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(11) **EP 1 029 692 B9**

(12) **CORRECTED EUROPEAN PATENT SPECIFICATION**

Note: Bibliography reflects the latest situation

(15) Correction information:
Corrected version no 1 (W1 B1)
Corrections, see page(s) 2, 4

(51) Int Cl.7: **B41J 2/505**, B41J 29/393,
B41J 2/165

(48) Corrigendum issued on:
03.12.2003 Bulletin 2003/49

(45) Date of publication and mention
of the grant of the patent:
02.05.2003 Bulletin 2003/18

(21) Application number: **99301170.9**

(22) Date of filing: **17.02.1999**

(54) **Printing apparatus**

Druckvorrichtung

Appareil d'impression

(84) Designated Contracting States:
DE GB NL

(43) Date of publication of application:
23.08.2000 Bulletin 2000/34

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Description

[0001] The present invention relates to determining the relative location of components of a printing apparatus, for example a large format printer. In particular, in inkjet printers having a printhead service station, there is a need to accurately position the inkjet printheads relative to their respective service station cartridges.

[0002] The service station is an essential subsystem in printers based on thermal inkjet technology (TIT). Its main purpose is to maintain optimal print quality and to do so, it can act on the printhead or pen in different ways (such as wiping, spitting...). These actions are termed "servicing primitives". They are arranged in complex sequences (servicing algorithms), that are executed in response to various triggers.

[0003] The functions a service station provides depend on the architecture, but as the printhead complexity increases, more and more sophisticated features need to be implemented. For instance, in the present printing apparatus there may be up to eight different "primitives", namely: capping, spitting, wiping, PEG (i.e. the application of polyethylene glycol liquid), scraping, snout wiping, priming and drop detection. Since the volume occupied by the service station is much the same as in previous products and because more functionality has been added, there is less space available for each "primitive".

[0004] The servicing functions can work correctly with a maximum placement error of 0.8 millimetres for the scan axis. The service station axis substantially perpendicular to the scan axis is somewhat more tolerant accepting up to 1.5 millimetres. Unfortunately, the mechanical tolerances alone, while meeting the goal in the service station axis, are unacceptable for the scan axis (the worst-case placement error is 1.4 millimetres).

[0005] Therefore, a method of reducing tolerance problems along the scan axis is required.

[0006] One possible way would involve an expensive production process with better tolerances. An alternative is to calibrate the error out of the system. This determines the physical position of the components and adjusts each function based on this measurement.

[0007] The printers in the series HP Designjet 2000 and 2500, first marketed in March 1997, adopted the solution of placing an optical reference mark on the service station housing which is scanned by an optical sensor mounted on the printer carriage. This did not allow for any tolerances between the housing and the position of the service station cartridges within the housing. Moreover, no measures were taken to allow for possible variations in the relative positions on the printer carriage of the optical sensor and the printhead cartridges. Such prior art printers are disclosed in U.S. patent application 09/031115.

[0008] EP-A-0863009 *[deletion(s)]* discloses an optical encoding arrangement incorporating a marker for orientation on a service station carriage and a label for

carrying information related to service station functions. The service station module may incorporate holes for storing and conveying information.

[0009] The present invention seeks to overcome or reduce one or more of the above problems.

[0010] According to a first aspect of the present invention, there is provided a method of determining the relative location of a component of a printer apparatus with respect to a printhead carriage of the printer apparatus, said component comprising one or more sub-units co-operating with a corresponding number of printheads on the carriage, wherein a sensor is used to determine the position of a reference location on said component relative to the sensor, characterised in that the sensor is also used to determine the position of at least one printhead relative to the sensor.

[0011] According to a second aspect of the present invention, there is provided a method of relatively locating at least one component of a printer apparatus to a printhead mounted on a printer carriage, wherein an optical sensor mounted on the carriage is used to scan a reference location on the component, characterised in that there is also determined the relative location of the optical sensor to the printhead on the printer carriage.

[0012] The sensor is preferably an optical sensor and, to determine the relative location of the optical sensor to the printhead (K), the printhead is caused to print during a carriage movement a reference mark extending substantially in the direction of the media axis, and the optical sensor subsequently scans the reference mark along the scan axis and there is determined therefrom the sensor to printhead distance ("j") in the direction of the scan axis. The reference mark is preferably a straight line.

[0013] In a preferred method the step of determining the sensor to printhead distance (j) is preceded by causing the printhead (K) to print a reference mark in the direction of the scan axis, then using the optical sensor to scan the reference mark along the media axis of the printing apparatus, and then determining the sensor to printhead distance (r) in the direction of the media axis and taking into account its effect on the determination of the sensor to printhead distance (j) in the direction of the scan axis. The reference mark extending in the direction of the scan axis is also preferably a straight line.

[0014] The components may be one or more service station insert members mounted in a service station. The insert members are preferably cartridges which perform various servicing functions and may each be associated with a respective printhead.

[0015] According to a third aspect of the present invention, there is provided an inkjet printing apparatus comprising one or more printheads mounted on a printer carriage and means for determining the position of at least one other component of the printing apparatus relative to the or each printhead, said determining means comprising a sensor mounted on the printer carriage, characterised in that calibration means are provided

which determine the relative positions of the sensor and the or each printhead. The sensor is preferably an optical sensor.

[0016] The component(s) may be one or more respective service station insert members mounted in a service station, the sensor being an optical sensor, means being provided which define one or more reference locations within the service station area, the reference locations being optically detectable by the optical sensor, and the or each reference location being provided on a respective service station insert member.

[0017] Preferably each reference location is constituted by a through hole in a part of the respective service station insert member, e.g. in its handle or lid.

[0018] Preferably, each service station insert member has a respective reference location. These locations may be averaged to reduce any residual errors.

[0019] A preferred embodiment of the present invention will now be described, by way of example only, with reference to the accompanying drawings, of which:

Fig. 1 is a partial perspective view of part of the optical sensor and a reference mark of a prior art printer;

Fig. 2 is a schematic front sectional view of the parts of a printing apparatus used for determining the relative location, the view being taken in a plane which bisects the printer components in the direction of the paper axis;

Fig. 3 is a top plan view of the printing apparatus of Fig. 2;

Fig. 4 is a front view of the printing apparatus with its printheads capped;

Figs. 5a and 5b are diagrams illustrating the distance calibration along the media advance axis;

Figs. 6a and 6b are diagrams illustrating the distance calibration along the scan axis;

Figs. 7a and 7b are optical sensor waveforms obtained with clean and dirty service station cartridges respectively; and

Fig. 8 shows the printouts produced on the print medium during calibration.

