



(11) **EP 1 514 686 B1**

(12) **EUROPEAN PATENT SPECIFICATION**

(45) Date of publication and mention
of the grant of the patent:
23.12.2009 Bulletin 2009/52

(51) Int Cl.:
B41J 2/045^(2006.01) B41J 2/14^(2006.01)

(21) Application number: **04028900.1**

(22) Date of filing: **25.11.1998**

(54) **Ink-jet printer and method of driving thereof**

Vorrichtung und Verfahren zum Antreiben eines Aufzeichnungskopfes für einen Tintenstrahldrucker

Dispositif et procédé pour commander une tête d'enregistrement d'une imprimante à jet d'encre

(84) Designated Contracting States:
BE CH DE ES FR GB IT LI NL

(30) Priority: **28.11.1997 JP 32785197**
17.12.1997 JP 34818297
17.12.1997 JP 34819697

(43) Date of publication of application:
16.03.2005 Bulletin 2005/11

(62) Document number(s) of the earlier application(s) in
accordance with Art. 76 EPC:
98309675.1 / 0 919 382

(73) Proprietor: **Sony Corporation**
Tokyo 141-0001 (JP)

(72) Inventors:
• **Horii, Shinichi**
Shinagawa-ku
Tokyo (JP)
• **Ikemoto, Yuichiro**
Shinagawa-ku
Tokyo (JP)
• **Yukita, Yasuo**
Shinagawa-ku
Tokyo (JP)
• **Tokunaga, Hiroshi**
Shinagawa-ku
Tokyo (JP)

- **Kishimoto, Masaki**
Shinagawa-ku
Tokyo (JP)
- **Yakura, Yuji**
Shinagawa-ku
Tokyo (JP)
- **Tanikawa, Tooru**
Shinagawa-ku
Tokyo (JP)
- **Nishi, Shota**
Shinagawa-ku
Tokyo (JP)
- **Suzuki, Kenji**
Shinagawa-ku
Tokyo (JP)

(74) Representative: **Ayers, Martyn Lewis Stanley**
J.A. Kemp & Co.
14 South Square
Gray's Inn
London
WC1R 5JJ (GB)

(56) References cited:
EP-A- 0 580 154 US-A- 4 672 398

- **PATENT ABSTRACTS OF JAPAN vol. 1996, no.**
09, 30 September 1996 (1996-09-30) & JP 08
118622 A (MITA IND CO LTD), 14 May 1996
(1996-05-14)

Note: Within nine months of the publication of the mention of the grant of the European patent in the European Patent Bulletin, any person may give notice to the European Patent Office of opposition to that patent, in accordance with the Implementing Regulations. Notice of opposition shall not be deemed to have been filed until the opposition fee has been paid. (Art. 99(1) European Patent Convention).

EP 1 514 686 B1

Description

[0001] The present invention relates to an ink-jet printer for ejecting ink droplets through a droplet outlet orifice (a nozzle) and recording an image on paper and a method of driving a recording head for an ink-jet printer.

[0002] Ink-jet printers for ejecting ink droplets through a droplet outlet orifice communicating with an ink chamber and recording on paper have been widely used. In such an ink-jet printer of related art, a single piezoelectric element is provided for each nozzle. The piezoelectric element is fixed to an oscillation plate forming an external wall of the ink chamber to which ink is fed through an ink duct. The piezoelectric element changes the ink chamber volume by bending in response to a voltage waveform of an applied drive signal so as to generate an ejection pressure. An ink droplet is ejected through the outlet orifice by the ejection pressure.

[0003] Since the ejection pressure is generated by changing the ink chamber in such an ink-jet printer as described above, ink ejected through the orifice flies in a columnar shape (in a trailing form). Differences in time and velocity result between the tip and the end of the flying ink droplet. Consequently, the preceding main ink droplet is accompanied by unwanted minute droplets (called satellite droplets in the following description). Such satellite droplets landing on paper affect the printing result. Although satellite droplets do not have a great effect on the quality of a high-density image recorded with relatively large droplets, the image quality is expected to be significantly reduced by satellite droplets when the image is recorded with small droplets for representing a low-density image or a half-tone image. Satellite droplets generated when small droplets are ejected therefore cause a great problem.

[0004] Some methods have been proposed in order to cope with the problem. For example, a method is disclosed in Japanese Patent Application Laid-open Hei 7-76087 (1995) wherein a single piezoelectric element is provided for each nozzle and the velocity of changing ejection voltage applied to the piezoelectric element is switched between two levels for ejecting ink droplets. In the method, as shown in FIG. 1, the ejection voltage is initially increased at first voltage changing velocity 'v1'. The ejection voltage is then increased at second voltage changing velocity 'v2' higher than v1. In FIG. 1, the vertical axis indicates voltage. The horizontal axis indicates time. According to the method, the next droplet is ejected to follow the tip of the preceding droplet. The difference in velocity between the tip and the end of the ink column is thereby decreased and satellite droplets are reduced.

[0005] Another method is disclosed in Japanese Patent Application Laid-open Sho 59-133067 (1984) wherein a single piezoelectric element is provided for each nozzle and an ink droplet is ejected by applying two independent voltage pulses to the piezoelectric element. In the method, as shown in FIG. 2, first pulse P1 is applied to the piezoelectric element to produce a first pressure

fluctuation for starting ink droplet ejection through a nozzle. First pulse P1 is then terminated and second pulse P2 is applied to the piezoelectric element before the ejection of droplet through the nozzle is completed to produce a second pressure fluctuation. In FIG. 2, the vertical axis indicates voltage. The horizontal axis indicates time. According to the method, the ink column ejected through the nozzle ruptures at an early stage and generation of satellite droplets is suppressed.

[0006] An ink droplet ejection apparatus is disclosed in Japanese Patent Application Laid-open Sho 51-45931 (1976) wherein two pressure generating means are provided for each nozzle and an ink droplet is ejected by oscillating ink by combining oscillations produced by the two pressure generating means.

[0007] In the method disclosed in Japanese Patent Application Laid-open Hei 7-76087 (1995) described above, however, first voltage changing velocity v1 is required to be lower than second voltage changing velocity v2. Consequently, the velocity of an ejected ink droplet is reduced when compared to the case wherein the voltage is changed at high velocity v2 throughout the ejection cycle. A reduction in velocity of an ejected ink droplet results in unstable ejection such as affected linearity of the droplet flying route and variations in droplet velocity. As a result, displacements of recorded dots may occur and printing quality may be reduced.

[0008] In the method disclosed in Japanese Patent Application Laid-open Sho 59-133067 (1984) described above, second pulse P2 is applied after interval Ti, having terminated first pulse P1. If interval Ti is too long, a trail of an ink column becomes long and satellite droplets may be produced. On the other hand, if interval Ti is too short, the piezoelectric element does not follow the voltage change and the intended operation will not be achieved. This is because the piezoelectric element in general has its intrinsic oscillation characteristic and does not operate at a frequency above the intrinsic oscillation. Although this problem may be solved by fabricating a piezoelectric element having a high intrinsic frequency, this is not realistic since there is a limitation of the intrinsic frequency of the piezoelectric element obtained in practice. In addition, fabricating such a piezoelectric element is accompanied by technical difficulties and manufacturing costs are thereby increased. Furthermore, in the above-mentioned publication, although voltage V1 of first pulse P1 is lower than voltage V2 of second pulse P2, voltage V1 is required to be higher than voltage V2 so that the trailing end of the ink column reaches the tip thereof and becomes integrated with the tip. However, an increase in the voltage applied to the piezoelectric element causes a reduction in the life of the piezoelectric element and the oscillation plate oscillated by the piezoelectric element. A residual oscillation is increased as well and the frequency characteristic may be affected.

[0009] The above-mentioned ink droplet ejection apparatus disclosed in Japanese Patent Application Laid-open Sho 51-45931 (1976) is provided for efficiently

ejecting ink droplets with a small power input. In order to achieve the object, high-frequency drive signals are each applied to the two pressure generating means and the phase difference between the drive signals and the amplitude are changed so that the oscillations generated by the pressure generating means are successfully combined to oscillate ink. An ink droplet is thereby ejected. That is, the apparatus is not intended for preventing satellite droplets. The method of driving the pressure generating means and the configuration required for preventing satellite droplets are not disclosed, either. No suggestion about such a method or configuration is made in the publication, either.

[0010] As thus described, it is difficult to satisfactorily reduce satellite droplets in the related art without reductions in velocity of an ejected droplet, in the apparatus life, in the frequency characteristic and without a limitation of the intrinsic oscillation characteristic of the piezoelectric element.

[0011] The related-art ink-jet printers have further problems. FIG. 3 is a schematic diagram of a recording head and a drive circuit thereof in a related-art ink-jet printer. As shown, a recording head 500 includes a nozzle 501 and a piezoelectric element 502 provided in correspondence with the nozzle 501. The piezoelectric element 502 is fixed to a wall of an ink chamber (not shown) to which ink is supplied through an ink duct (not shown). A drive signal 504 of a specific waveform is selectively inputted to the piezoelectric element 502 through an on/off switch 503. That is, the drive signal 504 is only inputted to the piezoelectric element 502 when the switch 503 is turned on. On the application of the drive signal 504, the piezoelectric element 502 is bent in such a direction that the ink chamber volume is reduced. An ink droplet is thereby ejected through the nozzle 501.

[0012] For such printers, one of the methods for producing halftone images is varying a droplet size dot by dot. In the drive circuit of the recording head of related art shown in FIG. 3, however, only one type of drive signal 504 is inputted so that merely whether to perform ejection or not is only controlled. Consequently, it is impossible to perform control for varying a size of ejected droplet from droplet to droplet although the interval between recorded dots is controlled. It is therefore difficult to faithfully achieve various image representations such as more natural halftone images.

[0013] According to a first aspect of the present invention, there is provided an ink-jet printer comprising: a droplet outlet orifice through which an ink droplet is ejected; a plurality of energy generating means provided for the outlet orifice each for generating energy for having the ink droplet ejected through the outlet orifice; and a plurality of selection means each provided for the respective energy generating means for selecting any of a plurality of drive signals for driving the energy generating means and supplying the selected signal to the respective energy generating means.

[0014] According to a second aspect of the present

invention, there is provided a method for driving a recording head for an ink-jet printer including a droplet outlet orifice through which an ink droplet is ejected; and a plurality of energy generating means provided for the outlet orifice each for generating energy for having the ink droplet ejected through the outlet orifice. The method comprises the steps of: selecting any of a plurality of drive signals for driving the energy generating means for each of the energy generating means; and supplying the selected drive signal to the respective energy generating means.

[0015] According to the ink-jet printer and the method of driving a recording head for an ink-jet printer, one of the drive signals is selected and supplied to each of the plurality of energy generating means provided for the outlet orifice. An ink droplet is ejected through the orifice with the drive signal.

[0016] Preferred embodiments of the invention are defined in dependent claims.

[0017] Further features and advantages of the invention will be apparent from the following description of preferred embodiments of the invention given by way of non-limitative example with reference to the accompanying drawings in which:

FIG. 1 is a plot for illustrating a method of driving a related-art ink-jet printer.

FIG. 2 is a plot for illustrating a method of driving another related-art ink-jet printer.

FIG. 3 is a block diagram of a recording head and a drive circuit thereof of a related-art ink-jet printer.

FIG. 4 is a block diagram of an ink-jet printer of a first embodiment of the invention.

FIG. 5 is a perspective cross section of an example of recording head.

FIG. 6 is a cross section of the recording head.

FIG. 7A and FIG. 7B show examples of drive signals outputted from the head controller shown in FIG. 4.

FIG. 8A to FIG. 8C show the relationship among the waveform of the drive signal for ejection shown in FIG. 7A, the state of ink chamber and the meniscus position in the nozzle.

FIG. 9A to FIG. 9D show the relationship among the waveforms of the drive signals shown in FIG. 7A and FIG. 7B and the displacement amounts of the piezoelectric elements.

FIG. 10 shows examples of states of ink droplets ejected by the drive signal waveforms shown in FIG. 7A and FIG. 7B.

FIG. 11A and FIG. 11B show examples of drive signals outputted from the head controller of an ink-jet printer of a second embodiment of the invention.

FIG. 12A to FIG. 12D show the relationship among the waveforms of the drive signals shown in FIG. 11A and FIG. 11B and the displacement amounts of the piezoelectric elements.

FIG. 13A and FIG. 13B show examples of drive signals outputted from the head controller of an ink-jet

printer of a third embodiment of the invention.

FIG. 14A to FIG. 14D show the relationship among the waveforms of the drive signals shown in FIG. 13A and FIG. 13B and the displacement amounts of the piezoelectric elements.

FIG. 15 shows examples of states of ink droplets ejected by the drive signal waveforms shown in FIG. 13A and FIG. 13B.

FIG. 16 is a top view of a modification example of a recording head used in the ink-jet printer of the embodiments of the invention.

FIG. 17 is a plot for showing an example of the relationship between the ejected droplet diameter and the voltage applied to the piezoelectric element.

FIG. 18 is a plot for showing an example of the relationship between the ejected droplet velocity and the voltage applied to the piezoelectric element.

FIG. 19 is a block diagram of a head controller as a drive apparatus of a recording head for an ink-jet printer of a fourth embodiment of the invention.

FIG. 20A and FIG. 20B show examples of drive signals outputted from the drive waveform generator shown in FIG. 4.

FIG. 21A to FIG. 21C show the relationship among the waveform of the drive signal for ejection shown in FIG. 20A, the state of ink chamber and the meniscus position in the nozzle.

FIG. 22 is a flowchart for illustrating the main operation of the head controller.

FIG. 23 shows some of ejection patterns selected and composed by the selectors shown in FIG. 19.

FIG. 24 shows the other ejection patterns selected and composed by the selectors shown in FIG. 19.

FIG. 25 shows still the other ejection patterns selected and composed by the selectors shown in FIG. 19.

FIG. 26 shows still the other ejection patterns selected and composed by the selectors shown in FIG. 19.

FIG. 27 is a top view of a modification example of a recording head used in the ink-jet printer of the embodiments of the invention.

[First Embodiment]

[0018] FIG. 4 is a schematic diagram for illustrating the main part of an ink-jet printer of a first embodiment of the invention. Although a multi-nozzle head ink-jet printer having a plurality of nozzles will be described in the embodiment, the invention may be applied to a single-nozzle head ink-jet printer having a single nozzle. An apparatus and a method of driving a recording head of an ink-jet printer of the embodiment which are implemented with the ink-jet printer of the embodiment will be described as well.

[0019] An ink-jet printer 1 comprises: a recording head 11 for recording on recording paper 2 through ejecting ink droplets thereon; an ink cartridge 12 for feeding ink to the recording head 11; a controller 13 for controlling the position of the recording head 11 and feeding of the

paper 2; a head controller 14 for controlling ink droplet ejection of the recording head 11 with a drive signal 21; an image processor 15 for performing a specific image processing on input image data and supplying the data as image printing data 22 to the head controller 14; and a system controller 16 for controlling the controller 13, the head controller 14 and the image processor 15 with control signals 23, 24 and 25, respectively. The head controller 14 corresponds to an 'ejection control means' of the invention.

[0020] FIG. 5 is a perspective cross section of the recording head 11 shown in FIG. 4. FIG. 6 is a cross section of the recording head 11 shown in FIG. 5 viewed in the direction of arrow Z. As shown, the recording head 11 comprises a thin nozzle plate 111, a duct plate 112 stacked on the nozzle plate 111; and an oscillation plate 113 stacked on the duct plate 112. The plates are bonded to each other with an adhesive not shown, for example.

[0021] Concaves are selectively formed on the upper surface of the duct plate 112. The concaves and the oscillation plate 113 make up a plurality of ink chambers 114 and a shared duct 115 communicating with the ink chambers 114. Communicating sections between the shared duct 115 and the ink chambers 114 are narrow.

The width of each ink chamber 114 increases towards the direction opposite to the shared duct 115. A pair of piezoelectric elements 116a and 116b are each fixed to the oscillation plate 113 directly above each ink chamber 114. Electrodes not shown are placed on the upper and lower surfaces of each of piezoelectric elements 116a and 116b. A drive signal from the head controller 14 (FIG. 4) is applied to the electrodes.

Each of the piezoelectric elements 116a and 116b and the oscillation plate 113 are thereby bent so as to increase (expand) and reduce (contract) the volume of each ink chamber 114. The ink chamber corresponds to an 'ink chamber' of the invention.

[0022] In the embodiment, the piezoelectric elements 116a and 116b are formed such that the amounts of displacement (called displacement capacity in the following description) in response to the same applied voltage are equal to each other. The piezoelectric elements 116a and 116b are therefore made of the same material and have the same thickness and surface area. As a result, a specific change in volume of ink chamber 114 is effected by the same applied voltage. Alternatively, the displacement capacities of the piezoelectric elements 116a and 116b may be changed by varying the thickness and surface areas between the elements 116a and 116b. The piezoelectric element 116a corresponds to a 'first pressure generating means' and the piezoelectric element 116b corresponds to a 'second pressure generating means' of the invention.

[0023] The width of the section of each ink chamber 114 opposite to the side communicating with the shared duct 115 is reduced by degrees. At the end of the ink chamber 114, a duct hole 117 is formed through the thickness of the duct plate 112. The duct hole 117 communi-

cates with a minute nozzle 118 formed in the nozzle plate 111 which is the lowest of the plates. An ink droplet is ejected through the nozzle 118. In the embodiment the recording head 11 has a plurality of nozzles 118 at even intervals in a row along the direction (arrow X in FIG. 5) of feeding the paper 2 (FIG. 4). The nozzles 118 may be arranged in any other way such as in staggered two rows. The nozzle 118 corresponds to a 'droplet outlet orifice' of the invention.

[0024] The shared duct 115 communicates with the ink cartridge 12 shown in FIG. 4 (not shown in FIG. 5 and FIG. 6). Ink is regularly fed into each ink chamber 114 at a constant speed from the ink cartridge 12 through the shared duct 115. Such ink feed may be performed by capillarity. Alternatively, a pressure mechanism may be provided for feeding ink by applying a pressure to the ink cartridge 12.

[0025] By a carriage drive motor and an associated carriage mechanism not shown, the recording head 11 of such a configuration is reciprocated in direction Y or orthogonal to direction X in which the paper 2 is carried while ejecting ink droplets. An image is thereby recorded on the paper 2.

[0026] Although not shown, the head controller 14 is made up of a microprocessor; a read only memory (ROM) for storing a program executed by the microprocessor; a random access memory (RAM) as a work memory used for particular computations performed by the microprocessor and temporary data storage and so on; a drive waveform storage section made up of nonvolatile memory; a digital-to-analog (D-A) converter for converting digital data read from the storage section into analog data; and an amplifier for amplifying an output of the D-A converter. The drive waveform storage section retains pairs of waveform data items representing voltage waveforms of drive signals 21a and 21b for driving the piezoelectric elements 116a and 116b of each nozzle of the recording head 11. The waveform data items are made through entering various values for the parameters (time and voltage parameters) shown in FIG. 7, for example. There is a specific relationship described below maintained between each pair of the drive signals 21a and 21b. The waveform data items are each read by the microprocessor and converted to analog signals by the D-A converter. The signals are amplified by the amplifier and outputted as pairs of the drive signals 21a and 21b. The number of the pairs is equal to the number of nozzles 'n'. The configuration of the head controller 14 is not limited to the one described above but may be implemented in any other way.

[0027] Of the pair of drive signals, the drive signal 21a is applied to the piezoelectric element 116a of the corresponding nozzle. The drive signal 21b is applied to the piezoelectric element 116b of the corresponding nozzle. In FIG. 4, pairs of the drive signals 21a and 21b wherein the number of the pairs is 'n' are shown as the drive signal 21.

[0028] FIG. 7A and FIG. 7B show examples of one

cycle (T) of waveforms of the drive signals 21a and 21b. FIG. 7A and FIG. 7B each show the drive signals 21a and 21b, respectively. The vertical axis indicates voltage. The horizontal axis indicates time. Time proceeds from left to right in the graphs. Of the drive signals, the drive signal 21a is a drive signal for generating a pressure for ejecting an ink droplet. The voltage of the drive signal 21a includes retraction voltage V_p and ejection voltage V_a besides reference voltage 0 V. The drive signal 21b is an auxiliary drive signal for generating a pressure for suppressing satellite droplets when an ink droplet is ejected. The voltage of the drive signal 21b includes retraction voltage V_p and auxiliary voltage V_b besides reference voltage 0 V. The pair of the drive signals 21a and 21b is appropriately switched to another pair by the head controller 14 between the ejection cycles and supplied to the corresponding nozzle.

[0029] Reference is now made to FIG. 8A to FIG. 8C for describing the significance of the drive signal 21a. FIG. 8A to FIG. 8C show the relationship among the waveform of the drive signal, the behavior of the piezoelectric element 116a to which the drive signal is applied; and the change in position of extremity of ink in the nozzle 118 (referred to as meniscus position in the following description). FIG. 8A shows a nearly one cycle of the waveform of the typical drive signal 21a. FIG. 8B illustrates the changing state of the ink chamber 114 when the drive signal 21a having a waveform as shown in FIG. 8A is applied to the piezoelectric element 116a. FIG. 8C illustrates the changing meniscus positions in the nozzle 118.

[0030] In FIG. 8A, a first preceding step is the step in which a drive voltage is changed from the reference voltage of 0 V to retraction voltage V_p (from A to B). A second preceding step is the step in which retraction voltage V_p is maintained for a specific period (from B to C). A first step is the step in which the drive voltage is changed from retraction voltage V_p to the reference voltage of 0 V (from C to D). Time required for the first step is defined as t_1 . A second step is the step in which the voltage of 0 V is maintained to be on standby (from D to E). Time required for the second step is defined as t_2 . A third step is the step in which the voltage of 0 V is changed to ejection voltage V_a (from E to F). Time required for the third step is defined as t_3 .

[0031] In the embodiment point E at which the third step is started is the point at which ejection is started. The first and second preceding steps and the first and second steps precede the start of ejection.

[0032] At and before point A, since the voltage applied to the piezoelectric element 116a is 0V, there is no bend in the oscillation plate 113 and the volume of the ink chamber 114 is maximum as P_A in FIG. 8B. At point A, as M_A in FIG. 8C, the meniscus position in the nozzle 118 retreats from the nozzle edge by a specific distance.

