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(54) **Workpiece support**

Werkstückträger

Support de pièce à travailler

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(73) Proprietor: **Surface Generation Limited**
Peterborough, PE3 8YF (GB)

(72) Inventor: **Halford, Ben John**
Rutland,
Leicestershire, LE15 8ES (GB)

(74) Representative: **Chapple, Colin Richard et al**
Marks & Clerk
144 New Walk
Leicester LE1 7JA (GB)

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Description

[0001] The present invention relates to a tool, according to the preamble of claim 1 and to a method of tooling according to the preamble of claim 11, as for example known from GB-A-868162, and more particularly to a reconfigurable modular tool.

[0002] The manufacture of a tool, or pattern, has conventionally involved machining from a billet of material, an additive process such as casting from a mould, sculpting or fettling, or fabrication, for example from sheet metal. For large scale tools, typically required in the aerospace and automotive industries, the length of time in preparing tools by such methods is slow, and is prohibitively expensive. This is due in part to the large size of the billets of material required, which must be committed to the tools in their manufacture, and which may have to be ordered months in advance of their supply.

[0003] Furthermore, the amount of skilled labour time and material required in producing a tool conventionally has made it uneconomical to produce a tool for limited volume production, for example in product development, limited batch production and mass customisation.

[0004] In order to overcome these problems, reconfigurable modular tools have been developed, typified by that disclosed in US Patent No. 5846464. In the tool disclosed in this patent, an array of vertically adjustable pins are mounted on a drive base, such that the height of each pin above the base can be individually set. A flexible surface, or face sheet, is attached to flexible supports, which are mounted at the ends of the pins. The surface contour of the face sheet can therefore be set to a desired contour by adjusting the individual heights of the pins. The adjustments are controlled automatically through a computer, which is pre-programmed with the desired contour. When the tool is in use, the face sheet surface acts either as a primary tooling surface, or as a secondary tooling surface for producing a pattern or mould, for example, for casting.

[0005] Reconfigurable tools of the kind described are suitable for some applications, but for other applications do not have sufficient robustness and/or definition in the tooling surface. The pins which support the flexible face sheet are spaced apart, and do not lie in the plane of the desired surface contour. Therefore the face sheet surface is only a point to point approximation of the desired surface contour. The resolution of the surface is dependent on the density, number and size of pins in the tool array, but as the density of the pins increases, and their size reduces, it becomes increasingly difficult to adjust the positions of the pins.

[0006] The combined strength of the pins is also much less than the strength of a solid tool, and therefore the tool is not strong enough for the majority of tooling operations. Furthermore, the aspect ratio, that is, the range of depth in the tooling surface in comparison to its width, is limited by the amount the face sheet can deform.

[0007] According to the present invention there is provided a tool comprising a plurality of elements arranged

in an array, the elements of the array being movable between a closed position in which the elements contact one another and are secured in position, and an open position in which the elements of the array are spaced apart and are capable of vertical movement relative to one another, and drive means for opening and closing the array.

[0008] The elements are preferably machinable to an exact surface contour, for example by milling, routing or laser ablation. Consequently, the elements may be re-used a number of times, the elements being machined with a new surface contour as desired for a particular tool. The whole length of the elements may be machinable and removable, or the elements may be constructed from an upper portion, and a lower portion, the upper portion being removable and machinable.

[0009] It is a further advantage of the invention that when the face of the tool is machined, the tool face is not a point to point approximation of the desired surface contour, but is exact. Furthermore, machining of the elements enables larger elements to be utilised for a given size of tool which are more easily vertically positioned, laterally moved and secured within the array. It is a further advantage of the invention that the number of pins can also be reduced.

[0010] Preferably a drive means or further drive means provides vertical drive to each of the elements. The further drive means may comprise a separate drive means for each element, a moveable drive means which drives each of the elements in turn, or a set of drive means, each driving one or more elements.

[0011] Alternatively, the elements may be set in a raised position and each element allowed to fall under gravity to a desired position, where the element is braked and secured.

[0012] Preferably the elements of the array tessellate to produce a continuous tooling surface. In a further alternative arrangement, the elements may not fully tessellate, but may be arranged with ducts between them for the application of a negative pressure to the tool surface for use of the tool in vacuum forming, and the application of a positive pressure to the tool surface for cooling the tool and/or for ejecting a product from the tool surface. Otherwise, the elements may be provided with through holes or channels on their surface for the application of a negative or positive pressure to the tool surface.

[0013] It is preferable that the cross-section of each element is substantially square with a pointed tip formed at a first apex of the square and a correspondingly shaped recess formed at the opposite vertex of the square. Alternatively, the cross-section of the elements may be square, rectangular or of any tessellating cross section.

[0014] The elements may be all of the same size. Alternatively, the elements may be of different sizes depending on the changing contour of the tooling surface, for example, a greater element density of smaller ele-

ments is preferable in an array having large changes in surface contour in order to reduce the machining required of the elements.

[0015] The elements of an array may also be of varying size depending on the product being produced by the tool, for example, in high detail areas of a product, a greater element density of smaller elements is required in the array.

[0016] The elements can be made from a wide range of materials, for example plastics, ceramics, metals, wood, composites and alloys, and the choice of material depends on the environment of application of the tool. The elements within an array may be made from the same or different materials. The choice of material can be limited by the requirement, if any, that the tooling surface be machined.

[0017] The array may include special elements known *per se* which special elements have a particular functionality in the array. Such special elements may include ejector pins, side action pins for producing an undercut and sprue pins, for the introduction of material into the mould.

