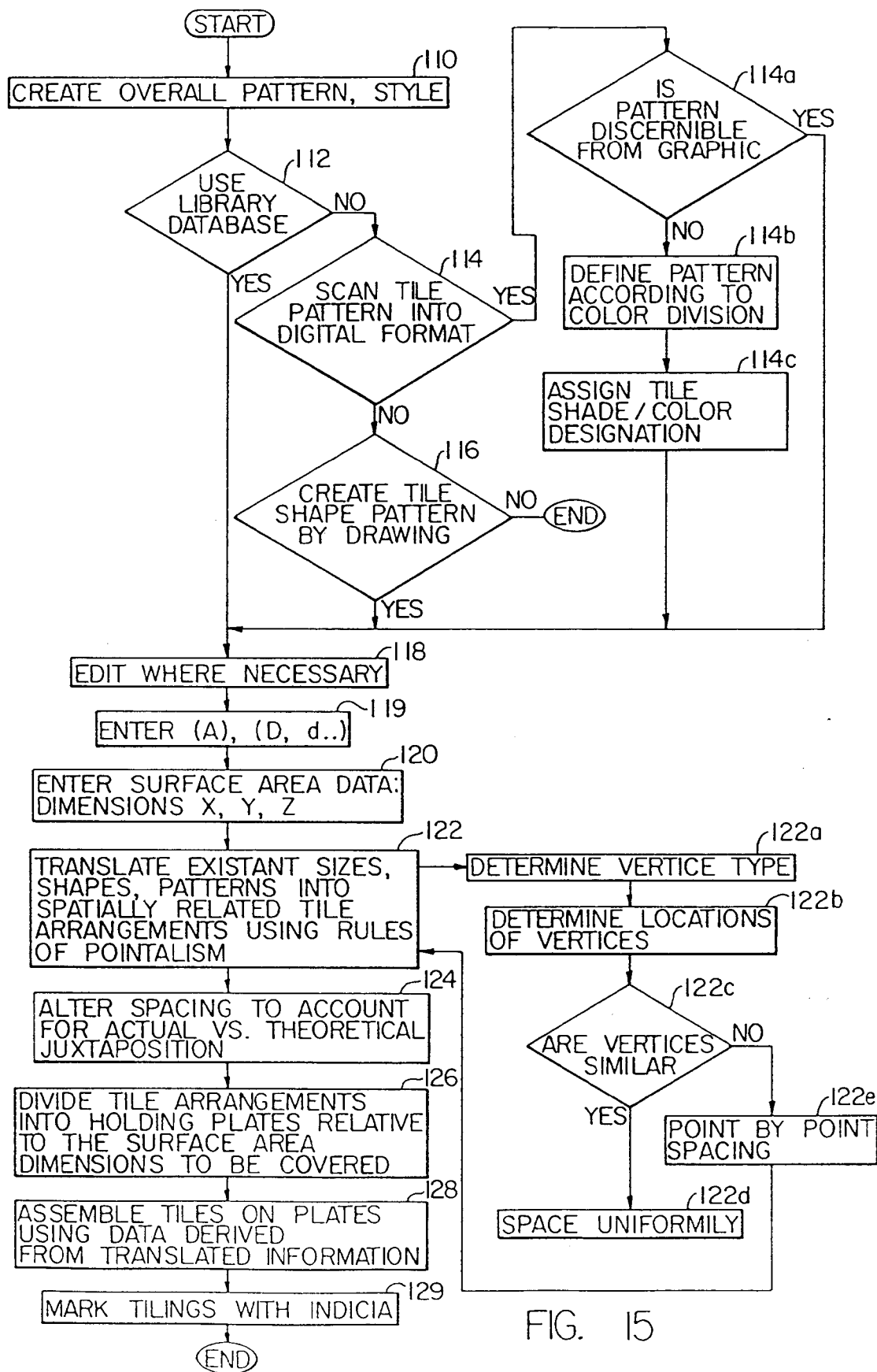


FIG. 16a



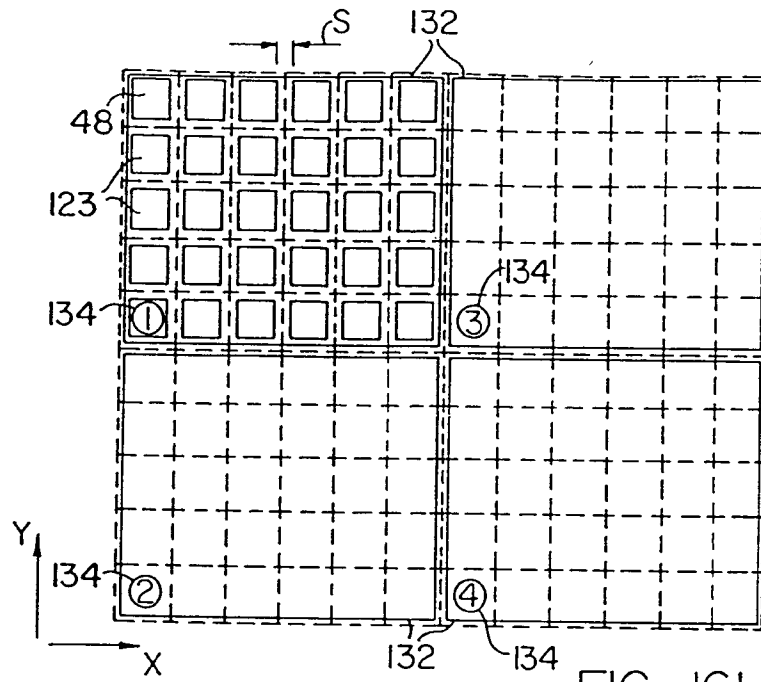


FIG. 16b

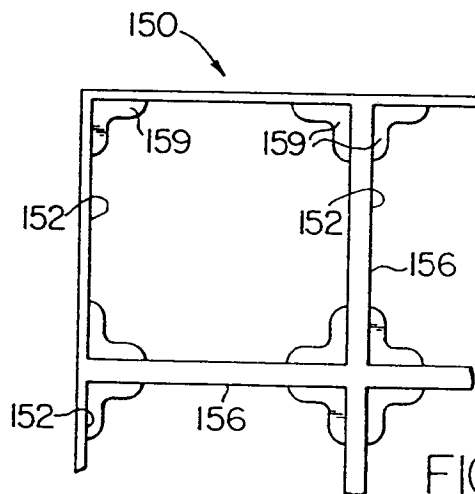


FIG. 17a

