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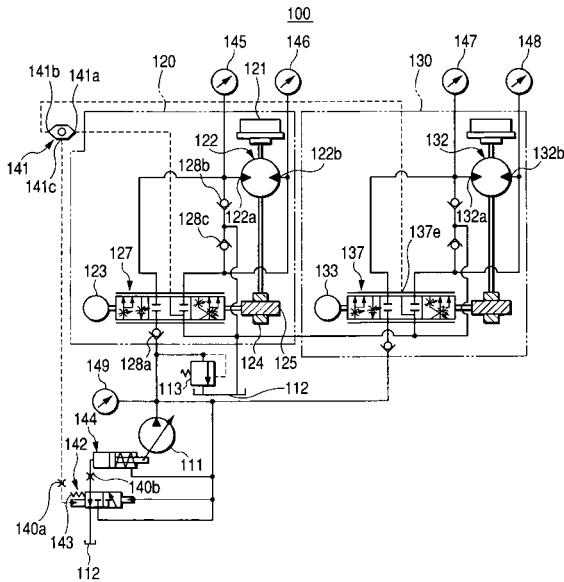
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(54) **ELECTROHYDRAULIC ACTUATION SYSTEM**

(57) An object of the invention is to provide an electro-hydraulic actuation system which can prevent the generation of a shortage in volume of a fluid supplied to a hydraulic actuator having a larger load pressure of hydraulic actuators of a plurality of electro-hydraulic actuators. The electro-hydraulic actuation system 100 changes a working fluid discharge volume of a variable displacement hydraulic pump 111 by a selector valve 141, a two-position valve 142, a spring 143 and a discharge volume changing hydraulic cylinder 144 based on the maximum pressure of load pressures of a hydraulic motor 122 and a hydraulic motor 132 and a working fluid discharge pressure of the variable displacement hydraulic pump 111.

FIG. 1



Description**Technical Field**

[0001] The present invention relates to an electro-hydraulic actuation system for use in a hydraulic shovel or asphalt finisher and more particularly to an electro-hydraulic actuation system to which a load sensing system (hereinafter, referred to as LS) is applied for changing the discharge volume of a pump based on the load pressure of an actuator so that a differential pressure between the load pressure of the actuator and the discharge pressure of the pump becomes substantially constant.

Background Art

[0002] Conventionally, as a hydraulic actuation system to which the LS is applied, there has been known, for example, a hydraulic actuation system 900 shown in Fig. 22.

[0003] The hydraulic actuation system 900 includes a variable displacement hydraulic pump 911 for discharging a working fluid, a tank 912 from which the working fluid is discharged and a relief valve 913 for keeping the working fluid discharge pressure of the variable displacement hydraulic pump 911 at a predetermined set pressure or lower.

[0004] In addition, the hydraulic actuation system 900 includes a unit 920 having reduction gears 921 connected to a load, not shown, a variable displacement hydraulic motor 922 for imparting a driving force to the reduction gears 921, an operation lever 923 adapted to be operated by an operator, a manual direction control valve 924 for changing the communication of the variable displacement hydraulic pump 911 and the tank 912 with the variable displacement hydraulic motor 922 in accordance with the operation amount of the operation lever 923 and an automatic two-position valve 925 for cutting off the communication of the variable displacement hydraulic pump 911 and the tank 912 with the variable displacement hydraulic motor 922 in accordance with the operation amount of the operation lever 923 when the communication of the variable displacement hydraulic pump 911 and the tank 912 with the variable displacement hydraulic motor 922 is cut off by the manual direction control valve 924.

[0005] In addition, the hydraulic actuation system 900 includes a unit 930 having a similar configuration to that of the unit 920, while the detailed description of the unit 930 is omitted here.

[0006] Additionally, the hydraulic actuation system 900 includes a selector valve 941 for selecting a working fluid having a greater pressure of a working fluid supplied from the variable displacement hydraulic pump 911 to the variable displacement hydraulic motor 922 of the unit 920 and a working fluid supplied to the variable

displacement hydraulic pump 911 to a variable displacement hydraulic motor 932 of the unit 930, a two-position electromagnetic valve 942 for allowing the working fluid discharged by the variable displacement hydraulic

5 pump 911 to pass when a pressure resulting from adding a predetermined set pressure to the pressure of the working fluid selected by the selector valve 941 is greater than the working fluid discharge pressure of the variable displacement hydraulic pump 911 discharges the
10 working fluid, a discharge volume changing hydraulic cylinder 943 for changing the discharge volume of the variable displacement hydraulic pump 911 based on the pressure of the working fluid which is allowed to pass by the two-position electromagnetic valve 942 and the
15 working fluid discharge pressure of the variable displacement hydraulic pump 911.