[0020] Referring to the drawings, Fig. 1 shows a prior art arrangement illustrating the type of location system used in Hewlett-Packard Designjet printers in the 2000 and 2500 series. Fig. 1 corresponds to Fig. 13 of the previously-mentioned pending U.S. patent application 09/031115. An optical sensor 17 including a light emitting diode and a photocell (not shown) is mounted on a printer carriage 10. A service station housing 24 is of

black plastics material and has a mount section 71 for an insert section 70 which is of white material for the purposes of contrast. Section 70 has a white top surface 75 which defines a rectangular slot 76 to constitute a reference mark which is traversed by the sensor 17 to locate its position relative to the printer carriage 10.

[0021] Figs. 2 and 3 show front and top plan views of a printing apparatus 100 in accordance with the present invention. Mounted on printer carriage 110 are a black printhead or pen K, three colour printheads C, M and Y, e.g. cyan, magenta and yellow, and a line sensor 117 incorporating a light-emitting diode and a photocell. The end 111 of carriage defines its position along the scan axis 120, which has a point of origin at a right bump position 122. Also illustrated in Fig. 2 are a "LED to K" distance "j" and a "carriage edge to K" distance "q" along the scan axis.

[0022] A service station 130 is located adjacent to one end of the carriage scan axis and comprises four respective service station insert members. The insert members are manufactured independently and subsequently inserted in the service station housing. The insert members are preferably service station cartridges incorporating four printhead cleaners 130C, 130M, 130Y, 130K, corresponding to the four colour printheads. As shown in Fig. 3, each cleaner lid has a handle or grip portion 131 which includes a through hole or slot 132 adjacent to and at a predetermined distance from one end of portion 131. At a central position of each portion 131 there is attached a label 133 which is originally blank but is subsequently inked to represent use of the printing apparatus. The label may incorporate information in written and/or coded form indicating the appropriate type of ink.

[0023] Because the nozzles of each printhead are spaced transversely to the scan axis, and because the printer carriage 110 moves continuously during printing, it is known to angle the printheads C, M, Y, K by a small angle of 1.79° relative to the true perpendicular direction, and this is shown in exaggerated fashion in the top plan view of Fig. 3. Of course, the printhead cleaners are also slanted at the same angle so that the paper movement axis 140 is at 1.79° to the so-called service station axis 142.

[0024] Fig. 3 also indicates a "LED to K" distance "r" (distance between centres) along the paper axis. Both Figs. 2 and 3 also indicate a reference hole 132 to printhead cleaner centre distance "s".

[0025] Fig. 4 is a view corresponding to Fig. 2 but with the printheads C, M, Y and K in their capped disposition, with carriage edge 111 in its "capping position". As will now be described, the purpose of the calibration process is to ensure that each printhead is aligned as accurately as possible with the centre of its corresponding cleaner.

[0026] The calibration process comprises the following steps:

a) LED Calibration

[0027] To have an optimal signal-to-noise ratio when using the line sensor 117, the printer needs to ascertain the optimum gain and LED type for the particular printing medium type which is loaded. This is accomplished by LED calibration by printing a black box 150, Fig. 8 on an inserted paper sheet 155, and then scanning over the black box and the adjacent white area. In practice, box 150 is printed solidly in black ink. The line sensor control block then modifies its internal parameters to work optimally in this range.

b) Drop detector calibration for the K printhead

[0028] The following step c) of the process involves the printing of a line in the direction of the scan axis. Since such a pattern is very sensitive to "nozzles out" (a nozzle out at the boundary produces an error of one dot), step b) involves facilitating the avoidance of such an error. To achieve independence from the K printhead status, the drop detector is calibrated and a drop detection process is then performed to look for a group of 32 consecutive working nozzles. This information is used subsequently when drawing the line in the direction of the scan axis.

c) Line sensor-to K pen distance "R" calibration for the media axis

[0029] A reference mark in the form of a black line pattern 144, Figs. 5a and 8, of 32-nozzle height "w", is drawn in the direction of the scan axis, in this case horizontally. Healthy nozzles are used, as a result of step b). Sensor 117 then scans (with bottom-up scanning) along the paper axis 140, to produce the sample shown in Fig. 5b, and the distance "r" from the line sensor to the K printhead is then determined, taking into account which 32 nozzles were used. Knowing the distance "h" of the first nozzle reached from the centre of the printhead, one obtains the result:

$$r = p - p' - h - w/2$$

where p represents the position of the centre of the printed line and p' represents the position as read by the sensor.

d) Line sensor to K pen distance "j" calibration for the scan axis

[0030] A reference mark in the form of a black line 146, Figs. 6a and 8, is drawn, by firing the K printhead during a carriage movement. The line 146 extends substantially in the direction of the media axis, in this case substantially vertically. As explained above, this pattern will actually have a slant of 1.79°. Sensor 117 then scans

(with left to right scanning) along the scan axis 120, to produce the sample shown in Fig. 6b, and the distance "j" from the line sensor to the K printhead is then determined. Knowing the distance "r" relating to the paper axis, one obtains the result:

$$j = p - p' - r \tan 1.79^\circ$$

where p represents the position of the centre of the printed line and p' represents the position as read by the sensor.

[0031] In practice, lines 144 and 146 are printed solidly in black ink.

e) Detection of printhead cleaners to determine the capping position

[0032] The line sensor 117 is then scanned over the portions 131 of the printhead cleaners, typically obtaining a waveform as shown in Fig. 7a for new printhead cleaners. The small "bumps" at the extreme left and right of the waveform represent the edges of the service station housing. The waveform in between represents features of the service station cartridges, and in particular, from the left, the vertical lines represent respectively:

left end of cartridge portion 131
left side of hole 132
right side of hole 132
left side of label 133
right side of label 133
right end of cartridge portion 131
left end of portion 131 of next cartridge etc.

[0033] The scanning process includes the following steps:

(i) Signal treatment

[0034] This involves signal normalization, non-linear morphological filter and derivative calculation. This normalizes the signal and eliminates noise peaks and valleys which could adversely affect the following steps.

(ii) Cross-shape recognition

[0035] This enables determination of the approximate position of each printhead cleaner cartridge. The samples are then divided and analyzed separately.

(iii) Feature extraction

[0036] For each printhead cleaner the various edges, holes and marks are identified. The position of hole 132 is selected as the most accurate indicator. The positions of the holes for the four service station cartridges are indicated at 132C, 132M, 132Y and 132K in Fig. 7. Fig.