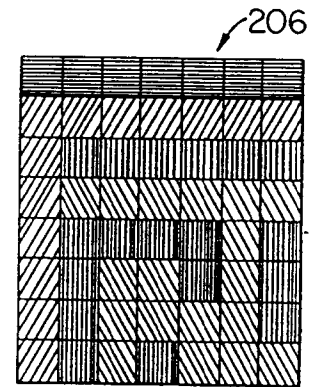


FIG. 22

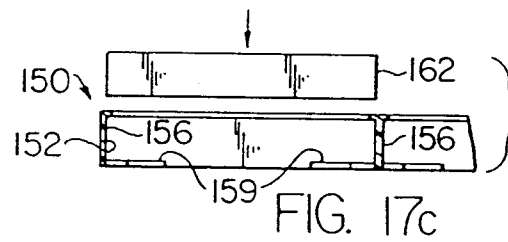


FIG. 17c

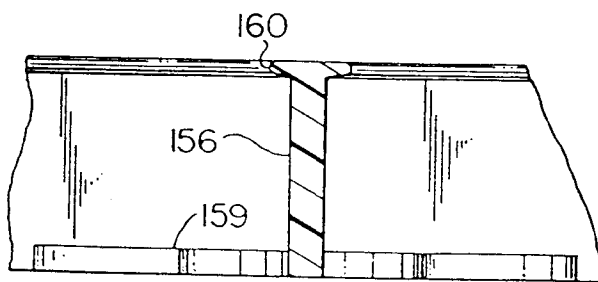


FIG. 17b

