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(54) **METHOD AND APPARATUS FOR PRINTING ON RIGID PANELS AND CONTOURED OR TEXTURED SURFACES**

VERFAHREN UND GERÄT ZUM DRUCKEN AUF STARREN PANEELN UND KONTURIERTEN ODER STRUKTURIERTEN OBERFLÄCHEN

PROCEDE ET APPAREIL D'IMPRESSION SUR DES PANNEAUX RIGIDES ET DES SURFACES PROFILEES OU STRUCTUREES

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## Description

### Field of the Invention

**[0001]** The present invention relates to printing onto rigid substrates, and to the printing onto textured, contoured or other three-dimensional substrates. The invention is particularly related to the printing onto such substrates as those having textile fabric surfaces or molded objects, rigid panels such as office partitions, automobile interior panels and other contoured objects, and to such printing using ink jet printing techniques.

### Background of the Invention

**[0002]** Applying ink to a substrate by ink jet printing requires a proper spacing between the ink jet nozzles and the surface of the substrate to which the printing is applied. Normally, this spacing must be set to within one or two millimeters to maintain effective printing by an ink jet process. If the distance from the nozzles to the surface being printed is too great, deviations from ideal parallel paths of the drops from different nozzles become magnified. Further, the longer the flight path of the drops from the print head to the substrate, the more dependent the accuracy of the printing becomes on the relative speed between the print head and the substrate. This dependency limits the rate of change in print head to substrate velocity, including changes in direction. Also, the velocity of the drops moving from the print head nozzles to the substrate declines with the distance traveled from the nozzles, and the paths of such drops become more greatly affected by air currents and other factors with increased nozzle to substrate distance. Additionally, droplet shape changes the farther the drop moves from the nozzle, which changes the effects of the drop on the substrate. Accordingly, variations in the distance from the print head to the substrate can cause irregular effects on the printed image.

**[0003]** In addition to problems in jetting ink onto contoured surfaces, the curing of UV inks that requires sharply focused UV energy to deliver sufficient curing energy to the ink is difficult to achieve where the surface is contoured.

**[0004]** Some substrates deform, even temporarily, when heated. Such deformation may be temporary, for example, where the material returns to its undeformed state when it cools. Nonetheless, even temporary deformation can adversely affect the print quality if it occurs when ink is being jetted onto the substrate. In spot curing of UV inks, which is performed by exposing ink to UV immediately upon its contacting the substrate, UV that is accompanied by heat producing radiation can deform substrates such as foam-board as the ink jets are making single or multiple passes over the print area.

**[0005]** For the reasons stated above, ink jet printing has not been successful on contoured materials and other three-dimensional substrates, particularly printing with

UV curable inks in ink jet printing processes.

**[0006]** US 4841306 discloses a fluid jet printing line which has a plurality of fluid jet printing devices arranged serially to sequentially print on a substrate. Each printing device includes a print bar movable relative to a print head and substrate. Each print head including the print bar carried thereby is mounted for movement between positions in the line and a clean or ready room. In the print line, a sensor detects any increased thickness of the substrate and a pneumatic-mechanical system responds to the sensor to raise the print bar above the thickened portion of the substrate as it passes below the orifice plate and to lower the print bar after the thickened portion has passed.

**[0007]** US 4712119 discloses a recording apparatus in which a plurality of recording heads are mounted on a head mounting base fixed on a carriage movable along a paper sheet. The recording heads are individually mountable on the head mounting table, and individually adjustable in position. The right-to-left position of each head can be regulated by a head fixing member.

### Summary of the Invention

**[0008]** An objective of the present invention is to provide for the printing onto three-dimensional substrates, particularly onto highly textured fabrics, tufted or irregular fabrics and other materials, contoured surfaces such as quilts, and mattress covers, and onto molded, stamped and otherwise shaped rigid or semi-rigid materials, and other three-dimensional surfaces. A particular objective of the invention is to print onto such surfaces with ink jet or digital printing processes. One more particular objective of the invention is to print onto such substrates with UV curable inks.

**[0009]** The invention provides a method of printing on a substrate with a plurality of ink jet print heads each having at least one nozzle thereon, the method comprising moving a print head carriage, having the plurality of ink jet print heads thereon, parallel to a plane on which is supported a substrate having a surface thereon to be printed by the jetting of ink from the nozzle, and jetting ink from the nozzles onto the surface of the substrate, wherein the substrate is moved longitudinally relative to the print heads and the print heads on the carriage are moved transversely relative to the substrate, characterized in that the method further comprises automatically adjusting the distance from the print heads to the plane in response to sensing the position of a portion of the surface with a sensor carried on the carriage to position the print heads at a predetermined distance from the surface of the substrate where ink is to be jetted from the nozzles.

**[0010]** The invention further provides an apparatus for printing on a surface of a three-dimensional substrate comprising a frame having a substrate support mounted thereon defining a substrate supporting plane and a print head track extending parallel to the plane, a plurality of

ink jet print heads each having at least one nozzle thereon moveably supported on the track via a print head carriage with the nozzles directed toward the surface of a substrate supported by the substrate support, the substrate support being operable to move the substrate longitudinally relative the print heads and the print heads on the carriage being moveable transversely relative the substrate and a control system operable to move and control the print heads to print on the substrate by jetting ink from the nozzles onto the surface of a substrate, characterized in that the apparatus further comprises a sensor carried on the carriage and operable to provide a distance measurement of a portion of the surface, and in that the print heads are moveable automatically perpendicular to the plane in response to the sensor to a predetermined distance from the surface of the substrate.

**[0011]** According to the principles of the present invention, printed images are applied to three-dimensional substrates with printing elements that are moveable relative to the plane of the substrate being printed. In certain embodiments, the invention provides a wide-substrate ink jet printing apparatus with print heads that move toward and away from the plane of a substrate to maintain a fixed distance between the nozzles of the printhead and the surface onto which the ink is being jetted. The variable distance over the plane of the substrate allows a controlled and uniform distance across which the ink is jetted.

**[0012]** In one preferred embodiment of the invention, the printing element is an ink jet print head set having a plurality of heads, typically four, each for dispensing one of a set of colors onto the substrate to form a multi-colored image. To maintain the constant distance or to otherwise control the distance, one or more sensors is provided to measure the distance from the print head or from the print head carriage track to the point on the substrate on which ink is to be projected. The sensors generate reference signals that are fed to a controller that controls a servo motor on the print head carriage. The print head is moveably mounted to the carriage, for example on a ball screw mechanism, and is moveable toward and away from the plane of the substrate by operation of the servo motor.

**[0013]** In a preferred embodiment of the invention, each print head of a set of four different color print heads is separately moveable relative to a common print head carriage, and is connected to one of a set of four servo motors by which its position relative to the plane of the substrate is capable of control relative to the positions of the other print heads. The print heads of the set are preferably arranged side by side in the transverse direction on the carriage so that one head follows the other across the width of the substrate as the carriage scans transversely across the substrate. Each head has a plurality of ink jet nozzles thereon for dispensing a given color of ink in a corresponding plurality of dots, for example 128 in number, that extend in a line transverse to the carriage, which is in a longitudinal direction perpendicular to the

scan direction of the carriage. Two laser or optical sensors are provided on the carriage, one on each side of the heads, so that a distance measurement of the surface to the substrate can be taken ahead of the print heads when the heads are scanning in either direction. The controller records the contour of the substrate ahead of the print heads and varies the position of each print head, toward and away from the substrate plane, as each print head passes over the points at which the measurements were taken, so that each of the independently moveable heads follows the contour and maintains a fixed distance from the surface being printed.

**[0014]** Preferably, UV ink is printed onto material and the cure of the ink is initiated by exposure to UV light. UV curing lights may be mounted on the print head carriage, one on each side of the print head set, to expose the printed surface behind the heads. By so mounting the UV curing lights on the print head carriage, the jetted ink can be spot cured immediately upon contacting the substrate, which freezes the dots in position and prevents their spreading on or wicking into the substrate. With certain substrates, conventional or broad spectrum UV curing lights include radiation that can heat the substrate. In the case of foam-board and several other commonly used substrates, the light heats the substrate and deforms it. Usually, this deposition is temporary in that the substrate blisters or swells when heated only to return to its original condition upon cooling. Where the UV exposure is carried out downstream of the print head carriage, no harm results. But with spot curing, the substrate deforms at the point of printing, thereby adversely affecting the quality of the ink jet printing operation. This is prevented by using a "cold UV" source, or a source that includes a filter or other energy limiting device, for example, a limited bandwidth UV source, to prevent the energy from the source striking the substrate from carrying enough energy to heat the substrate. This may be done by providing sufficient UV energy at the relevant frequencies for curing the ink without heating the substrate. The invention is useful in printing onto substrates that can deform, even temporarily, when heated. Such deformation, even if temporary such that the material returns to its undeformed state when it cools, adversely affects the print quality with spot curing, which deforms the substrate as the ink jets are making single or multiple passes over the print area. This is particularly the case with printing onto form boards that make up the largest application of printing onto rigid substrates. Such deformation of the board from heat during printing would otherwise force adjustment of the head height above the deformation zone. The higher the head height the worse the print quality due to satellite and time of flight issues to name a few. With a cold UV system, the head to substrate distance can be minimized to maximize print quality.

**[0015]** In prior practice, spot curing has not been used to ink jet print onto rigid substrates, except as proposed by us in our parent application. However, cold UV is known for curing UV ink downstream of a printing station,

where it has been used to prevent permanent deformation or heat damage to the substrate. Temporary deformation that will disappear after the substrate cools has not been a problem in the prior art. Such deformation would be a problem where slight raising or warping of the surface occurs as the ink is being jetted onto the substrate, which can occur during spot curing.

**[0016]** With or following the exposure to the UV light, the printed textile substrates or other textured or porous fabric is subjected to heat, preferably by blowing heated air onto the material downstream of the printing station, which extends the UV light initiated curing process and removes uncured components of the ink. With quilted bedding fabric materials, UV curable ink is jetted onto the fabric and the jetted ink is exposed to UV curing light to cure the ink preferably to about 90 to 97% polymerization, with the fabric bearing the partially cured, jetted ink then heated in a hot air blower curing oven at which the UV light initiated polymerization continues, uncured monomers are vaporized, or both, in order to produce a printed image of UV ink that contains a low quantity of uncured monomer or other ink components, for example, less than 0.01%.

**[0017]** Where UV ink is jetted onto a highly textured fabric such as a mattress cover ticking material, the ink is jetted at a dot density of from about 180x254 dots per inch per color to about 300x300 dots per inch per color. For certain common UV inks, four colors of a CMYK color palette are applied, each in drops or dots of, for example, about 75 picoliters, or approximately 80 nanograms, per drop, utilizing a UV ink jet print head. A UV curing light head is provided, which moves either with the print head or independent of the print head and exposes the deposited drops of UV ink with a beam of about 300 watts per linear inch, applying about 1 joule per square centimeter, thereby producing at least a 90% UV cure. The fabric on which the jetted ink has been thereby partially UV cured is then passed through an oven where it is heated to about 300°F for from about 30 seconds up to about three minutes. Forced hot air is preferably used to apply the heat in the oven, but other heating methods such as infrared or other radiant heaters may be used. Similar parameters may be used for cloth covered rigid panels such as office partitions.