[0018] Where it is desirable or required that the surface of the part to be produced in the tooling system of the invention has a surface free of witness marks, caused by the presence of gaps between the elements, the elements may be bonded together at the tooling surface. Depending on the material from which the elements are made, they may be bonded by any suitable technique, for example by resin bonding or by welding. When it is required to reconfigure the tool, the bonding may be removed, for example either mechanically by machining or chemically. The surface free of witness marks may be required for example for cosmetic or aesthetic reasons or to ensure structural integrity.

[0019] In use, a coolant or heating medium may be applied to the rear face of the tooling system according to the various aspects of the present invention.

[0020] According to a further aspect of the present invention there is provided a method of tooling surface generation using a modular tool in which a plurality of elements are arranged in an array, comprising the steps of;

moving the elements from a closed position, in which the elements contact one another, to an open position in which the elements of the array are spaced apart;

moving the elements vertically relative to one another to create a desired surface contour of the tool, and moving the elements back from the open position to the closed position.

[0021] Preferably the elements of the array are machined when the array is in the closed position, although the elements may be machined when the array is in the open position.

[0022] Alternatively, upper parts of the elements of the array may be removed and machined independently of the array.

[0023] The invention will now be described by way of example only with reference to the accompanying drawings in which;

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|----|-----------|---|
| 5 | Fig 1 | shows a known arrangement of a reconfigurable modular tool in which a flexible face sheet is mounted on an array of vertically adjustable pins; |
| 10 | Fig 2 | shows a tool according to the invention including a plurality of elements in an array; |
| 15 | Fig 3 | shows the tool of Fig 2 in which the elements have been moved vertically moved relative to one another; |
| 20 | Fig 4 | shows the tool of Figs 2 and 3 in which the surface contour of the tool is being cut to a desired shape with a milling cutter; |
| 25 | Fig 5 | shows a clamp frame for locking the elements in the closed position; |
| 30 | Fig 6 | shows an alternative embodiment of the invention in which the elements of the array are moved to an open position before vertical movement of the elements; |
| 35 | Fig 7 | shows the tool of Fig 6 in which the elements are being moved vertically in the open position; |
| 40 | Fig 8 | shows a plurality of square elements mounted in an alternative array on supporting rails in the closed position; |
| 45 | Fig 9 | shows the elements of the array of Fig 8 moved to the open position; |
| 50 | Fig 10 | shows a plurality of self guiding elements mounted in an array on supporting rails in the closed position; |
| | Fig 11 | shows the elements of the array of Fig 10 moved to the open position and |
| | Figure 12 | shows an alternative embodiment of the invention in which the elements of the array are arranged in modules. |

[0024] Referring firstly to Fig 1, a known reconfigurable modular tool is indicated generally at 10. A plurality of spaced apart vertically adjustable pins 12 are mounted on a drive base 14, such that the height of each pin 12 above the drive base 14 can be individually set. A flexible face sheet 16 is attached to the ends of the pins 12. A desired surface contour of the face sheet 16 can be set by adjusting the individual heights of the pins 12. The

adjustments are controlled automatically through a computer (not shown), which is pre-programmed with the desired contour.

[0025] A first embodiment of a tool in accordance with the invention will now be described with reference to Figs 2 to 5. The tool is indicated generally at 15 and comprises a plurality of elements 18 arranged in a closed position, that is, with the sides of adjacent elements 18 in contact with one another. An upper end 20 of each element 18 forms part of a tooling surface 22. As shown in Fig 5, the tool 15 comprises nine elements 18 which are arranged in an array 28.

Clamping members 24,26 provide additional lateral support and secure the elements 18 of the array 28 relative to one another, when the tool 15 is being machined and is in use.

[0026] In order to change the surface contour 22 of the tool 15, the clamping members 24,26 are released, and the elements 18 moved vertically relative to one another by a drive means in order to produce an approximation of the desired tool surface contour 22, as shown in Fig 3. The drive means is optionally removable.

[0027] In the preferred arrangement (not shown), the drive means comprises a downwardly extending threaded rod rotatably mounted to the underside of each element, and threadingly engaged in a base portion. The elements 18 are positioned by rotation of the threaded rods, each of which is driven by an electric motor. In an alternative arrangement (not shown), all of the elements 18 are lifted manually and each element is allowed to fall under gravity to a desired position, where the element is secured.

[0028] When the elements have been positioned vertically, the tooling surface 22 is machined by a milling cutter 62, as seen in Fig 4. A minimum amount of machining is required, because the elements 18 have already been positioned before machining, as described above. Only a finishing cut should be required, which means that typically, less than 5% of each element is sacrificed in machining.

[0029] The elements 18 are formed in two parts, a removable and machinable upper part 64, and a lower part 66 which is a permanent part of the tool and is capable of being driven as described. When the tooling surface 22 is machined, it is preferred that the upper parts 64 of the elements 18 are machined in the assembled tool 15. However, if this is not possible due to the large size of the tool 15, then the upper parts 64 can be removed from the tool 15 and machined independently.

[0030] In an alternative embodiment of the invention, shown in Figs 6 and 7, the elements 18 of the array 28 are moved from the position shown in Fig 2, that is a closed position, to an open position, shown in Fig 6. The elements 18 are driven apart by means of an electric motor, gearing and cross slides (not shown). When the array 28 is in the open position, the elements 18 are moved vertically relative to one another, as indicated in Fig 7 by arrows A.

[0031] Once the elements 18 have been positioned vertically, the array 28 is moved back from the open position to the closed position. Finally the elements 18 of the array 28 are secured by the clamping members 24,26, see Fig 5, and the tooling surface 22 is machined ready for use.