[0007] By the configuration that has been described above, the discharge volume changing hydraulic cylinder 943 used to change the working fluid discharge volume of the variable displacement hydraulic pump 911 so that a difference between a larger pressure of the pressure of the working fluid supplied from the variable displacement hydraulic pump 911 to the variable displacement hydraulic motor 922 of the unit 920, that is, 20 the load pressure of the unit 920 and the pressure of the working fluid supplied from the variable displacement hydraulic pump 911 to the variable displacement hydraulic motor 932 of the unit 930, that is, the load pressure of the unit 930 and the working fluid discharge pressure 25 of the variable displacement hydraulic pump 911 becomes the set pressure of the two-position electromagnetic valve 942.

[0008] In the conventional hydraulic actuation system 900, however, there was a problem that the amount of 30 the working fluid is short which is supplied to the variable displacement hydraulic motor having a larger load pressure of the variable displacement hydraulic motor 922 of the unit 920 and the variable displacement hydraulic motor 932 of the unit 930.

[0009] When the load pressure of the variable displacement hydraulic motor 922 of the unit 920 or the variable displacement hydraulic motor 932 of the unit 930 is increased, the working fluid discharge pressure of the variable displacement hydraulic pump 911 is increased 40 due to the actions of the selector valve 941, the two-position electromagnetic valve 942 and the discharge volume changing hydraulic cylinder 943. However, in a case where the relationship between the working fluid discharge volume and discharge pressure of the variable displacement hydraulic pump 911 is such as shown 45 in Fig. 23, namely, in a case where the variable displacement hydraulic pump 911 is a pump whose horse power is constant, the working fluid discharge volume of the variable displacement hydraulic pump 911 decreases 50 as the working fluid discharge pressure thereof increases.

[0010] Here, when the working fluid discharge volume of the variable displacement hydraulic pump 911 be-

comes smaller than a total amount of working fluid needed to be supplied to the variable displacement hydraulic motor 922 of the unit 920 and the variable displacement hydraulic motor 932 of the unit 930, the working fluid discharged by the variable displacement hydraulic pump 911 flows to the variable displacement hydraulic motor having a smaller load pressure in preference to the other.

[0011] Then, there occurs a shortage in volume of the working fluid supplied to the variable displacement hydraulic motor having a larger load pressure of the variable displacement hydraulic motor 922 of the unit 920 and the variable displacement hydraulic motor 932 of the unit 930, and the output thereof is reduced when compared with a case where there occurs no shortage in volume of the working fluid supplied thereto.

[0012] Consequently, for example, in a case where the variable displacement hydraulic motor 922 of the unit 920 is used for driving a right side caterpillar of a hydraulic shovel and the variable displacement hydraulic motor 932 of the unit 930 is used for a left side caterpillar of the hydraulic shovel, when the operator attempts to move the hydraulic shovel straight forward by inputting substantially equal operation amounts to the operation lever 923 of the unit 920 and an operation lever 933 of the unit 930, in the event that a load borne by the right side caterpillar becomes larger than a load borne by the left side caterpillar as a result of, for example, the right side caterpillar riding on a stone or the left side caterpillar entering a puddle, the movement of the right side caterpillar becomes slower than the movement of the left side caterpillar, and the hydraulic shovel advances while turning to the right.

[0013] Then, an object of the invention is to provide an electro-hydraulic actuation system which can prevent the generation of a shortage in volume of a fluid supplied to a hydraulic actuator having a larger load pressure of hydraulic actuators of a plurality of electro-hydraulic actuators.

Disclosure of the Invention

[0014] With a view to solving the problem, according to the invention, there is provided an electro-hydraulic actuation system including a pump, a plurality of electro-hydraulic actuators each having an electric motor, a hydraulic actuator and a fluid volume changing valve for changing the volume of a fluid discharged by the pump based on driving amounts of the electric motor and the hydraulic actuator for supply to the hydraulic actuator, a discharge volume changing means for changing the volume of the fluid discharged by the pump based on a maximum pressure of pressures of the fluid supplied to the hydraulic actuators of the plurality of electro-hydraulic actuators and the discharge pressure of the fluid discharged by the pump and a rotational speed changing means for changing the rotational speed of the electric motors of the plurality of electro-hydraulic actuators at

substantially the same ratio relative to the electric motors of the plurality of electro-hydraulic actuators based on a maximum pressure of pressures of the fluid supplied to the hydraulic actuators of the plurality of electro-hydraulic actuators and the discharge pressure of the fluid discharged by the pump.