7b indicates a waveform corresponding to Fig. 7a but of a dirty printhead cleaner, e.g. after a prolonged period of use. Despite general deterioration of the waveform because of ink covering portions 131, the locations of the through holes 132 are still distinct because they provide a sharper contrast.

(iv) Determination of centre of service station cartridges

[0037] This is simply achieved by adding the distance "s" to the hole positions.

(v) Determination of "K printhead to K service station cartridge" distance

[0038] Once the location of the centre of the cartridge 130K relative to the line sensor is known from step (iv), the position relative to the K printhead can be calculated simply by adding the LED to K printhead distance "j". In practice, the centre positions of the other three cartridges 130C, 130M and 130Y are also taken into account by means of a suitable averaging process. In this way, the effect of any misalignment of these other cartridges is minimized, and a satisfactory capping of all printheads can occur. Accuracy of positioning with less than $\pm 0.7\text{mm}$ of error is obtained.

[0039] The above-described calibration process typically occurs only once during the lifetime of a printer. If the printheads or the service station cartridges are replaced, they usually remain within satisfactory tolerances. However, should there be a loss of memory, or should the entire service station housing need replacing, for example, then the control system is configured so that a service engineer may use the process to recalibrate the positions of the printer components.

[0040] The above-described arrangement has the advantage of reducing tolerance problems in two ways, namely calibrating the position of the service station cartridges 130 themselves, rather than the housing, and also taking into account the actual "LED to K" distance "j". Using holes 132 in the cartridges provides accurate location thereof, and taking into account the location of all four cartridges 130. and then averaging their displacements from a nominal position, reduces any residual errors in positioning for the capping process. The capping function of the service station is the one requiring the tightest tolerance and so the capping region is the best region to locate the calibration holes 132. The thus-determined capping position serves as a reference for the rest of the servicing "primitives".

[0041] Various modifications may be made to the above-described arrangement. For example, in addition to averaging over the four printhead cleaner cartridges, one could also average over the four printhead positions to obtain a modified value for "j". Also, or in addition, to shorten and simplify the process, only the distance to the hole 132K of the black printhead cleaner 130K may be determined.

[0042] The calibrated part of the service station cartridge may be other than the capping position.

[0043] If desired, a hole or other reference marking on the service station housing could be used, as in the prior art. This still gives an improved positioning accuracy, since the distance "j" is more accurately determined than allowed previously by the tolerance of the mechanical housing. Indeed, the reference location may be on a component of the printer other than the service station. For example, the precise determination of "j" can be used in the printhead alignment process to accurately place the line sensor 117 over narrow patterns. It can also be used to allow the calculation of the real position of the media margins, which is crucial for the media loader.

[0044] Alternatively, the value of "j" may be taken as a preset value, in which case the improved calibration results from the determination of the actual positions of one or more of the printhead cleaner cartridges.

[0045] In other printers it may be arranged that the scan axis and media axis have other orientations, e.g. vertical and horizontal respectively.

Claims

1. A method of determining the relative location of a component (130) of a printer apparatus (100) with respect to a printhead carriage (110) of the printer apparatus, said component comprising one or more sub-units (130C, 130M, 130Y, 130K) co-operating with a corresponding number of printheads (C, M, Y, K) on the carriage (110), wherein a sensor (117) is used to determine the position of a reference location (132) on said component relative to the sensor (117), **characterised in that** the sensor (117) is also used to determine the position of at least one printhead relative to the sensor.
2. A method of determining the relative location of at least one component (130) of a printer apparatus (100) to a printhead (K) mounted on a printer carriage (110), wherein an optical sensor (117) mounted on the carriage (110) is used to scan a reference location (132) on the component (130), **characterised in that** there is also determined the relative location of the optical sensor (117) to the printhead (K) on the printer carriage.
3. A method according to claim 1 or 2, wherein there is first determined the sensor to printhead distance (j) in the direction of the scan axis or the sensor to printhead distance (r) in the direction of the media axis and then there is determined the other (r,j) of said distances.
4. A method according to claim 3, wherein the sensor is an optical sensor (117) and, to determine the rel-

ative location of the optical sensor to the printhead (K), the printhead is caused to print during a carriage movement a reference mark (146) extending substantially in the direction of the media axis, and the optical sensor (117) subsequently scans the reference mark along the scan axis (120) and there is determined therefrom the sensor to printhead distance ("j") in the direction of the scan axis.

5. A method according to claim 4, wherein the step of determining the sensor to printhead distance (j) is preceded by causing the printhead (K) to print a reference mark (144) in the direction of the scan axis, then using the optical sensor (117) to scan the reference mark (144) along the media axis (140) of the printing apparatus, and then determining the sensor to printhead distance (r) in the direction of the media axis and taking into account its effect on the determination of the sensor to printhead distance (j) in the direction of the scan axis.
6. A method according to claim 5, wherein the reference mark (144) in the direction of the scan axis is printed by a selected group of adjacent nozzles of the printhead (K) and wherein, before printing the reference mark (144), a check is made for an appropriately-sized group of working nozzles, the distance (h) of said group from the centre of the printhead being taken into account when calculating the sensor to printhead distance (r) in the direction of the media axis.
7. A method according to any preceding claim, wherein the reference location (132) is constituted by a through hole.
8. A method according to any preceding claim, wherein the sensor (117) scans a plurality of reference locations (132C, 132M, 132Y, 132K) respectively on mutually-associated sub-units (130C, 130M, 130Y, 130K) of said component (130) and the results are subjected to an averaging process.
9. A method according to claim 8, wherein the mutually-associated sub-units are the printhead cleaners (130C, 130M, 130Y, 130K) of a printer service station (130).
10. A method according to claim 2, wherein the component(s) is/are one or more service station insert members (130C, 130M, 130Y, 130K) mounted in a service station (130).
11. A method according to claim 10, wherein the sensor detects reference locations arranged on respective ones of said service station insert members and the results are averaged.

12. A method of operating printing apparatus wherein, to co-ordinate the cooperation of sub-units (C, M, Y, K) of a first component with respective sub-units (130C, 130M, 130Y, 130K) of a second component (130), there is performed a relative location determining step according to any preceding claim.

13. An inkjet printing apparatus (100) comprising one or more printheads (C, M, Y, K) mounted on a printer carriage (110) and means for determining the position of at least one other component (130) of the printing apparatus relative to the or each printhead, said determining means comprising a sensor (117) mounted on the printer carriage (110), **characterised in that** calibration means are provided which determine the relative positions of the sensor (117) and the or each printhead.