[0032] An alternative array 30 is shown in Figs 8 and 9 in the closed and open positions respectively. Supporting rails 31 to 38 support respective elements 41 to 48, and are driven apart in order to move the elements of the array 30 between the closed and open positions as indicated by arrows B.

[0033] The vertices of adjacent elements, for example elements 41 and 42, having diagonals which are aligned in the closed position, touch one another. In order to separate the vertices 71,72 of the adjacent elements 41,42, the elements 41,42 are mounted on separate supporting rails 31,32. Similarly adjacent elements 43,44; 45,46 and 47,48 are mounted on separate supporting rails.

[0034] Figs 10 and 11 show a further array 50 in the closed and open positions respectively. Supporting rails 51 to 54 support respective elements 55 to 58, and are driven apart in order to move the elements of the array 50 between the closed and open positions as indicated by arrows C. In the array 50, the elements 55 to 58 are not square in cross section, but are substantially square and are formed with a pointed tip and correspondingly shaped recess, indicated respectively at 59 and 60 on one of the elements 55.

[0035] The pointed tip 59 and recess 60 are positioned in axial alignment at opposite vertices of each element 55,56,57,58, and are co-axial with the direction of opening and closing movement of the array 50.

[0036] Consequently, when the array 50 is in the closed position, the tips 59 engage in respective recesses 60 of adjacent elements, for example, the tip 61 of element 57 locates in the recess 60 of element 55.

[0037] This arrangement has the advantage that the vertices 75 of the adjacent elements 55 do not touch one another in the closed position. Consequently only one supporting rail 51 is required to support the adjacent elements 55 in the movement from the closed to the open position of the array 50. Similarly the other adjacent elements 56,57,58 only require one respective supporting rail 52,53,54 for each row of adjacent elements. Furthermore, the interlocking nature of the tips and recesses adds strength to the tool 15, and assists in guiding the elements of the array 50 in the movement from the open to the closed position.

[0038] A further alternative arrangement is shown in Figure 12 in which the elements of the array are arranged in modules identified as A, B and C. The modules A, B and C may be arranged in the same plane or may be stacked in a multi-plane arrangement as shown in Figure 12.

[0039] Although the elements 18 shown in the Figures are all of the same size, different sizes of element 18 can be used in different tooling applications. For example, in

areas of the tooling surface 22 where large aspect ratios are required, that is, the range of depth in the tooling surface contour is large in comparison to its width, then by using a larger number of smaller elements 18, less machining is required of each of the elements.

[0040] For tools 15 which are to be used in vacuum forming, through holes (not shown) are provided in the elements 18 between the tooling surface 22 and the underside of the elements, which are connected to a vacuum pump. Alternatively, the elements may be formed in a cross section which does not tessellate completely. When arranged in a closed array, these elements (not shown) have ducts between them, which extend to the tooling surface, and which can be used for the application of a vacuum. A positive pressure can also be applied to the tooling surface 22 through the holes or ducts for cooling of the tool, or removal of a product from the tooling surface 22.

Claims

1. A tooling system (15) comprising a plurality of elements (18) arranged in an array (28), the elements (18) of the array (28) being moveable between a closed position in which the elements (18) are secured in position, and an open position in which the elements (18) of the array (28) are capable of vertical movement relative to one another, and drive means for opening and closing the array (28), **characterised in that**, in the closed position, the elements (18) of the array (28) contact one another and in the open position the elements (18) of the array (28) are spaced apart.
2. A tooling system (15) as claimed in claim 1 in which the elements (18) of the array (28) tessellate in the closed position to produce a continuous tooling surface (22).
3. A tooling system (15) as claimed in claim 1 or claim 2 in which the cross-section of each element (55, 56, 57, 58) is substantially square with a pointed tip (59) formed at a first apex of the square and a correspondingly shaped recess (60) formed at the opposite vertex of the square.
4. A tooling system (15) as claimed in claim 3 in which the elements (18) are provided with through holes for the application of a positive or negative pressure to the tooling surface (22).
5. A tooling system (15) as claimed in claim 4 in which the elements (18) are of varying size.
6. A tooling system (15) as claimed in claim 5 in which the elements (18) are of varying density in the array (28).

7. A tooling system (15) as claimed in claim 6 in which a further drive means provides vertical drive to each of the elements (18).
8. A tooling system (15) as claimed in any preceding claim in which the elements (18) are machinable.
9. A tooling system (15) as claimed in any preceding claim in which the elements (18) are removable.
10. A tooling system, (15) as claimed in any of claims 1 to 7 in which the elements (18) are constructed from an upper portion (64) and a lower portion (66), the upper portion (64) being removable and machinable.
11. A method of tooling using a modular tool (15) in which a plurality of elements (18) are arranged in an array (28), comprising the steps of:
 - moving the elements (18) from a closed position, moving the elements (18) vertically relative to one another to create a desired surface contour (22) of the tool, and
 - moving the elements (18) back from the open position to the closed position,**characterised in that** in the closed position the elements (18) of the array (28) contact one another and in the open position the elements (18) of the array (28) are spaced apart.
12. A method of tooling as claimed in claim 11 in which the elements (18) of the array (28) are machined when the array (28) is in the closed position.
13. A method of tooling as claimed in claim 11 in which the elements (18) of the array (28) are machined when the array (28) is in the open position.
14. A method of tooling as claimed in claim 11 in which upper parts (64) of the elements (18) of the array (28) are removed and machined independently of the array (28).
15. A tooling system as claimed in any of claims 2 to 10 in which the elements (18) are bonded together at the tooling surface (22).
16. A tooling system as claimed in any of claims 2 to 10 in which the elements (18) within the array (28) are arranged in modules, which modules may be arranged in the same plane is stacked in a multi-plane arrangement.