[0033] Next, the first preceding step is performed for gradually increasing the drive voltage from the voltage of 0 V at point A to retraction voltage V_p at point B. The

oscillation plate 113 is thereby bent inward and the ink chamber 114 is contracted (P_B in FIG. 8B). Since the contraction speed of the ink chamber 114 is slow, the reduction in volume of the ink chamber 114 allows the meniscus position in the nozzle 118 to advance and causes backflow of ink into the shared duct 115. The ratio of the amount of ink flowing forward to the amount flowing backward mainly depends on the flow passage resistance in the nozzle 118 and that in the communicating section between the ink chamber 114 and the shared duct 115. By optimizing the ratio, the meniscus position at point B is controlled to almost reach the nozzle edge, as M_B in FIG. 8C, without projecting from the nozzle edge.

[0034] Next, the second preceding step is performed for maintaining the volume of the ink chamber 114 constant by keeping the drive voltage at retraction voltage V_p from point B to point C. Since ink is continuously fed from the ink cartridge 12 during this step, the meniscus position in the nozzle 118 shifts towards the nozzle edge. At point C the meniscus position advances to the position slightly protruding from the nozzle edge as M_C in FIG. 8C.

[0035] Next, the first step is performed for reducing the drive voltage from retraction voltage V_p at point C to the reference voltage of 0 V at point D. The voltage applied to the piezoelectric element 116 is thereby reduced to zero so that the bend in the oscillation plate 113 is eliminated and the ink chamber 114 is expanded as P_D in FIG. 8B. Consequently, the meniscus in the nozzle 118 is retracted towards the ink chamber 114. At point D the meniscus retreats as deep as M_D in FIG. 8C, that is, moves away from the nozzle edge. The amount of retraction of the meniscus in the first step is changed by changing retraction voltage V_p , that is, the potential difference between points C and D. It is thereby possible to control the droplet size. This is because the droplet size depends on the meniscus position at the start point of ejection and the deeper the meniscus position, the smaller the droplet size is.

[0036] Next, the second step is performed for maintaining the volume of the ink chamber 114 by fixing the drive voltage to zero so as to keep the oscillation plate 113 unbent during time t_2 from point D to point E (P_D to P_E in FIG. 8C). During time t_2 ink is continuously fed from the ink cartridge 12. The meniscus position in the nozzle 118 thus shifts towards the nozzle edge. The meniscus position proceeds as far as the state of M_E shown in FIG. 8C. The amount of movement of the meniscus may be varied by changing time t_2 in the second step. The meniscus position at the start point of the third step is thereby controlled. That is, the droplet size is controllable by adjusting time t_2 .

[0037] Next, the third step is performed for abruptly increasing the drive voltage from the voltage of 0 V at point E to ejection voltage V_a at point F. Point E is the ejection start point as described above. At point F, the oscillation plate 113 is greatly bent inward as P_F in FIG. 8B. The ink chamber 114 is thereby abruptly contracted. Consequently, as M_F in FIG. 8C, the meniscus in the

nozzle 118 is pressed towards the nozzle edge at a stretch through which an ink droplet is ejected. The droplet ejected flies in the air and lands on the paper 2 (FIG. 5).

[0038] Next, at point G until which a specific period has elapsed with the drive voltage maintained at ejection voltage V_a , the drive voltage is reduced to 0 V again. The oscillation plate 113 thereby returns to the unbent state as P_G in FIG. 8B at point H. This state is maintained until point I at which the first preceding step of next ejection cycle is started. At point H immediately after the drive voltage is reduced to 0 V again, as M_H in FIG. 18C, the meniscus position is retreated by the amount corresponding to the total of the volume of ink ejected and the increase in volume of the ink chamber 114. With ink refilling, the meniscus position shifts to the level similar to M_A at initial point A, as M_I in FIG. 8C, at point I at which the first preceding step of next ejection cycle is started. The cycle of ejection is thus completed. Such a cycle of operation is repeated for each of the nozzles 118 in a parallel manner. Image recording on the paper 2 (FIG. 5) is thereby continuously performed.

[0039] In the embodiment, time t_2 required for the second step is less than the time required for the meniscus retracted in the first step to reach the nozzle edge. Ejection voltage V_a in the third step falls within the range that allows ink droplet ejection. In FIG. 7A, time required for the periods other than CD, DE and EF is represented as: $AB = \tau_1$, $BC = \tau_2$, $FG = t_4$, and $GH = t_5$.

[0040] Referring again to FIG. 7A and FIG. 7B, the waveform of the drive signal 21b will now be described. In the embodiment, the section from A to D of the drive signal 21b is the same as the waveform of the drive signal 21a. Time t_6 required for period DE' during which the voltage of 0 V is maintained is longer than time t_2 required for the second step of the drive voltage 21a. Point E' at which the drive signal 21b starts to rise from the reference voltage of 0 V to auxiliary voltage V_b lags behind ejection start point 'te' (point E) of the drive signal 21a by time 'td'. In FIG. 7B time required for period E'F' during which the drive voltage 21b changes from the reference voltage of 0V to auxiliary voltage V_b is shown as 't7'. Time required from point F' at which the drive voltage 21b reaches auxiliary voltage V_b to terminal point G' of maintaining auxiliary voltage V_b is shown as 't8'. Time required for period G'H' during which the drive voltage 21b changes from auxiliary voltage V_b to the reference voltage of 0V is shown as 't9'. As will be described below, one of the features of the invention is that delay time t_d is appropriately determined.

[0041] The operation of the ink-jet printer 1 shown in FIG. 4 as a whole will now be briefly described.

[0042] In FIG. 4 printing data is inputted to the ink-jet printer 1 from an information processing apparatus such as a personal computer. The image processor 15 performs specific image processing on the input data (such as expansion of compressed data) and outputs the data as the image printing data 22 to the head controller 14.

[0043] On receipt of the image printing data 22 of 'n'

dots corresponding to the number of nozzles of the recording head 11, the head controller 14 determines an ink droplet size for forming a dot for each nozzle 118 based on the image printing data 22. The head controller 14 then determines pairs of drive signals 21a and 21b each to be supplied to each nozzle based on the determined droplet sizes. For example, a pair of drive waveforms (wherein t_2 , V_p and V_a are large) that achieve a droplet of large size are selected for representing high density. A pair of drive waveforms (wherein t_2 , V_p and V_a are small) that achieve a droplet of small size are selected for representing low density or high resolution. For representing a delicate halftone image, a pair of drive waveforms that achieve a droplet size slightly different from neighboring dots are selected. If there are variations in droplet ejection characteristics among the nozzles, a pair of drive waveforms that adjust the variations may be selected.

[0044] Having determined the pairs of the drive signals for 'n' dots (that is, the drive signals to be supplied to the nozzles 118 whose number is 'n'), the head controller 14 supplies the selected drive signal 21a to the piezoelectric element 116a of each nozzle 118 of the recording head 11 at the point between the ejection cycles. At the same time, the head controller 14 supplies the selected drive signal 21b to the piezoelectric element 116b of each nozzle 118. The piezoelectric element 116a of each nozzle 118 performs the steps described with reference to FIG. 8B, in accordance with the voltage waveform of the supplied signal 21a for ejecting an ink droplet. The piezoelectric element 116b of each nozzle 118 is displaced in accordance with the voltage waveform of the supplied drive signal 21b and performs the operation for assisting the ejection performed by the piezoelectric element 116a.

[0045] Referring to FIG. 7A and FIG. 7B, FIG. 9A to FIG. 9D, and FIG. 10A and FIG. 10B, the functions specific to the ink-jet printer of the embodiment will now be described.

[0046] As described in the section on the related-art techniques, satellite droplets, that is, minute droplets produced when an ink droplet is ejected, are often generated in a system wherein an ink droplet is ejected by generating a pressure with a piezoelectric element. The trailing end of the ink flying in a columnar form is separated from the tip thereof due to differences in time and velocity. The separated end part of the ink forms minute droplets.

[0047] In the embodiment, in order to prevent generation of such satellite droplets, the ink chamber 114 is contracted by raising the drive signal 21a at point E (ejection start point 'te') and changing from the reference voltage of 0 V to ejection voltage V_a . The ink chamber 114 is further contracted by raising the drive signal 21b from the reference voltage of 0 V to auxiliary voltage V_b while the drive signal 21a is maintained at ejection voltage V_a . and the ink chamber 114 is in the state of contraction. This feature will be further described, referring to FIG. 9A to FIG. 9D.

[0048] FIG. 9A to FIG. 9D show the relationship be-

tween changes of voltage waveforms of the drive signals 21a and 21b and displacements of the piezoelectric elements 116a and 116b. To be specific, FIG. 9A shows the main part of the waveform of the drive signal 21a. FIG. 9B shows the displacement of the piezoelectric element 116a. FIG. 9C shows the main part of the waveform of the drive signal 21b. FIG. 9D shows the displacement of the piezoelectric element 116b. The horizontal axes each indicate time. The vertical axes in FIG. 9A and FIG. 9C each indicate voltage. The vertical axes in FIG. 9A and FIG. 9C each indicate displacement.

[0049] As shown in FIG. 9A and FIG. 9B, the piezoelectric element 116a is shifted in the direction of contracting the ink chamber 114 with an increase in voltage of the drive signal 21a started from point E. The amount of displacement of the piezoelectric element 116b reaches maximum at point P that overruns point F at which the voltage reaches ejection voltage V_a by an inertial force. The ink chamber 114 is most contracted at point P. As shown in FIG. 9C and FIG. 9D, the drive signal 21b starts to change from the reference voltage of 0 V to auxiliary voltage V_b at point P (that is, point E') at which the amount of displacement of the piezoelectric element 116b reaches maximum. The piezoelectric element 116b is thereby further shifted in the direction of contracting the ink chamber 114. The amount of displacement of the piezoelectric element 116b reaches maximum at point P' that overruns point F at which the voltage reaches ejection voltage V_b by an inertial force as described above. The ink chamber 114 is thus most contracted at point P'. In such a manner the time required for the piezoelectric element 116a to reach maximum displacement point P from the displacement of zero is defined as delay time 'td' in the embodiment.

[0050] The piezoelectric element 116a to which ejection voltage V_a of the drive signal 21a is applied is shifted in the direction of contracting the ink chamber so as to generate a pressure in the ink chamber 114. Ink is ejected out of the nozzle 118 by the pressure. At this point the ink ejected out of the nozzle 118 is trailing and takes a columnar form. The piezoelectric element 116b to which auxiliary voltage V_b of the drive signal 21b is applied at the maximum displacement point of the piezoelectric element 116a is displaced so as to generate another pressure in the ink chamber 114. The ink column being ejected out of the nozzle 118 is further extruded by the pressure. The trailing end of the ink column therefore reaches the tip thereof and is integrated with the tip so as to form a single droplet. At the same time, discontinuity results in the ink flow and the ink column is cut immediately after the trailing end. The trail of the ink column is thereby prevented from extending and generation of satellite droplets is suppressed.

[0051] While ejection voltage V_a is maintained, intrinsic oscillations are effected in the piezoelectric element 116a. The displacement of the piezoelectric element 116a returns to zero when the drive signal 21a changes from ejection voltage V_a at point G to the reference volt-

age of 0 V at point H. Intrinsic oscillations gradually attenuating are further effected. Similarly, intrinsic oscillations are effected in the piezoelectric element 116b while auxiliary voltage Vb is maintained. The displacement of the piezoelectric element 116b returns to zero when the drive signal 21b changes from auxiliary voltage Vb at point G' to the reference voltage of 0 V at point H'. Intrinsic oscillations gradually attenuating are further effected.

[0052] FIG. 10A and FIG. 10B show the states of ink droplet ejection wherein delay time td is changed to various values. FIG. 10A shows the changes of cutting points of the trails of ink droplets wherein delay time td is set to 14, 15 and 16 μ sec, respectively. FIG. 10B shows the states of ink droplets 36 μ sec after ejection start point 'te' wherein the piezoelectric element 116a is only shifted by the drive signal 21a and delay time td is set to 14, 15 and 16 μ sec, respectively. The thickness of the piezoelectric elements 116a and 116b is 25 μ m and the thickness of the oscillation plate 113 is 25 μ m. The time and voltage parameters of the drive signals 21a and 21b shown in FIG. 7A and FIG. 7B are determined as follows. The unit of each time parameter is ' μ sec.' The unit of each voltage parameter is 'vol.'

$$\tau_1 = 30, \tau_2 = 10;$$

t1 = 9, t2 = 2, t3 = 4, t4 = 20, t5 = 8, t6 = 17, t7 = 4, t8 = 20, t9 = 8;
td = 15;
Vp = 35, Va = 30, Vb = 30.

[0053] As shown in FIG. 10A, the points of cutting the ink droplets wherein delay time td is set to 14, 15 and 16 μ sec, respectively, are the points each after a lapse of 31.2, 29.2 and 31.6 μ sec, respectively, from ejection starting point 'te'. In the states each after a lapse of 36 μ sec from ejection starting point 'te', as shown in FIG. 10B, the trail of the ink droplet is cut earlier in any of the cases wherein delay time td is set to 14, 15 and 16 μ sec, respectively, than the case wherein ejection is performed with the piezoelectric element 116a only. In particular, the droplet length when delay time td is set to 15 μ sec is shorter than the cases wherein delay time td is set to 14 and 16 μ sec, respectively.

[0054] As thus described, the point of cutting the ink droplet trail is advanced by applying the drive signal 21b to the piezoelectric element 116b. Generation of satellite droplets is thereby suppressed. In particular, the droplet trail is cut at the earliest point wherein delay time td is set to 15 μ sec and generation of satellite droplets is most efficiently suppressed. In the embodiment the delay time of 15 μ sec nearly equal to the time required for the piezoelectric element 116a to reach the maximum displacement point from the point at which the displacement of the piezoelectric element 116a is started. That is, generation of satellite droplets is most efficiently suppressed by performing control such that the piezoelectric element

116b is started to be shifted by raising auxiliary voltage Vb of the drive signal 21b at the point when the displacement amount of the piezoelectric element 116a is made maximum by the ejection voltage Va of the drive signal 21a.

[0055] According to the embodiment described so far, the two piezoelectric elements 116a and 116b are provided for each ink chamber 114 corresponding to each nozzle. Having started ink droplet ejection by the one piezoelectric element 116a, the ink chamber 114 is further contracted by effecting displacement of the other piezoelectric element 116b while the ink chamber 114 is contracted by the displacement of the piezoelectric element 116a. As a result, the ink droplet trail is cut at an early stage and generation of satellite droplets is suppressed. In particular, generation of satellite droplets is most efficiently suppressed by starting the displacement of the piezoelectric element 116b at the point when the amount of displacement of the piezoelectric element 116a is maximum.

[0056] The invention is not limited to the embodiment wherein the displacement of the piezoelectric element 116b is started at the point when the amount of displacement of the piezoelectric element 116a is maximum as shown in FIG. 9A to FIG. 9D. Although the embodiment is preferable, similar effects will be achieved by starting the displacement of the piezoelectric element 116b at any time when the ink chamber 114 is contracted (that is, between points E and H in FIG. 9B).

[Second Embodiment]

[0057] Another embodiment of the invention will now be described.

[0058] In the ink-jet printer of the second embodiment of the invention for preventing generation of satellite droplets, as shown in FIG. 11A and FIG. 11B, a drive signal 21a' outputted from the head controller 14 is raised from the reference voltage of 0 V to ejection voltage Va at point E (ejection start point 'te') so as to shift the piezoelectric element 116a in the direction of contracting the ink chamber. Then, the operation is started for shifting the piezoelectric element 116a in the direction of expanding the ink chamber 114 at point G. At the same time, a drive signal 21b' outputted from the head controller 14 is raised from the reference voltage of 0 V to auxiliary voltage Vb so as to shift the piezoelectric element 116b in the direction of contracting the ink chamber with timing nearly parallel with the operation of displacing the piezoelectric element 116a in the direction of expanding the ink chamber. The basic configuration of the ink-jet printer of the second embodiment is similar to that of the first embodiment shown in FIG. 4 to FIG. 6 and description thereof is omitted.

[0059] FIG. 11A and FIG. 11B show the waveforms of the drive signals 21a' and 21b' of one cycle (T) that correspond to FIG. 7A and FIG. 7B of the foregoing first embodiment. Since the drive signals 21a' and 21b' have

the waveform patterns similar to those of the drive signals 21a and 21b shown in FIG. 7A and FIG. 7B, like numerals are assigned to the corresponding voltage changing points, voltage parameters and time parameters for convenience of description.

[0060] The drive signal 21a' is a drive signal for generating a pressure for ejecting an ink droplet. The voltage of the drive signal 21a' includes retraction voltage Vp and ejection voltage Va besides the reference voltage of 0 V. The significance of the drive signal 21a' is similar to that of the drive signal 21a of the foregoing embodiment described with reference to FIG. 8A to FIG. 8C and description thereof is omitted. The drive signal 21b' is an auxiliary drive signal for generating a pressure for suppressing satellite droplets when an ink droplet is ejected. The voltage of the drive signal 21b' includes retraction voltage Vp and auxiliary voltage Vb besides the reference voltage of 0 V. The pair of the drive signals 21a' and 21b' are appropriately switched to another pair by the head controller 14 between the ejection cycles and supplied to the corresponding nozzle. In the second embodiment, too, time t2 required for the second step is less than the time required for the meniscus retracted in the first step to reach the nozzle edge. Ejection voltage Va in the third step falls within the range that allows ink droplet ejection.

[0061] Referring to FIG. 11A and FIG. 11B, the waveform of the drive signal 21b' will be further described in detail. In the embodiment, the section from A to D of the drive signal 21b' is similar to that of the waveform of the drive signal 21a'. Time t6 required for period DE' during which the voltage of 0 V is maintained is equal to period DG (= t2 + t3 + t4) of the drive signal 21a'. The drive signal 21b' starts rising from the reference voltage of 0 V to auxiliary voltage Vb at point G (= point E') at which the drive signal 21a' starts falling from ejection voltage Va to the reference voltage of 0V. As thus described, one of the features of the invention is that the drive signal 21b' is raised so as to shift the piezoelectric element 116b in the direction of contracting the ink chamber in parallel with having the drive signal 21a' fall so as to shift the piezoelectric element 116a in the direction of expanding the ink chamber. This feature will be described below.

[0062] Referring to FIG. 11A and FIG. 11B and FIG. 12A to FIG. 12D, the operation specific to the second embodiment will now be described. FIG. 12A to FIG. 12D show the relationship between changes of voltage waveforms of the drive signals 21a' and 21b' and displacements of the piezoelectric elements 116a and 116b, which correspond to FIG. 9A to FIG. 9D of the foregoing first embodiment.

[0063] As shown in FIG. 12A and FIG. 12B, the piezoelectric element 116a is shifted in the direction of contracting the ink chamber with an increase in voltage of the drive signal 21a' started from point E. The amount of displacement of the piezoelectric element 116a reaches maximum at point P that overruns point F at which the voltage reaches ejection voltage Va by an inertial force. The ink chamber 114 is most contracted at point P. The

drive signal 21a' starts to fall at point P (point G in FIG. 12A) and reaches the reference voltage of 0 V at point H. The piezoelectric element 116a is thereby shifted in the direction of expanding the ink chamber and returns to the initial state. As shown in FIG. 12C and FIG. 12D, the drive signal 21b' starts to rise from the reference voltage of 0 V to auxiliary voltage Vb at point E' equal to point G at which the drive signal 21a' starts to fall. The piezoelectric element 116b is thereby shifted in the direction of contracting the ink chamber 114. The amount of displacement of the piezoelectric element 116b reaches maximum by an inertial force as described above at point P' that overruns point F' at which the voltage reaches ejection voltage Vb.

[0064] In the embodiment as thus described, the piezoelectric element 116b is shifted from the state of no displacement to the direction of contracting the ink chamber in parallel with the piezoelectric element 116a being shifted to the direction of expanding the ink chamber. That is, displacements of the piezoelectric elements 116a and 116b take place in the directions opposite to each other in a parallel manner.

[0065] The piezoelectric element 116a to which ejection voltage Va of the drive signal 21a is applied is shifted in the direction of contracting the ink chamber so as to generate a pressure in the ink chamber 114. Ink is ejected out of the nozzle 118 by the pressure. At this point the ink ejected out of the nozzle 118 is trailing and takes a columnar form. Next, the piezoelectric element 116a starts to be shifted in the direction of expanding the ink chamber, the trailing end of ink is retracted and becomes thin. At point P (point E') the piezoelectric element 116b is shifted in the direction of contracting the ink chamber so as to generate another pressure in the ink chamber 114. The ink column is then extruded by the pressure and discontinuity results in the ink flow. The ink column is thereby cut in an earlier stage and the trail of the ink column is prevented from extending. Consequently, generation of satellite droplets is suppressed.

[0066] At point H, the displacement of the piezoelectric element 116a returns to zero and then intrinsic oscillations are effected in the piezoelectric element 116a that gradually attenuates. Similarly, the displacement of the piezoelectric element 116b returns to zero at point H' and then intrinsic oscillations are effected in the piezoelectric element 116b that gradually attenuates.

[0067] A specific example will now be described. The thickness of the piezoelectric elements 116a and 116b is 25 μ m and the thickness of the oscillation plate 113 is 25 μ m. The time and voltage parameters of the drive signals 21a' and 21b' shown in FIG. 11A and FIG. 11B are determined as follows. The unit of each time parameter is ' μ sec.' The unit of each voltage parameter is 'volt.'

$$\tau_1 = 30, \tau_2 = 10;$$

$t_1 = 9, t_2 = 2, t_3 = 2, t_4 = 3, t_5 = 11, t_6 = 7, t_7 = 2, t_8 = 8, t_9 = 8;$
 $V_p = 35, V_a = 33, V_b = 30.$

[0068] According to the embodiment described so far, the two piezoelectric elements 116a and 116b are provided for each ink chamber 114 corresponding to each nozzle. Ink droplet ejection is started by shifting the one piezoelectric element 116a in the direction of contracting the ink chamber. The other piezoelectric element 116b is then shifted from the state of displacement of zero to the direction of contracting the ink chamber in parallel with shifting the piezoelectric element 116a to the direction of expanding the ink chamber. As a result, the ink droplet trail is cut at an early stage and generation of satellite droplets is thereby suppressed. In particular, generation of satellite droplets is more efficiently suppressed by having the piezoelectric element 116a start to return (start to be shifted in the direction of expanding the ink chamber) at or near the point when the amount of displacement of the piezoelectric element 116a is maximum in the direction of contracting the ink chamber.