14. An inkjet printing apparatus according to claim 13, wherein the sensor is an optical sensor (117) and said other component is a printhead cleaner insert member (130K) of a printer service station (130) and having a through hole (132) in a portion thereof which is detected by the optical sensor.

15. An inkjet printing apparatus (100) according to claim 13 wherein said component is at least one service station insert member (130C, 130M, 130Y, 130K) mounted in a service station (130), the sensor is an optical sensor (117), there are provided means defining one or more reference locations within the service station area, the reference locations being optically detectable by the optical sensor (117), and the or each reference location (132C, 132M, 132Y, 132K) is provided on a respective service station insert member.

16. A printing apparatus according to claim 15, wherein the or each reference location is constituted by a through hole (132) in a portion (131) of its respective service station insert member (130K).

17. A printing apparatus according to claim 15 or 16, wherein each service station insert member (130C, 130M, 130Y, 130K) has a respective reference location (132C, 132M, 132Y, 132K) and means are provided for averaging the results for a plurality of reference locations and taking the averaged result into account when determining a printhead to service station insert member distance.

Patentansprüche

1. Ein Verfahren zum Bestimmen des relativen Ortes einer Komponente (130) einer Druckervorrichtung (100) im Hinblick auf einen Druckkopfwagen (110) der Druckervorrichtung, wobei die Komponente ei-

ne oder mehrere Teileinheiten (130C, 130M, 130Y, 130K) aufweist, die mit einer entsprechenden Anzahl von Druckköpfen (C, M, Y, K) auf dem Wagen (110) zusammenarbeiten, wobei ein Sensor (117) verwendet wird, um die Position eines Referenzortes (132) auf der Komponente relativ zu dem Sensor (117) zu bestimmen, **dadurch gekennzeichnet, daß** der Sensor (117) ferner verwendet wird, um die Position von zumindest einem Druckkopf relativ zu dem Sensor zu bestimmen.

2. Ein Verfahren zum Bestimmen des relativen Ortes von zumindest einer Komponente (130) einer Druckervorrichtung (100) zu einem Druckkopf (K), der auf einem Druckerwagen (110) befestigt ist, wobei ein optischer Sensor (117), der an dem Wagen (110) befestigt ist, verwendet wird, um einen Referenzort (132) auf der Komponente (130) abzutasten, **dadurch gekennzeichnet, daß** ferner der relative Ort des optischen Sensors (117) zu dem Druckkopf (K) auf dem Druckerwagen bestimmt wird.
3. Ein Verfahren gemäß Anspruch 1 oder 2, bei dem zuerst die Sensor-zu-Druckkopf-Distanz (j) in der Richtung der Bewegungsachse oder die Sensor-zu-Druckkopf-Distanz (r) in der Richtung der Medienachse bestimmt wird, und dann die anderen (r, j) der Distanzen bestimmt werden.
4. Ein Verfahren gemäß Anspruch 3, bei dem der Sensor ein optischer Sensor (117) ist und der Druckkopf veranlaßt wird, während einer Wagenbewegung eine Referenzmarkierung (146) zu drucken, die sich im wesentlichen in der Richtung der Medienachse erstreckt, um den relativen Ort des optischen Sensors zu dem Druckkopf (K) zu bestimmen, und wobei der optische Sensor (117) nachfolgend die Referenzmarkierung entlang der Bewegungsachse (120) abtastet und aus derselben die Sensor-zu-Druckkopf-Distanz ("j") in der Richtung der Bewegungsachse bestimmt wird.
5. Ein Verfahren gemäß Anspruch 4, bei dem dem Schritt des Bestimmens der Sensor-zu-Druckkopf-Distanz (j) das Bewirken vorausgeht, daß der Druckkopf (K) eine Referenzmarkierung (144) in der Richtung der Bewegungsachse druckt, dann der optische Sensor (117) verwendet wird, um die Referenzmarkierung (144) entlang der Medienachse (140) der Druckvorrichtung abzutasten, und dann die Sensor-zu-Druckkopf-Distanz (r) in der Richtung der Medienachse bestimmt wird und deren Auswirkung auf die Bestimmung der Sensor-zu-Druckkopf-Distanz (j) in der Richtung der Bewegungsachse berücksichtigt wird.
6. Ein Verfahren gemäß Anspruch 5, bei dem die Re-

ferenzmarkierung (144) in der Richtung der Bewegungsachse durch eine ausgewählte Gruppe von benachbarten Düsen des Druckkopfs (K) gedruckt wird, und wobei vor dem Drucken der Referenzmarkierung (144) eine Prüfung für eine geeignet dimensionierte Gruppe von Arbeitsdüsen durchgeführt wird, wobei die Distanz (h) der Gruppe von dem Zentrum des Druckkopfs berücksichtigt wird, wenn die Sensor-zu-Druckkopf-Distanz (r) in der Richtung der Medienachse berechnet wird.

7. Ein Verfahren gemäß einem der vorangehenden Ansprüche, bei dem der Referenzort (132) durch ein Durchgangsloch gebildet wird.
8. Ein Verfahren gemäß einem der vorangehenden Ansprüche, bei dem der Sensor (117) jeweils eine Mehrzahl von Referenzorten (132C, 132M, 132Y, 132K) auf sich gegenseitig zugeordneten Teileinheiten (130C, 130M, 130Y, 130K) der Komponente (130) abtastet und die Ergebnisse einem Mittelungsprozeß unterzogen werden.
9. Ein Verfahren gemäß Anspruch 8, bei dem die sich gegenseitig zugeordneten Teileinheiten Druckkopf-reiniger (130C, 130M, 130Y, 130K) einer Drucker-servicestation (130) sind.
10. Ein Verfahren gemäß Anspruch 2, bei dem die eine oder die mehreren Komponenten ein oder mehrere Servicestationseinfügebauglieder (130C, 130M, 130Y, 130K) sind, die in einer Servicestation (130) befestigt sind.
11. Ein Verfahren gemäß Anspruch 10, bei dem der Sensor Referenzorte erfaßt, die an jeweiligen der Servicestationseinfügebauglieder angeordnet sind, und bei dem die Ergebnisse gemittelt werden.
12. Ein Verfahren zum Betreiben der Druckvorrichtung, bei dem ein Relativer-Ort-Bestimmungsschritt gemäß einem der vorangehenden Ansprüche durchgeführt wird, um die Zusammenarbeit der Teileinheiten (C, M, Y, K) einer ersten Komponente mit jeweiligen Teileinheiten (130C, 130M, 130Y, 130K) einer zweiten Komponente (130) zu koordinieren.
13. Eine Tintenstrahldruckvorrichtung (100), die einen oder mehrere Druckköpfe (C, M, Y, K), die auf einem Druckerwagen (110) befestigt sind, und eine Einrichtung zum Bestimmen der Position von mindestens einer anderen Komponente (130) der Druckvorrichtung relativ zu dem oder jedem Druckkopf aufweist, wobei die Bestimmungseinrichtung einen Sensor (117) aufweist, der auf dem Druckerwagen (110) befestigt ist, **dadurch gekennzeichnet, daß** eine Kalibrierungseinrichtung bereitgestellt ist, die die relativen Orte des Sensors (117)

und des oder jedes Druckkopfs bereitstellt.