**[0018]** When printing onto contoured material, the distance from the print heads to the substrate where the ink is to be deposited can be determined by measuring the distance from a sensor to the substrate ahead of the print heads and mapping the location of the surface. For bidirectional print heads that move transversely across the longitudinally advancing fabric, providing two distance measuring sensors, one on each of the opposite sides of the print heads, are provided to measure the distance to the contoured fabric surface when the print heads are moving in either direction. For some inks and for sufficiently rigid materials, a mechanical rolling sensor may be used, for example, by providing a pair of rollers, with one roller ahead of, and one head behind, the print head

so that the average distance between the two rollers and a reference point on the print head can be used to control the distance of the print head from the plane of the substrate. To achieve this, one or more print heads can be mounted to a carriage having the rollers on the ends thereof so that the mechanical link between the rollers moves the print head relative to the plane of the substrate. In most cases, a non-contact sensor, such as a laser or photo eye sensor, is preferred in lieu of each roller. The outputs of two sensors on opposite sides of the print heads can be communicated to a processor, to measure the distance from the heads to the fabric ahead of the bidirectional heads, to drive a servo motor connected to the print head to raise and lower the head relative to the substrate plane so that the print heads move parallel to the contoured surface and jet ink onto the fabric across a fixed distance.

**[0019]** These and other objects of the present invention will be more readily apparent from the following detailed description of the preferred embodiments of the invention.

#### **Brief Description of the Drawings**

**[0020]**

**Fig. 1** is a perspective view of one embodiment of an apparatus embodying principles of the present invention in which ink jet printing is applied to panels of rigid office partitions that are covered with textured or contoured textile material or fabric.

**Fig. 1A** is a perspective view, similar to **Fig. 1**, of another embodiment of an apparatus embodying principles of the present invention in which ink jet printing is applied to rigid panels.

**Fig. 2** is a cross-sectional view along line 2-2 of **Fig. 1** showing structure for maintaining print head to substrate distance where a substrate is more highly contoured.

**Fig. 2A** is a cross-sectional view similar to **Fig. 2** showing alternative structure for maintaining print head to substrate distance.

**Fig. 3** is a cross-sectional view along line 3-3 of **Fig. 1A** showing structure for maintaining print head to substrate distance on a contoured substrate.

#### **Detailed Description of the Preferred Embodiment**

**[0021]** **Fig. 1** illustrates a machine 10 for printing onto rigid panels. The machine 10 includes a stationary frame 11 with a longitudinal extent represented by an arrow 12 and a transverse extent represented by an arrow 13. The machine 10 has a front end 14 into which is advanced a rigid panel 15, such as that of which an office partition may be formed. The panel 15 may include a metal or wooden frame 17 on which is stretched a facing material that forms the surface 16 to be printed. The surface 16 may also be a flat but highly textured fabric, a molded

material such as a foam or some other contoured or variable surface. Panels 15 are carried longitudinally on the machine 10 by a conveyor or conveyor system 20, formed of a pair of opposed pin tenting belt sets 21 which extend through the machine 10 and onto which the panels 15 are fed at the front end 14 of the machine 10. The belt sets 21 retain the panels 15 in a precisely known longitudinal position on the belt sets 21 to carry the panels 15 through the longitudinal extent of the machine 10, preferably with an accuracy of 1/4 inch. The longitudinal movement of the belts 21 of the conveyor 20 is controlled by a conveyor drive 22. The conveyor 20 may take alternative forms including, but not limited to, opposed cog-belt side securements, longitudinally moveable positive side clamps that engage the panels 15 or other securing structure for holding the panels 15 fixed relative to the conveyor 20.

**[0022]** Along the conveyor 20 are provided three stations, including an ink jet printing station 25, a UV light curing station 24, and a heated drying station 26. The printing station 25 includes an ink jet carriage having one or more ink jet printing heads 30 thereon. The carriage of the print heads 30 is shown as transversely moveable on the front of a cross bar 28 that extends transversely across the frame 11 and may, but not necessarily, also be longitudinally moveable on the frame 11 under the power of a transverse servo drive motor 31 and an optional longitudinal drive 32. Alternatively, the heads 30 may extend across the width of the web 15 and be configured to print an entire transverse line of selectable points simultaneously onto the panel 15.

**[0023]** The ink jet printing heads 30 are configured to jet UV ink, for example, at 75 picoliters, or approximately 80 nanograms, per drop, and may do so for each of four colors according to a CMYK color palette. The dots are preferably dispensed at a resolution of about 180 dots per inch by about 254 dots per inch. The resolution may be higher or lower as desired, but the 180x254 resolution is preferred. If desirable for finer images or greater color saturation, 300x300 dots per inch is preferable. The drops of the different colors can be side-by-side or dot-on-dot. Dot-on-dot (sometimes referred to as drop-on-drop) produces higher density.

**[0024]** The print heads 30 are provided with controls that allow for the selective operation of the heads 30 to selectively print designs of one or more colors onto the surface of the panel 15. The drive 22 for the conveyor 20, the drives 31,32 for the print head 30 and the operation of the print heads 30 are program controlled to print patterns 33 at known locations on the panel 15 by a controller 35, which includes a memory 36 for storing programmed patterns, machine control programs and real time data regarding the nature and longitudinal and transverse location of printed designs 33 on the panel 15 and the relative longitudinal position of the panel 15 in the machine 10.

**[0025]** The UV curing station 24 includes a UV light curing head 23 that may move with the print heads 30

or, as is illustrated, move independently of the print heads 30. The UV light curing head 23 is configured to sharply focus a narrow, longitudinally extending beam of UV light onto the printed surface of the fabric. The UV curing head 23 is provided with a transverse drive 19 which is controlled to transversely scan the printed surface of the fabric to move the light beam across the fabric.

**[0026]** Preferably, the curing head 23 is intelligently controlled by the controller 35 to selectively operate and quickly move across areas having no printing and to scan only the printed images with UV light at a rate sufficiently slow to UV cure the ink, thereby avoiding wasting time and UV energy scanning unprinted areas. If the head 23 is included in the printing station 25 and is coupled to move with the print heads 30, UV curing light can be used in synchronism with the dispensing of the ink immediately following the dispensing of the ink.

**[0027]** The UV curing station 24, in the illustrated embodiment, is preferably located either immediately downstream of the printing station 25, or on the print head carriage to the sides of the print heads, so that the fabric, immediately following printing, is subjected to a UV light cure. Such carriage mounting of the curing heads allows for the dots of ink to be frozen where they are deposited, avoiding drop spread and wicking of the ink. The UV curing heads, particularly when mounted on the carriage, are cold-UV light, which, through the use of filters or narrow bandwidth radiation, avoids heating a sensitive substrate such as foam-board and deforming it at the location where the ink drops are being deposited. Such cold-UV curing light systems use cold mirrors, infrared cut filters, and water cooled UV curing to keep the temperature of the substrate low.

**[0028]** In theory, one photon of UV light is required to cure one free radical of ink monomer so as to set the ink. In practice, one joule of UV light energy per square centimeter of printed surface area is supplied by the UV curing head 23. This is achieved by sweeping a UV beam across the printed area of the fabric at a power of 300 watts per linear inch of beam width. This is sufficient to produce a UV cure of at least 90%. Increasing the UV light power up to 600 watts per linear inch can be done to achieve a 97% or better cure. Alternatively, if fabric thickness and opacity are not too high, curing light can be projected from both sides of the fabric to enhance the curing of the UV ink. Using power much higher can result in the burning or even combustion of the fabric, so UV power has an upper practical limit.

**[0029]** The heat curing or drying station 26 may be fixed to the frame 11 downstream of the UV light curing station or may be located off-line. With 97% UV cure, the ink will be sufficiently colorfast so as to permit the drying station to be off-line. When on-line, the drying station should extend sufficiently along the length of fabric to adequately cure the printed ink at the rate that the fabric is printed. When located off-line, the heat curing station can operate at a different rate than the rate of printing. Heat cure at the oven or drying station 26 maintains the

ink on the fabric at about 300°F for up to three minutes. Heating of from 30 seconds to three minutes is the anticipated advantageous range. Heating by forced hot air is preferred, although other heat sources, such as infrared heaters, can be used as long as they adequately penetrate the fabric to the depth of the ink.

**[0030]** A quilting station may be located on-line with the printing station or off-line, and either before or after the printing station. Locating a quilting station downstream of the oven 26 is advantageous in the case of quilted comforters and mattress covers and where quilting is to be applied and registered with printing on the fabric. A single-needle quilting station may be used, such as is described in U.S. Patent No. 5,832,849, to Kaetterhenry et al. entitled "Web-fed Chainstitch Single-needle Mattress Cover Quilter with Needle Deflection Compensation". Other suitable single-needle type quilting machines with which the present invention may be used are disclosed in U.S. Patent Nos. 5,640,916 and 5,685,250, respectively, both entitled "Quilting Method and Apparatus". Such a quilting station may also include a multi-needle quilting structure such as that disclosed in U.S. Patent No. 5,154,130.

**[0031]** Where quilting, molding or other contouring of a substrate is carried out before the printing onto the substrate, registration of the printing to the pre-applied contouring will usually be desired. To register the printing to pre-applied contours, the location of the contour pattern can be calculated in relation to a reference point on the substrate that can be sensed by sensors at "the printing station. The location of the pattern can be directly sensed with a sensor 40 mounted on the print head 30, as illustrated respectively as 40a, 40b in **Figs. 2** and **2A**. The print head 30 includes a nozzle or ink jet nozzle array 41 that is directed downward toward the upwardly facing surface 16 of a substrate such as the panel 15. The panel 15 may have, for example, depressions or channels 43 on its surface 16 that have been formed by stitching or molding, as illustrated in **Fig. 2**. The sensor 40 measures the distance from the nozzle 41 to the surface 16. Information from the sensor 40 can be communicated to the controller 35 and correlated with the longitudinal and transverse position information of the print head 30 and interpreted to determine the location of the contoured pattern so that the printed image can be applied to the surface 16 in registration with the pre-applied contour pattern.

**[0032]** In the embodiment of **Fig. 2**, the sensor 40 is a mechanical sensor 40a that includes a wheeled carriage 45. The nozzle array 41 is mounted at the midpoint of the carriage 45, which is, in turn, pivotally connected to the print head 30 about a longitudinal axis 46 through the center of the carriage 45. The carriage 45 has left and right sensing wheels 47, 48, respectively, that ride on the surface 16 of the panel 15 and follow the contour. The carriage 45 moves vertically relative to the print head 30 and follows the contour of the surface 16. The nozzle array 41, being midway between the wheels 47, 48, will

be positioned vertically at the average of the vertical positions of the wheels 47, 48. In this way, the nozzle array 41 is passively positioned at a controlled distance relative to the surface 16 of the panel 15 in response to the detected location of the surface 16 of the panel 15 as determined by the carriage 45 as the wheels 47, 48 ride on the surface 16.

**[0033]** The distance between the UV head 23 and the fabric is preferably also controllable so that the curing light is always precisely focused onto the printed contoured surface of the fabric. This distance may be controlled by mounting the UV curing head to move with the print heads, such as by communicating the UV light through optic fibers adjacent the print heads, for example, one fiber on each side of the print heads, or by mounting the UV curing head 23 on a separate carriage and providing it with a separate distance adjusting servo motor. Separate control of the UV curing head 23 can be in response to the sensors used to measure print head distance or in response to separate sensors provided to measure curing head distance. Where the print head sensors are used to control curing head to fabric distance, a memory can be used to store a map of the surface or portion of the surface while a controller retrieves the correct distance information from the memory that corresponds to the position of the curing head over the fabric. Alternatively, the UV curing head can be fixed and the focal length of the UV light from the source automatically varied.