Patentansprüche

1. Werkstückträgersystem (15), das eine Mehrheit von

- Elementen (18) umfasst, die in einer Gruppe (28) angeordnet sind, wobei die Elemente (18) der Gruppe (28) zwischen einer geschlossenen Position, in der die Elemente (18) in Position gesichert sind, und einer offenen Position bewegbar sind, in der die Elemente (18) der Gruppe (28) vertikaler Bewegung relativ zueinander fähig sind und Antriebsmittel zum Öffnen und Schließen der Gruppe (28) umfasst, **dadurch gekennzeichnet, dass** die Elemente (18) der Gruppe (28) in der geschlossenen Position einander berühren und in der offenen Position die Elemente (18) der Gruppe (28) mit Abstand angeordnet sind.
2. Werkstückträgersystem (15) nach Anspruch 1, in dem sich die Elemente (18) der Gruppe (28) in der geschlossenen Position schachbrettartig einlegen, um eine kontinuierliche Bearbeitungsfläche (22) zu produzieren.
3. Werkstückträgersystem (15) nach Anspruch 1 oder Anspruch 2, in dem der Querschnitt jedes Elements (55, 56, 57, 58) im Wesentlichen quadratisch mit einer spitzen Spitze (59) ist, die an einem ersten Scheitelpunkt des Quadrats und einer entsprechend geformten Aussparung (60) an der entgegengesetzten Spitze des Quadrats gebildet ist.
4. Werkstückträgersystem (15) nach Anspruch 3, in dem die Elemente (18) mit Durchgangslöchern für die Auftragung eines positiven oder negativen Drucks auf die Bearbeitungsfläche (22) versehen sind.
5. Werkstückträgersystem (15) nach Anspruch 4, in dem die Elemente (18) variierender Größe sind.
6. Werkstückträgersystem (15) nach Anspruch 5, in dem die Elemente (18) variierender Dichte in der Gruppe (28) sind.
7. Werkstückträgersystem (15) nach Anspruch 6, in dem ein weiteres Antriebsmittel vertikalen Antrieb für jedes der Elemente (18) bereitstellt.
8. Werkstückträgersystem (15) nach einem beliebigen vorhergehenden Anspruch, in dem die Elemente (18) maschinell bearbeitbar sind.
9. Werkstückträgersystem (15) nach einem beliebigen vorhergehenden Anspruch, in dem die Elemente (18) entfernbar sind.
10. Werkstückträgersystem, (15) nach einem beliebigen der Ansprüche 1 bis 7, in dem die Elemente (18) aus einem oberen Abschnitt (64) und einem unteren Abschnitt (66) konstruiert sind, wobei der obere Abschnitt (64) entfernbar und maschinell bearbeitbar ist.
11. Bestückungsverfahren, mithilfe eines modularen Werkstückträgers (15), indem eine Mehrheit von Elementen (18) in einer Gruppe (28) angeordnet ist und das folgende Schritte umfasst:
- Bewegen der Elemente (18) aus einer geschlossenen Position,
Bewegen der Elemente (18) vertikal relativ zueinander, um eine gewünschte Oberflächenkontur (22) des Werkzeugs zu schaffen, und
Zurückbewegen der Elemente (18) aus der offenen Position in die geschlossene Position,
- dadurch gekennzeichnet, dass** die Elemente (18) der Gruppe (28) in der geschlossenen Position einander berühren und die Elemente (18) der Gruppe (28) in der offenen Position mit Abstand angeordnet sind.
12. Bestückungsverfahren nach Anspruch 11, in dem die Elemente (18) der Gruppe (28) maschinell bearbeitet werden, wenn sich die Gruppe (28) in der geschlossenen Position befindet.
13. Bestückungsverfahren nach Anspruch 11, in dem die Elemente (18) der Gruppe (28) maschinell bearbeitet werden, wenn sich die Gruppe (28) in der offenen Position befindet.
14. Bestückungsverfahren nach Anspruch 11, in dem obere Abschnitte (64) der Elemente (18) der Gruppe (28) entfernt und unabhängig von der Gruppe (28) maschinell bearbeitet werden.
15. Werkstückträgersystem nach einem beliebigen der Ansprüche 2 bis 10, in dem die Elemente (18) an der Bearbeitungsfläche (22) miteinander verbunden sind.
16. Werkstückträgersystem nach einem beliebigen der Ansprüche 2 bis 10, in dem die Elemente (18) in der Gruppe (28) in Modulen angeordnet sind, welche Module in derselben Ebene angeordnet oder in einer Anordnung mehrfacher Ebene gestapelt werden könnten.

Revendications

1. Système d'outillage (15) comprenant une pluralité d'éléments (18) disposés sous forme de matrice (28), les éléments (18) de la matrice (28) étant mobiles entre une position fermée dans laquelle les éléments (18) sont fixés en position, et une position ouverte dans laquelle les éléments (18) de la matrice (28) sont capables de réaliser un déplacement ver-