14. Eine Tintenstrahldruckvorrichtung gemäß Anspruch 13, bei der der Sensor ein optischer Sensor (117) ist und die andere Komponente ein Druckkopf-
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15. Eine Tintenstrahldruckvorrichtung (100) gemäß Anspruch 13, bei der die Komponente zumindest ein Servicestationseinfügebauglied (130C, 130M, 130Y, 130K) ist, das in einer Servicestation (130) befestigt ist, wobei der Sensor ein optischer Sensor (117) ist, wobei eine Einrichtung bereitgestellt ist, die einen oder mehrere Referenzorte innerhalb des Servicestationsbereichs definieren, wobei die Referenzorte optisch durch den optischen Sensor (117) erfaßbar sind und der oder jeder Referenzort (132C, 132M, 132Y, 132K) an einem jeweiligen Servicestationseinfügebauglied bereitgestellt ist.

16. Eine Druckvorrichtung gemäß Anspruch 15, bei der der oder jeder Referenzort durch ein Durchgangsloch (132) in einem Abschnitt (131) von dessen jeweiligem Servicestationseinfügebauglied (130K) gebildet wird.

17. Eine Druckvorrichtung gemäß Anspruch 15 oder 16, bei der jedes Servicestationseinfügebauglied (130C, 130M, 130Y, 130K) einen jeweiligen Referenzort (132C, 132M, 132Y, 132K) aufweist und eine Einrichtung zum Mitteln der Ergebnisse für eine Mehrzahl von Referenzorten bereitgestellt ist, und das gemittelte Ergebnis berücksichtigt wird, wenn eine Druckkopf-Zu-Servicestations-Einfügebauglied-Distanz bestimmt wird.

Revendications

1. Procédé pour déterminer l'emplacement relatif d'un composant (130) d'un appareil d'imprimante (100) par rapport à un chariot de tête d'impression (110) de l'appareil d'imprimante, ledit composant comprenant un ou plusieurs sous-ensembles (130C, 130M, 130Y, 130K) coopérant avec un nombre correspondant de têtes d'impression (C, M, Y, K) sur le chariot (110), dans lequel un capteur (117) est utilisé pour déterminer la position d'un emplacement de référence (132) sur ledit composant par rapport au capteur (117), **caractérisé en ce que** le capteur (117) est aussi utilisé pour déterminer la position d'au moins une tête d'impression par rapport au capteur.

2. Procédé pour déterminer l'emplacement relatif d'au

moins un composant (130) d'un appareil imprimant (100) par rapport à une tête d'impression (K) montée sur un chariot d'imprimante (110), dans lequel un capteur optique (117) monté sur le chariot (110) est utilisé pour balayer un emplacement de référence (132) sur le composant (130), **caractérisé en ce qu'il** est aussi déterminé l'emplacement relatif du capteur optique (117) par rapport à la tête d'impression (K) sur le chariot d'imprimante.

3. Procédé selon la revendication 1 ou 2, dans lequel il est d'abord déterminé la distance entre le capteur et la tête d'impression (j) dans la direction de l'axe de balayage ou la distance entre le capteur et la tête d'impression (r) dans la direction de l'axe médian et ensuite il est déterminé l'autre (r, j) desdites distances.

4. Procédé selon la revendication 3, dans lequel le capteur est un capteur optique (117) et, pour déterminer l'emplacement relatif du capteur optique par rapport à la tête d'impression (K), la tête d'impression est amenée à imprimer, durant un mouvement du chariot, une marque de référence (146) se prolongeant sensiblement dans la direction de l'axe médian, et le capteur optique (117) par la suite balaye la marque de référence le long de l'axe de balayage (120) et à partir de ceci il est déterminé la distance entre le capteur et la tête d'impression (« j ») dans la direction de l'axe de balayage.

5. Procédé selon la revendication 4, dans lequel l'étape de détermination de la distance entre le capteur et la tête d'impression (j) est précédée par le fait d'amener la tête d'impression (K) à imprimer une marque de référence (144) dans la direction de l'axe de balayage, ensuite le fait d'utiliser le capteur optique (117) pour balayer la marque de référence (144) le long de l'axe médian (140) de l'appareil imprimant, et ensuite les faits de déterminer la distance entre le capteur et la tête d'impression (r) dans la direction de l'axe médian et de prendre en compte son effet sur la détermination de la distance entre le capteur et la tête d'impression (j) dans la direction de l'axe de balayage.

6. Procédé selon la revendication 5, dans lequel la marque de référence (144) dans la direction de l'axe de balayage est imprimée par un groupe sélectionné de jets contigus de la tête d'impression (K) et dans lequel, avant d'imprimer la marque de référence (144), une vérification est faite pour un groupe de taille appropriée de jets en état de marche, la distance (h) dudit groupe par rapport au centre de la tête d'impression étant prise en compte durant le calcul de la distance entre le capteur et la tête d'impression (r) dans la direction de l'axe médian.