[0069] The invention is not limited to the embodiment wherein point G at which the piezoelectric element 116a starts to shift in the direction of expanding the ink chamber coincides with point E' at which the piezoelectric element 116b starts to shift in the direction of contracting the ink chamber. Timing may be determined so that the piezoelectric element 116b shifts in the direction of contracting the ink chamber in nearly parallel with the piezoelectric element 116a shifting in the direction of expanding the ink chamber. The condition for achieving the state is that the time parameters shown in FIG. 11A and FIG. 11B satisfy expressions (1) and (2) below.

$$t_2 + t_3 + t_4 < t_6 + t_7 \quad \dots(1)$$

$$t_2 + t_3 + t_4 + t_5 > t_6 \quad \dots(2)$$

[0070] The invention is not limited to the embodiment wherein the piezoelectric element 116a starts to return to the initial state (in the direction of expanding the ink chamber) at the point when the amount of displacement of the piezoelectric element 116a itself is maximum. Alternatively, the piezoelectric element 116a may start to return to the initial state at any other point. However, the ink droplet trail is made thin at an earlier stage if the piezoelectric element 116a starts to return to the initial state at or near the point when the amount of displacement of the piezoelectric element 116a is maximum. The droplet size is thereby made smaller.

[Third Embodiment]

[0071] Still another embodiment of the invention will now be described.

[0072] In the ink-jet printer of the third embodiment of the invention for preventing generation of satellite droplets, as shown in FIG. 13A and FIG. 13B, a drive signal 21b" outputted from the head controller 14 is maintained at retraction voltage V_p in advance so as to keep the piezoelectric element 116a contracted. In this state, the first to third steps of the piezoelectric element 116a (FIG. 8A to FIG. 8C) are performed by means of a drive signal 21a" outputted from the head controller 14. In the state wherein the piezoelectric element 116a is shifted in the direction of contracting the ink chamber by means of the drive signal 21a" after the third step, the drive signal 21b" is made to fall so as to shift the piezoelectric element 116b in the direction of expanding the ink chamber. The basic configuration of the ink-jet printer of the second embodiment is similar to that of the first embodiment shown in FIG. 4 to FIG. 6 and description thereof is omitted.

[0073] FIG. 13A and FIG. 13B show the waveforms of the drive signals 21a" and 21b" of one cycle (T) that correspond to FIG. 7A and FIG. 7B of the foregoing first embodiment. Since the drive signal 21a" has the waveform pattern similar to that of the drive signal 21a shown in FIG. 7A and the drive signal 21b" has the waveform pattern similar to the first half of the waveform of the drive signal 21b shown in FIG. 7B, like numerals are assigned to the corresponding voltage changing points, voltage parameters and time parameters for convenience of description.

[0074] The drive signal 21a" is a drive signal for generating a pressure for ejecting an ink droplet. The voltage of the drive signal 21a" includes retraction voltage V_p and ejection voltage V_a besides the reference voltage of 0 V. The significance of the drive signal 21a" is similar to that of the drive signal 21a of the foregoing embodiment described with reference to FIG. 8A to FIG. 8C and description thereof is omitted. The drive signal 21b" is an auxiliary drive signal for generating a pressure for suppressing satellite droplets when an ink droplet is ejected. The voltage of the drive signal 21b" includes the reference voltage of 0 V and retraction voltage V_p . The pair of the drive signals 21a" and 21b" are appropriately switched to another pair by the head controller 14 between the ejection cycles and supplied to the corresponding nozzle. In the third embodiment, too, time t_2 required for the second step is less than the time required for the meniscus retracted in the first step to reach the nozzle edge. Ejection voltage V_a in the third step falls within the range that allows ink droplet ejection.

[0075] Referring to FIG. 13A and FIG. 13B, the waveform of the drive signal 21b" will be further described in detail. In the embodiment the drive signal 21b" changes from the reference voltage of 0 V to retraction voltage V_p in section AB as the drive signal 21a". Retraction voltage V_p is maintained until specific point C' after point F at the drive signal 21a" reaches ejection voltage V_a . At point C' retraction voltage V_p abruptly falls to the reference voltage of 0 V. In FIG. 13A and FIG. 13B time 'td' is from

ejection start point 'te' of the drive signal 21a" (that is, point E at which the drive signal 21a" starts rising from the reference voltage of 0V to ejection voltage Va) until point C' at which the drive signal 21b" starts falling from retraction voltage Vp to the reference voltage of 0V. Time required for section BC' during which retraction voltage Vp is maintained is expressed as $t_1 + t_2 + t_d$ where $t_d > t_3$. In FIG. 13B time required for section C'D' during which the drive signal 21b" changes from retraction voltage Vp to the reference voltage of 0V is shown as t_1' . One of the features of the invention is that delay time t_d is appropriately determined.

[0076] Referring to FIG. 13A and FIG. 13B to FIG. 15, the operation specific to the third embodiment will now be described. FIG. 14A to FIG. 14D show the relationship between changes of voltage waveforms of the drive signals 21a" and 21b" and displacements of the piezoelectric elements 116a and 116b, which correspond to FIG. 9A to FIG. 9D of the foregoing first embodiment.

[0077] As shown in FIG. 14C and FIG. 14D, the piezoelectric element 116b closer to the nozzle is maintained in the state shifted in the direction of contracting the ink chamber by maintaining the drive signal 21b" at retraction voltage Vp in advance. In this state, as shown in FIG. 14A and FIG. 14B, the piezoelectric element 116a closer to the duct starts to shift in the direction of contracting the ink chamber at point E with an increase in voltage of the drive signal 21a". The amount of displacement of the piezoelectric element 116a reaches maximum by an inertial force at point P that overruns point F at which the voltage reaches ejection voltage Va. As shown in FIG. 14C and FIG. 14D, the drive signal 21b" starts to fall from retraction voltage Vp to the reference voltage of 0 V at specific point C' after point F at which the drive signal 21a" reaches ejection voltage Va (that is, the point after a lapse of time 'td' from ejection start point 'tc' [= point E]). The drive signal 21b" then reaches the reference voltage of 0 V at point D'. The piezoelectric element 116b is thereby abruptly shifted in the direction of expanding the ink chamber.

[0078] As shown in FIG. 14A and FIG. 14B, the piezoelectric element 116a to which ejection voltage Va of the drive signal 21a" is applied is shifted in the direction of contracting the ink chamber so as to generate a pressure in the ink chamber 114. Ink is ejected out of the nozzle 118 by the pressure. At this point the ink ejected out of the nozzle 118 is trailing and takes a columnar form. On the other hand, the voltage applied to the piezoelectric element 116b falls from retraction voltage Vp to the reference voltage of 0 V. at point C' after a lapse of time 'td' since the piezoelectric element 116a starts shifting. The piezoelectric element 116b is thereby abruptly shifted in the direction of expanding the ink chamber so as to generate a negative pressure in the ink chamber 114. The trailing end of the ink column being extruded through the nozzle 118 is pulled back by the negative pressure. Discontinuity thereby results in the ink flow and the ink column is cut between the tip and the trail thereof. The ink

column trail is thus prevented from extending and generation of satellite droplets is suppressed.

[0079] While ejection voltage Va is maintained, intrinsic oscillations are effected in the piezoelectric element 116a. When the drive signal 21a" changes from ejection voltage Va at point G to the reference voltage of 0 V at point H, the displacement of the piezoelectric element 116a returns to zero and then intrinsic oscillations are effected in the piezoelectric element 116a that gradually attenuates. After point D' at which the voltage reaches the reference voltage of 0 V, intrinsic oscillations around the intended displacement position are effected in the piezoelectric element 116b that gradually attenuates.

[0080] FIG. 15A and FIG. 15B show the states of ink droplet ejection wherein delay time 'td' between ejection start point 'te' (point E) and point C' at which the drive signal 21b" is changed to various values. FIG. 15A shows the changes of points at which the trails of ink droplets are cut wherein delay time t_d is set to 10, 9, 8 and 7 μ sec, respectively. FIG. 15B shows the states of ink droplets 32 μ sec after ejection start point 'te' wherein the piezoelectric element 116a is only shifted by the drive signal 21a" and delay time t_d is set to 10, 9, 8 and 7 μ sec, respectively. The thickness of the piezoelectric elements 116a and 116b is 25 μ m and the thickness of the oscillation plate 113 is 25 μ m. The time and voltage parameters of the drive signals 21a" and 21b" shown in FIG. 13A and FIG. 13B are determined as follows. The unit of each time parameter is ' μ sec.' The unit of each voltage parameter is 'volt.'

$$\tau_1 = 30, \tau_2 = 10;$$

$$t_1 = 9, t_2 = 2, t_3 = 5, t_4 = 50, t_5 = 50, t_6 = 1; \\ t_d = 9;$$

$$V_p = 35, V_a = 35, V_b = 35.$$

[0081] As shown in FIG. 15A, the points of cutting the ink droplets wherein delay time t_d is set to 10, 9, 8 and 7 μ sec, respectively, are the points each after a lapse of 23, 21.8, 22.8 and 36 μ sec, respectively, from ejection start point 'te'. In the states each after a lapse of 32 μ sec from ejection start point 'te', as shown in FIG. 15B, the trail of the ink droplet is cut earlier in any of the cases wherein delay time t_d is set to 10, 9 and 8 μ sec, respectively, than the case wherein ejection is performed with the piezoelectric element 116a only. In particular, no satellite droplets are produced when delay time t_d is set to 9 μ sec in contrast to the cases wherein delay time t_d is set to the other values. However, if delay time t_d is set to 7 μ sec or below, the ejection pressure generated by the piezoelectric element 116a is cancelled out by the negative pressure generated by the piezoelectric element 116b and the velocity of ink droplet ejected is reduced. In particular, no ink droplet is ejected if delay time t_d is set to 5 μ sec.

[0082] As thus described, the point of cutting the ink

droplet trail is advanced by applying the drive signal 21b" to the piezoelectric element 116b. Generation of satellite droplets is thereby suppressed. In particular, the droplet trail is cut at the earliest point if delay time t_d is set to 9 μ sec and generation of satellite droplets is most efficiently suppressed. In the embodiment the delay time of 9 μ sec nearly equal to the time required for the piezoelectric element 116a to reach maximum displacement point P (FIG. 9B) from the point at which the displacement of the piezoelectric element 116a is started. That is, generation of satellite droplets is most efficiently suppressed by starting displacement of the piezoelectric element 116b in the direction of expanding the ink chamber by having the drive signal 21b" fall at the point when the displacement amount of the piezoelectric element 116a is made maximum by ejection voltage V_a of the drive signal 21a".

[0083] According to the embodiment described so far, the two piezoelectric elements 116a and 116b are provided for each ink chamber 114 corresponding to each nozzle. The piezoelectric element 116b closer to the nozzle is shifted in the direction of contracting the ink chamber in advance. In this state, ink droplet ejection is started by shifting the piezoelectric element 116a closer to the ink feed in the direction of contracting the ink chamber. The other piezoelectric element 116b is then shifted in the direction of expanding the ink chamber so as to generate a negative pressure in the ink chamber 114. As a result, the ink droplet trail is cut at an early stage and generation of satellite droplets is thereby suppressed. In particular, generation of satellite droplets is most efficiently suppressed by having the piezoelectric element 116b started to shift in the direction of expanding the ink chamber at the point when the amount of displacement of the piezoelectric element 116a is maximum in the direction of contracting the ink chamber.

[0084] The invention is not limited to the embodiment wherein the piezoelectric element 116b starts to shift at the point when the amount of displacement of the piezoelectric element 116a is maximum. Although the embodiment is preferable, similar effects are achieved by starting the displacement of the piezoelectric element 116b at any other point after the piezoelectric element 116a starts shifting.

[0085] The invention is not limited to the embodiments described so far but may be practiced in still other ways.

[0086] For example, the time and voltage parameter values mentioned in the foregoing embodiments (FIG. 7A and FIG. 7B, FIG. 11A and FIG. 11B, FIG. 13A and FIG. 13B) are no more than examples and may be appropriately changed to other values. For example, although the retraction voltages of the drive signals 21a and 21b and so on are both V_p in the foregoing embodiments, the voltages may be of different values.

[0087] In the foregoing embodiments, the piezoelectric element 116a closer to the ink feed is used as the means for generating a pressure for ejection and the piezoelectric element 116b closer to the nozzle is used as the

means for generating a pressure for preventing satellite droplets. Alternatively, the piezoelectric element 116b closer to the nozzle may be used as the means for generating a pressure for ejection and the piezoelectric element 116a closer to the ink feed may be used as the means for generating a pressure for preventing satellite droplets.

[0088] Although two piezoelectric elements are provided for each nozzle in the foregoing embodiments, three or more piezoelectric elements may be provided for each nozzle. These piezoelectric elements are divided into those for ejection and those for suppressing satellite droplets. The drive signals 21a and so on are applied to the piezoelectric elements for ejection while the drive signals 21b and so on are applied to the piezoelectric elements for suppressing satellite droplets. The displacement capacities of the three or more piezoelectric elements may be either equal to one another or different from one another. As a result, more delicate control is performed for suppressing satellite droplets.

[0089] In the foregoing embodiments the one ink chamber 114 is provided for the one nozzle 118 and the two piezoelectric elements 116a and 116b corresponding to the ink chamber 114 are provided. Alternatively, as shown in FIG. 16, for example, two ink chambers 114a and 114b may be provided for the one nozzle 118 and the piezoelectric elements 116a and 116b each corresponding to the ink chambers 114a and 114b, respectively, may be provided. FIG. 16 is a top view of part of the recording head 11 wherein like numerals are assigned to the components similar to those shown in FIG. 5 and the oscillation plate 13 is omitted. In the configuration as shown, the behavior of the piezoelectric element 116a with regard to the one ink chamber 114a has less effect on the state of the other ink chamber 114b. As a result, crosstalk between the piezoelectric elements 116a and 116b is reduced and printed images of higher quality will be achieved.

[0090] Referring to FIG. 17 and FIG. 18, the function specific to the ink-jet printer of the invention will now be described.

[0091] FIG. 17 shows the relationship between ink droplet diameters and applied voltages wherein ink droplet ejection is performed by either piezoelectric element 116a or 116b or both. The horizontal axis indicates applied voltages. The vertical axis indicates ink droplet diameters. A curve 200a with dots indicates ink droplet diameters wherein droplet ejection is performed by the piezoelectric element 116a away from the nozzle 118 (that is, closer to the ink feed) only. A curve 200b with deltas indicates ink droplet diameters wherein droplet ejection is performed by the piezoelectric element 116b closer to the nozzle 118 only. A curve 200ab with squares indicates ink droplet diameters wherein droplet ejection is performed by both piezoelectric elements 116a and 116b.

[0092] As shown, regardless of the applied voltage, the shortest droplet diameter is obtained when ejection

is performed by the piezoelectric element 116a closer to the ink feed. The droplet diameter is longer when ejection is performed by the piezoelectric element 116b closer to the nozzle and still longer when ejection is performed by both piezoelectric elements 116a and 116b. That is, a smaller droplet is obtained by performing ejection by the piezoelectric element 116a closer to the ink feed than the piezoelectric element 116b closer to the nozzle.

[0093] FIG. 18 shows the relationship between velocities of ejected ink droplets and applied voltages wherein ink droplet ejection is performed by either piezoelectric element 116a or 116b or both. The horizontal axis indicates applied voltages. The vertical axis indicates velocities of ejected ink droplets. A curve 201a with dots indicates ejected droplet velocities wherein droplet ejection is performed by the piezoelectric element 116a closer to the ink feed only. A curve 201b with deltas indicates ejected droplet velocities wherein droplet ejection is performed by the piezoelectric element 116b closer to the nozzle 118 only. A curve 201ab with squares indicates ejected droplet velocities wherein droplet ejection is performed by both piezoelectric elements 116a and 116b.

[0094] As shown, regardless of the applied voltage, the highest droplet velocity is obtained when ejection is performed by both piezoelectric elements 116a and 116b. The velocity is lower when ejection is performed by the piezoelectric element 116a closer to the ink feed and still lower when ejection is performed by the piezoelectric element 116b closer to the nozzle. That is, a higher droplet velocity is obtained by performing ejection by the piezoelectric element 116a closer to the ink feed than the piezoelectric element 116b closer to the nozzle.

[0095] Based on the results, the piezoelectric element 116a away from the nozzle is used for droplet ejection while the piezoelectric element 116b closer to the nozzle is used for suppressing satellite droplets. That is a reason why, the drive signal 21a is applied to the piezoelectric element 116a and the drive signal 21b to the piezoelectric element 116b. Generation of satellite droplets is thereby suppressed, the droplet size is reduced and the ejected droplet velocity is increased.

[0096] The invention is not limited to the embodiments described so far but may be practiced in still other ways. For example, although the piezoelectric element 116b as the means for generating an auxiliary pressure is used for suppressing satellite droplets, the invention may be applied to a case wherein the means for generating an auxiliary pressure is used for any other purpose.

[0097] For example, the inventors of the invention have observed the meniscus position of ink after ink droplet ejection is performed with the piezoelectric element for ejection to confirm that the meniscus position exhibits great fluctuations (long-period residual oscillations) even after the short-period oscillations of the piezoelectric element for ejection almost disappear. The inventors have proposed that the auxiliary piezoelectric element be driven with appropriate timing in order to suppress such residual oscillations of the meniscus. In such a case, too,

a higher velocity of an ejected ink droplet and a smaller droplet size are both achieved as well as suppression of residual oscillations by placing the auxiliary piezoelectric element closer to the nozzle and the piezoelectric element for ejection away from the nozzle.

[0098] The inventors of the invention have proposed an ink-jet printer that allows smooth ink droplet ejection through a nozzle by giving preliminary small oscillations to the meniscus by the auxiliary piezoelectric element before ejection when droplet ejection is first performed after power-up of the printer or when a droplet is to be ejected through a nozzle that has not been used for ejection for a long time. In such a case, too, a higher velocity of an ejected ink droplet and a smaller droplet size are both achieved as well as smooth droplet ejection by placing the auxiliary piezoelectric element closer to the nozzle and the piezoelectric element for ejection away from the nozzle.

[Fourth Embodiment]

[0099] Another embodiment of the invention will now be described.

[0100] In the fourth embodiment, the piezoelectric elements 116a and 116b (FIG. 5 and FIG. 6) have ink drive capacities different from each other in response to the same applied voltage. The ink drive capacity means the capacity for changing the volume of the ink chamber 114. To be specific, the piezoelectric element 116a has the ink drive capacity greater than the piezoelectric element 116b. The piezoelectric elements 116a and 116b are therefore made of the same material and have the same thickness while the piezoelectric element 116a has a surface area greater than the piezoelectric element 116b. As a result, a change in volume of the ink chamber 114 effected by the piezoelectric element 116a is greater than a change effected by the piezoelectric element 116b in response to the same applied voltage. Consequently, as long as the ejection voltage (described below) applied is equal, a shorter ink droplet diameter is achieved when the voltage is applied to the piezoelectric element 116b compared to the piezoelectric element 116a. The surface area ratio between the elements 116a and 116b may be two to one. Alternatively, the ratio may be any other ratio. The piezoelectric elements 116a and 116b correspond to an 'ejection energy generating means' of the invention.

[0101] FIG. 19 is a block diagram of the head controller 14 shown in FIG. 4. As shown, the head controller 14 comprises: a plurality of selectors 141-1 to 141-n; a drive waveform generator 142 for generating two kinds of fundamental drive signals 145-1 and 145-2; and a selection controller 143 for controlling the operation of the waveform selectors 141-1 to 141-n; wherein 'n' represents a positive integer equal to the number of the nozzles 118.

[0102] The drive signals 145-1 and 145-2 outputted from the drive waveform generator 142 are each branched into 'n' in number to be inputted to the selectors 141-1 to 141-n, respectively. The selection controller 143

inputs selection signals 146-1 to 146-n to the respective selectors 141-1 to 141-n with specific timing. The selection signals 146-1 to 146-n are signals for selecting either the fundamental drive signal 145-1 or 145-2 for each nozzle 118 of the recording head 11 and for instructing to apply the signal to either the piezoelectric element 116a or 116b. The selectors 141-1 to 141-n each select either the drive signal 145-1 or 145-2 in accordance with the selection signal. The selectors 141-1 to 141-n supply the selected drive signals to the respective piezoelectric elements 116a (and 116b) in the ink droplet ejection section as drive signals 21-1a (and 21-1b) to 21-na (and 21-nb) respectively. The drive signals 21-1a to 21-na and 21-1b to 21-nb correspond to the drive signal 21 in FIG. 4 and FIG. 19. The selectors 141-1 to 141-n each correspond to a "means for selecting" of the invention.

[0103] Although not shown, the drive waveform generator 142 is made up of a microprocessor; a read only memory (ROM) for storing a program executed by the microprocessor; a random access memory (RAW as a work memory used for particular computations performed by the microprocessor and temporary data storage and so on; a drive waveform storage section made up of nonvolatile memory; a digital-to-analog (D-A) converter for converting digital data read from the storage section into analog data; and an amplifier for amplifying an output of the D-A converter. The drive waveform storage section retains waveform data representing the voltage waveforms of the fundamental drive signals 145-1 and 145-2 for driving the recording head 11. The waveform data items are each read by the microprocessor and converted to analog signals by the D-A converter. The signals are amplified by the amplifier and outputted as the drive signals 145-1 and 145-2. The configuration of the drive waveform generator 142 is not limited to the one described above but may be implemented in any other way.

[0104] FIG. 20A and FIG. 20B show examples of one cycle (T) of waveforms of the fundamental drive signals 145-1 and 145-2 outputted from the drive waveform generator 142. FIG. 20A and FIG. 20B each show the drive signals 145-1 and 145-2, respectively. The vertical axis indicates voltage. The horizontal axis indicates time. Time proceeds from left to right in the graphs. Of the drive signals, the drive signal 145-1 has a waveform of a constant voltage (V1) that does not allow ink droplet ejection. Constant voltage V1 is other than 0 V. On the other hand, the drive signal 145-2 has a waveform with a specific undulation. The voltages of the drive signal 145-2 include 0 V and voltage V2 higher than V1 besides reference voltage V1.