**[0034]** Whether the panel 15 has a contoured pattern on its surface 16 or merely a textured material, print quality is maintained by maintaining precise spacing between the nozzle 41 and the surface 16 of the panel 15. **Fig. 2A** illustrates a rigid panel 15 having its outer upwardly facing surface 16 covered with a coarse woven or textured fabric. As the print head 30 moves transversely on the cross bar 28, the vertical position, relative to the print head 30, of the point on the surface 16 of the panel 15 at which the nozzle 41 is directed varies, often one or more millimeters. To measure such distance variations, an optical or laser sensor 40b is provided either on the print head 30 or on the carriage at a fixed height from the plane of support of the fabric. The sensor 40b instantaneously measures the distance from the nozzle 41 to the surface 16 of the panel 15 and communicates the measurement to the controller 35. The nozzle 41 is mounted on an output actuator 51 of a servo motor 50 mounted in the print head 30. The controller 35 sends a control signal to the servo motor 50 to move the nozzle 41 on the print head 30 vertically in response to the distance measurement from the sensor 40b to maintain a constant distance from the nozzle 41 to the surface 16 of the panel 15.

**[0035]** Printing on rigid panels, even where the surface is not textured or contoured, can benefit from the sensing and adjustment of the distance from print nozzle to surface of the panel since the rigid frame of the panel and the thickness of the panel when supported on the frame of a printing apparatus makes the position of the upper surface of the panel unpredictable.

**[0036]** Fig. 1 A illustrates an alternative embodiment 100 of the machine 10 described above. The machine embodiment 100 includes a stationary frame 111 with a longitudinal extent represented by an arrow 112 and a transverse extent represented by an arrow 113. The machine 100 has a front end 114 into which the rigid office partition panel 15 may be loaded onto a belt 121 of a conveyor system 120 having one or more flights which carry the panel 15 longitudinally through the machine 100. The belt 121 of the conveyor 120 extends across the width of the frame 111 and rests on a smooth stainless steel vacuum table 105, which has therein an array of upwardly facing vacuum holes 106 which communicate with the underside of the belt 121. The belt 121 is sufficiently porous that the vacuum from the table 105 communicates through the belt 121 to the underside of the rigid panel 15 to assist gravity in holding the panel 15 in place against the top side of the belt 121. Preferably, the belt 121 has a high friction rubber-like surface 108 to help prevent a horizontal sliding of a panel resting on it, through which an array of holes 109 is provided to facilitate communication of the vacuum from the table 105 to the substrate.

**[0037]** The top surface of the belt 121 of the conveyor 120 is such that it provides sufficient friction between it and the underside of the panel 15 to keep the panel 15 from sliding horizontally on the conveyor 120. The conveyor 120 is further sufficiently non-elastic so that it can be precisely advanced. To this end, the belt 121 has a non-elastic open weave backing 107 to provide dimensional stability to the belt while allowing the vacuum to be communicated between the holes 106 of the table 105 and the holes 109 in the surface of the belt 121. The forward motion of the panel 15 on the frame 111 is precisely controllable by indexing of the belt 121 by control of a servo drive motor 122 with signals from the controller 35. The belt 121 thereby retains the panels 15 in a precisely known longitudinal position on the belt 121 so as to carry the panels 15 through the longitudinal extent of the machine 100. Such indexing of the belt 121 should be controllable to an accuracy of about 0.0005 inches where used to move the panel 15 relative to a print head on a fixed bridge (which embodiment is not shown).

**[0038]** In the embodiment 100 illustrated in Fig. 1A, the longitudinal movement of the belt 121 of the conveyor 120 is controlled by the conveyor drive 122 to move the panel into printing position and then to advance it downstream after it is printed. One or more additional separately controllable drives 132 may be provided to control the downstream flights, if any, of the conveyor 120.

**[0039]** Along the length of travel of the conveyor 120 are provided three stations, including an ink jet printing station 125 and one or more curing or drying stations, which may include UV light curing stations 124 and/or a heating station 126. The printing station 125 includes a bridge 128. Where the belt 121 is operable to precisely index the panel 15 relative to the bridge 128, the bridge may be fixed to the frame 111 and extend transversely

across it. A printhead carriage 129 is transversely moveable across the bridge 128 and has one or more sets 130 of ink jet printing heads thereon. The carriage 129 is preferably fixed to the armature of a linear servo motor 131 which has a linear array of stator magnets extending transversely across the bridge 128, so that the carriage 129 is transversely moveable across the bridge 128 by positioning and drive control signals sent to the servo 131 by the controller 35, described above.

**[0040]** In the illustrated embodiment, the bridge 128 is mounted to the moveable armatures 133a, 134a that ride on longitudinal tracks 133b, 134b of linear servo motors 133, 134 at each side of the conveyor 120. Once a panel 15 is positioned under the bridge 128 by movement of the belt 121, the bridge 128 is indexed in the longitudinal direction as transverse bands of an image are printed in successive scans of print heads 130, described below. This indexing should be as accurate as needed to insure that the scans register one with another and can be interlaced, as required, to produce the desired print quality and resolution. Such accuracy is preferred to be about 0.0005 inches. Lower resolution, and thus less accuracy, is acceptable for printing on textile surfaces than on smoother surfaces such as vinyl.

**[0041]** Fig. 3 illustrates a set 130 of four ink jet printing heads 130a-130d configured to respectively apply the four colors of a CMYK color set. The ink jet printing heads 130a-d each include a linear array of one hundred twenty-eight (128) ink jet nozzles that extend in the longitudinal direction relative to the frame 111 and in a line perpendicular to the direction of travel of the carriage 129 on the bridge 128. The nozzles of each of the heads 130 are configured and controlled to simultaneously but selectively jet UV ink of one of the CMYK colors side by side across the substrate 15, and to do so in a series of cycles as the nozzles scan the substrate 15. The heads 130a-d of a set are arranged side-by-side to print consecutively across the same area of the substrate 15 as the carriage 129 moves across the bridge 128, each depositing one of the four colors sequentially on each dot position across the substrate 15.

**[0042]** Each of the heads 130a-d is moveably mounted to the carriage to individually move vertically, or perpendicular to the plane of the substrate 15. The distance of each head 130a-d from the plane of the substrate 15 is controlled by a respective one of a set of servos 137a-d mounted to the carriage 129 to follow one behind the other over the same contour of the substrate 15. The servos 137a-d are responsive to signals from the controller 35 which controls the positions of the heads 130a-d to maintain each a controlled distance from the surface of the substrate 15 where the surface 16 of the substrate 15 is contoured.

**[0043]** Usually, it is desirable to maintain the heads a fixed distance from the surface 16 on which they are to print. This is achieved by providing optical sensors 138a, 138b on the opposite transverse sides of the carriage 129. The printhead set 130 is bidirectional and prints

whether moving to the right or to the left. As the print head carriage 129 moves on the bridge 128, the leading one of the sensors 138a or 138b measures the distance from the sensor 138 and the surface 16 of the substrate 15 at a point directly in line with, typically directly below, the sensor 138. This measurement is communicated to the controller 35, which records the measured distance and the coordinates on the surface 16 of the substrate 15 at which the measurement was taken. These coordinates need only include the transverse position on the substrate 15 where the information is to be used in the same pass or scan of the carriage in which the measurement was taken. However, the controller 35 may also record the longitudinal coordinate by taking into account the position of the panel 15 on the frame 111 relative to the bridge 128.

**[0044]** In response to the measurements, the controller 35 controls the servos 137 to vertically position the each of the heads 130 to a predetermined distance from the contoured surface 16 of the substrate 15 as the respective head arrives at the transverse coordinate on the substrate 15 at which each measurement was taken. As a result, the nearest of the heads 130 to the leading sensor 138, which are spaced a distance  $B$  from the sensor 138, follows the contour of the fabric at a delay of  $V/B$  seconds after a given measurement was taken, where  $V$  is the velocity of the carriage 129 on the bridge 128. Similarly, the heads 130 are spaced apart a distance  $A$  and will each sequentially follow the same contour as the first head at  $V/A$  seconds after the preceding head.

**[0045]** The extent of the heads 130 in the longitudinal direction determines the accuracy with which the heads can follow the contours of the substrate 15. Greater accuracy can be maintained, and more variable contours can be followed, by using narrower heads, for example, of 64 or 32 jets per head in the longitudinal direction. Accordingly, multiple sets of heads 130 can be arranged in a rectangular or other array on the carriage 129, with heads of the different sets being arranged side-by-side across the carriage 129 in the longitudinal direction of the substrate 15 and frame 111. For example, two sets of heads having 64 jets per head each or four sets of heads having 32 jets per head each will produce the same 128 dot wide scan, but with greater ability to maintain spacing from head to substrate where the contours vary in the longitudinal direction on the substrate 15.

**[0046]** Where UV curable ink is used, the UV curing station 124 is provided as illustrated in Fig. 1A. It may include a printhead 23 transversely moveable independently of the print heads 130 across the downstream side of the bridge 128 or otherwise located downstream of the printing station 125, and/or may include UV light curing heads 123a and 123b mounted on the carriage 129. As the carriage 129 moves transversely on the bridge 128, only the curing head 123a, 123b that trails the print heads 130 is operated so that the UV light exposes ink after its deposition onto the substrate 15. The curing heads 123a, 123b may also be moveable toward and away from the

plane of the substrate 15 and controllable by servos 139a, 139b, respectively, to maintain their spacing from the surface 16, as illustrated in Fig. 3. Proper curing of UV ink requires that the UV light be focused on the surface bearing the ink. Therefore, moving the UV heads 123a, 123b to maintain a constant spacing from the surface 16 maintains the focus of the curing UV light. UV light curing heads are typically configured to sharply focus a narrow, longitudinally extending beam of UV light onto the printed surface. Therefore, instead of physically moving the UV light curing heads or sources 123a, 123b, the focal lengths of the light curing heads 123a, 123b may be varied to follow the contours of the substrate 15. The light curing head 123, where used, may similarly be configured to move perpendicular to the surface 16 of the substrate 15.

**[0047]** The heat curing or drying station 126 may be fixed to the frame 111 downstream of the printing station 125 and the UV light curing station, if any, may be located off-line. Such a drying station 126 may be used to dry solvent based inks with heated air, radiation or other heating techniques. It may also be used to further cure or dry UV inks.

**[0048]** Printing on rigid panels, even where the surface is not textured or contoured, can benefit from the sensing and adjustment of the distance from print nozzle to surface of the panel since the rigid frame of the panel and the thickness of the panel when supported on the frame of a printing apparatus makes the position of the upper surface of the panel unpredictable.