- tical les uns par rapport aux autres, et un moyen d'entraînement pour ouvrir et fermer la matrice (28), **caractérisé en ce que**, dans la position fermée, les éléments (18) de la matrice (28) sont en contact les uns avec les autres et dans la position ouverte, les éléments (18) de la matrice (28) sont espacés les uns des autres.
2. Système d'outillage (15) selon la revendication 1, dans lequel les éléments (18) de la matrice (28) forment un pavage en mosaïque dans la position fermée pour produire une surface d'outillage continue (22).
 3. Système d'outillage (15) selon la revendication 1 ou la revendication 2, dans lequel la section transversale de chaque élément (55, 56, 57, 58) est sensiblement carrée avec une extrémité pointue (59) formée au niveau d'un premier apex du carré et un évidement de forme correspondante (60) formé au vertex opposé du carré.
 4. Système d'outillage (15) selon la revendication 3, dans lequel les éléments (18) sont munis de trous traversants pour l'application d'une pression positive ou négative à la surface d'outillage (22).
 5. Système d'outillage (15) selon la revendication 4, dans lequel les éléments (18) sont de taille variable.
 6. Système d'outillage (15) selon la revendication 5, dans lequel les éléments (18) sont de densité variable dans la matrice (28).
 7. Système d'outillage (15) selon la revendication 6, dans lequel un autre moyen d'entraînement assure l'entraînement vertical de chacun des éléments (18).
 8. Système d'outillage (15) selon l'une quelconque des revendications précédentes, dans lequel les éléments (18) sont usinables.
 9. Système d'outillage (15) selon l'une quelconque des revendications précédentes, dans lequel les éléments (18) sont amovibles.
 10. Système d'outillage (15) selon l'une quelconque des revendications 1 à 7, dans lequel les éléments (18) sont construits à partir d'une partie supérieure (64) et d'une partie inférieure (66), la partie supérieure (64) étant amovible et usinable.
 11. Procédé de fabrication d'outillage utilisant un outil modulaire (15) dans lequel une pluralité d'éléments (18) est disposée en formant une matrice (28), comprenant les étapes consistant à:
 - déplacer les éléments (18) depuis une position
- fermée,
- déplacer les éléments (18) verticalement les uns par rapport aux autres pour créer un contour de surface souhaité (22) de l'outil, et
 - redéplacer les éléments (18) de la position ouverte à la position fermée,
- caractérisé en ce que**, dans la position fermée, les éléments (18) de la matrice (28) sont en contact les uns avec les autres et dans la position ouverte, les éléments (18) de la matrice (28) sont espacés les uns des autres.
12. Procédé de fabrication d'outillage selon la revendication 11, dans lequel les éléments (18) de la matrice (28) sont usinés lorsque la matrice (28) est dans la position fermée.
 13. Procédé de fabrication d'outillage selon la revendication 11, dans lequel les éléments (18) de la matrice (28) sont usinés lorsque la matrice (28) est dans la position ouverte.
 14. Procédé de fabrication d'outillage selon la revendication 11, dans lequel des parties supérieures (64) des éléments (18) de la matrice (28) sont retirées et usinées indépendamment de la matrice (28).
 15. Système d'outillage selon l'une quelconque des revendications 2 à 10, dans lequel les éléments (18) sont liés les uns aux autres au niveau de la surface d'outillage (22).
 16. Système d'outillage selon l'une quelconque des revendications 2 à 10, dans lequel les éléments (18) dans la matrice (28) sont disposés en modules, modules pouvant être disposés dans le même plan ou empilés selon une disposition multi-plans.

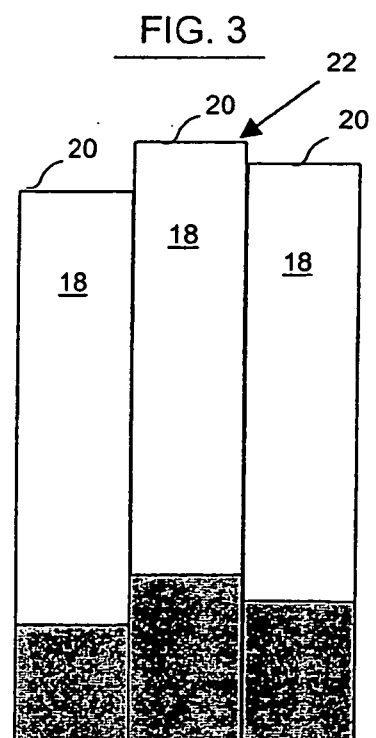
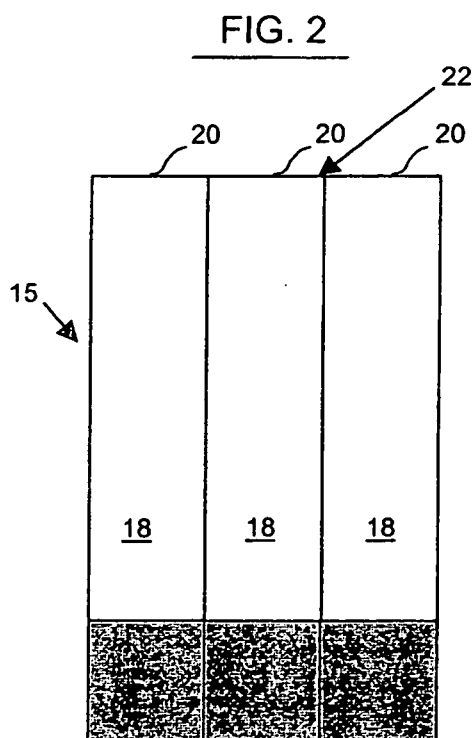
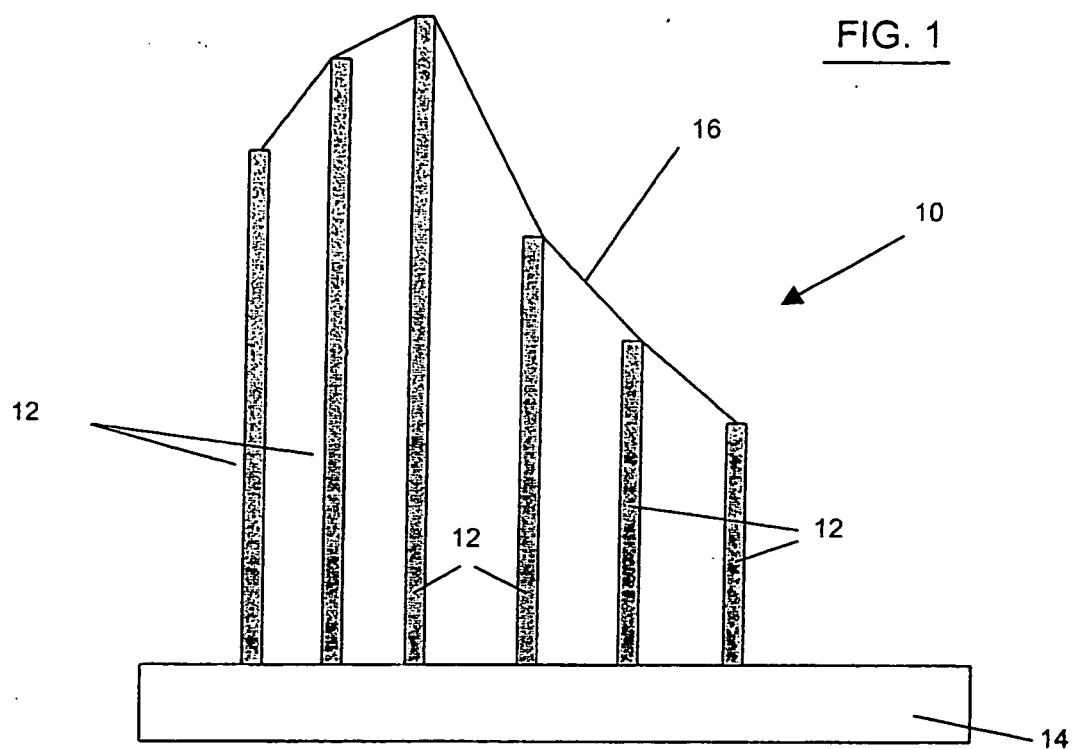