[0105] As shown in FIG. 20A and FIG. 20B, the drive signals are switched to other signals at switching point t_s between the ejection cycles at the selectors 141-1 to 141-n. The drive signals may be switched to others at specific point t_s' within the cycle. Switching point t_s' is the point at which the drive signal waveform crosses reference voltage V1 in the course of changing from 0 V to

voltage V2. Time between switching point t_s' and the end of the cycle is shown as τ_1 and time between the start point of the cycle and switching point t_s' is shown as τ_2 .

[0106] Reference is now made to FIG. 21A to FIG. 21C for describing the significance of the drive signal 145-2. FIG. 21A to FIG. 21C show the relationship among the waveform of the drive signal 145-2, the behavior of the piezoelectric element (the piezoelectric element 116a in the embodiment), and the position of extremity of ink in the nozzle 118 (referred to as meniscus position in the following description). FIG. 21A shows the waveform of the fundamental drive signal 145-2. The section divided with switching points t_s corresponds to one cycle of the waveform. Letters t_s indicate the switching point provided between the cycles. Letters t_s' indicate the switching point provided within the cycle. Letters t_e indicate the ejection start point. FIG. 21B illustrates the changing state of the ink chamber 114 when the drive signal having a waveform as shown in FIG. 21A is applied to the piezoelectric element 116a. FIG. 21C illustrates the changing meniscus positions in the nozzle 118. For convenience of description, FIG. 21A illustrates a cyclic repetition of the drive signal of the same waveform.

[0107] In FIG. 21A, a first step is the step in which the drive voltage is changed from first voltage V1 (constant) to the voltage of 0 V (from A to B). Time required for the first step is defined as t_1 . A second step is the step in which the voltage of 0 V is maintained to be on standby (from B to C). Time required for the second step is defined as t_2 . A third step is the step in which the voltage of 0 V is changed to second voltage V2 (from C to D). Time required for the third step is defined as t_3 . In the following description, first voltage V1 is called retraction voltage. Second voltage V2 is called ejection voltage.

[0108] The recording head 11 is driven at a constant frequency (of the order of 1 to 10 kHz, for example). Cycle T of ink droplet ejection is determined depending on the drive frequency. Points C and G and so on at which the third step is started are the points at which ejection is started (ejection start point ' t_e '). The first and second steps precede the start of ejection.

[0109] At and before point A, as P_A in FIG. 21B, the oscillation plate 113 is slightly bent inward with an application of voltage V1 to the piezoelectric element 116a and remains at rest. The ink chamber 114 is thereby brought to a state of contraction. At point A, as M_A in FIG. 21C, the meniscus position in the nozzle 118 is nearly equal to the nozzle edge.

[0110] Next, the first step is performed for reducing the drive voltage from voltage V1 at point A to the voltage of 0 V at point B. The voltage applied to the piezoelectric element 116a is thereby reduced to zero so that the bend in the oscillation plate 113 is eliminated and the ink chamber 114 is expanded as P_B in FIG. 21B. Consequently, the meniscus in the nozzle 118 is retracted towards the ink chamber 114. At point B the meniscus is retracted as deep as M_B in FIG. 21C, that is, moves away from the nozzle edge.

[0111] The amount of retraction of the meniscus in the first step is changed by changing the potential difference between points A and B (retraction voltage V1). Therefore it is consequentially possible to adjust the meniscus position at the point of completion of the second step, that is, at the start point of the third step. The meniscus position, that is, the distance between the nozzle edge and the meniscus at the start point of the third step has an effect on the droplet size ejected in the third step. The droplet size is reduced with an increase in the distance. The droplet size is thus reduced by increasing the amount of retraction of the meniscus (to be specific, retraction voltage V1) in the first step.

[0112] Next, the second step is performed for maintaining the volume of the ink chamber 114 by fixing the drive voltage to zero so as to keep the oscillation plate 113 unbent during time t2 from point B to point C (P_B to P_C in FIG. 21C). During time t2 ink is continuously fed from the ink cartridge 12. The meniscus position in the nozzle 118 is thus shifted towards the nozzle edge. The meniscus position proceeds as far as the state of M_C shown in FIG. 21C at point C.

[0113] The amount of movement of the meniscus may be varied by changing time t2 required for the second step. The meniscus position at the start point of the third step is thereby adjusted. As a result, the droplet size is controllable by adjusting time t2. To be specific, the droplet size is reduced with a reduction in time t2.

[0114] Next, the third step is performed for abruptly increasing the drive voltage from the voltage of 0 V at point C to ejection voltage V2 at point D. Point C is ejection start point te as described above. Since high ejection voltage V2 is applied to the piezoelectric element 116a at point D, the oscillation plate 113 is greatly bent inward as P_D in FIG. 21B. The ink chamber 114 is thereby abruptly contracted. Consequently, as M_D in FIG. 21C, the meniscus in the nozzle 118 is pressed towards the nozzle edge at a stretch through which an ink droplet is ejected. The droplet ejected flies in the air and lands on the paper 2 (FIG. 4). As described above, the droplet size is reduced with an increase in the distance between the nozzle edge and the meniscus position at point C at which the third step is started.

[0115] Since the amount of bend in the oscillation plate 113 changes with the magnitude of ejection voltage V2, the ejected droplet size may be changed by adjusting ejection voltage V2. To be specific, the droplet size is reduced with a reduction in ejection voltage V2.

[0116] Next, the drive voltage is reduced to V1 again so that the oscillation plate 113 is slightly bent inward to be in the initial state (P_E in FIG. 21B). This state is maintained until point F at which the first step of next ejection cycle is started. At point E at which the drive voltage is reduced to V1 again, as M_E in FIG. 21C, the meniscus position is retreated by the amount nearly corresponding to the total of the volume of ink ejected and the increase in volume of the ink chamber 114. With ink refilling, the meniscus position returns to the position of the nozzle

edge, as M_F in FIG. 21C, at point F at which the first step of next ejection cycle is started. This state is similar to M_A at point A.

[0117] The cycle of ejection is thus completed. Such a cycle of operation is repeated for each of the nozzles 118 in a parallel manner. Image recording on the paper 2 (FIG. 4) is thereby continuously performed. Time t2 required for the second step is less than the time required for the meniscus retracted in the first step to reach the nozzle edge. Ejection voltage V2 in the third step falls within the range that allows ink droplet ejection. The gradient of voltage in the third step is constant.

[0118] Reference is now made to FIG. 22 for describing the operation of the ink-jet printer 1 shown in FIG. 19 as a whole. FIG. 22 shows the main operation of one ejection cycle in the head controller 14 (FIG. 19).

[0119] In FIG. 4, printing data is inputted to the ink-jet printer 1 from an information processing apparatus such as a personal computer. The image processor 15 performs specific image processing on the input data (such as expansion of compressed data) and outputs the data as the image printing data 22 to the head controller 14.

[0120] On receipt of the image printing data 22 of 'n' dots corresponding to the number of nozzles of the recording head 11 (step S101 in FIG. 22), the controller 143 in the head controller 14 determines an ink droplet size for forming a dot for each nozzle 118 based on the image printing data 22. The controller 143 then determines a combination of a pair of drive signal waveforms to be selected at the selectors 141-1 to 141-n and the piezoelectric element 116a or 116b to which the drive signal is applied, based on the determined droplet sizes. To be specific, the controller 143 determines the drive signal waveform to be selected at the selector 141-j while incrementing variable 'j' from '1' to 'n' and determines to which of the piezoelectric elements 116a and 116b the drive signal is applied (steps S102 to S105). The selected fundamental drive signal 145-1 or 145-2 may be switched every cycle (at switching point ts) so as to use the original waveforms as they are. Alternatively, the selected drive signal 145-1 or 145-2 may be switched at switching points ts' during the cycle so as to generate a composite waveform. Furthermore, the selected drive signal 145-1 or 145-N may be switched at both point between the cycles and points during the cycle.

[0121] For example, a combination of drive waveforms and the piezoelectric element that achieves a large droplet is selected for representing high density and a droplet of small size for representing low density or high resolution. For representing a delicate halftone image, a combination of drive waveforms and the piezoelectric element that achieves a droplet size slightly different from neighboring dots is selected. If there are variations in droplet ejection characteristics among the nozzles, a combination of drive waveforms and the piezoelectric element that adjusts the variations may be selected.

[0122] Having determined the combination patterns of the drive waveforms and the piezoelectric element for all

the waveform selectors 141-1 to 141-n whose number is 'n' (Y in step S105), the controller 143 outputs the selection signals 146-1 to 146-n to the respective selectors 141-1 to 141-n for instructing the selected drive signals having the determined waveforms and the selected piezoelectric element (116a or 116b) to which the drive signals are applied. The controller 143 outputs the selection signals at switching points between the cycles or points ts' during the cycle, or both (step S106).

[0123] Based on the selection signal 146-1 inputted at the points described above, the selector 141-1 selects the drive signal 145-1 or 145-2 to supply to each of the piezoelectric elements 116a and 116b of the corresponding nozzle. The same applies to the other selectors 141-2 to 141-n. The drive signal 145-1 or 145-2 having the waveform as shown in FIG. 20A and 20B or the signal having the composite waveform is thereby supplied to the piezoelectric element 116a of each nozzle in the recording head 11 as the drive signal 21-1a to 21-na. The composite waveform is generated by switching the drive signals 145-1 and 145-2 at points ts' during the cycle. At the same time, the drive signal 145-1 or 145-2 or the signal having the composite waveform is thereby supplied to the piezoelectric element 116b of each nozzle in the recording head 11 as the drive signal 21-1b to 21-nb. The three steps described with reference to FIG. 21A to FIG. 21C are performed on the piezoelectric elements 116a and 116b for each nozzle of the recording head 11, based on the voltage waveform of the supplied drive signal. An ink droplet of size specified for each nozzle is thereby ejected.

[0124] FIG. 23 to FIG. 26 show examples of the drive signal waveforms applied to the piezoelectric elements 116a and 116b, attention being focused on a specific nozzle. In the examples the total of (12 + 1) types of ejection patterns are obtained by switching the selection between the drive signals 145-1 and 145-2 at points ts' between the cycles and points ts' during the cycle and switching between the piezoelectric elements 116a and 116b to which the drive signals are applied. The type of '+ 1' means the pattern that does not allow ink droplet ejection wherein the drive signal 145-1 (FIG. 20A) of a constant voltage is applied to both piezoelectric elements 116a and 116b in both first part τ 2 and second part τ 1. However, this pattern is not shown in FIG. 23 to FIG. 26.

[0125] Referring to FIG. 23 to FIG. 26, the ejection patterns will be described. In the tables, 'name' means the name of each ejection pattern. The piezoelectric elements 116a and 116b to which the drive signals are applied are each represented by 'a' and 'b' respectively, in the 'piezoelectric element' column. The 'drive signal waveform applied' shows the voltage waveforms of the drive signals actually applied to the piezoelectric elements 116a and 116b through selection and composition of the waveforms. '1' means that the drive signal 145-1 shown in FIG. 20A is selected. '2' means that the drive signal 145-2 shown in FIG. 20B is selected. On the waveforms shown, the dot indicates the point at which switch-

ing is actually performed. In the 'retraction step' and 'ejection step' columns, 'a' and 'b' each indicates which of the piezoelectric elements 116a and 116b allows meniscus retraction in the first step and ink droplet ejection in the third step, respectively. The 'a + b' indicates that both piezoelectric elements 116a and 116b allow retraction or ejection. The '-' means that the step is not performed.

[0126] As shown in FIG. 23, ejection patterns α 1 to α 3 each allow retraction by the piezoelectric element 116b only. Ejection pattern α 1 allows ejection by the piezoelectric element 116b as well. Ejection pattern α 2 allows ejection by the piezoelectric element 116a. Ejection pattern α 3 allows ejection by both piezoelectric elements 116a and 116b.

[0127] To be specific, in ejection pattern α 1, the drive signal 145-1 is selected both in first part τ 2 and second part τ 1 for the piezoelectric element 116a. The drive signal 145-2 is selected both in first part τ 2 and second part τ 1 for the piezoelectric element 116b. In ejection pattern α 2, the drive signal 145-1 is selected in first part τ 2 and the drive signal 145-2 is selected in second part τ 1 for the piezoelectric element 116a. The drive signal 145-2 is selected in first part τ 2 and the drive signal 145-1 is selected second part τ 1 for the piezoelectric element 116b. In ejection pattern α 3, the drive signal 145-1 is selected in first part τ 2 and the drive signal 145-2 is selected in second part τ 1 for the piezoelectric element 116a. The drive signal 145-2 is selected both in first part τ 2 and second part τ 1 for the piezoelectric element 116b. Therefore, the waveforms each applied to the piezoelectric elements 116a and 116b in ejection pattern α 1 and the waveform applied to the piezoelectric element 116b in ejection pattern α 3 are the same as the waveforms of the drive signals 145-1 and 145-2 shown in FIG. 20A and FIG. 20B, respectively. The other waveforms are newly created composite waveforms.

[0128] As shown in FIG. 24, ejection patterns β 1 to β 3 each allow retraction by the piezoelectric element 116a only. Ejection pattern β 1 allows ejection by the piezoelectric element 116b. Ejection pattern β 2 allows ejection by the piezoelectric element 116a as well. Ejection pattern β 3 allows ejection by both piezoelectric elements 116a and 116b. The details of the ejection patterns are similar to those shown in FIG. 23 and descriptions thereof are omitted.

[0129] As shown in FIG. 25, ejection patterns γ 1 to γ 3 each allow retraction by both piezoelectric elements 116a and 116b. Ejection pattern γ 1 allows ejection by the piezoelectric element 116b. Ejection pattern γ 2 allows ejection by the piezoelectric element 116a. Ejection pattern γ 3 allows ejection by both piezoelectric elements 116a and 116b. The details of the ejection patterns are similar to those shown in FIG. 23 and descriptions thereof are omitted.

[0130] As shown in FIG. 26, ejection patterns δ 1 to δ 3 each does not allow retraction but allow ejection. Ejection pattern δ 1 allows ejection by the piezoelectric element 116b. Ejection pattern δ 2 allows ejection by the

piezoelectric element 116a. Ejection pattern δ 3 allows ejection by both piezoelectric elements 116a and 116b. The details of the ejection patterns are similar to those shown in FIG. 23 and descriptions thereof are omitted.

[0131] In any of ejection patterns α 1 to α 3 shown in FIG. 23, as described above, the meniscus is retracted by applying the drive signal 145-2 to the piezoelectric element 116b in the first part τ 2 and the drive signal 145-2 is selected in the second part τ 1. However, in the ejection step of the second part τ 1, with an increase in suffix 'i' of α , the piezoelectric element to which the signal is applied changes from the element 116b only to the element 116a only, and further to both elements 116a and 116b. As described above, since the piezoelectric element 116b has a surface area smaller than the piezoelectric element 116a, the amount of change in volume of the ink chamber 114 effected by the element 116a is greater than that effected by the element 116b with an application of the same drive signal 145-2. Similarly, the amount of change in volume of the ink chamber 114 effected by both elements 116a and 116b is greater than that effected by the element 116a only. Therefore, the ejected ink droplet size increases in order of ejection patterns α 1 to α 3.

[0132] Similarly, in FIG. 24, the ejected droplet size increases from ejection patterns 1 to 3. The same applies to the group of ejection patterns γ 1 to γ 3 shown in FIG. 25 and the group of ejection patterns δ 1 to δ 3 shown in FIG. 26. In each group the droplet size increases with an increase in suffix 'i'.

[0133] For example, the ejection patterns with the same suffixes of the group of ejection patterns α 1 to α 3 (group α) and the group of ejection patterns β 1 to β 3 (group β) being compared to each other, the amount of retracting the meniscus is greater in group β since retraction is performed with the piezoelectric element 116b whose surface area is smaller in group α while retraction is performed with the piezoelectric element 116a whose surface area is greater in group β . Therefore, in this respect, a smaller droplet tends to be obtained in group β as long as the ejection patterns with the same suffixes are compared to each other. In group β , however, the meniscus shifts due to the motion of the piezoelectric element 116a that allows a greater change in volume in the specific period immediately after ejection starts on completion of the second step (the period during which the voltage changes from 0 V to reference voltage V1). Therefore, a reverse effect may result, depending on the surface area ratio between the piezoelectric elements 116a and 116b and the ratio of reference voltage V1 to ejection voltage V2 (that is, a greater droplet may be obtained in group β). The same applies to the relationship between group β shown in FIG. 24 and group γ shown in FIG. 25 and the relationship between group δ shown in FIG. 26 and the other groups. Therefore, conversely, the ejected droplet size is controllable by appropriately determining the surface area ratio between the piezoelectric elements 116a and 116b and the ratio of reference

voltage V1 to ejection voltage V2.

[0134] Attention being focused on one particular cycle, the ejection patterns of the nozzles are independent of one another. It is therefore possible to vary the sizes of droplets ejected through the nozzles from one another while synchronizing ejection performed in all the nozzles and to adjust variations among the nozzles by changing the ejection patterns in accordance with the ejection characteristics of the nozzles.

[0135] According to the embodiment described so far, the two piezoelectric elements 116a and 116b having ink drive capacities different from each other are provided for each ink chamber 114 corresponding to each nozzle. To each of the piezoelectric elements 116a and 116b, a selection of a plurality of fundamental drive signals is supplied by switching between the signals at points between the ejection cycles and points during the cycle. As a result, droplet ejection patterns far more than the fundamental waveforms are obtained. A variety of image representations is thus achieved. In other words, control for various ink droplet ejections is achieved without generating many types of waveforms at the drive waveform generator 142. As a result, a load applied to the generator 142 as well as the head controller 14 is reduced.

[0136] The invention is not limited to the foregoing embodiment but may be practiced in still other ways.

[0137] For example, in the foregoing embodiment, the one ink chamber 114 is provided for the single nozzle 118 and the two piezoelectric elements 116a and 116b corresponding to the ink chamber 114 are provided. Alternatively, as shown in FIG. 27, for example, two ink chambers 114a and 114b may be provided for the single nozzle 118 and the piezoelectric elements 116a and 116b each corresponding to the ink chambers 114a and 114b, respectively, may be provided. FIG. 27 is a top view of part of the recording head 11 wherein like numerals are assigned to the components similar to those shown in FIG. 5 and the oscillation plate 13 is omitted. In the configuration as shown, the behavior of the piezoelectric element 116a with regard to the one ink chamber 114a has less effect on the state of the other ink chamber 114b. As a result, crosstalk between the piezoelectric elements 116a and 116b is reduced and printed images of higher quality will be achieved.

[0138] Although the drive signals shown in FIG. 20A and FIG. 20B are used as the fundamental waveforms, signals having any other waveform may be applied. That is, the drive waveform generator 142 generates the one type of drive signal 145-2 as the drive signal having a specific undulation besides the constant voltage waveform (the drive signal 145-1) in the foregoing embodiment. Alternatively, two or more drive signals each having a specific undulation may be generated by appropriately determining retraction voltage V1, ejection voltage V2 and time t_2 required for the second step. These drive signals may be used for waveform selection and composition. In this case, more ejection patterns are obtained.

[0139] Although the two piezoelectric elements whose

ink drive capacities are different from each other are provided for every nozzle in the foregoing embodiment, three or more piezoelectric elements whose ink drive capacities are different from each other may be provided for every nozzle. To each piezoelectric element, the signal having a waveform selected or composed out of the two fundamental waveforms may be applied. More ejection patterns are thereby obtained.

[0140] Furthermore, three or more piezoelectric elements whose ink drive capacities are different from each other may be provided and three or more drive signals each having a specific undulation may be used as the fundamental waveforms. Selection and composition of the waveforms to be applied to the piezoelectric elements may be performed based on the fundamental waveforms. Still more ejection patterns are thereby obtained.

[0141] Although the ink drive capacities of the piezoelectric elements 116a and 116b are made different from each other in the foregoing embodiment by varying the surface areas thereof, the different capacities may be obtained by any other way. For example, the materials and thicknesses thereof may be different from each other. For example, a reduction in thicknesses increases the ink drive capacity.

[0142] Furthermore, the piezoelectric elements 116a and 116b may be made of the same material and have the same surface area and thickness so as to have the same ink drive capacity. In this case, referring to FIG. 23 to FIG. 26, ejection patterns α 1, α 2, β 1 and β 2 are equal to one another. Patterns α 3 and β 3 are equal as well. Patterns γ 1 and γ 2 are equal and patterns δ 1 and δ 2 are equal. Therefore, the number of ejection patterns is six which is fewer than twelve patterns in the foregoing embodiment (FIG. 23 to FIG. 26) but the variety of ejection patterns is still obtained, compared to the case wherein a single piezoelectric element is used. Alternatively, three or more piezoelectric elements having the same ink drive capacities may be provided.

[0143] Although the foregoing embodiment provides waveform selection and composition focusing on control of ink droplet sizes, waveform selection and composition focusing on control of droplet velocity may be performed. Furthermore, both droplet sizes and velocity may be controlled.

[0144] Although drive signal selection is switched at not only points between the ejection cycles but also points during the cycle, selection may be switched at either the former points or the latter points. However, more waveforms are obtained by switching at both points.

[0145] As thus described, the foregoing embodiments may be combined so as to provide a plurality of piezoelectric elements for each nozzle. To each piezoelectric element some of the drive signals may be selected and supplied, the signals including those for modulating an ink droplet size and those for suppressing minute droplets accompanying the ejected droplet. Control of droplet ejection through the nozzle and control of suppressing satellite droplets are performed by the drive signals. As

a result, the ejection status such as the droplet size may be changed variously. Generation of unwanted satellite droplets is suppressed as well.

[0146] Furthermore, when the piezoelectric element for generating a pressure for ejection is shifted and ejection is performed, a drive signal may be applied to the piezoelectric element for generating an auxiliary pressure, the drive signal preventing the piezoelectric element for generating an auxiliary pressure from shifting due to the pressure generated by displacement of the piezoelectric element for generating an ejection pressure. The displacement of the piezoelectric element for generating an auxiliary pressure is thereby prevented due to the displacement of the piezoelectric element for generating an ejection pressure when the ink droplet is ejected by the piezoelectric element for generating an ejection pressure. As a result, the ejection pressure thus generated is used for the droplet ejection with little loss. The ejection characteristic is thus maintained. Consequently, an intended droplet size and velocity are obtained and constant droplet ejection is steadily performed.

[0147] As previously described, the piezoelectric element for generating an auxiliary pressure may generate a pressure for suppressing minute droplets accompanying the ejected ink droplet. As a result, constant droplet ejection is steadily performed while suppressing unwanted accompanying droplets.