7. Procédé selon une revendication précédente quelconque, dans lequel l'emplacement de référence (132) est constitué par un trou débouchant.
8. Procédé selon une revendication précédente quelconque, dans lequel le capteur (117) balaye une pluralité d'emplacements de référence (132C, 132M, 132Y, 132K) respectivement sur des sous-ensembles mutuellement associés (130C, 130M, 130Y, 130K) dudit composant (130) et les résultats sont sujets à un processus de calcul de moyenne.
9. Procédé selon la revendication 8, dans lequel les sous-ensembles associés mutuellement sont les nettoyeurs de têtes d'impression (130C, 130M, 130Y, 130K) d'une unité d'entretien d'imprimante (130).
10. Procédé selon la revendication 2, dans lequel le(s) composant(s) est/sont un ou plusieurs éléments d'insertion d'unité d'entretien (130C, 130M, 130Y, 130K) montés dans une unité d'entretien (130).
11. Procédé selon la revendication 10, dans lequel le capteur détecte les emplacements de références agencés sur ceux respectifs desdits éléments d'insertion de l'unité d'entretien et la moyenne des résultats est faite.
12. Procédé d'exploitation d'un appareil imprimant dans lequel, pour coordonner la co-opération des sous-ensembles (C, M, Y, K) d'un premier composant avec les sous-ensembles respectifs (130C, 130M, 130Y, 130K) d'un deuxième composant (130), il est réalisé une étape de détermination d'emplacement relatif selon une revendication précédente quelconque.
13. Appareil imprimant à jet d'encre (100) comprenant une ou plusieurs têtes d'impression (C, M, Y, K) montées sur un chariot d'imprimante (110) et un moyen pour déterminer la position d'au moins un autre composant (130) de l'appareil imprimant par rapport à la ou chaque tête d'impression, ledit moyen de détermination comprenant un capteur (117) monté sur le chariot d'imprimante (110), **caractérisé en ce que** des moyens de calibrage sont fournis qui déterminent les positions relatives du capteur (117) et de la ou chaque tête d'impression.
14. Appareil imprimant à jet d'encre selon la revendication 13, dans lequel le capteur est un capteur optique (117) et l'autre dit composant est un élément d'insertion de nettoyeur de tête d'impression (130K) d'une unité d'entretien d'imprimante (130) et ayant un trou débouchant (132) se trouvant dans une partie de celui-ci qui est détecté par le capteur optique.
15. Appareil imprimant à jet d'encre (100) selon la revendication 13, dans lequel ledit composant est au moins un élément d'insertion de nettoyeur de tête d'impression (130C, 130M, 130Y, 130K) monté sur une unité d'entretien (130), le capteur est un capteur optique (117), il est fourni des moyens définissant un ou plusieurs emplacements de référence à l'intérieur de la zone d'unité d'entretien, les emplacements de référence étant détectables optiquement par le capteur optique (117), et le ou chaque emplacement de référence (132C, 132M, 132Y, 132K) est fourni sur un élément d'insertion d'unité d'entretien.
16. Appareil imprimant selon la revendication 15, dans lequel le ou chaque emplacement de référence est constitué par un trou débouchant (132) se trouvant dans une partie (131) de son élément d'insertion d'unité d'entretien respectif (130K).
17. Appareil imprimant selon la revendication 15 ou 16, dans lequel chaque élément d'insertion d'unité d'entretien (130C, 130M, 130Y, 130K) a un emplacement de référence respectif (132C, 132M, 132Y, 132K) et des moyens sont fournis pour faire une moyenne des résultats pour une pluralité d'emplacements de référence et prendre en compte le résultat moyen durant la détermination d'une distance entre la tête d'impression et l'élément d'insertion d'unité d'entretien.