FIG. 4

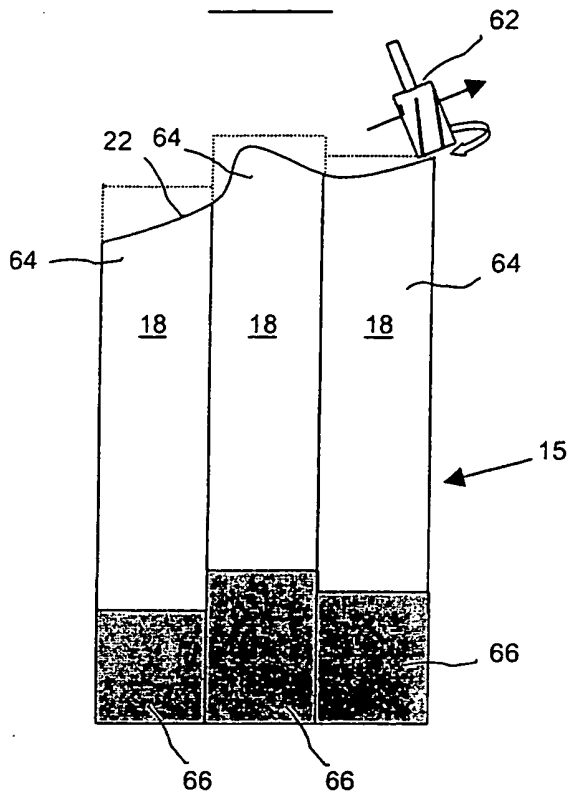


FIG. 5

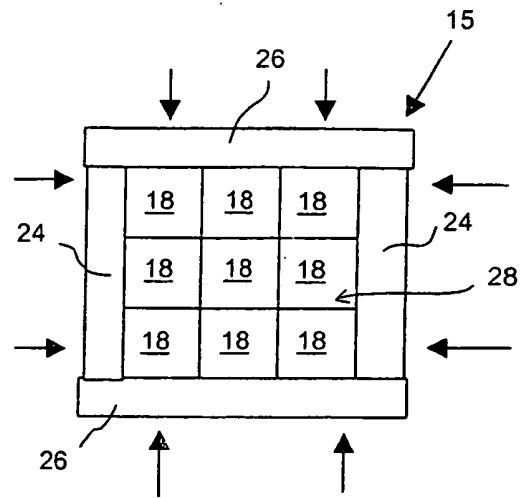


FIG. 6

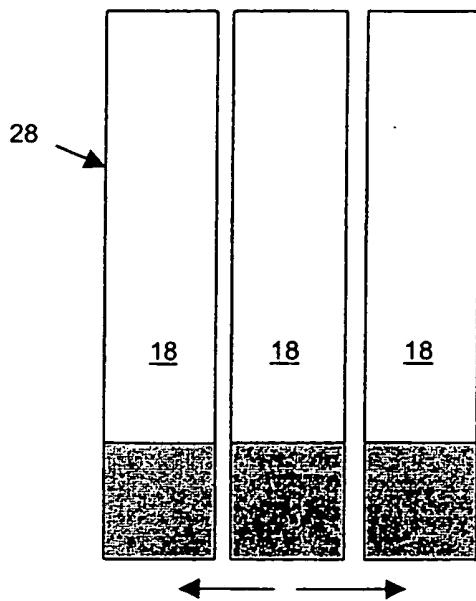