[0148] In addition, a several types of drive signals may be generated, including signals for modulating the droplet size and auxiliary drive signals for canceling out the effects resulting from droplet ejection performed by another nozzle. To each piezoelectric element some of the drive signals may be selected and supplied. As a result, an effect of crosstalk among the nozzles is reduced. Variations in the droplet ejection status among the nozzles are thereby reduced and high-quality print output is steadily obtained.

[0149] Obviously many modifications and variations of the present invention are possible in the light of the above teachings. It is therefore to be understood that within the scope of the appended claims the invention may be practiced otherwise than as specifically described.

Claims

1. An ink-jet printer comprising:

- a droplet outlet orifice through which an ink droplet is ejected;
- a plurality of energy generating means provided for the outlet orifice each for generating energy having the ink droplet ejected through the outlet orifice; and
- a plurality of selection means each provided for the respective energy generating means for selecting any of a plurality of drive signals for driv-

ing the energy generating means and supplying the selected signal to the respective energy generating means.

2. An ink-jet printer according to claim 1, wherein the energy generating means have ink ejection drive capacities different from one another in response to an application of a specific one of the drive signals. 5
3. An ink-jet printer according to claim 1 or 2, wherein the selection means switches the selection of the drive signal to another at a point between a cycle in which the ink droplet is ejected and the next cycle. 10
4. An ink-jet printer according to any one of the preceding claims, wherein the selection means switches the selection of the drive signal to another at any point including a point during a cycle in which the ink droplet is ejected. 15
5. A method of driving a recording head of an ink-jet printer including a droplet outlet orifice through which an ink droplet is ejected; and a plurality of energy generating means provided for the outlet orifice each for generating energy for having the ink droplet ejected through the outlet orifice; comprising the steps of: 20

selecting any of a plurality of drive signals for driving the energy generating means for each of the energy generating means and supplying the selected drive signal to the respective energy generating means. 30
6. A method according to claim 5, wherein the energy generating means have ink ejection drive capacities different from one another in response to an application of a specific one of the drive signals. 35
7. A method according to claim 5 or 6, wherein the selection of the drive signal is switched to another at a point between a cycle in which the ink droplet is ejected and the next cycle. 40
8. A method according to any one of claims 5 to 7, wherein the selection of the drive signal is switched to another at any point including a point during a cycle in which the ink droplet is ejected. 45

Patentansprüche 50

1. Tintenstrahldrucker, umfassend:

eine Tröpfchenauslassöffnung, durch die ein Tintentröpfchen ausgestoßen wird, mehrere für die Auslassöffnung bereitgestellte Energieerzeugungseinrichtungen, jede zur Erzeugung von Energie, mittels der das Tinten-

tröpfchen durch die Auslassöffnung ausgestoßen werden kann, und mehrere Auswahleinrichtungen, jede bereitgestellt für die jeweilige Energieerzeugungseinrichtung zur Auswahl irgendeines von mehreren Ansteuerungssignalen zur Ansteuerung der Energieerzeugungseinrichtungen und Zufuhr des ausgewählten Signals zur jeweiligen Energieerzeugungseinrichtung.

2. Tintenstrahldrucker nach Anspruch 1, wobei die Energieerzeugungseinrichtungen Tintenausstoßsteuerungskapazitäten aufweisen, die sich voneinander unterscheiden in Abhängigkeit von einer Anwendung eines Spezifischen der Ansteuerungssignale.
3. Tintenstrahldrucker nach Anspruch 1 oder 2, wobei die Auswahleinrichtung die Auswahl des Ansteuerungssignals an einem Punkt zwischen einem Zyklus, in welchem das Tintentröpfchen ausgestoßen wird, und dem nächsten Zyklus zu einer anderen schaltet.
4. Tintenstrahldrucker nach einem der vorhergehenden Ansprüche, wobei die Auswahleinrichtung die Auswahl des Ansteuerungssignals an irgendeinem Punkt einschließlich eines Punkts während eines Zyklus, in welchem das Tintentröpfchen ausgestoßen wird, zu einer anderen schaltet.
5. Verfahren zur Ansteuerung eines Aufzeichnungskopfs eines Tintenstrahldruckers, mit einer Tröpfchenauslassöffnung, durch die ein Tintentröpfchen ausgestoßen wird, und mehreren für die Auslassöffnung bereitgestellten Energieerzeugungseinrichtungen, jede zur Erzeugung von Energie, mittels der das Tintentröpfchen durch die Auslassöffnung ausgestoßen werden kann, umfassend die Schritte:

Auswählen irgendeines von mehreren Ansteuerungssignalen zur Ansteuerung der Energieerzeugungseinrichtungen für jede der Energieerzeugungseinrichtungen und Zuführen des ausgewählten Ansteuerungssignals zur jeweiligen Energieerzeugungseinrichtung.
6. Verfahren nach Anspruch 5, wobei die Energieerzeugungseinrichtungen Tintenausstoßsteuerungskapazitäten aufweisen, die sich voneinander unterscheiden in Abhängigkeit von einer Anwendung eines Spezifischen der Ansteuerungssignale.
7. Verfahren nach Anspruch 5 oder 6, wobei die Auswahl des Ansteuerungssignals an einem Punkt zwischen einem Zyklus, in welchem das Tintentröpfchen ausgestoßen wird, und dem nächsten Zyklus

auf eine andere geschaltet wird.

8. Verfahren nach einem der Ansprüche 5 bis 7, wobei die Auswahl des Ansteuerungssignals an irgendeinem Punkt einschließlich eines Punkts während eines Zyklus, in welchem das Tintentröpfchen ausgestoßen wird, auf eine andere geschaltet wird.

Revendications

1. Imprimante à jet d'encre comprenant :

un orifice de sortie de gouttelette à travers lequel est éjectée une gouttelette d'encre ;
une pluralité de moyens générateurs d'énergie prévus pour l'orifice de sortie, destinés chacun à générer de l'énergie pour éjecter la gouttelette d'encre à travers l'orifice de sortie ; et
une pluralité de moyens de sélection chacun étant prévu pour que les moyens générateurs d'énergie respectifs sélectionnent un signal quelconque d'une pluralité de signaux de commande pour commander les moyens générateurs d'énergie et délivrer le signal sélectionné au moyen générateur d'énergie respectif.

2. Imprimante à jet d'encre selon la revendication 1, dans laquelle les moyens générateurs d'énergie ont des capacités de commande d'éjection d'encre différentes les uns des autres en réponse à l'application d'un signal spécifique des signaux de commande.

3. Imprimante à jet d'encre selon la revendication 1 ou 2, dans laquelle les moyens de sélection commutent la sélection du signal de commande à un autre signal à un moment compris entre un cycle dans lequel la gouttelette d'encre est éjectée et le cycle suivant.

4. Imprimante à jet d'encre selon l'une quelconque des revendications précédentes, dans laquelle le moyen de sélection commute la sélection du signal de commande à un autre signal à un moment quelconque incluant un moment durant un cycle au cours duquel la gouttelette d'encre est éjectée.

5. Procédé de commande d'une tête d'enregistrement d'une imprimante à jet d'encre incluant un orifice de sortie de gouttelette à travers lequel est éjectée une gouttelette d'encre ; et une pluralité de moyens générateurs d'énergie prévus pour l'orifice de sortie, destinés chacun à générer de l'énergie pour que la gouttelette d'encre soit éjectée à travers l'orifice de sortie ; comprenant les étapes consistant à :

sélectionner un signal quelconque d'une pluralité de signaux de commande pour commander les moyens générateurs d'énergie pour chacun

des moyens générateurs d'énergie respectif et délivrer le signal de commande sélectionné au moyen générateur d'énergie respectif.

6. Procédé selon la revendication 5, dans lequel les moyens générateurs d'énergie ont des capacités de commande d'éjection d'encre différentes les uns des autres en réponse à l'application d'un signal spécifique des signaux de commande.

7. Procédé selon la revendication 5 ou 6, dans lequel la sélection du signal de commande est commutée à un autre signal à un moment compris entre un cycle dans lequel la gouttelette d'encre est éjectée et le cycle suivant.

8. Procédé selon l'une quelconque des revendications 5 à 7, dans lequel la sélection du signal de commande est commutée à un autre signal à un moment quelconque incluant un moment durant un cycle au cours duquel la gouttelette d'encre est éjectée.

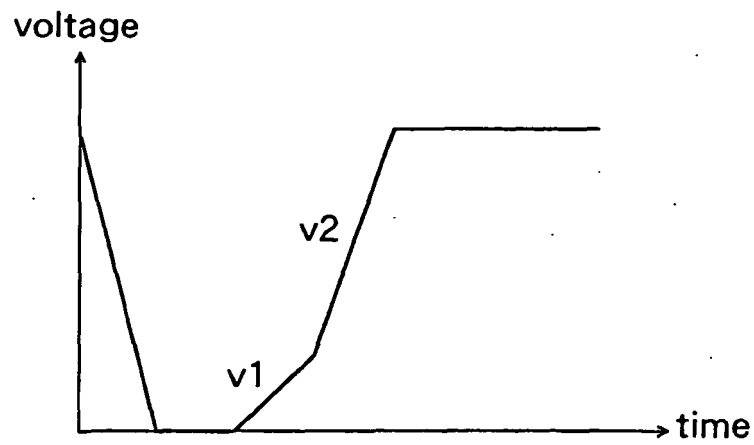


FIG.1
RELATED ART

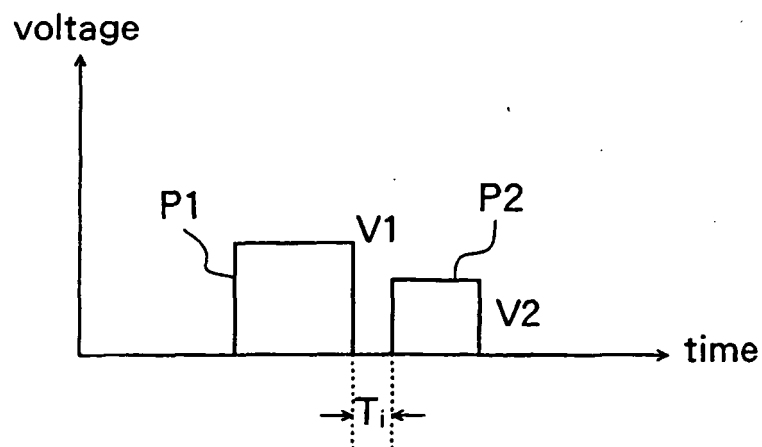


FIG.2
RELATED ART

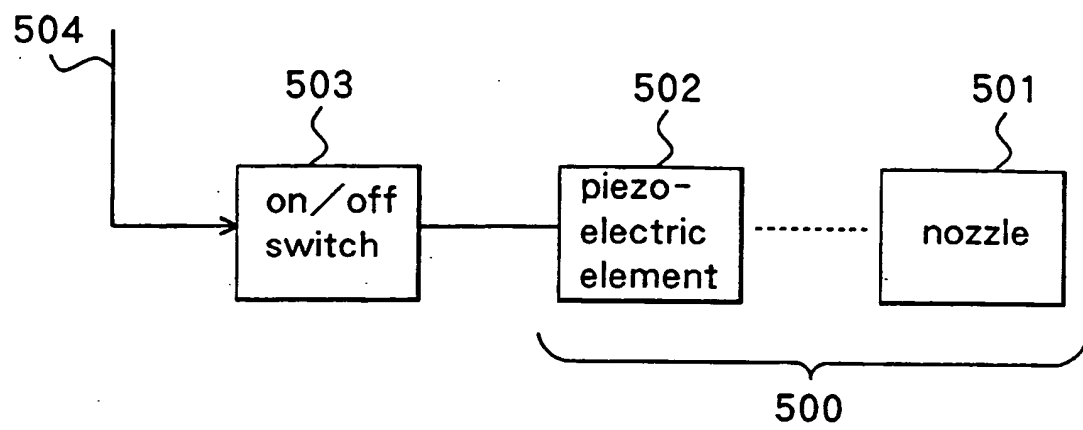


FIG.3
RELATED ART

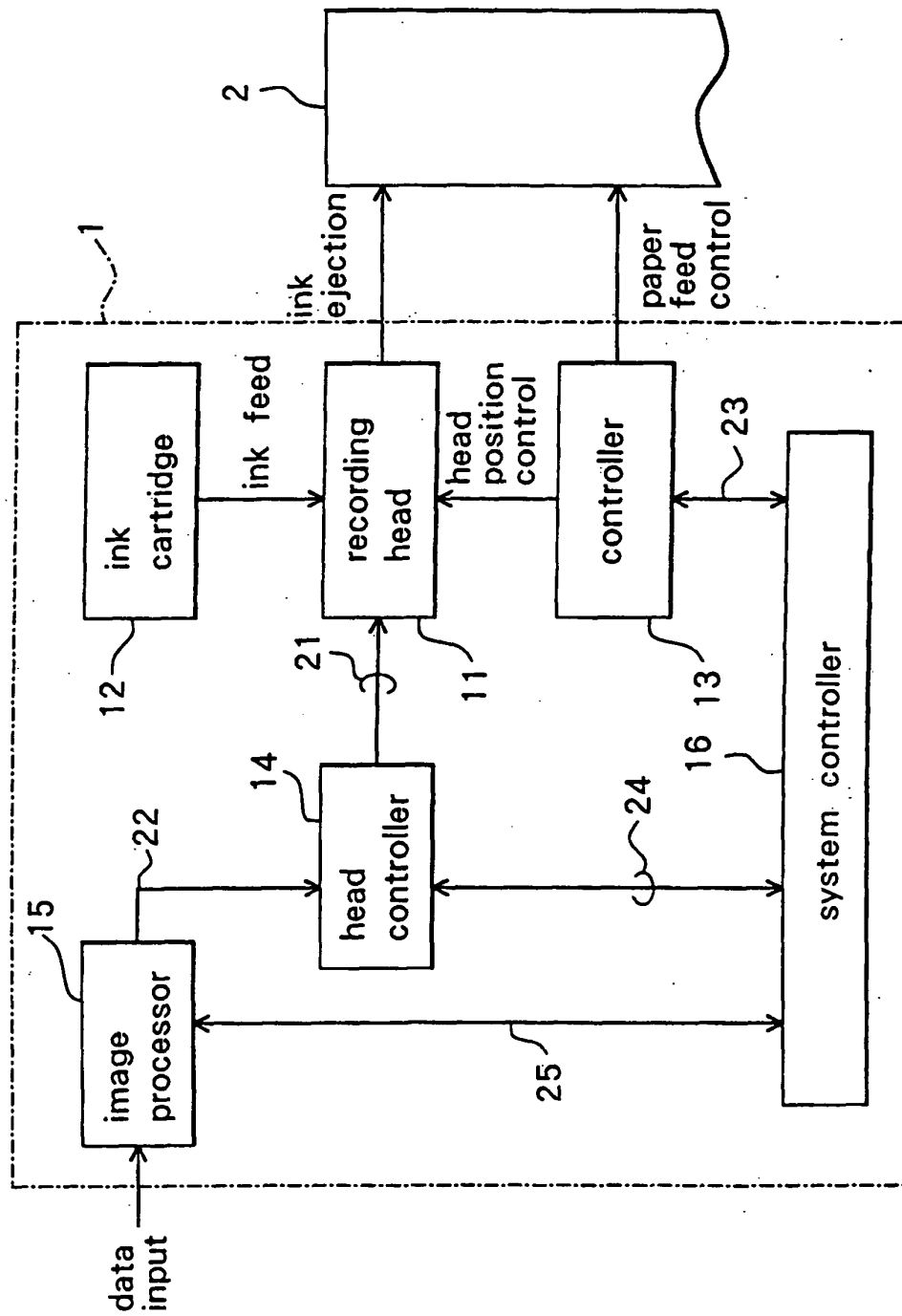


FIG.4

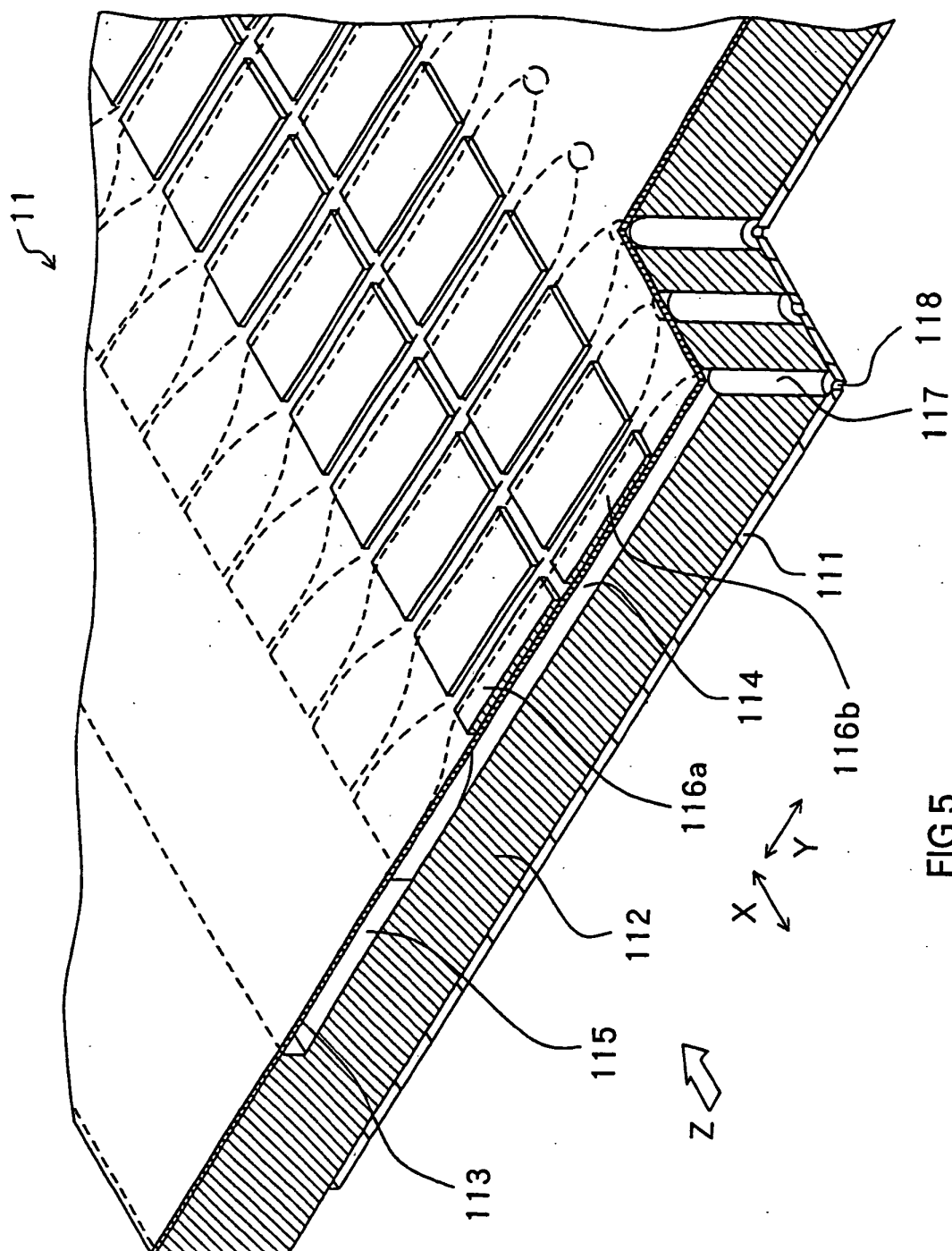


FIG. 5

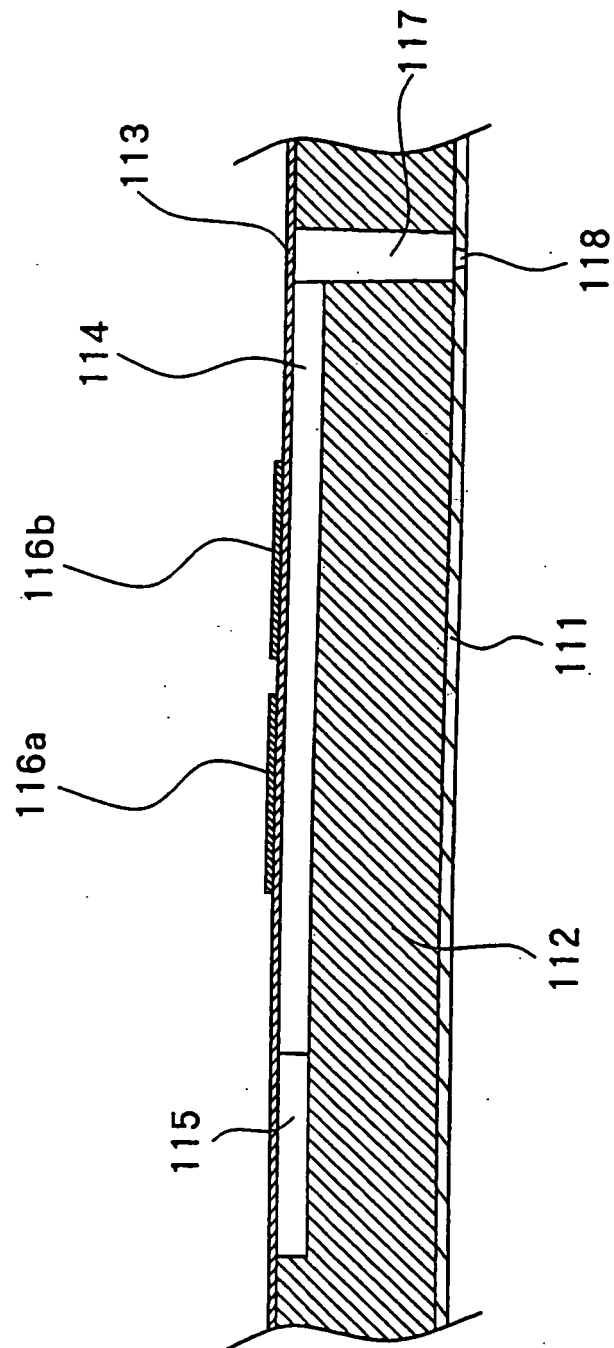


FIG.6

FIG.7A
drive
signal
21a

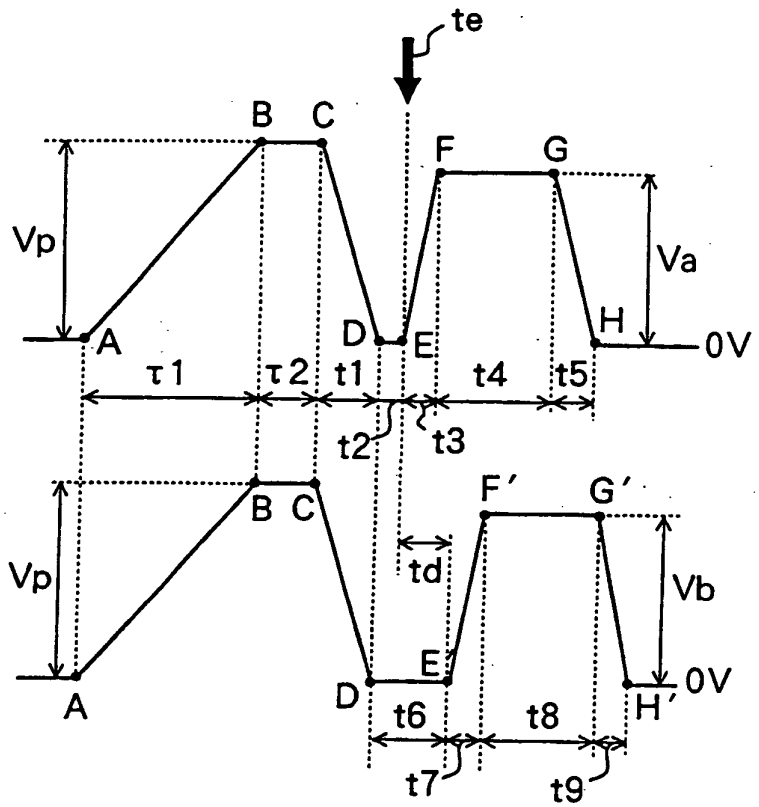
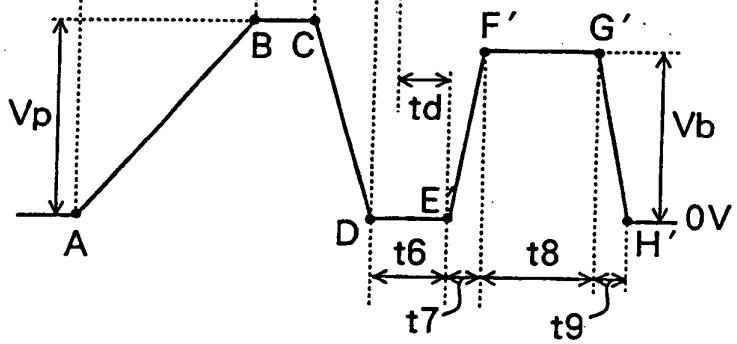