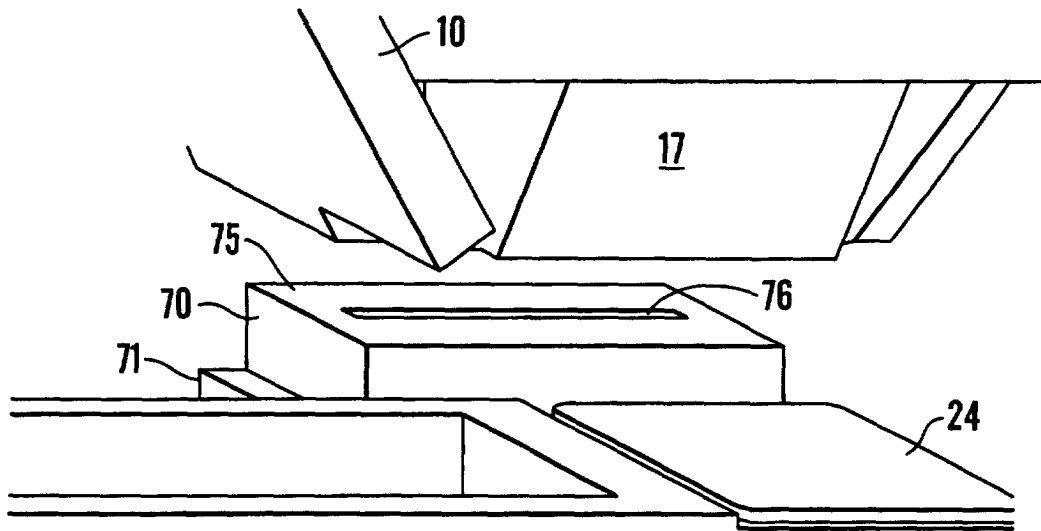


Fig. 1

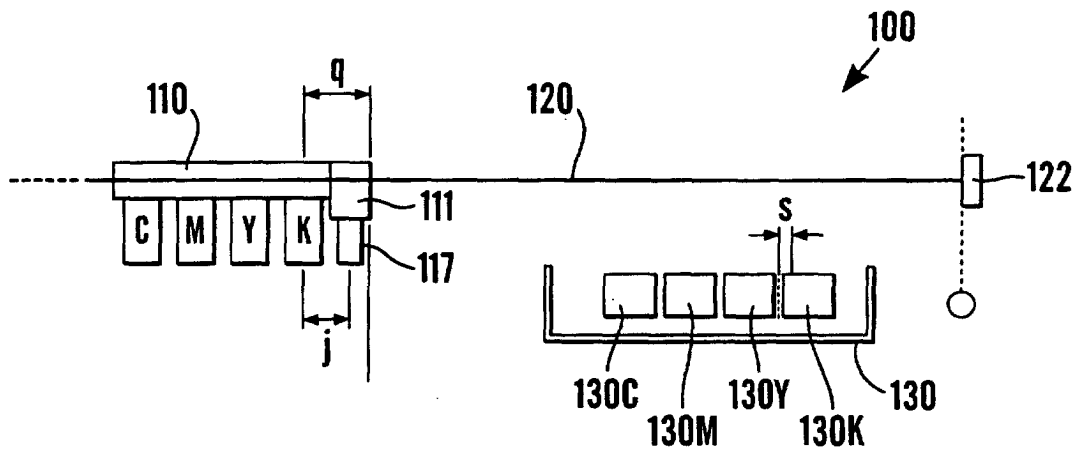


Fig. 2

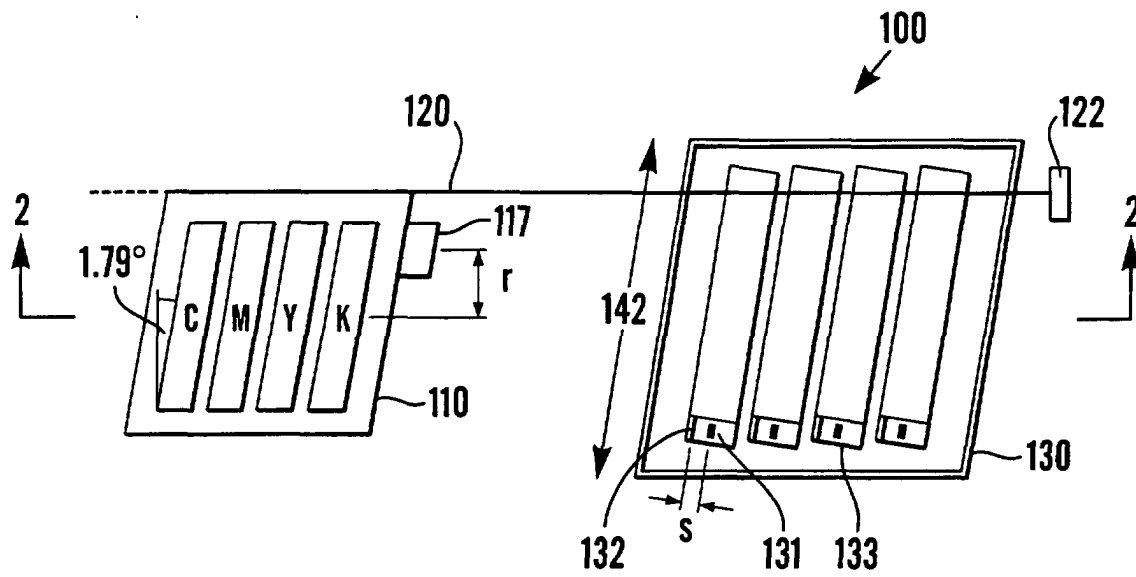


Fig.3

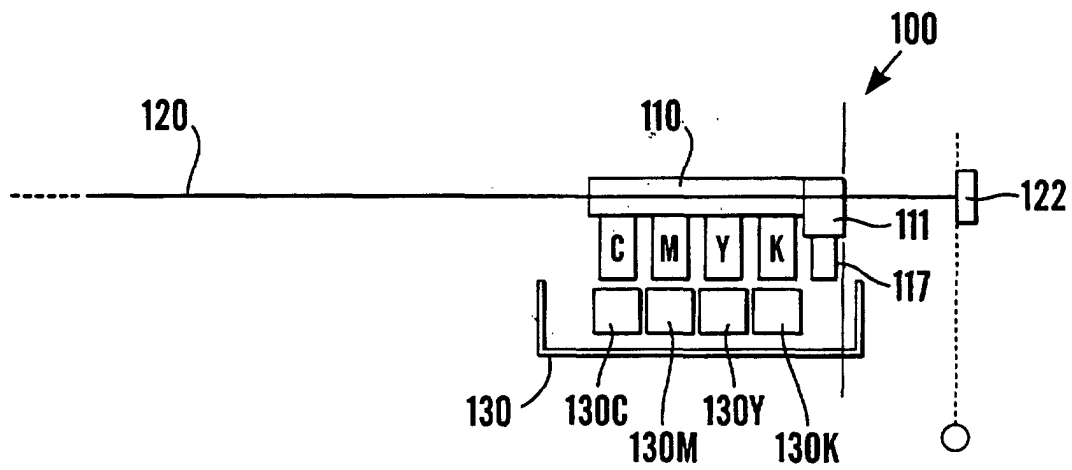


Fig.4

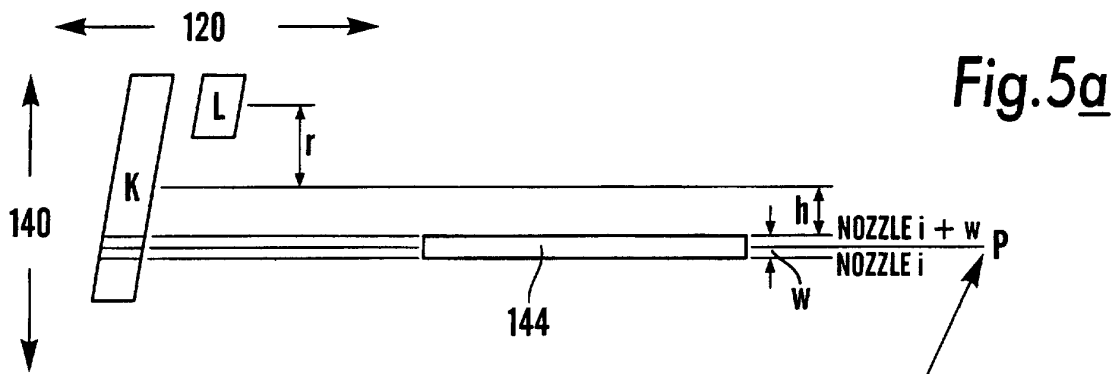


Fig. 5a

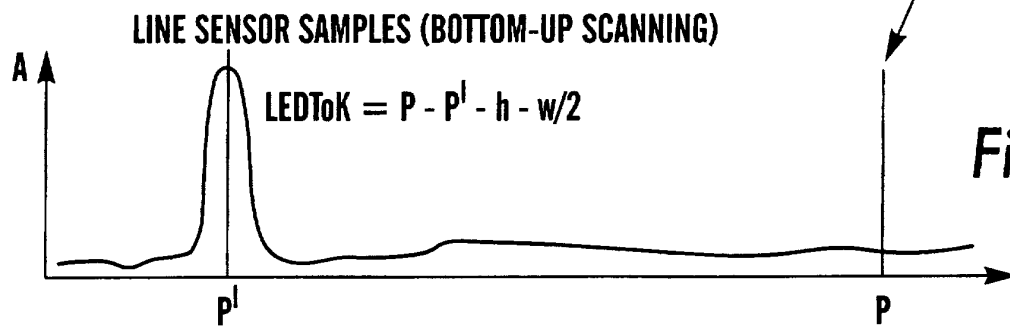