FIG. 7

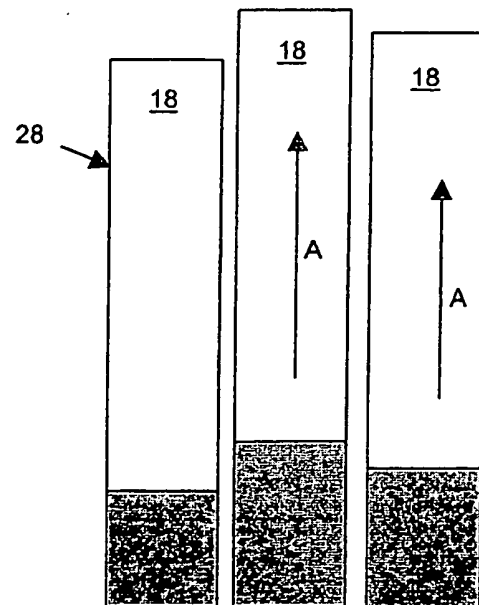


FIG. 8

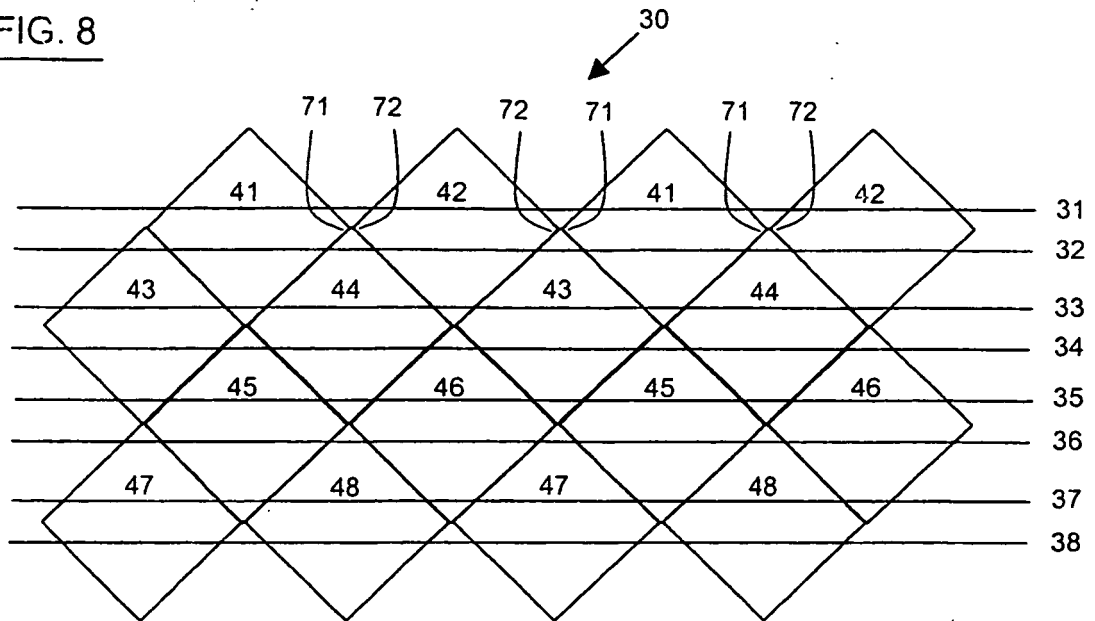


FIG. 9