[0015] By adopting this configuration, since the electro-hydraulic actuation system of the invention can reduce the volume of the fluid supplied to the hydraulic actuators of the plurality of electro-hydraulic actuators at substantially the same ratio when there occurs a shortage in volume of the fluid supplied to the hydraulic actuators of the plurality of electro-hydraulic actuators, it is possible to prevent the occurrence of a shortage in volume of the fluid supplied to the actuator having a larger load pressure of the hydraulic actuators of the plurality of electro-hydraulic actuators.

Brief Description of the Drawings

[0016]

- Fig. 1 is a hydraulic circuit diagram of an electro-hydraulic actuation system according to a first embodiment of the invention.
- Fig. 2 is a hydraulic circuit diagram of the electro-hydraulic actuation system shown in Fig. 1 in the vicinity of an electro-hydraulic servo valve thereof.
- Fig. 3 is a hydraulic circuit diagram of the electro-hydraulic actuation system shown in Fig. 1 in the vicinity of a discharge volume changing hydraulic cylinder thereof.
- Fig. 4 is a sectional view of a unit of the electro-hydraulic actuation system shown in Fig. 1.
- Fig. 5 is a sectional view taken along the line indicated by arrows A-A in Fig. 4 and viewed in a direction indicated by the arrows.
- Fig. 6 is a sectional view taken along the line indicated by arrows B-B in Fig. 4 and viewed in a direction indicated by the arrows.
- Fig. 7 is a sectional view taken along the line indicated by arrows C-C in Fig. 4 and viewed in a direction indicated by the arrows.
- Fig. 8 is a hydraulic circuit diagram of an electro-hydraulic actuation system according to a second embodiment of the invention.
- Fig. 9 is a hydraulic circuit diagram of the electro-hydraulic actuation system shown in Fig. 8 in the vicinity of an electro-hydraulic servo valve thereof.
- Fig. 10 is a sectional view of a unit of the electro-hydraulic actuation system shown in Fig. 8.
- Fig. 11 is a sectional view taken along the line indicated by arrows E-E in Fig. 10 and viewed in a direction indicated by the arrows.
- Fig. 12 is a sectional view taken along the line indicated by arrows F-F in Fig. 10 and viewed in a direction indicated by the arrows.
- Fig. 13 is a sectional view taken along the line indi-

cated by arrows G-G in Fig. 10 and viewed in a direction indicated by the arrows.

Fig. 14 is a sectional view taken along the line indicated by arrows H-H in Fig. 10 and viewed in a direction indicated by the arrows.

Fig. 15 is a hydraulic circuit diagram of an electro-hydraulic actuation system according to a third embodiment of the invention.

Fig. 16 is a hydraulic circuit diagram of the electro-hydraulic actuation system shown in Fig. 15 in the vicinity of an electro-hydraulic servo valve thereof.

Fig. 17 is a sectional view of a unit of the electro-hydraulic actuation system shown in Fig. 15.

Fig. 18 is a sectional view taken along the line indicated by arrows J-J in Fig. 17 and viewed in a direction indicated by the arrows.

Fig. 19 is a sectional view taken along the line indicated by arrows K-K in Fig. 17 and viewed in a direction indicated by the arrows.

Fig. 20 is a sectional view taken along the line indicated by arrows L-L in Fig. 17 and viewed in a direction indicated by the arrows.

Fig. 21 is a hydraulic circuit diagram of an electro-hydraulic actuation system according to a fourth embodiment of the invention.

Fig. 22 is a hydraulic circuit diagram of a conventional electro-hydraulic actuation system.

Fig. 23 is a diagram showing the discharge volume and discharge pressure of a variable displacement hydraulic pump of the electro-hydraulic actuation system shown in Fig. 22.

Best Mode for Carrying out the Invention

[0017] Embodiments of the invention will be described below using the drawings.

(First Embodiment)

[0018] Firstly, the configuration of an electro-hydraulic actuation system according to a first embodiment will be described.

[0019] In Figs. 1 to 3, an electro-hydraulic actuation system 100 as an electro-hydraulic actuation system according to the first embodiment includes a variable displacement hydraulic pump 111 as a pump of a constant horse power for discharging a working fluid (fluid), a tank 112 from which the working fluid is discharged and a relief valve 113 for keeping the working fluid discharge pressure of the variable displacement hydraulic pump 111 at a predetermined set pressure or lower.