**[0049]** The above description is representative of certain preferred embodiments of the invention.

## Claims

1. A method of printing on a substrate with a plurality of ink jet print heads each having at least one nozzle (41) thereon, the method comprising moving a print head carriage (129), having the plurality of ink jet print heads (30, 130) thereon, parallel to a plane on which is supported the substrate (15) having a surface (16) thereon to be printed by the jetting of ink from the nozzle (41), and jetting ink from the nozzles (41) onto the surface (16) of the substrate (15), wherein the substrate (15) is moved longitudinally relative to the print heads (130) and the print heads (130) on the carriage (129) are moved transversely relative to the substrate (15), **characterized in that** the method further comprises automatically adjusting the distance from the print heads to the plane in response to sensing the position of a portion of the surface (16) with a sensor (138a, 138b) carried on the carriage (129) to position the print heads at a predetermined distance from the surface (16) of the substrate (15) where ink is to be jetted from the nozzles.

2. The method of claim 1 wherein the substrate includes a rigid panel (15) and the ink jet nozzles (41) are directed toward a surface (16) of the panel (15), the adjusting includes automatically adjusting the distance of the print heads (30, 130) from the panel (15) to maintain the predetermined distance between the print heads (30, 130) and the surface of the panel (15) at a location onto which ink is to be jetted from the nozzles (41), and while moving the print head carriage (129), jetting ink from the nozzles (41) across the predetermined distance and onto the surface (16) of the rigid panel (15). 5
3. The method of claim 2 wherein the surface (16) of the panel (15) onto which the ink is jetted varies across the panel in its distance from the carriage (129), and the adjusting includes varying the position of the print heads (30, 130) relative to the panel (15) as the print heads (30, 130) are moved to maintain the predetermined spacing between the print heads (30, 130) and the location on the surface at which the ink is jetted. 10
4. The method of claim 1 wherein the substrate includes a rigid panel (15) and the ink jet nozzles (41) is directed toward a surface of the panel, the surface (16) of the panel (15) onto which the ink is jetted varies across the panel in its distance from the carriage (129), the sensing includes sensing the contour of the surface of the panel, and the adjusting includes moving the carriage (129) parallel to the panel to locations determined in response to the sensed contour and jetting the ink onto the surface of the panel (15) at the locations. 15
5. The method of any preceding claim wherein the sensing of the position is carried out while moving the print head carriage (129), and the adjusting includes varying the position of the print heads (30, 130) relative to the plane as the print head carriage (129) moves so as to maintain the predetermined distance across the substrate (15) in response to the sensing. 20
6. The method of any preceding claim wherein the sensing includes sensing the distance between the print head carriage (129) and locations on the surface at which ink is to be jetted, and the adjusting includes varying the position of the print heads (30, 130) relative to the print head carriage (129) in response to the sensed distance. 25
7. The method of any preceding claim wherein the ink is UV curable ink, and the method further comprises the step of at least partially curing the ink jetted onto the surface (16) by exposing the jetted ink to ultra-violet light. 30
8. The method of claim 7 wherein the exposing of the ink includes adjusting the distance of the UV light from a light source to said plane as the carriage (129) is moved parallel to said plane. 35
9. The method of claim 7 wherein the exposing of the ink includes adjusting the focus of the UV light onto the surface that bears the jetted ink as the carriage (129) is moved parallel to said plane. 40
10. The method of any of claims 7 to 9 wherein the method further comprises heating the surface (16) having the at least partially cured ink thereon to reduce the content of unpolymerized monomers of the ink on the substrate. 45
11. The method of claim 10 wherein the heating includes flowing heated air onto the surface (16) of the substrate (15) having the at least partially cured UV light cured ink thereon to remove uncured components of the ink from the substrate (15). 50
12. The method of any preceding claim further comprising the steps of thereafter combining one or more secondary layers of material with the substrate (16), and quilting a quilted pattern on the combined layers of material and substrate in coordination with the pattern printed on the substrate (16). 55
13. The method of any one of claims 1 to 11 further comprising the steps of combining one or more secondary layers of material with the substrate (16), quilting the combined layers of material and substrate, and then registering the surface where the ink is to be jetted with contours of the quilted substrate and performing the printing step by printing onto the substrate in registration with the quilted pattern.
14. The method of any one of claims 1 to 11 further comprising the steps of combining one or more secondary layers of material with the substrate (16), quilting the combined layers of material and substrate, and then sensing the contours of the quilted substrate and performing the printing step by printing onto the substrate at points determined in response to the sensing of the contours.
15. The method of any preceding claim wherein the distances from each of the print heads (130) to the plane is separately adjusted to position each of the heads (130) at a respective predetermined distance from the surface (16) of the substrate (15) onto which ink is to be jetted from the heads (130), and the method further comprises jetting ink from the heads (130), at their adjusted distances from said plane, across the respective predetermined distances onto the surface (16) of the substrate (15), then further moving the print head carriage (129) parallel to the plane

- while the substrate (15) is supported therein, then separately readjusting the distances from each of the print heads (130) to the plane to reposition each of the heads (130) to maintain the respective predetermined distance from the surface (16) that varies relative to the plane, and further jetting ink from the heads (130), at their readjusted distances from said plane, across the respective predetermined distances onto the surface (16) of a substrate (15).
16. The method of any of claims 1 to 14 wherein the method further comprises automatically and separately adjusting the positions of each of the print heads (130) toward and away from the substrate (15), as the carriage (129) is moving parallel to the substrate (15), to maintain respective predetermined distances between the print heads and the surface of the substrate onto which ink is jetted from the print heads (130).
17. The method of either claim 15 or claim 16 further comprising separately adjusting the position of each print head (130) and applying a different color of ink with different ones of the print heads.
18. The method of any of claims 15 through 17, further comprising detecting the distance between the print heads (130) and the substrate (15).
19. The method of claim 18, further comprising transmitting the distance information to a controller (35) and re-adjusting the position of the print heads (130) based on the distance information detected.
20. The method of claim 19 further comprising transmitting the information from at least one of at least two sensors (138a, 138b) mounted on the carriage.
21. An apparatus for printing on a surface of a three-dimensional substrate comprising a frame (11, 111) having a substrate support (20, 120) mounted thereon defining a substrate supporting plane and a print head track (28, 128) extending parallel to the plane, a plurality of ink jet print heads (30, 130) each having at least one nozzle (41) thereon moveably supported on the track (28, 128) via a print head carriage (129) with the nozzles directed toward the surface (16) of a substrate (15) supported by the substrate support (20, 120), the substrate support (20, 120) being operable to move the substrate (15) longitudinally relative the print heads (130) and the print heads (130) on the carriage (129) being moveable transversely relative the substrate (15), and a control system (35) operable to move and control the print heads (30, 130) to print on the substrate (15) by jetting ink from the nozzles (41) onto the surface (16) of a substrate (15), **characterized in that** the apparatus further comprises a sensor (40a, 40b, 138a, 138b) carried on the carriage (129) and operable to provide a distance measurement of a portion of the surface (16), and **in that** the print heads (30, 130) are moveable automatically perpendicular to the plane in response to the sensor (40a, 40b, 138a, 138b) to a predetermined distance from the surface (16) of the substrate (15).
22. The apparatus of claim 21 further comprising a UV light curing head (23, 123a, 23b) positioned so as to expose to UV light ink jetted onto the surface (16) of the substrate by the print head (30, 130).
23. The apparatus of claim 23 wherein the UV light curing head (23, 123a, 123b) is moveable relative to the plane, and the control system (35) is operable to move the curing head (23, 123a, 123b) to maintain focus of UV light from the curing head (23, 123a, 123b) on ink jetted onto the surface (16) of the substrate (15).
24. The apparatus of either claim 22 or claim 23 further comprising:  
a heating station (26, 126) positioned so as to heat UV light exposed ink on the substrate.
25. The apparatus of claim 24 wherein the heating station (26, 126) includes a blower oriented to direct heated air onto a substrate on the support.
26. The apparatus of any of claims 21 to 25 further comprising a quilting station positioned to quilt the substrate (15) to impart a contour to the surface of the substrate (15).
27. The apparatus of any of claims 21 to 26 wherein the sensor (40b, 138a, 138b) is mounted in the carriage (129).
28. The apparatus of any of claims 21 to 27 wherein the sensor includes two sensors (138a, 138b) mounted in the carriage (129).
29. The apparatus of any one of claims 21 to 28 wherein the sensor is a non-contact, distance measuring device (40b, 138a, 138b) that includes a light source and light detector mounted on the track.
30. The apparatus of any of claims 21 to 29 wherein the sensor (138a, 138b) is operable to determine a location on the surface (16) of the substrate (15) and the print heads (130) are separately and selectively moveable perpendicular to the plane in response to the sensor (138a, 138b) to respective predetermined distances from the determined location on the surface (16) of the substrate (15), and the control system (35) being operable to separately move and control

each of the print heads (130) to print on the substrate (15) by jetting ink from the print heads (130) across the respective predetermined distances and onto the substrate.

31. The apparatus of any of claims 21 to 29 wherein the print heads (130) are individually moveable and spaced in the direction of movement of the carriage (129) so as to sequentially pass over the same areas of the substrate (15) and each print one of a set of colors thereon, the print heads (130) are separately and selectively moveable toward and away from the plane, and the control system (35) is operable to control the print heads (130) in response to the sensor (138a, 138b) to sequentially follow the contour of the substrate surface as the carriage moves across the substrate to maintain a constant distance of travel of ink from each print head to the surface of the substrate.
32. The apparatus of any of claims 21 to 29 wherein the print heads (130) are individually moveable and arranged side-by-side on the carriage (129) perpendicular to the direction of movement of the carriage (129) so that each can maintain a controlled spacing from the substrate where the contour of the substrate (15) varies in the direction perpendicular to the movement of the carriage (129).
33. The apparatus of either claim 31 or claim 32 wherein the print heads (130) are bidirectional print heads that print while moving transversely across a substrate (15) that is moveable longitudinally relative to the print heads (130), the sensor includes two sensors (138a, 138b) mounted on the carriage (129) transversely of the print heads (130), one on each side of the print heads.
34. The apparatus of any of claims 21 to 33 wherein the track (128) has further mounted thereon a plurality of servo motors (137a-d), each responsive to an output signal from the sensor (138a, 138b) to adjust the position of the print heads (130) relative to the substrate (15) to control the distance across which ink is jetted during printing.

#### Patentansprüche

1. Verfahren zum Drucken auf ein Trägermaterial mit mehreren Tintenstrahl-Druckköpfen, an denen sich jeweils mindestens eine Düse (41) befindet, wobei das Verfahren Folgendes umfasst: Bewegen eines Druckkopfwagens (129), auf dem sich die mehreren Tintenstrahl-Druckköpfe (30, 130) befinden, parallel zu einer Ebene, auf der das Trägermaterial (15) gelagert ist, auf dem sich eine Oberfläche (16) befindet, die durch das Spritzen von Tinte aus der Düse (41)

zu bedrucken ist; und Spritzen von Tinte aus den Düsen (41) auf die Oberfläche (16) des Trägermaterials (15), wobei das Trägermaterial (15) in Längsrichtung relativ zu den Druckköpfen (130) bewegt wird und die Druckköpfe (130) auf dem Wagen (120) in Querrichtung relativ zu dem Trägermaterial (15) bewegt werden; **dadurch gekennzeichnet, dass** das Verfahren weiter das automatische Einstellen des Abstands von den Druckköpfen zu der Ebene als Reaktion auf das Abfühlen der Lage eines Abschnitts der Oberfläche (16) mit einem auf dem Wagen (129) getragenen Sensor (138a, 138b) umfasst, um die Druckköpfe in einem vorherbestimmten Abstand von der Oberfläche (16) des Trägermaterials (15) zu positionieren, wo Tinte aus den Düsen gespritzt werden soll.