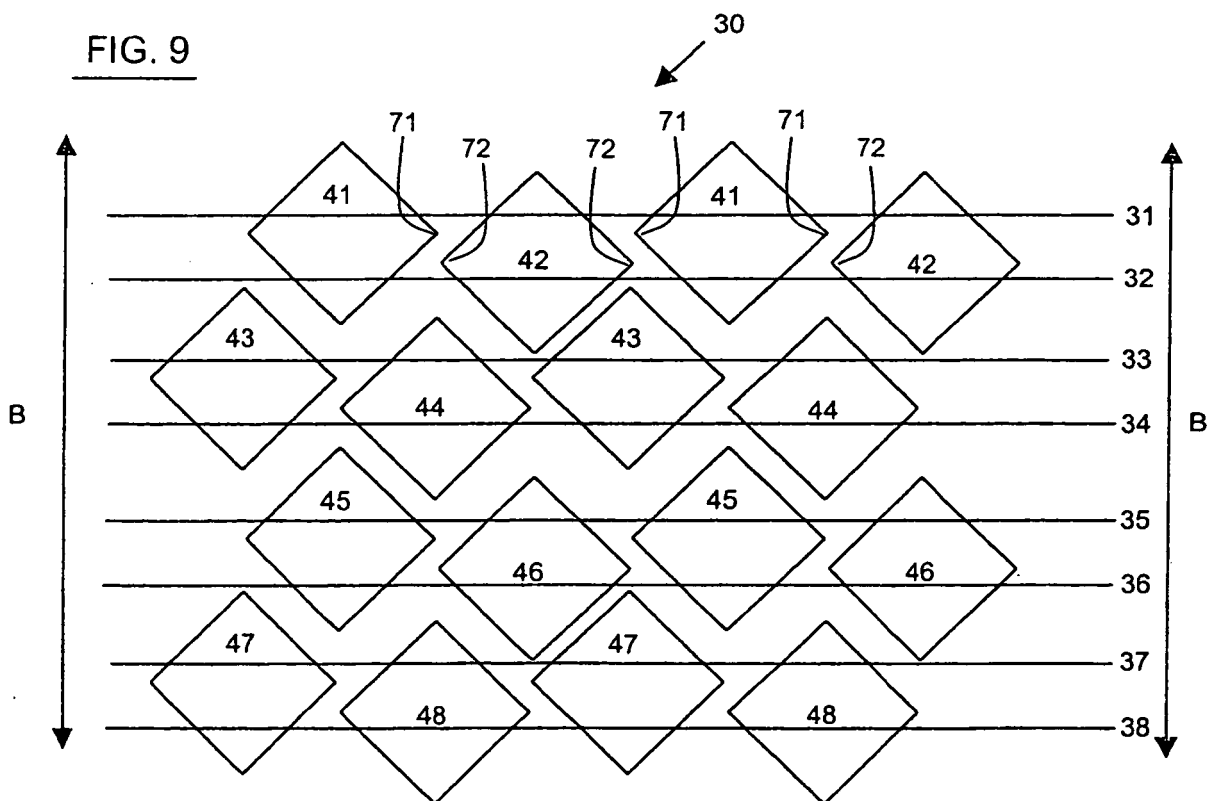


FIG. 10

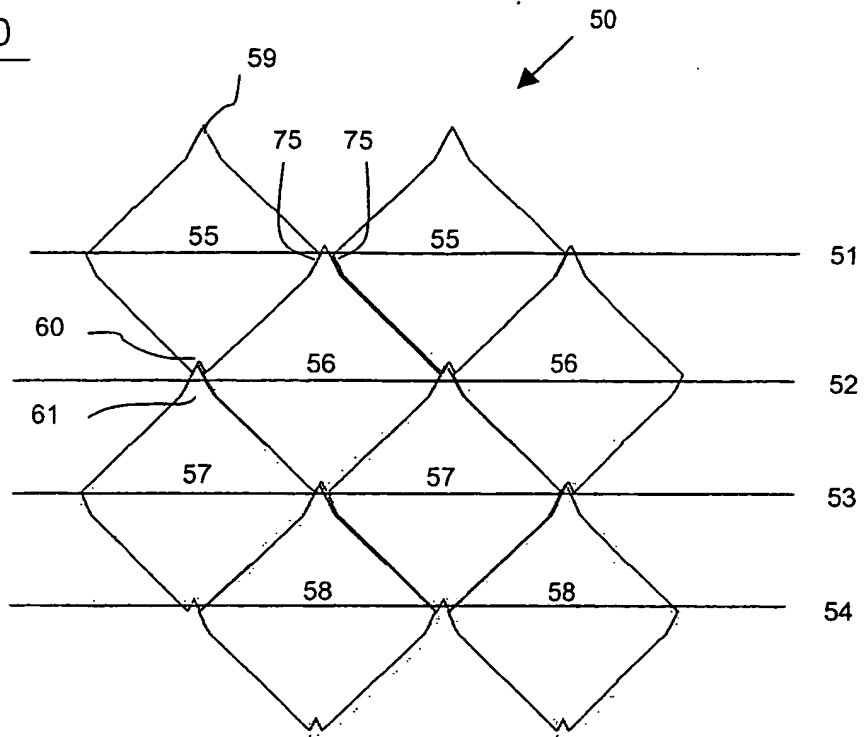


FIG. 11

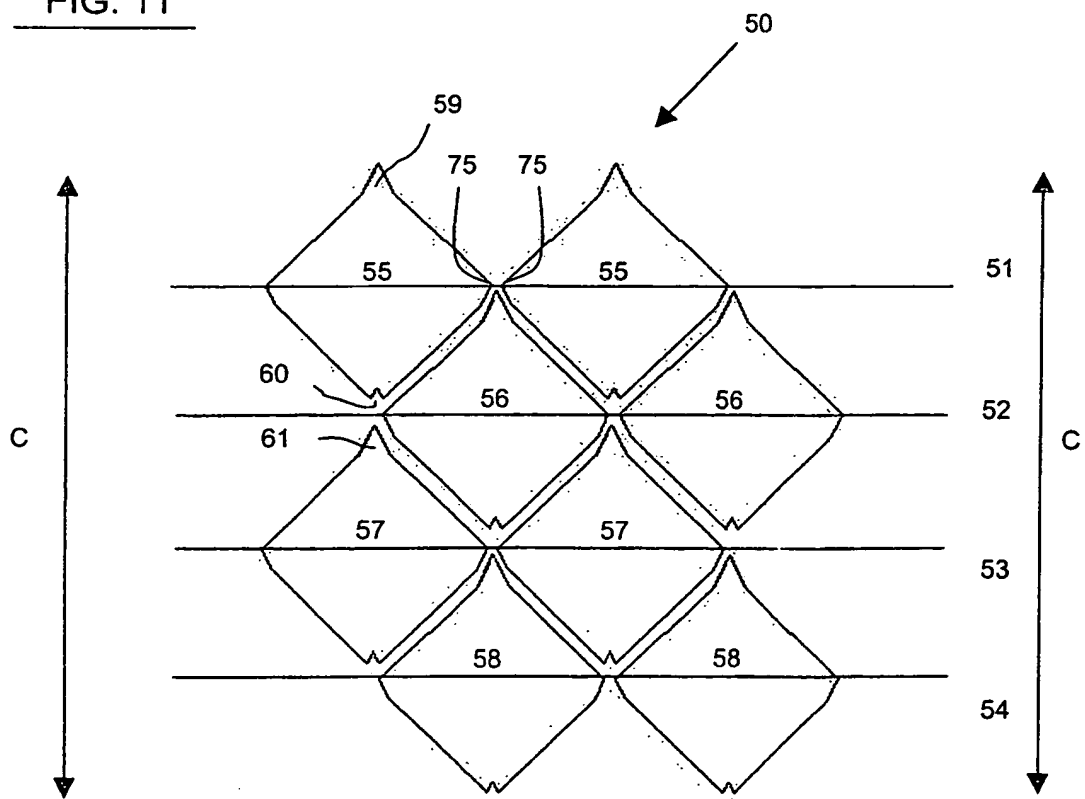


FIG. 12