FIG.7B
drive
signal
21b



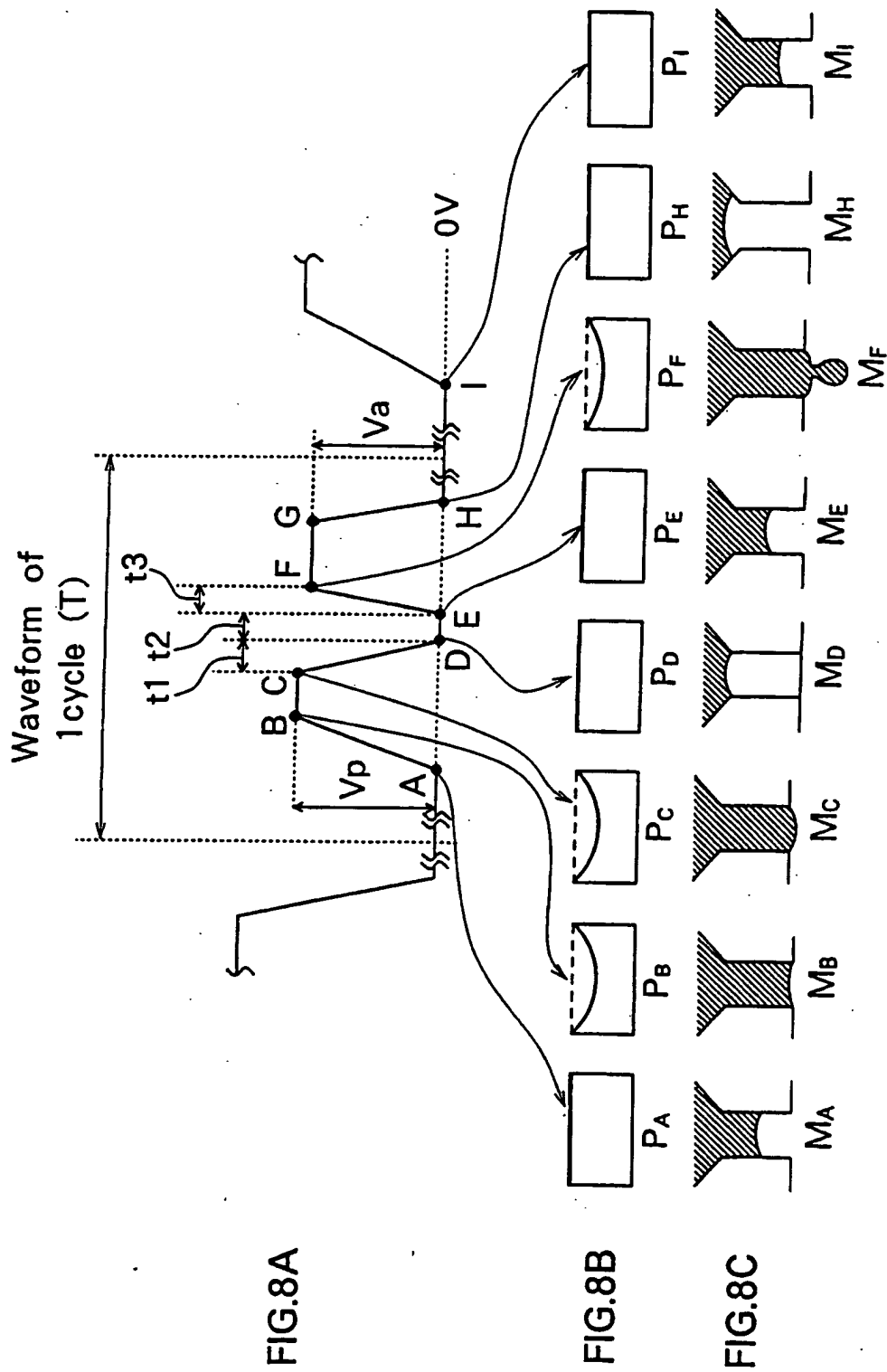


FIG.9A

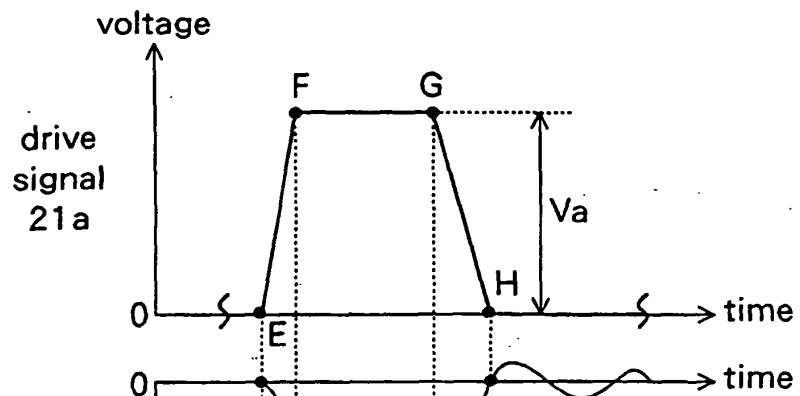


FIG.9B

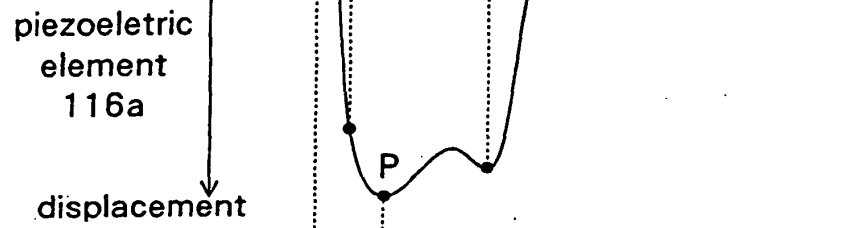


FIG.9C

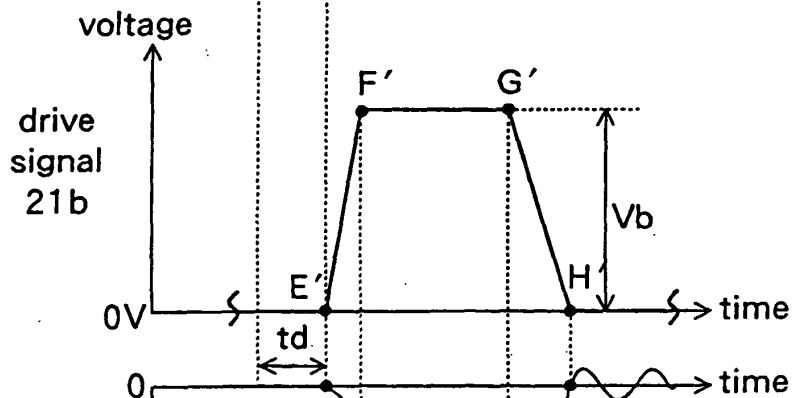
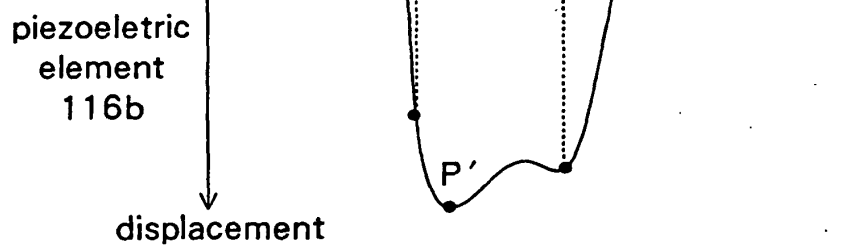