Fig. 5b

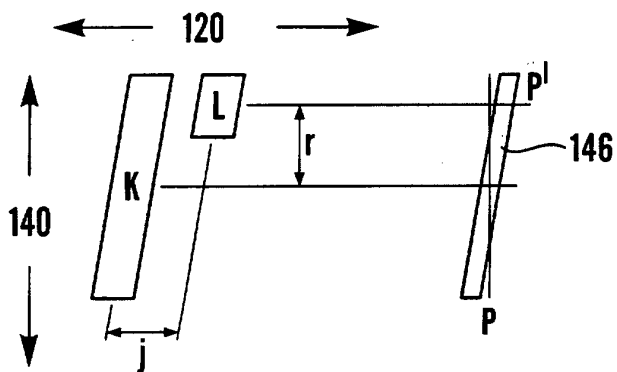


Fig. 6a

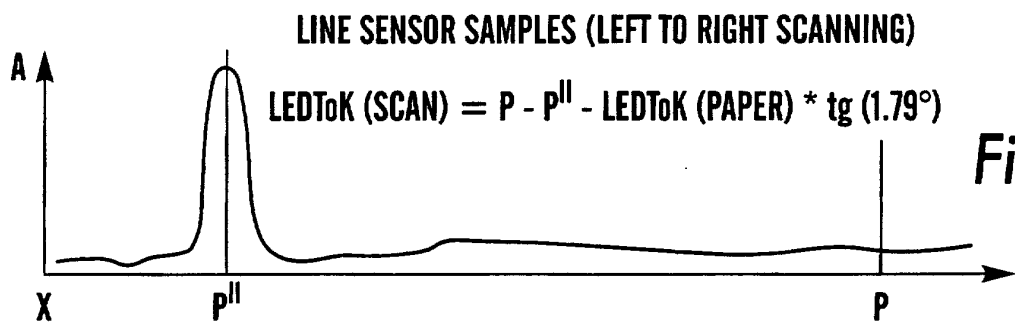


Fig. 6b

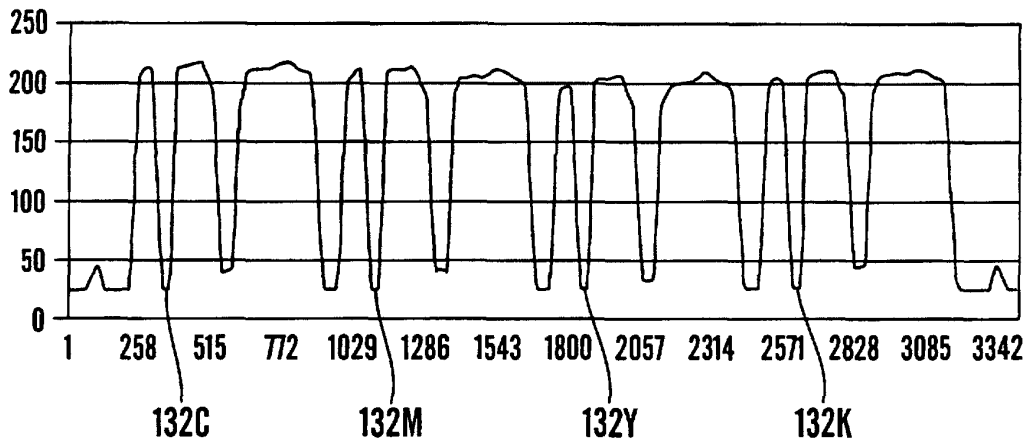


Fig. 7a

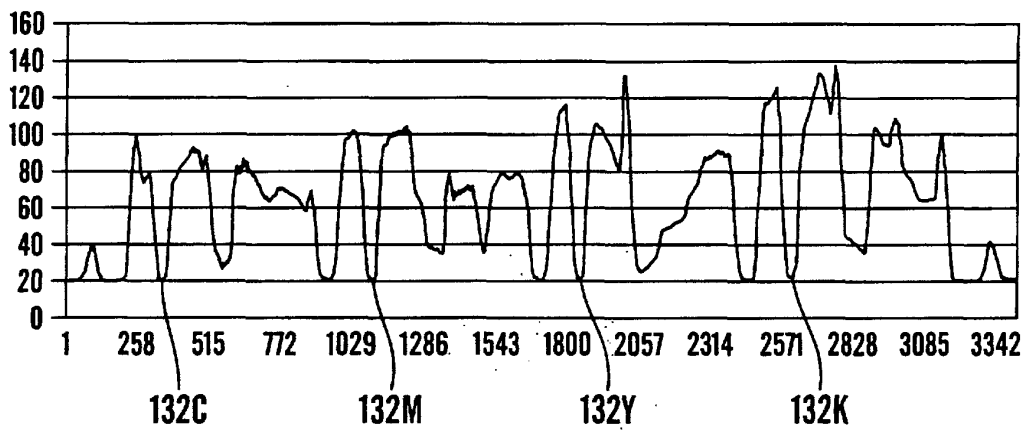


Fig. 7b

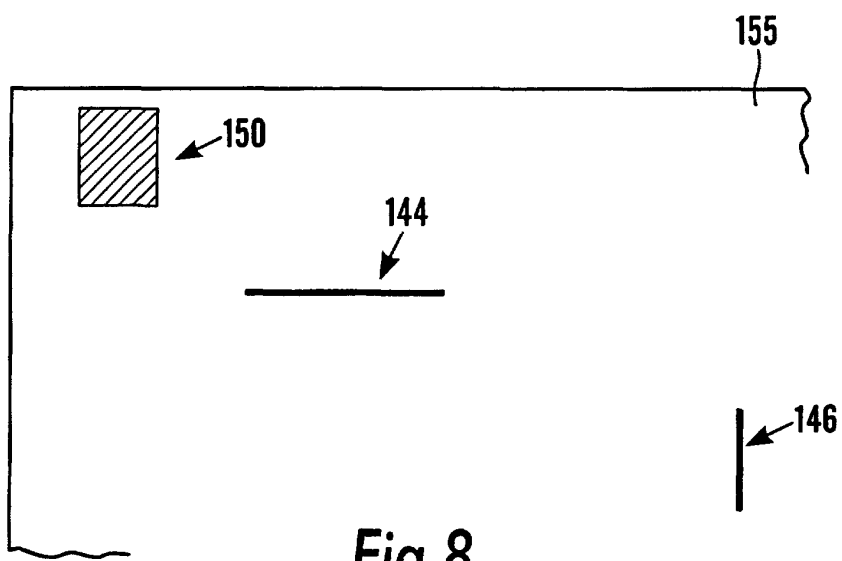


Fig. 8