2. Verfahren nach Anspruch 1, wobei das Trägermaterial eine starre Tafel (15) umfasst und die Tintenstrahldüsen (41) zu einer Oberfläche (16) der Tafel (15) gerichtet sind, wobei das Einstellen das automatische Einstellen des Abstands der Druckköpfe (30, 130) von der Tafel (15) umfasst, um den vorherbestimmten Abstand zwischen den Druckköpfen (30, 130) und der Oberfläche der Tafel (15) an einem Ort beizubehalten, auf den Tinte von den Düsen (41) gespritzt werden soll, und Spritzen von Tinte aus den Düsen (41) über den vorherbestimmten Abstand und auf die Oberfläche (16) der starren Tafel (15) während des Bewegens des Druckkopfwagens (129) umfasst.
3. Verfahren nach Anspruch 2, wobei die Oberfläche (16) der Tafel (15), auf die die Tinte gespritzt wird, sich über die Tafel in ihrem Abstand von dem Wagen (129) verändert und das Einstellen das Verändern der Lage der Druckköpfe (30, 130) relativ zu der Tafel (15) umfasst, während die Druckköpfe (30, 130) bewegt werden, um die vorherbestimmte Beabstandung zwischen den Druckköpfen (30, 130) und dem Ort auf der Oberfläche, an den die Tinte gespritzt wird, beizubehalten.
4. Verfahren nach Anspruch 1, wobei das Trägermaterial eine starre Tafel (15) umfasst und die Tintenstrahldüsen (41) zu einer Oberfläche der Tafel gerichtet sind, die Oberfläche (16) der Tafel (15) auf die die Tinte gespritzt wird, sich über der Tafel in ihrem Abstand von dem Wagen (129) verändert, das Abfühlen das Abfühlen der Kontur der Oberfläche der Tafel umfasst und das Einstellen das Bewegen des Wagens (129) parallel zu der Tafel an Orte, die als Reaktion auf die abgefühlte Kontur bestimmt wurden und Spritzen der Tinte auf die Oberfläche der Tafel (15) an den Orten umfasst.
5. Verfahren nach einem der vorangehenden Ansprüche, wobei das Abfühlen der Lage während des Be-

- wegens des Druckkopfwagens (129) ausgeführt wird und das Einstellen das Verändern der Lage der Druckköpfe (30, 130) relativ zu der Ebene umfasst, während sich der Druckkopfwagen (129) bewegt, um den vorherbestimmten Abstand über dem Trägermaterial (15) als Reaktion auf das Abfühlen beizubehalten.
6. Verfahren nach einem der vorangehenden Ansprüche, wobei das Abfühlen das Abfühlen des Abstands zwischen dem Druckkopfwagen (129) und Orten auf der Oberfläche, an die Tinte gespritzt werden soll, umfasst und das Einstellen das Verändern der Lage der Druckköpfe (30, 130) relativ zum Druckkopfwagen (129) als Reaktion auf den abgefühlten Abstand umfasst.
  7. Verfahren nach einem der vorangehenden Ansprüche, wobei es sich bei der Tinte um UV-härtende Tinte handelt und das Verfahren weiter den Schritt des mindestens teilweisen Härtens der auf die Oberfläche (16) gespritzten Tinte durch Aussetzen der gespritzten Tinte an Ultraviolettlicht umfasst.
  8. Verfahren nach Anspruch 7, wobei das Belichten der Tinte das Einstellen des Abstands des UV-Lichts von einer Lichtquelle zur genannten Ebene umfasst, während der Wagen (129) parallel zur genannten Ebene bewegt wird.
  9. Verfahren nach Anspruch 7, wobei das Belichten der Tinte das Einstellen des Fokus des UV-Lichts auf die die gespritzte Tinte tragende Oberfläche umfasst, während der Wagen (129) parallel zur genannten Ebene bewegt wird.
  10. Verfahren nach einem der Ansprüche 7 bis 9, wobei das Verfahren weiter das Erwärmen der Oberfläche (16), auf der sich die mindestens teilweise gehärtete Tinte befindet, umfasst, um den Gehalt an unpolymerisierten Monomeren der Tinte auf dem Trägermaterial zu verringern.
  11. Verfahren nach Anspruch 10, wobei das Erwärmen das Strömen erwärmter Luft auf die Oberfläche (16) des Trägermaterials (15), auf der sich die mindestens teilweise gehärtete UV-lichtgehärtete Tinte befindet, umfasst, um ungehärtete Bestandteile der Tinte von dem Trägermaterial (15) zu entfernen.
  12. Verfahren nach einem der vorangehenden Ansprüche, weiter umfassend die Schritte des darauf folgenden Kombinierens einer oder mehrerer Sekundärschichten von Material mit dem Trägermaterial (16) und Steppen eines gesteppten Musters auf die kombinierten Schichten von Material und Trägermaterial in Koordination mit dem auf das Trägermaterial (16) gedruckten Muster.
  13. Verfahren nach einem der Ansprüche 1 bis 11, weiter umfassend die Schritte des Kombinierens einer oder mehrerer Sekundärschichten von Material mit dem Trägermaterial (16), Steppen der kombinierten Schichten von Material und Trägermaterial und dann ins Register bringen der Oberfläche, wo die Tinte hingespritzt werden soll, mit den Konturen des gesteppten Trägermaterials und Ausführen des Druckschritts durch Drucken auf das Trägermaterial im Register mit dem gesteppten Muster.
  14. Verfahren nach einem der Ansprüche 1 bis 11, weiter umfassend die Schritte des Kombinierens einer oder mehrerer Sekundärschichten von Material mit dem Trägermaterial (16), Steppen der kombinierten Schichten von Material und Trägermaterial und dann Abfühlen der Konturen des gesteppten Trägermaterials und Ausführen des Druckschritts durch Drucken auf das Trägermaterial an Stellen, die als Reaktion auf das Abfühlen der Konturen bestimmt werden.
  15. Verfahren nach einem der vorangehenden Ansprüche, wobei die Abstände von jedem der Druckköpfe (130) zu der Ebene einzeln eingestellt werden, um jeden der Druckköpfe (130) in einem jeweiligen vorherbestimmten Abstand von der Oberfläche (16) des Trägermaterials (15), auf die Tinte von den Köpfen (130) gespritzt werden soll, zu positionieren und das Verfahren weiter Folgendes umfasst: Spritzen von Tinte von den Köpfen (130) in ihren eingestellten Abständen von der genannten Ebene über die jeweiligen vorherbestimmten Abstände auf die Oberfläche (16) des Trägermaterials (15), dann weiter Bewegen des Druckkopfwagens (129) parallel zu der Ebene, während das Trägermaterial (15) darin getragen wird, dann getrenntes Neueinstellen der Abstände von jedem der Druckköpfe (130) zur Ebene, um jeden der Köpfe (130) neu zu positionieren, um den jeweiligen vorherbestimmten Abstand von der Oberfläche (16) beizubehalten, der sich relativ zur Ebene verändert, und weiteres Spritzen von Tinte von den Köpfen (130) in ihren neu eingestellten Abständen von der genannten Ebene über die jeweiligen vorherbestimmten Abstände auf die Oberfläche (16) eines Trägermaterials (15).
  16. Verfahren nach einem der Ansprüche 1 bis 14, wobei das Verfahren weiter das automatische und getrennte Einstellen der Lagen von jedem der Druckköpfe (130) zu dem und von dem Trägermaterial (15) weg umfasst, während sich der Wagen (129) parallel zum Trägermaterial (15) bewegt, um jeweilige vorherbestimmte Abstände zwischen den Druckköpfen und der Oberfläche des Trägermaterials, auf die Tinte von den Druckköpfen (130) gespritzt wird, beizubehalten.
  17. Verfahren nach Anspruch 15 oder Anspruch 16, wei-

ter umfassend das getrennte Einstellen der Lage jedes Druckkopfs (130) und Aufbringen von Tinte verschiedener Farbe mit verschiedenen der Druckköpfe.

18. Verfahren nach einem der Ansprüche 15 bis 17, weiter umfassend das Erfassen des Abstands zwischen den Druckköpfen (130) und dem Trägermaterial (15).
19. Verfahren nach Anspruch 18, weiter umfassend das Übertragen der Abstandsinformationen an einen Controller (35) und neues Einstellen der Lage der Druckköpfe (130) basierend auf den erfassten Abstandsinformationen.
20. Verfahren nach Anspruch 19, weiter umfassend das Übertragen der Informationen von mindestens einem von mindestens zwei Sensoren (138a, 138b), die an dem Wagen angebracht sind.
21. Vorrichtung zum Drucken auf einer Oberfläche eines dreidimensionalen Trägermaterials, umfassend einen Rahmen (11, 111) mit einem daran angebrachten Trägermaterialhalter (20, 120), der eine Trägermaterial-Tragebene und eine sich parallel zu der Ebene erstreckende Druckkopfbahn (28, 128) definiert, mehrere Tintenstrahl-Druckköpfe (30, 130), an denen sich jeweils mindestens eine Düse (41) befindet, die über einen Druckkopfwagen (129), mit den Düsen zur Oberfläche (16) eines Trägermaterials (15), das von dem Trägermaterialhalter (20, 120) getragen wird, gerichtet, bewegbar auf der Bahn (28, 128) getragen wird, wobei der Trägermaterialhalter (20, 120) wirksam ist, das Trägermaterial (15) in Längsrichtung relativ zu den Druckköpfen (130) zu bewegen und die Druckköpfe am Wagen (129) in Querrichtung relativ zum Trägermaterial (15) bewegbar sind; und eine Steuerung (35), die wirksam ist, die Druckköpfe (30, 130) zu bewegen und zu steuern, um auf das Trägermaterial (15) zu drucken, indem Tinte von den Düsen (41) auf die Oberfläche (16) eines Trägermaterials (15) gespritzt wird; **dadurch gekennzeichnet, dass** die Vorrichtung weiter einen Sensor (40a, 40b, 138a, 138b) umfasst, der auf dem Wagen (129) getragen wird, und wirksam ist, eine Abstandsmessung eines Abschnitts der Oberfläche (16) zu liefern und dass die Druckköpfe (30, 130) automatisch als Reaktion auf den Sensor (40a, 40b, 138a, 138b) zu einem vorherbestimmten Abstand von der Oberfläche (16) des Trägermaterials (15) senkrecht zur Ebene bewegbar sind.
22. Vorrichtung nach Anspruch 21, weiter umfassend einen UV-Licht-Härtekopf (23, 123a, 23b), der so positioniert ist, dass durch den Druckkopf (30, 130) auf die Oberfläche (16) des Trägermaterials gespritzte

Tinte an UV-Licht ausgesetzt wird.