FIG.9D



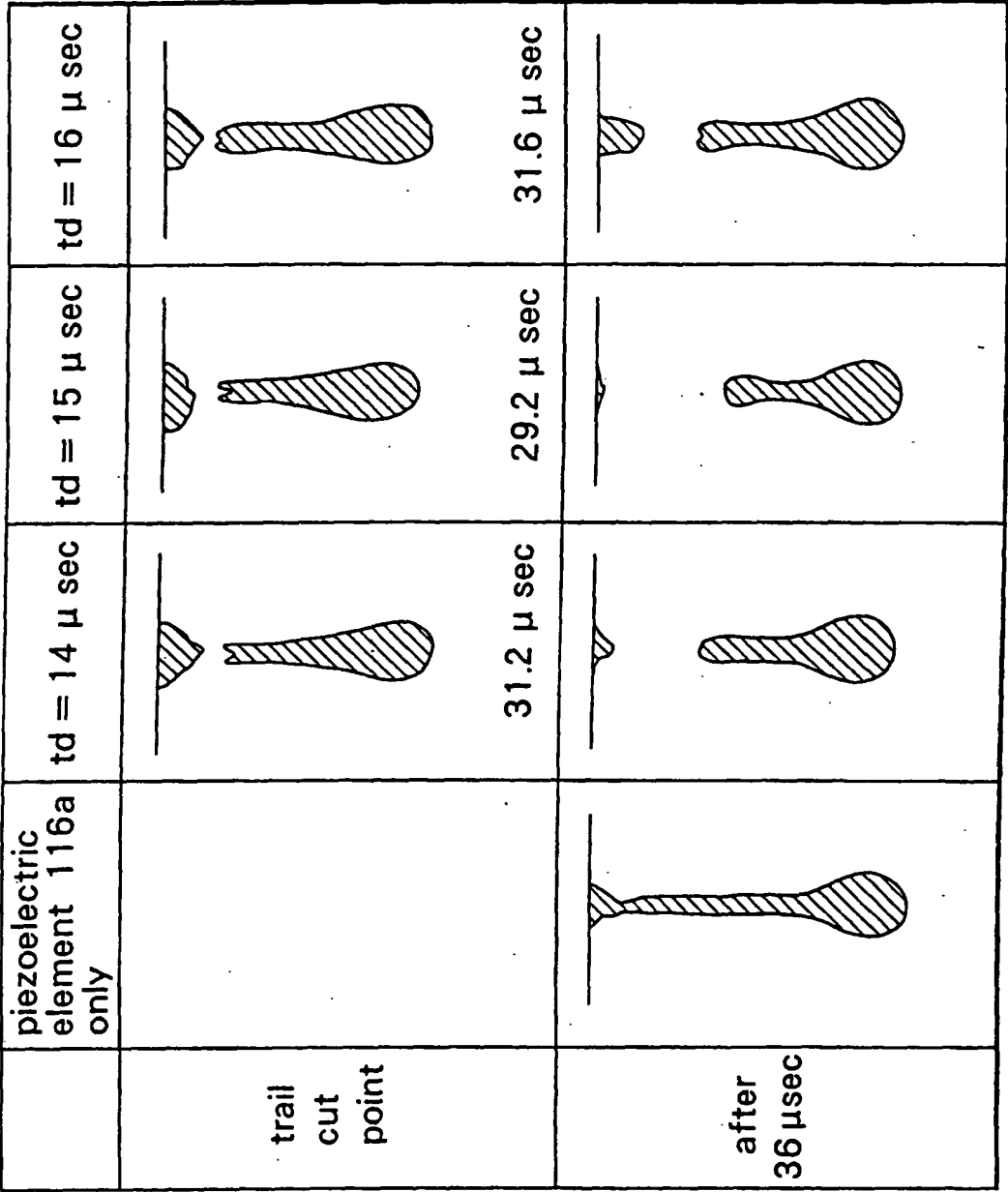


FIG.10A

FIG.10B

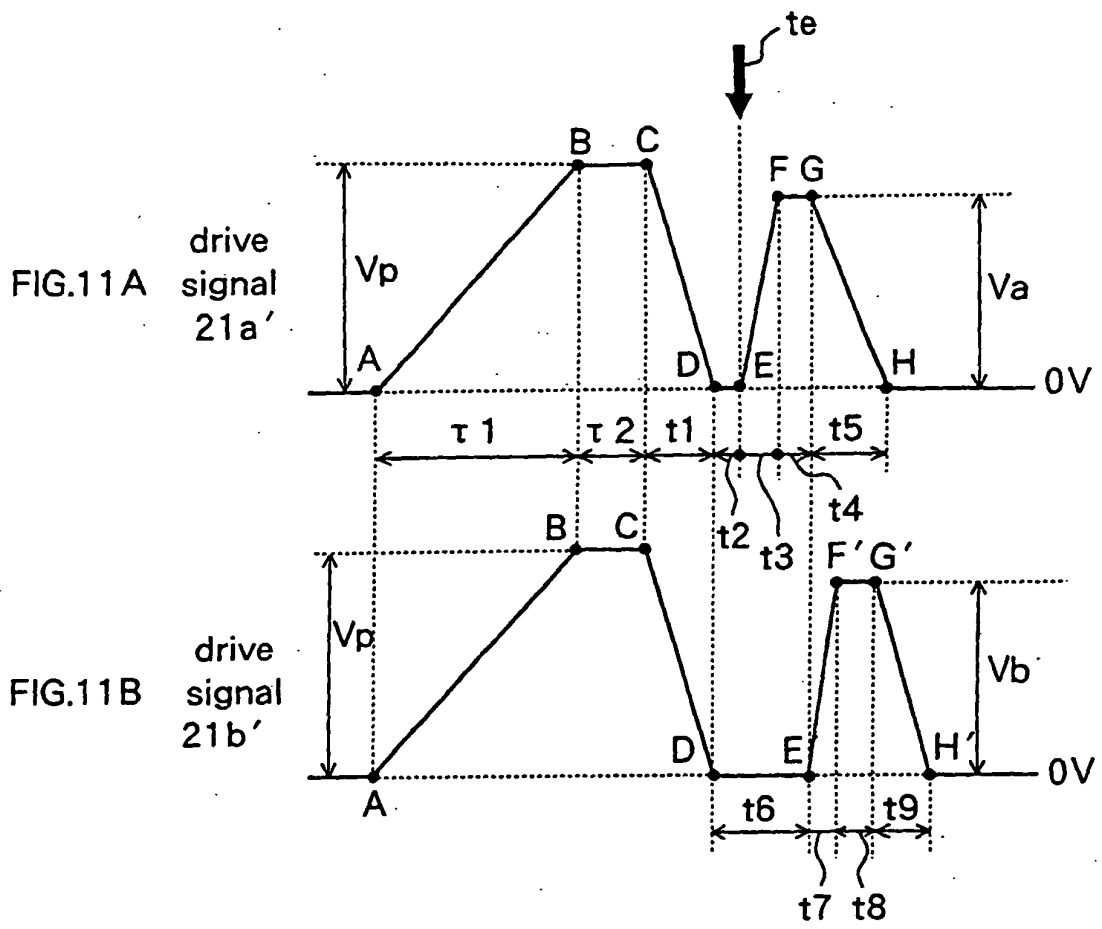


FIG.12A

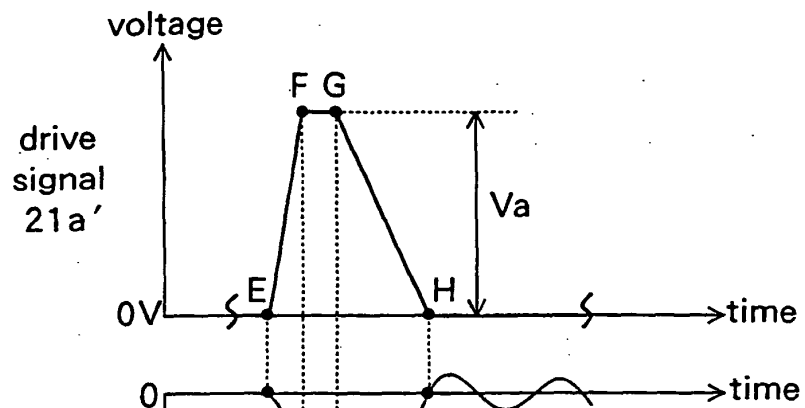


FIG.12B

piezoelectric
element
116a

displacement

FIG.12C

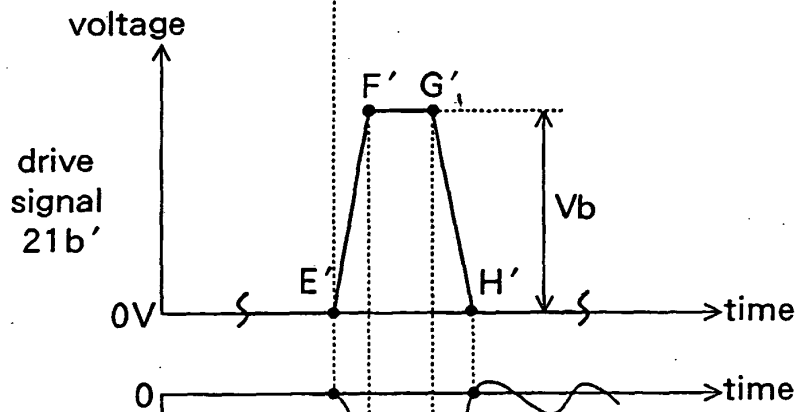


FIG.12D

piezoelectric
element
116b

displacement

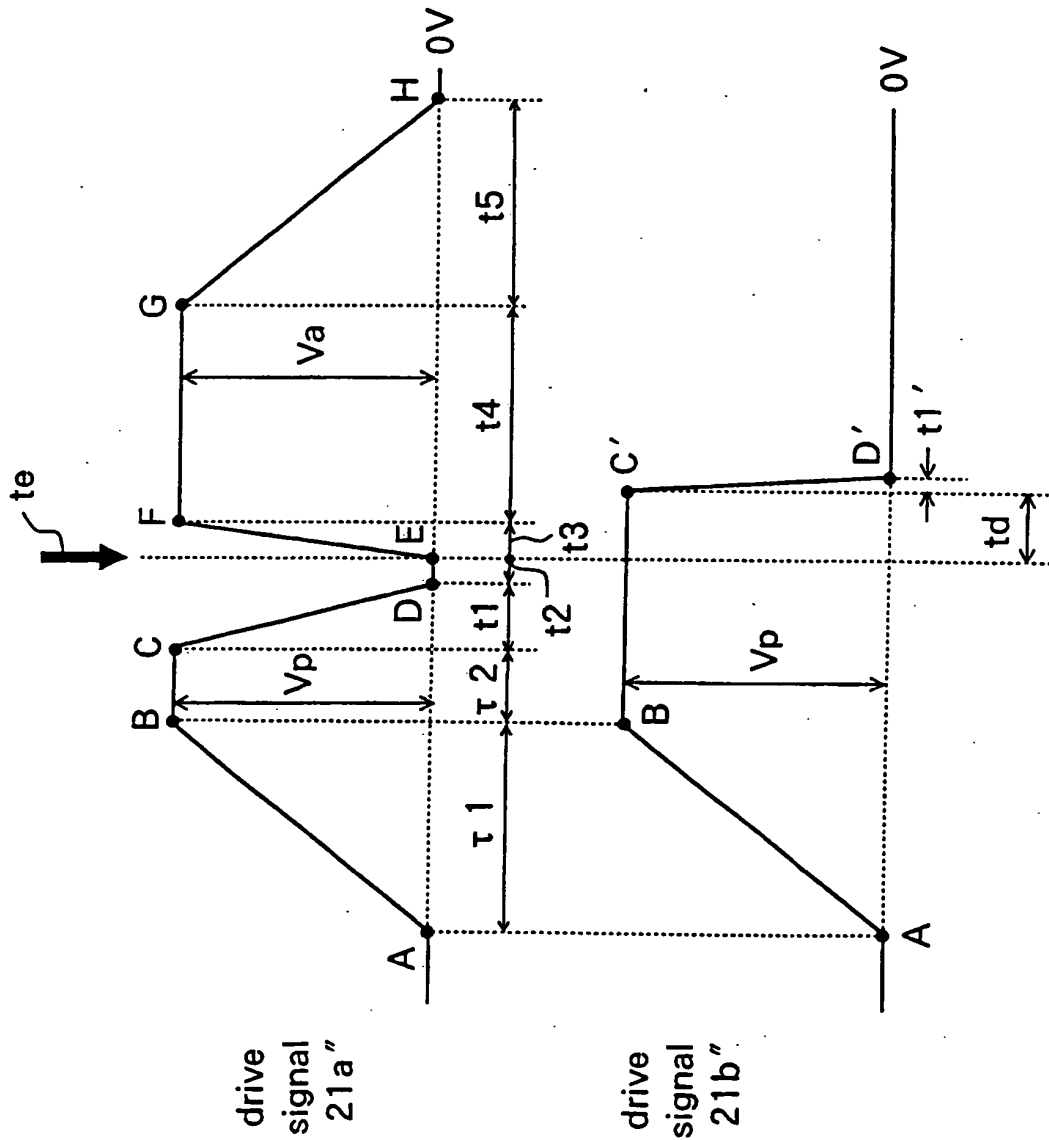


FIG.13A

FIG.13B

FIG.14A

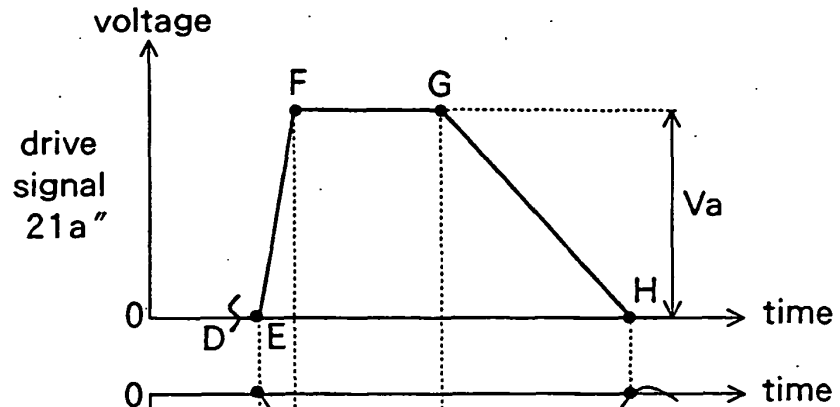


FIG.14B

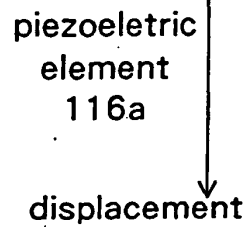


FIG.14C

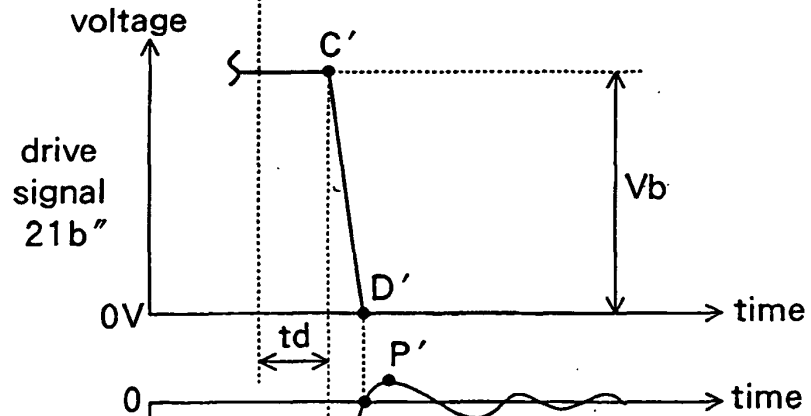
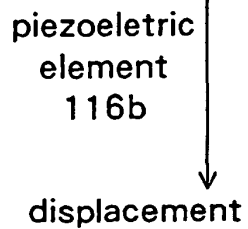


FIG.14D



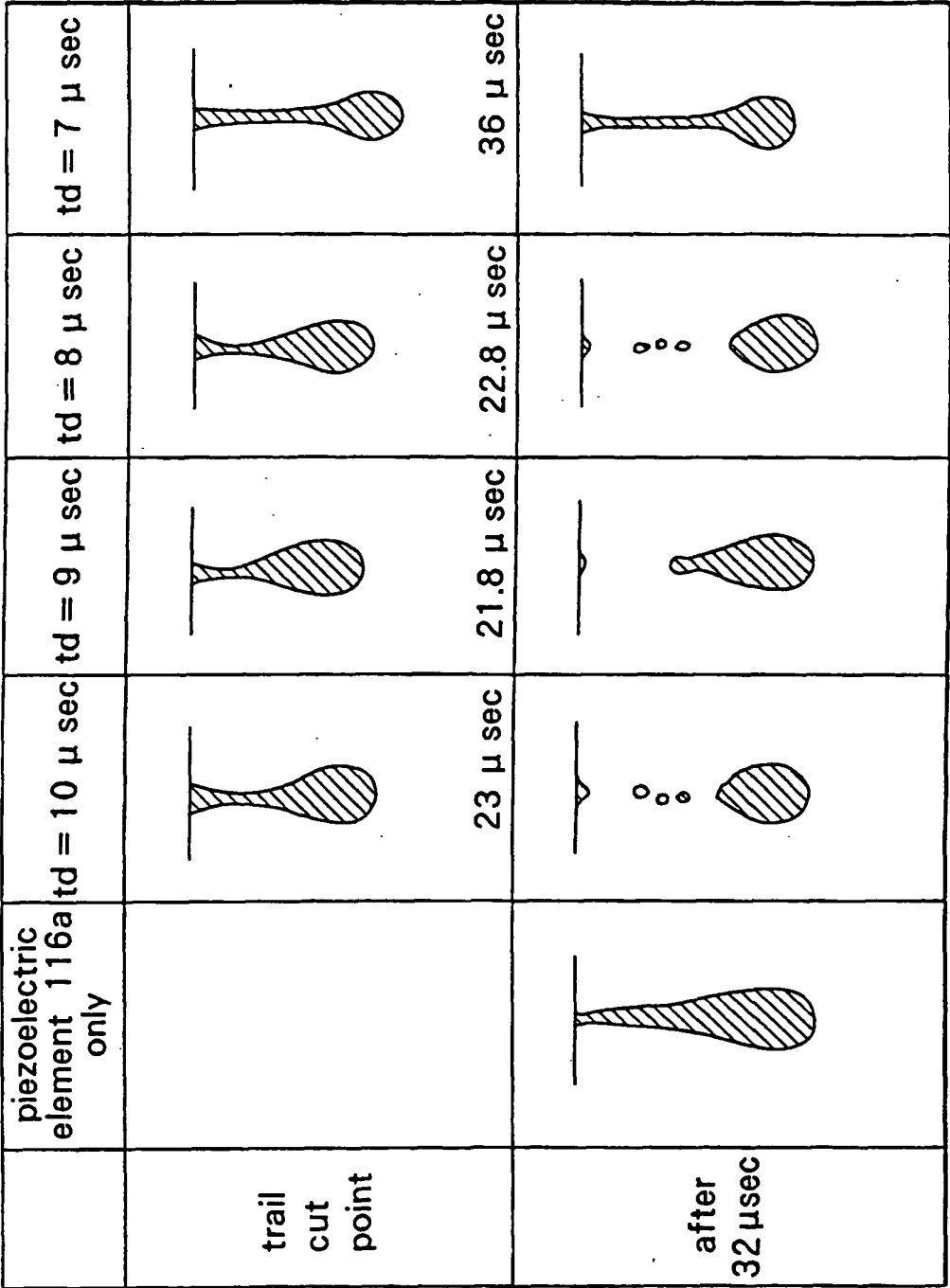


FIG.15A

FIG.15B

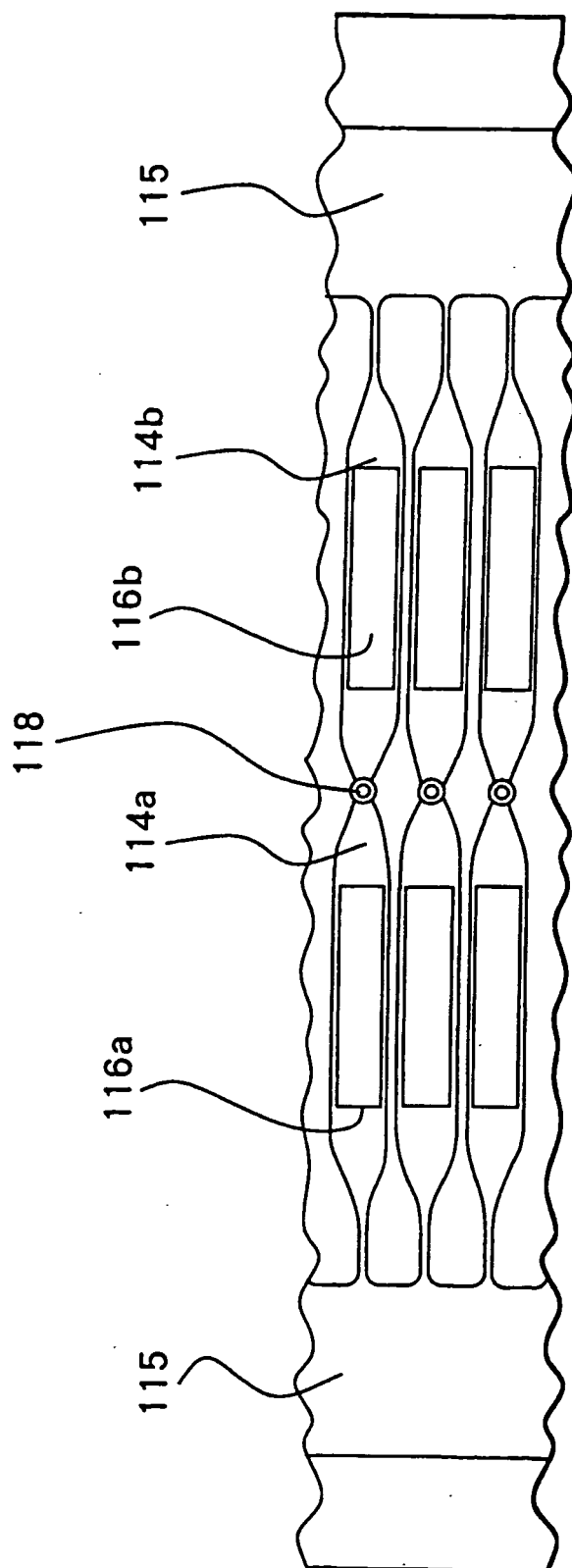


FIG.16

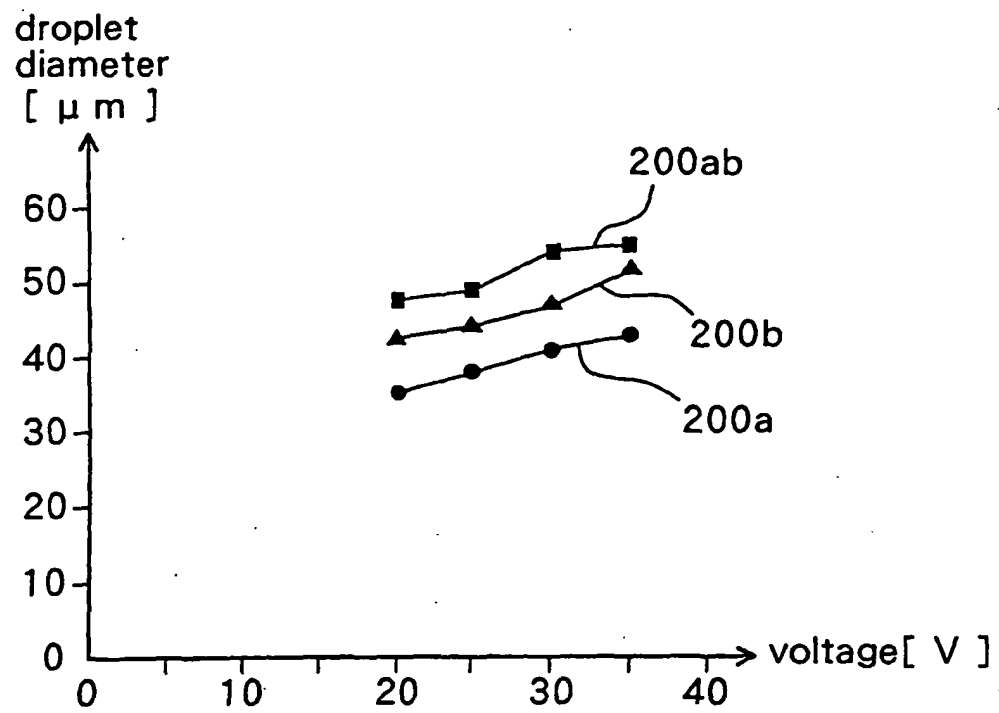


FIG.17

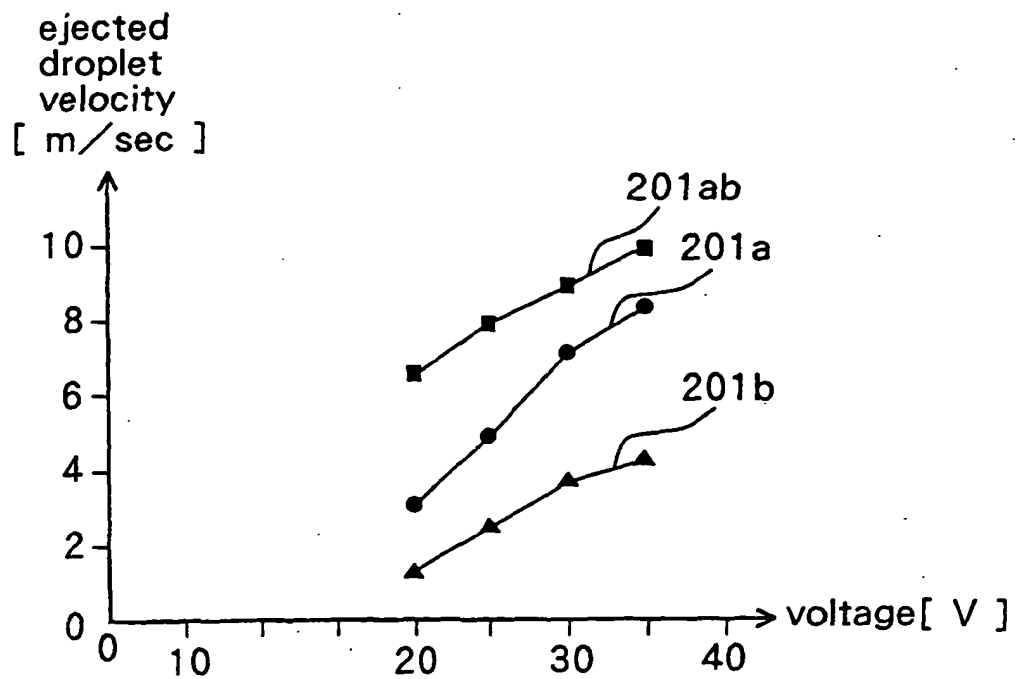


FIG.18

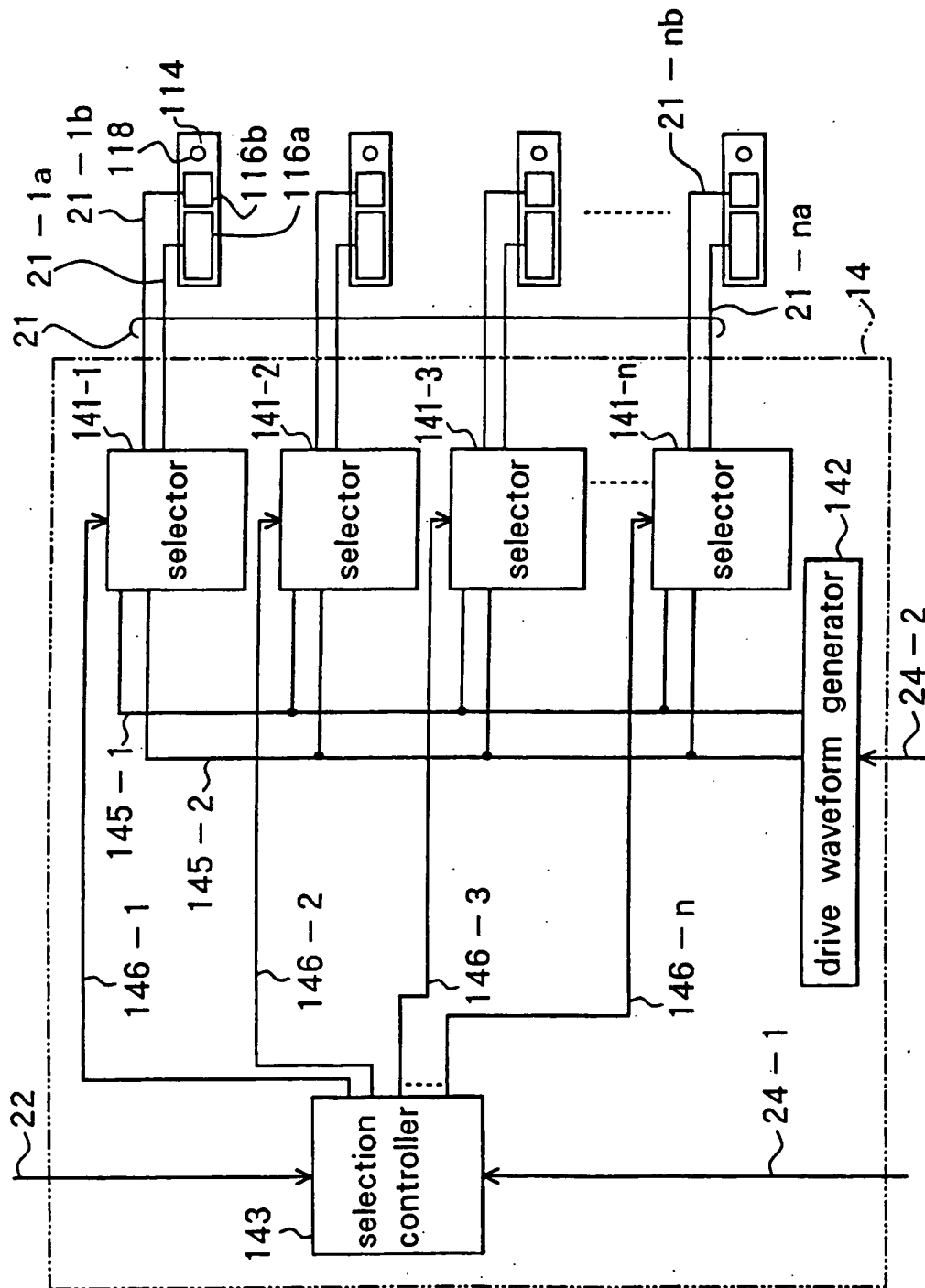
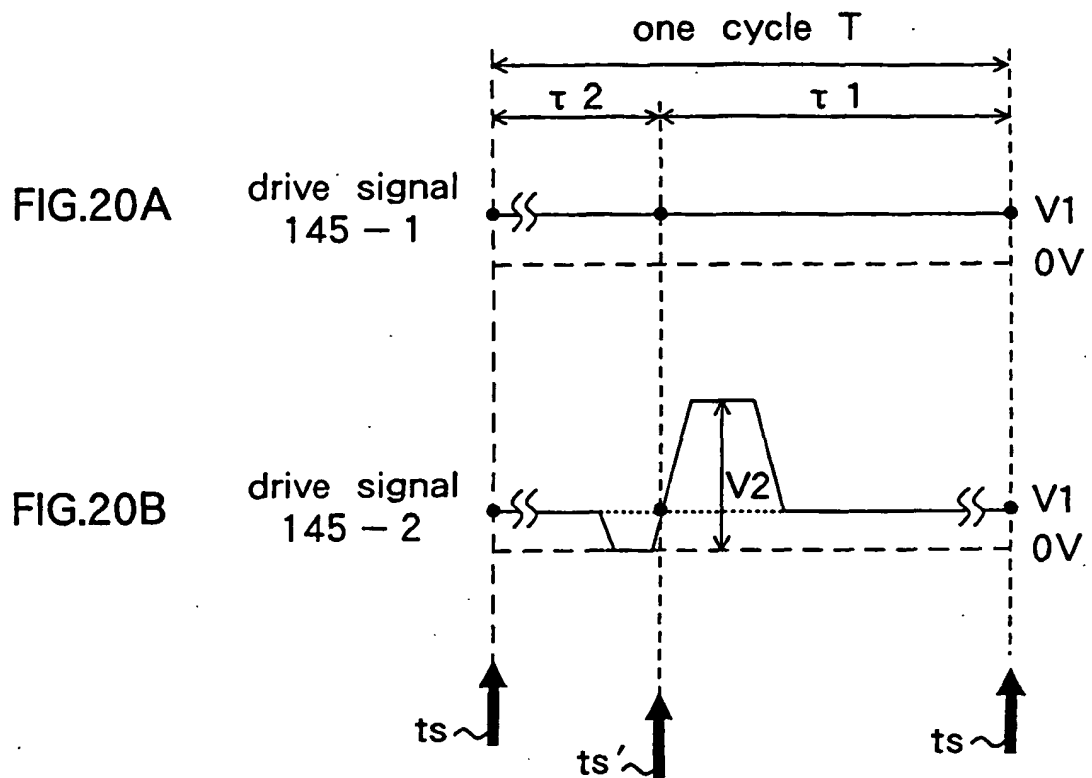
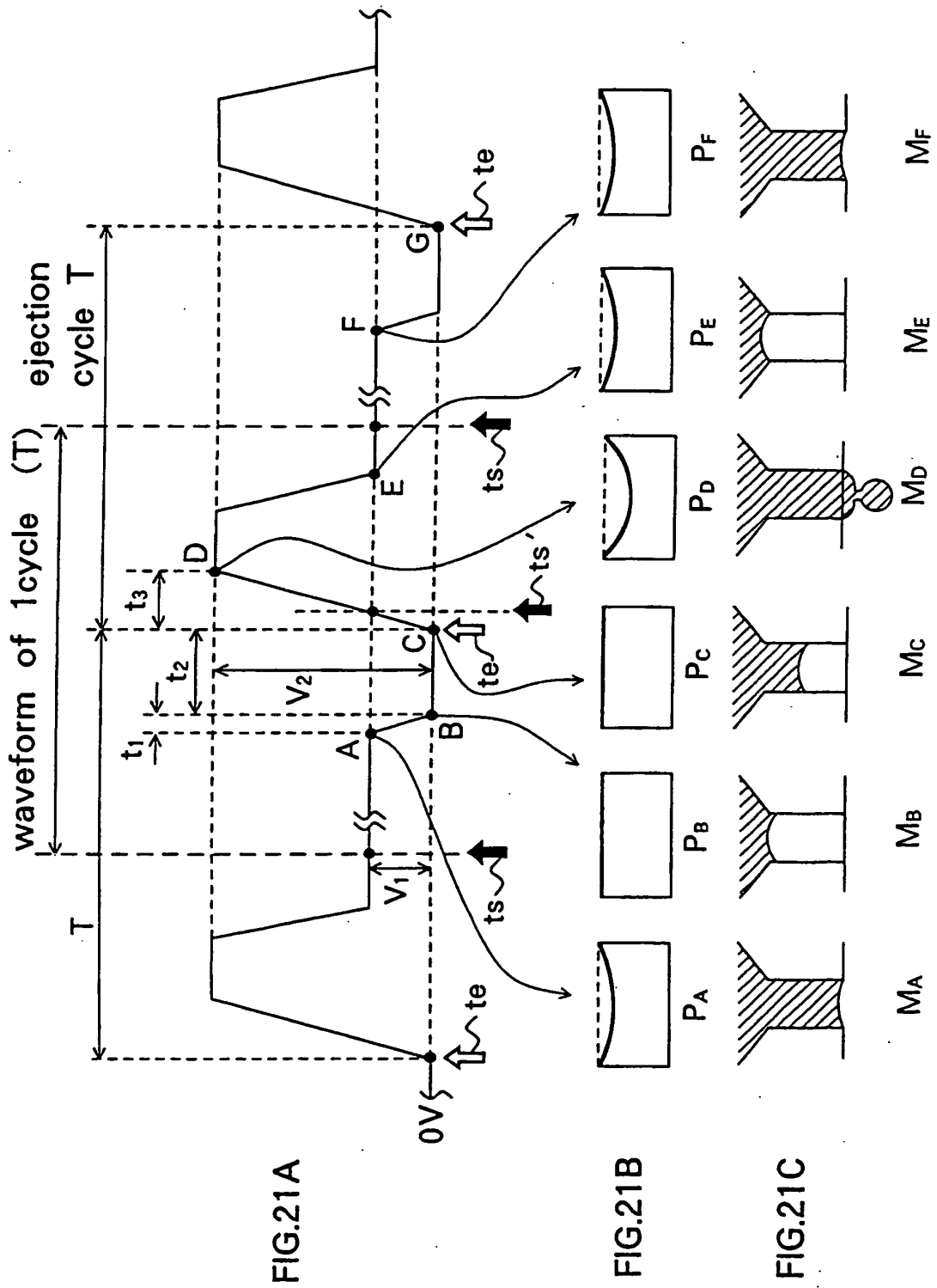


