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EP 1 447 546 A3

(12)

EUROPEAN PATENT APPLICATION

(88) Date of publication A3:

27.09.2006 Bulletin 2006/39

(51) Int Cl.: F02D 11/10 (2006.01)

(11)

F02D 41/30 (2006.01)

(43) Date of publication A2: 18.08.2004 Bulletin 2004/34

(21) Application number: 04003045.4

(22) Date of filing: 11.02.2004

(84) Designated Contracting States:

AT BE BG CH CY CZ DE DK EE ES FI FR GB GR HU IE IT LI LU MC NL PT RO SE SI SK TR Designated Extension States:

AL LT LV MK

(30) Priority: 12.02.2003 JP 2003034232

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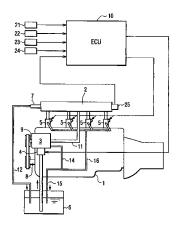
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(54) Engine control unit including phase advance compensator

(57) A peak gain of target torque with respect to a change in an accelerator position from 40% to 70% is expressed by a constant K. A time constant of phase advance compensation corresponding to a period for the target torque to change from a peak value to 63.2% of the peak value in the case where the accelerator position is changed from 40% to 70% is expressed by a constant ω . A target torque response with respect to the change in the accelerator position is calculated through a phase advance compensator (26) by using the peak gain K and the time constant ω , which have physical meanings. Thus, the target torque response with respect to the change in the accelerator position can be defined quantitatively, directly based on an elapsed time.

FIG. 1





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