23. Vorrichtung nach Anspruch 23, wobei der UV-Licht-Härtekopf (23, 123a, 123b) relativ zur Ebene bewegbar ist und die Steuerung (35) wirksam ist, den Härtekopf (23, 123a, 123b) zu bewegen, um Fokussierung von UV-Licht vom Härtekopf (23, 123a, 123b) auf die Oberfläche (16) des Trägermaterials (15) gespritzte Tinte beizubehalten.
24. Vorrichtung nach Anspruch 22 oder Anspruch 23, weiter umfassend: eine Heizstation (26, 126), die so positioniert ist, dass sie an UV-Licht ausgesetzte Tinte auf dem Trägermaterial erwärmt.
25. Vorrichtung nach Anspruch 24, wobei die Heizstation (26, 126) ein Gebläse umfasst, das dazu orientiert ist, erwärmte Luft auf ein Trägermaterial auf dem Halter zu richten.
26. Vorrichtung nach einem der Ansprüche 21 bis 25, weiter umfassend eine Steppstation, die dazu positioniert ist, das Trägermaterial (15) zu steppen, um der Oberfläche des Trägermaterials (15) eine Kontur zu verleihen.
27. Vorrichtung nach einem der Ansprüche 21 bis 26, wobei der Sensor (40b, 138a, 138b) im Wagen (129) montiert ist.
28. Vorrichtung nach einem der Ansprüche 21 bis 27, wobei der Sensor zwei Sensoren (138a, 138b) umfasst, die im Wagen (129) montiert sind.
29. Vorrichtung nach einem der Ansprüche 21 bis 28, wobei es sich bei dem Sensor um eine berührungslose Abstandsmessvorrichtung (40b, 138a, 138b) handelt, die eine Lichtquelle und einen Lichtdetektor umfasst, die auf der Bahn montiert sind.
30. Vorrichtung nach einem der Ansprüche 21 bis 29, wobei der Sensor (138a, 138b) wirksam ist, einen Ort auf der Oberfläche (16) des Trägermaterials (15) zu bestimmen und die Druckköpfe (130) als Reaktion auf den Sensor (138a, 138b) einzeln und selektiv senkrecht zur Ebene zu jeweiligen vorherbestimmten Abständen vom bestimmten Ort auf der Oberfläche (16) des Trägermaterials (15) bewegbar sind und wobei die Steuerung (35) wirksam ist, jeden der Druckköpfe (130) einzeln zu bewegen und zu steuern, um auf das Trägermaterial (15) zu drucken, indem Tinte von den Druckköpfen (130) über die jeweiligen vorherbestimmten Abstände und auf das Trägermaterial gespritzt wird.
31. Vorrichtung nach einem der Ansprüche 21 bis 29, wobei die Druckköpfe (130) einzeln bewegbar und in der Richtung der Bewegung des Wagens (129)

beabstandet sind, um sich nacheinander über die selben Bereiche des Trägermaterials (15) zu bewegen und jeweils eine einer Menge von Farben darauf zu drucken, wobei die Druckköpfe (130) einzeln und selektiv zu der und von der Ebene weg bewegbar sind und die Steuerung (35) wirksam ist, die Druckköpfe (130) als Reaktion auf den Sensor (138a, 138b) zu steuern, um nacheinander der Kontur der Trägermaterialoberfläche zu folgen, während sich der Wagen über das Trägermaterial bewegt, um eine konstante Bewegungsstrecke von Tinte von jedem Druckkopf zur Oberfläche des Trägermaterials beizubehalten.

32. Vorrichtung nach einem der Ansprüche 21 bis 29, wobei die Druckköpfe (130) einzeln bewegbar sind und nebeneinander senkrecht zur Bewegungsrichtung des Wagens (129) auf dem Wagen (129) angeordnet sind, so dass sie jeweils eine kontrollierte Beabstandung vom Trägermaterial beibehalten können, wenn sich die Kontur des Trägermaterials (15) in der Richtung senkrecht zur Bewegung des Wagens (129) verändert.
33. Vorrichtung nach Anspruch 31 oder Anspruch 32, wobei die Druckköpfe (130) bidirektionale Druckköpfe sind, die Drucken, während sie sich in Querrichtung über ein Trägermaterial (15) bewegen, das in Längsrichtung relativ zu den Druckköpfen (130) bewegbar ist und der Sensor zwei Sensoren (138a, 138b) umfasst, die jeweils einer auf jeder Seite der Druckköpfe, quer zu den Druckköpfen (130) an dem Wagen (129) montiert sind.
34. Vorrichtung nach einem der Ansprüche 21 bis 33, wobei an der Bahn (128) weiter mehrere Servomotoren (137a-d) angebracht sind, die jeweils auf ein Ausgangssignal von dem Sensor (138a, 138b) reagieren, um die Lage der Druckköpfe (130) relativ zu dem Trägermaterial (15) einzustellen, um den Abstand zu steuern, über den Tinte während des Druckens gespritzt wird.

## Revendications

1. Procédé d'impression sur un substrat avec une pluralité de têtes d'impression à jet d'encre sur chacune desquelles est montée au moins une buse (41), le procédé comprenant le déplacement d'un chariot de têtes d'impression (129), sur lequel est montée la pluralité de têtes d'impression à jet d'encre (30, 130), parallèlement à un plan sur lequel est supporté le substrat (15) ayant une surface (16) destinée à être imprimée par la projection d'encre depuis la buse (41), et la projection d'encre depuis les buses (41) sur la surface (16) du substrat (15), dans lequel le substrat (15) est déplacé longitudinalement par rap-

port aux têtes d'impression (130) et les têtes d'impression (130) sur le chariot (129) sont déplacées transversalement au substrat (15), **caractérisé en ce que** le procédé comprend en outre le réglage automatique de la distance des têtes d'impression par rapport au plan en réponse à la détection de la position d'une partie de la surface (16) avec un capteur (138a, 138b) porté sur le chariot (129) afin de positionner les têtes d'impression à une distance prédéterminée de la surface (16) du substrat (15) où de l'encre doit être projetée depuis les buses.

2. Procédé selon la revendication 1, dans lequel le substrat comporte un panneau rigide (15) et les buses de jet d'encre (41) sont dirigées vers une surface (16) du panneau (15), le réglage comporte le réglage automatique de la distance des têtes d'impression (30, 130) par rapport au panneau (15) afin de maintenir la distance prédéterminée entre les têtes d'impression (30, 130) et la surface du panneau (15) à une position sur laquelle de l'encre doit être projetée depuis les buses (41), et tout en déplaçant le chariot de têtes d'impression (129), la projection d'encre depuis les buses (41) à la distance prédéterminée et sur la surface (16) du panneau rigide (15).
3. Procédé selon la revendication 2, dans lequel la surface (16) du panneau (15) sur lequel l'encre est projetée varie sur tout le panneau en terme de distance depuis le chariot (129), et le réglage comporte la variation de la position des têtes d'impression (30, 130) par rapport au panneau (15) durant le déplacement des têtes d'impression (30, 130) afin de maintenir l'espacement prédéterminé entre les têtes d'impression (30, 130) et l'emplacement sur la surface auquel l'encre est projetée.
4. Procédé selon la revendication 1, dans lequel le substrat comporte un panneau rigide (15) et les buses de jet d'encre (41) sont dirigées vers une surface du panneau, la surface (16) du panneau (15) sur laquelle l'encre est projetée varie sur tout le panneau en terme de distance par rapport au chariot (129), la détection comporte la détection du contour de la surface du panneau, et le réglage comporte le déplacement du chariot (129) parallèlement au panneau jusqu'à des emplacements déterminés en réponse au contour détecté et la projection de l'encre sur la surface du panneau (15) aux emplacements.
5. Procédé selon l'une quelconque des revendications précédentes, dans lequel la détection de la position est effectuée durant le déplacement du chariot de têtes d'impression (129), et le réglage comporte la variation de la position des têtes d'impression (30, 130) par rapport au plan durant le déplacement du chariot de têtes d'impression (129) de façon à maintenir la distance prédéterminée sur tout le substrat

(15) en réponse à la détection.

6. Procédé selon l'une quelconque des revendications précédentes, dans lequel la détection comporte la détection de la distance entre le chariot de têtes d'impression (129) et les emplacements sur la surface auxquels de l'encre doit être projetée, et le réglage comporte la variation de la position des têtes d'impression (30, 130) par rapport au chariot de têtes d'impression (129) en réponse à la distance détectée. 5
7. Procédé selon l'une quelconque des revendications précédentes, dans lequel l'encre est une encre à séchage aux UV, et le procédé comporte en outre l'étape de séchage au moins partiel de l'encre projetée sur la surface (16) en exposant l'encre projetée à une lumière ultraviolette. 10
8. Procédé selon la revendication 7, dans lequel l'exposition de l'encre comporte le réglage de la distance de la lumière UV depuis une source de lumière jusqu'audit plan lors du déplacement du chariot (129) parallèlement audit plan. 20
9. Procédé selon la revendication 7, dans lequel l'exposition de l'encre comporte le réglage du foyer de la lumière UV sur la surface qui porte l'encre projetée lors du déplacement du chariot (129) parallèlement audit plan. 25
10. Procédé selon l'une quelconque des revendications 7 à 9, dans lequel le procédé comprend en outre le chauffage de la surface (16) comportant l'encre au moins partiellement séchée afin de réduire le contenu de monomères non polymérisés de l'encre sur le substrat. 30
11. Procédé selon la revendication 10, dans lequel le chauffage comporte le passage d'un air chauffé sur la surface (16) du substrat (15) comportant l'encre au moins partiellement séchée aux UV afin d'éliminer du substrat (15) des composants non séchés de l'encre. 35
12. Procédé selon l'une quelconque des revendications précédentes, comprenant en outre les étapes consistant désormais à combiner une ou plusieurs couches secondaires de matière avec le substrat (16), et à piquer un motif piqué sur les couches combinées de matière et de substrat en coordination avec le motif imprimé sur le substrat (16). 40
13. Procédé selon l'une quelconque des revendications 1 à 11, comprenant en outre les étapes consistant à combiner une ou plusieurs couches secondaires de matière avec le substrat (16), à piquer les couches combinées de matière et de substrat, puis à aligner 45

la surface sur laquelle l'encre doit être projetée avec des contours du substrat piqué et à exécuter l'étape d'impression en imprimant sur le substrat en alignement avec le motif piqué.

14. Procédé selon l'une quelconque des revendications 1 à 11, comprenant en outre les étapes consistant à combiner une ou plusieurs couches secondaires de matière avec le substrat (16), à piquer les couches combinées de matière et de substrat, puis à détecter les contours du substrat piqué et à exécuter l'étape d'impression en imprimant sur le substrat aux points déterminés en réponse à la détection des contours. 50
15. Procédé selon l'une quelconque des revendications précédentes, dans lequel les distances depuis chacune des têtes d'impression (130) jusqu'au plan sont réglées individuellement afin de positionner chacune des têtes (130) à une distance prédéterminée respective de la surface (16) du substrat (15) sur laquelle de l'encre doit être projetée depuis les têtes (130), et le procédé comprend en outre la projection d'encre depuis les têtes (130), à leurs distances réglées par rapport audit plan, aux distances prédéterminées respectives sur la surface (16) du substrat (15), puis le déplacement supplémentaire du chariot de têtes d'impression (129) parallèlement au plan tandis que le substrat (15) est supporté dans celui-ci, puis le réglage à nouveau individuellement des distances de chacune des têtes d'impression (130) par rapport au plan afin de repositionner chacune des têtes (130) pour maintenir la distance prédéterminée respective par rapport à la surface (16) qui varie relativement au plan, et la projection supplémentaire d'encre depuis les têtes (130), à leurs distances réglées à nouveau par rapport audit plan, aux distances prédéterminées respectives sur la surface (16) d'un substrat (15). 55
16. Procédé selon l'une quelconque des revendications 1 à 14, dans lequel le procédé comprend en outre le réglage automatique et individuel des positions de chacune des têtes d'impression (130) vers le substrat (15) et à l'écart de celui-ci, lors du déplacement du chariot (129) parallèlement au substrat (15), afin de maintenir des distances prédéterminées respectives entre les têtes d'impression et la surface du substrat sur laquelle de l'encre est projetée depuis les têtes d'impression (130). 60
17. Procédé selon la revendication 15 ou la revendication 16, comprenant en outre le réglage individuel de la position de chaque tête d'impression (130) et l'application d'une couleur d'encre différente avec des têtes d'impression différentes. 65
18. Procédé selon l'une quelconque des revendications 15 à 17, comprenant en outre la détection de la dis-

tance entre les têtes d'impression (130) et le substrat (15).