FIG.19





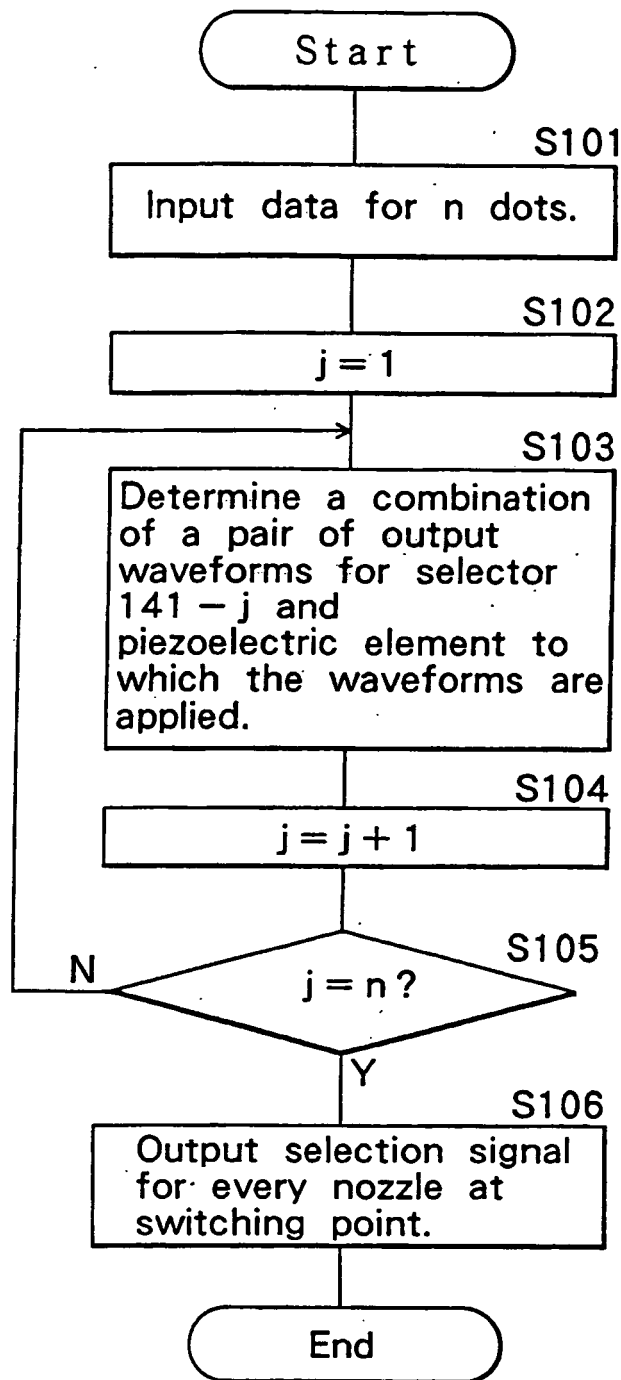


FIG.22

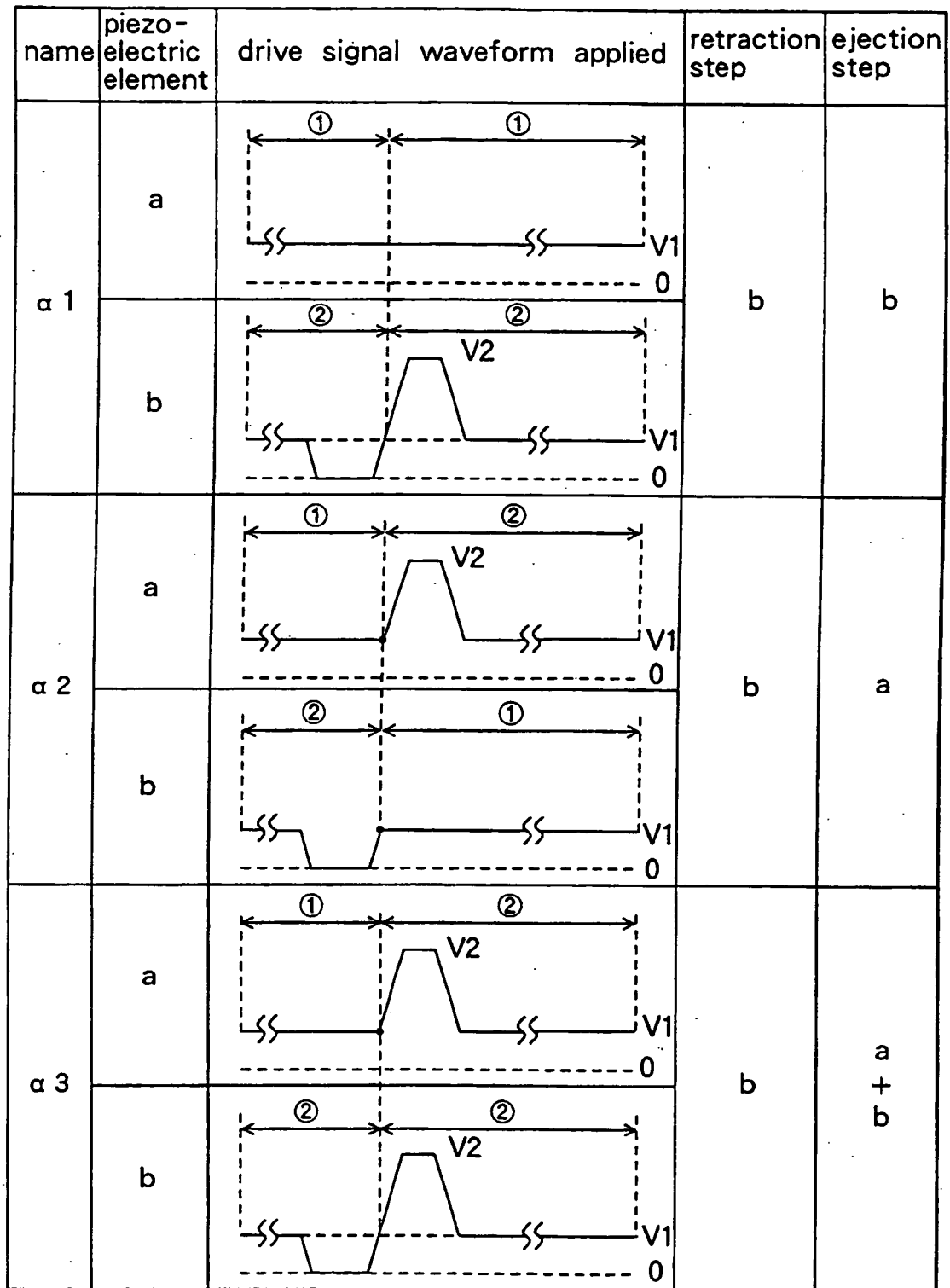


FIG.23

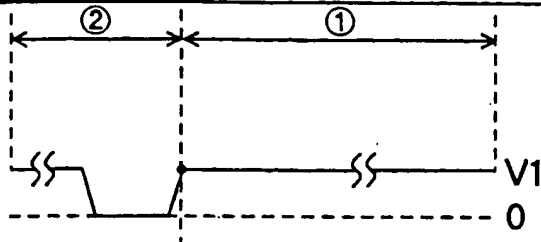
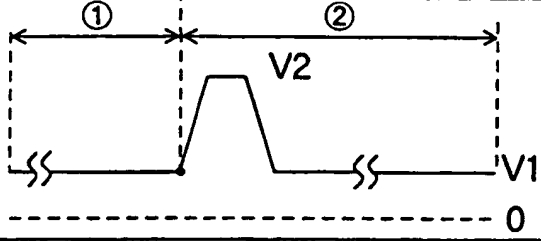
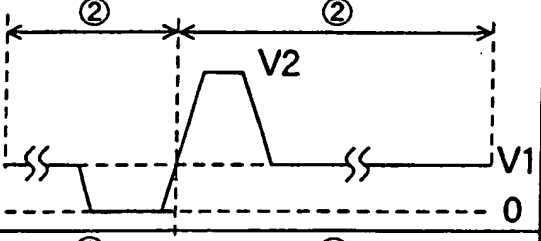
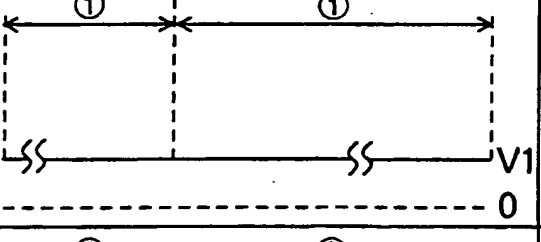
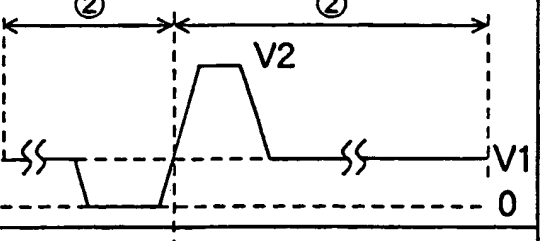
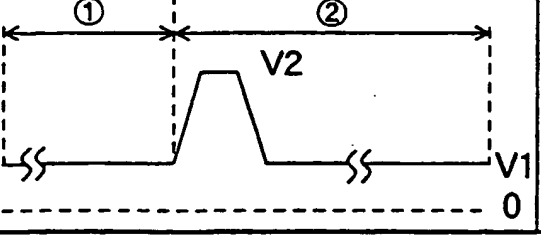
name	piezo-electric element	drive signal waveform applied	retraction step	ejection step
$\beta 1$	a		a	b
	b			
$\beta 2$	a		a	a
	b			
$\beta 3$	a		a	a + b
	b			

FIG.24

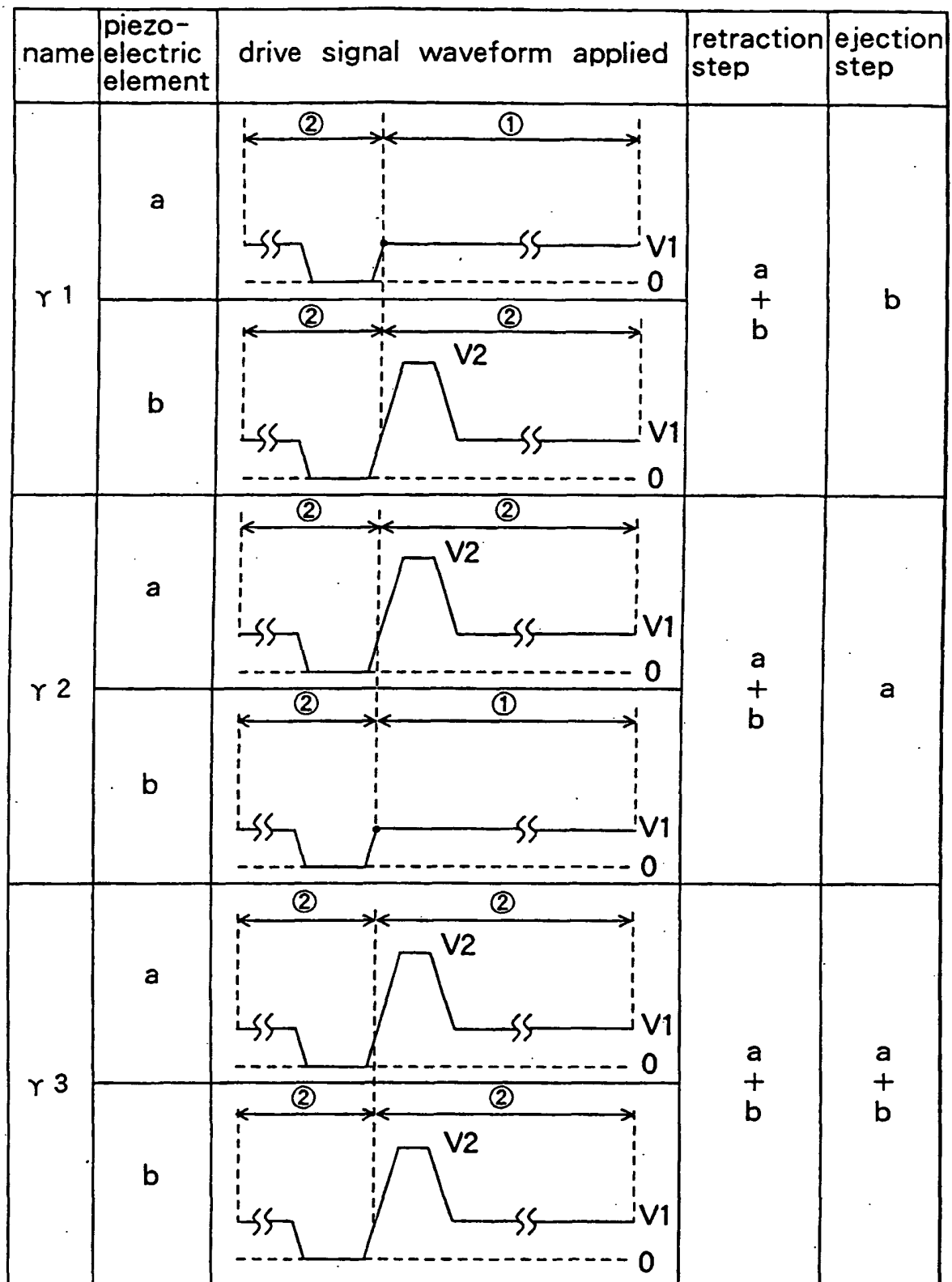


FIG.25

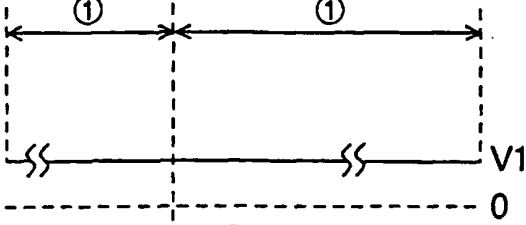
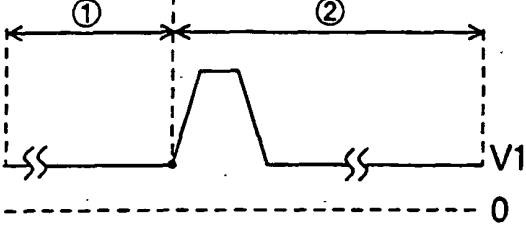
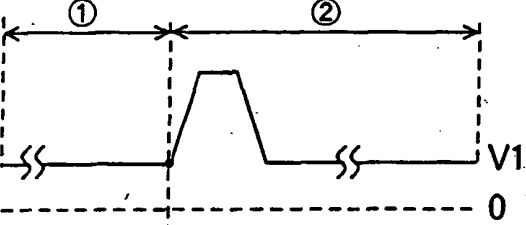
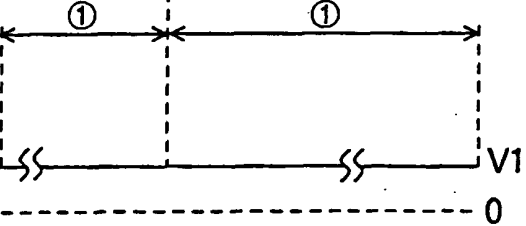
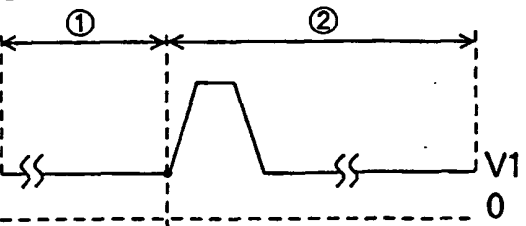
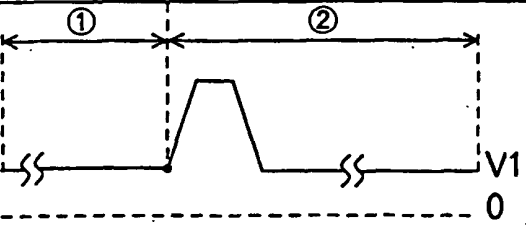
name	piezo-electric element	drive signal waveform applied	retraction step	ejection step
$\delta 1$	a		-	b
	b			
$\delta 2$	a		-	a
	b			
$\delta 3$	a		-	a + b
	b			

FIG.26

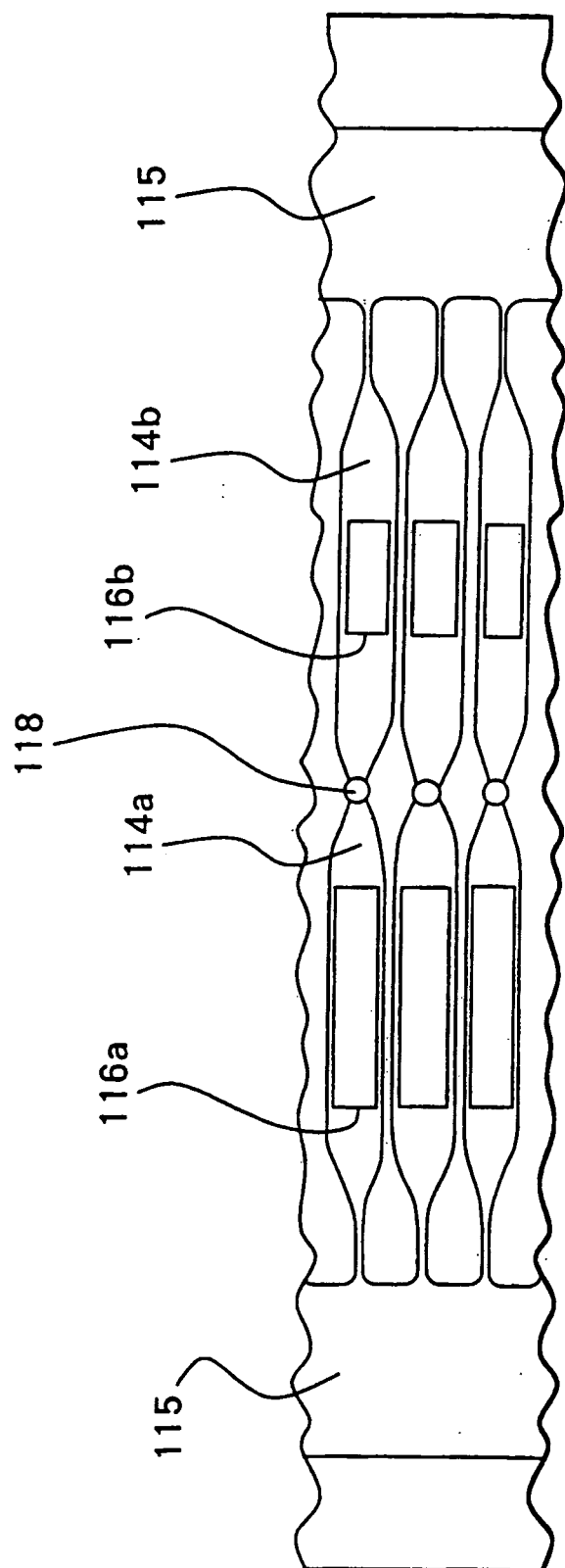


FIG. 27

REFERENCES CITED IN THE DESCRIPTION

This list of references cited by the applicant is for the reader's convenience only. It does not form part of the European patent document. Even though great care has been taken in compiling the references, errors or omissions cannot be excluded and the EPO disclaims all liability in this regard.

Patent documents cited in the description

- JP 7776087 A [0004] [0007]
- JP 59133067 A [0005] [0008]
- JP 51459311976 A [0006] [0009]