19. Procédé selon la revendication 18, comprenant en outre la transmission des informations de distance à un contrôleur (35) et le réglage à nouveau de la position des têtes d'impression (130) en fonction des informations de distance détectées. 5
20. Procédé selon la revendication 19, comprenant en outre la transmission des informations depuis au moins l'un d'au moins deux capteurs (138a, 138b) montés sur le chariot. 10
21. Appareil pour imprimer sur une surface d'un substrat tridimensionnel comprenant un cadre (11, 111) sur lequel est monté un support de substrat (20, 120) définissant un plan de support de substrat et une piste de têtes d'impression (28, 128) s'étendant parallèlement au plan, une pluralité de têtes d'impression à jet d'encre (30, 130) sur chacune desquelles est montée au moins une buse (41) supportées en mouvement sur la piste (28, 128) par l'intermédiaire d'un chariot de têtes d'impression (129) avec les buses orientées vers la surface (16) d'un substrat (15) supporté par le support de substrat (20, 120), le support de substrat (20, 120) étant actionnable pour déplacer le substrat (15) longitudinalement par rapport aux têtes d'impression (130) et les têtes d'impression (130) sur le chariot (129) pouvant être déplacées transversalement au substrat (15), et un système de commande (35) actionnable pour déplacer et commander les têtes d'impression (30, 130) afin d'imprimer sur le substrat (15) en projetant de l'encre depuis les buses (41) sur la surface (16) d'un substrat (15), **caractérisé en ce que** l'appareil comprend en outre un capteur (40a, 40b, 138a, 138b) porté sur le chariot (129) et actionnable pour assurer une mesure de distance d'une partie de la surface (16), et **en ce que** les têtes d'impression (30, 130) sont déplaçables automatiquement perpendiculairement au plan en réponse au capteur (40a, 40b, 138a, 138b) jusqu'à une distance prédéterminée de la surface (16) du substrat (15). 25 30 35 40 45
22. Appareil selon la revendication 21, comprenant en outre une tête de séchage par lumière UV (23, 123a, 23b) positionnée de façon à exposer à la lumière UV l'encre projetée sur la surface (16) du substrat par la tête d'impression (30, 130). 50
23. Appareil selon la revendication 23, dans lequel la tête de séchage par lumière UV (23, 123a, 123b) est déplaçable par rapport au plan, et le système de commande (35) est actionnable pour déplacer la tête de séchage (23, 123a, 123b) afin de maintenir le foyer de la lumière UV provenant de la tête de séchage (23, 123a, 123b) sur l'encre projetée sur la 55

surface (16) du substrat (15).

24. Appareil selon la revendication 22 ou la revendication 23, comprenant en outre : une station de chauffage (26, 126) positionnée de façon à chauffer l'encre exposée à la lumière UV sur le substrat.
25. Appareil selon la revendication 24, dans lequel la station de chauffage (26, 126) comporte une soufflante orientée pour diriger de l'air chauffé sur un substrat sur le support.
26. Appareil selon l'une quelconque des revendications 21 à 25, comprenant en outre une station de piquage positionnée pour piquer le substrat (15) afin de donner un contour à la surface du substrat (15).
27. Appareil selon l'une quelconque des revendications 21 à 26, dans lequel le capteur (40b, 138a, 138b) est monté dans le chariot (129).
28. Appareil selon l'une quelconque des revendications 21 à 27, dans lequel le capteur comporte deux capteurs (138a, 138b) montés dans le chariot (129).
29. Appareil selon l'une quelconque des revendications 21 à 28, dans lequel le capteur est un dispositif de mesure de distance sans contact (40b, 138a, 138b) qui comporte une source de lumière et un détecteur de lumière montés sur la piste.
30. Appareil selon l'une quelconque des revendications 21 à 29, dans lequel le capteur (138a, 138b) est actionnable pour déterminer un emplacement sur la surface (16) du substrat (15) et les têtes d'impression (130) sont déplaçables individuellement et sélectivement perpendiculairement au plan en réponse au capteur (138a, 138b) jusqu'à des distances prédéterminées de l'emplacement déterminé sur la surface (16) du substrat (15), et le système de commande (35) étant actionnable pour déplacer et commander individuellement chacune des têtes d'impression (130) afin d'imprimer sur le substrat (15) en projetant de l'encre depuis les têtes d'impression (130) aux distances prédéterminées respectives et sur le substrat.
31. Appareil selon l'une quelconque des revendications 21 à 29, dans lequel les têtes d'impression (130) sont déplaçables individuellement et espacées dans le sens du déplacement du chariot (129) de façon à passer séquentiellement par-dessus les mêmes zones du substrat (15) et à imprimer chacune un ensemble de couleurs sur celles-ci, les têtes d'impression (130) sont déplaçables individuellement et sélectivement vers le plan et à l'écart de celui-ci, et le système de commande (35) est actionnable pour commander les têtes d'impression (130) en réponse

au capteur (138a, 138b) afin de suivre séquentiellement le contour de la surface de substrat lorsque le chariot se déplace en travers du substrat pour maintenir une distance constante de parcours de l'encre depuis chaque tête d'impression par rapport à la surface du substrat. 5

- 32.** Appareil selon l'une quelconque des revendications 21 à 29, dans lequel les têtes d'impression (130) sont déplaçables individuellement et agencées côte à côte sur le chariot (129) perpendiculairement au sens de déplacement du chariot (129) de façon à ce qu'elles puissent chacune maintenir un espacement commandé par rapport au substrat où le contour du substrat (15) varie dans le sens perpendiculaire au déplacement du chariot (129). 10 15

- 33.** Appareil selon la revendication 31 ou la revendication 32, dans lequel les têtes d'impression (130) sont des têtes d'impression bidirectionnelles qui impriment tout en se déplaçant transversalement à un substrat (15) qui peut être déplacé longitudinalement par rapport aux têtes d'impression (130), le capteur comporte deux capteurs (138a, 138b) montés sur le chariot (129) transversalement aux têtes d'impression (130), un de chaque côté des têtes d'impression. 20 25

- 34.** Appareil selon l'une quelconque des revendications 21 à 33, dans lequel sur la piste (128) est en outre montée une pluralité de servomoteurs (137a à d), répondant chacun à un signal de sortie du capteur (138a, 138b) afin de régler la position des têtes d'impression (130) par rapport au substrat (15) pour commander la distance à laquelle de l'encre est projetée durant l'impression. 30 35

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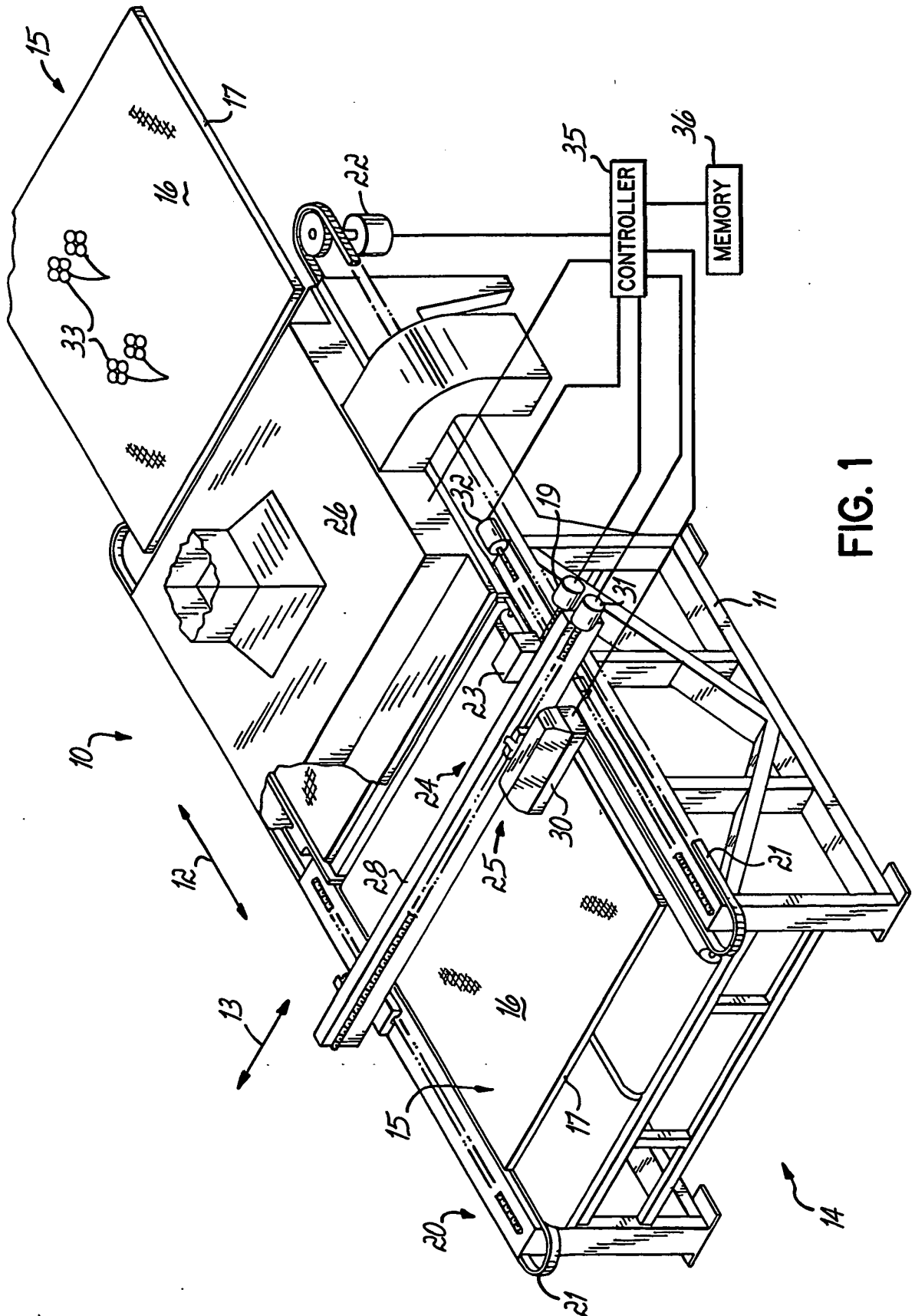


FIG. 1

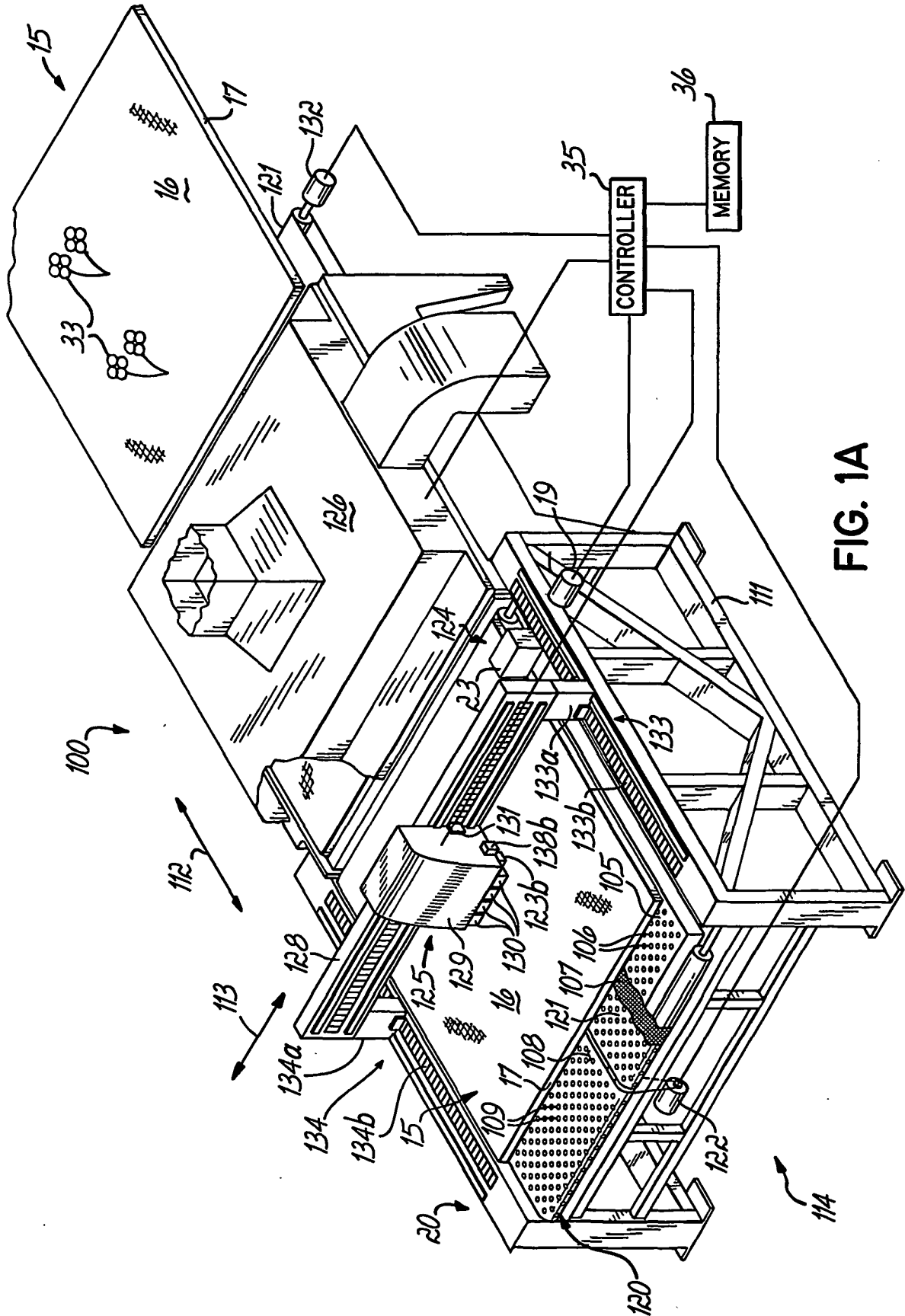
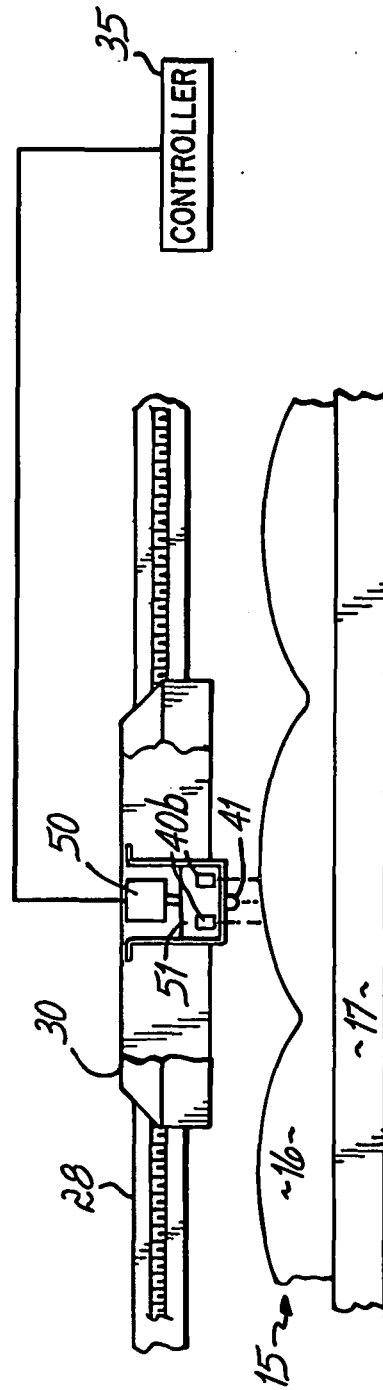
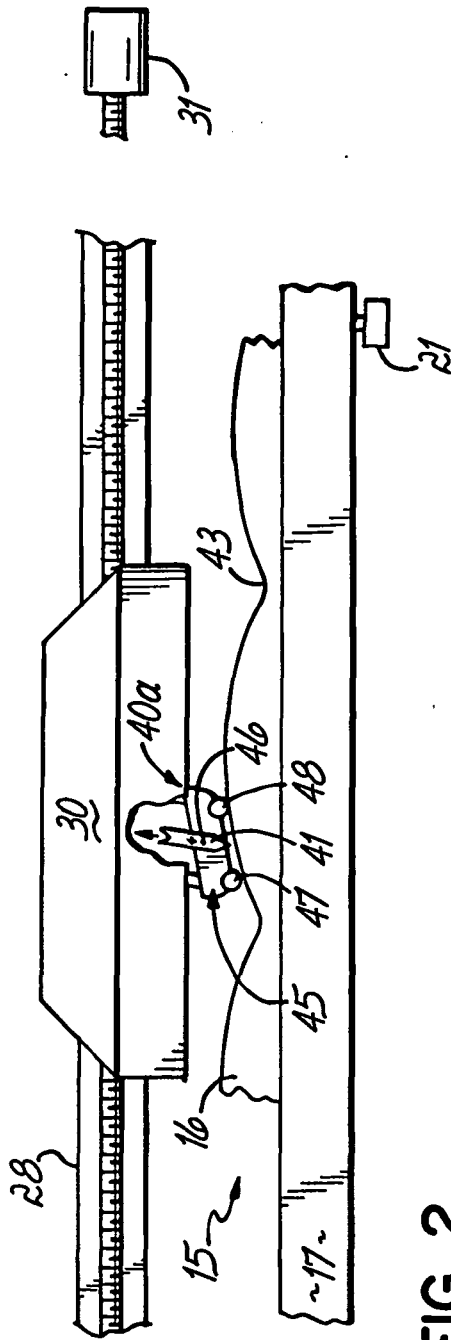


FIG. 1A



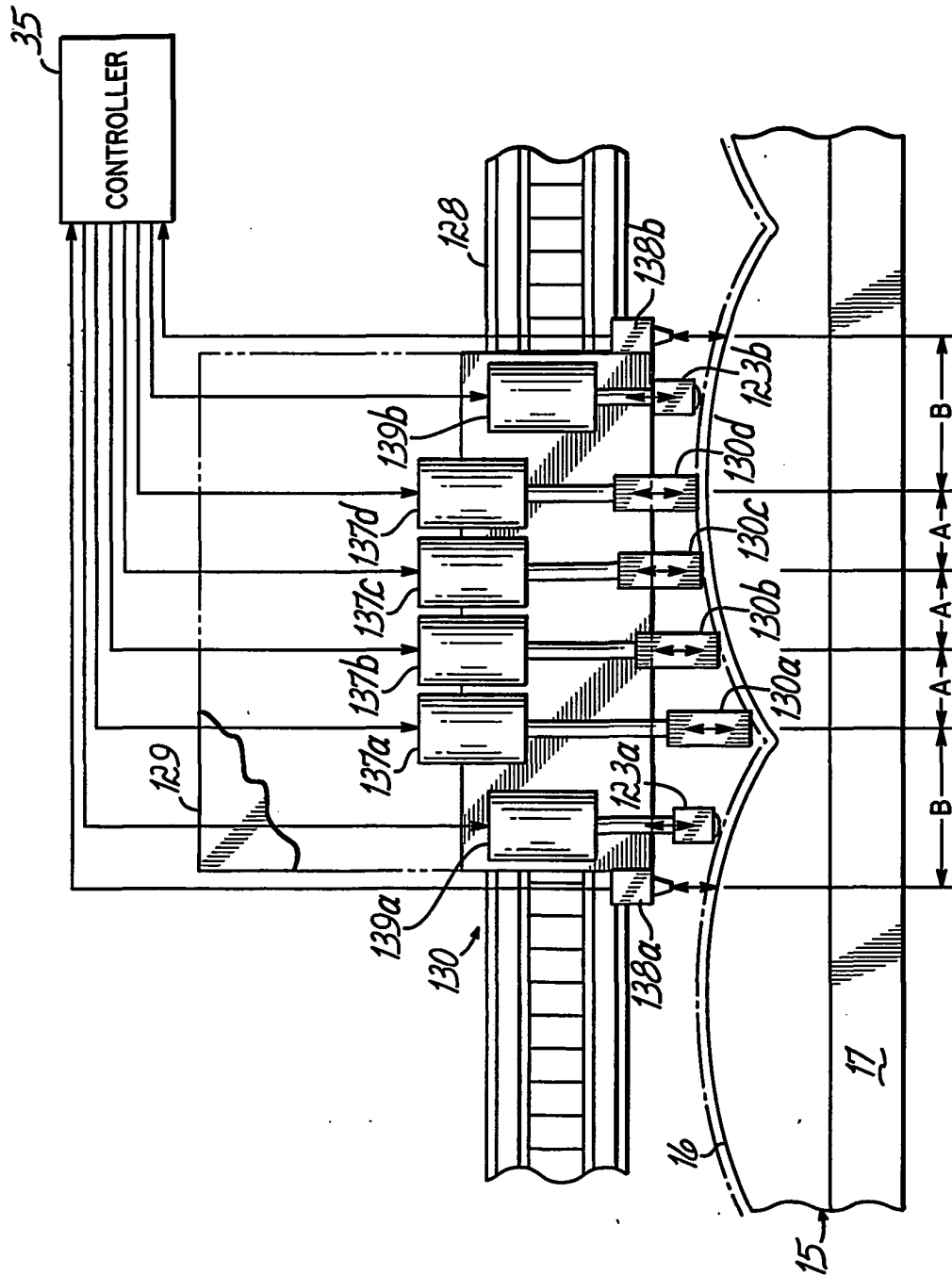


FIG. 3

**REFERENCES CITED IN THE DESCRIPTION**

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