[0020] In addition, the electro-hydraulic actuation system 100 includes a unit (refer to Figs. 4 to 7) as an electro-hydraulic actuator having reduction gears 121 connected to a load not shown, a hydraulic motor 122 as a hydraulic actuator having formed therein a port 122a and a port 122b which are made to communicate with the variable displacement hydraulic pump 111 or the

tank 112 and adapted to impart a driving force to the reduction gears 121 by virtue of the pressure of a working fluid supplied to the port 122a and the port 122b, an electric motor 123 driven in accordance with an electric signal entered, a first toothed shaft 124 adapted to rotate together with a driving shaft of the hydraulic motor 122 and a second toothed shaft 125 which is brought into a screw connection with a rotating shaft of the electric motor 123 and is brought into a mesh engagement with the first toothed shaft 124.

[0021] Here, the hydraulic motor 122 has, as shown in Figs. 4 to 7, a box body 151 to which the electric motor 123 is fixed, a box body 152 fixed to the box body 151, a swash plate 153 fixed in the interior of the box body 152, a motor shaft 154 connected to the reduction gears 121 at one end and brought into engagement with the first toothed shaft 124 at the other end thereof in such a manner as to rotate in synchronism with the first toothed shaft 124, a bearing 155 and a bearing 156 which rotatably support the motor shaft 154 on the box body 151 and the box body 152, respectively, a cylinder block into which the motor shaft 154 is inserted at the center thereof, in which a plurality of cylinder chambers 157a are formed and which is in engagement with the motor shaft 154 in such a manner as to rotate in synchronism with the motor shaft 154, a plurality of pistons 158 accommodated in the cylinder chambers 157a in the cylinder block 157, shoe members 159 mounted on distal ends of the pistons 158, a spring 160 for biasing the cylinder block 157 towards the box body 151 side and a seal 161 and a seal 162 for preventing the leakage of a working fluid.

[0022] In addition, the unit 120 has, as shown in Figs. 1 to 3, an electro-hydraulic servo valve 127 as a fluid volume changing valve having formed therein a port 127a communicating with the variable displacement hydraulic pump 111, a port 127b communicating with the tank 112, a port 127c communicating with the port 122a of the hydraulic motor 122, a port 127d communicating with the port 122b of the hydraulic motor 122 and a port 127e, adapted to take any of a first position 127A, a second position 127B and a third position 127C based on the rotating amount of the second toothed shaft 125 and the driving amount of the electric motor 123 and adapted to change the volume of a working fluid discharged by the variable displacement hydraulic pump 111 for supply to the hydraulic motor 122.

[0023] Note that the first position 127A is a position where the port 127a is made to communicate with the port 127c and the port 127e, and the port 127b is made to communicate with the port 127d, the second position 127B is a position where the communication between the port 127a, port 127c and port 127d is cut off, while the port 127b is made to communicate with the port 127e, and the third position 127C is a position where the communication between the port 127a, port 127d and port 127e is established, and the port 127b is made to communicate with the port 127c.

[0024] Here, the electro-hydraulic servo motor 127 has, as shown in Figs. 4 to 7, a moving body 171 for changing the communication of the box body 151 with the port 127a, port 127b, port 127c, port 127d and port 127e, a bearing 172 for transmitting an axial movement of the second toothed shaft 125 to the moving body 171 and a cap 173, a cap 174, the seal 161 and a seal 175 which are adapted to prevent the leakage of working fluid from the inside to the outside of the box body 151.

[0025] In addition, the unit 120 has, as shown in Figs. 1 to 3, a check valve 128a (refer to Fig. 5) disposed between the variable displacement hydraulic pump 111 and the port 127a of the electro-hydraulic servo valve 127 for preventing the passage of a working fluid from the port 127a of the electro-hydraulic servo valve 127 to the variable discharge volume hydraulic valve 111, a check valve 128b (refer to Figs. 6 and 7) disposed between the port 122a of the hydraulic motor 122 and the port 127c of the electro-hydraulic servo valve 127 and the tank 112 for preventing the passage of a working fluid from the port 122a of the hydraulic motor 122 and the port 127c of the electro-hydraulic servo valve 127 to the tank 112 and a check valve 128c (refer to Figs. 6 and 7) disposed between the port 122b of the hydraulic motor 122 and the port 127c of the electro-hydraulic servo valve 127 and the tank 112 for preventing the passage of a working fluid from the port 122b of the hydraulic motor 122 and the port 127c of the electro-hydraulic servo valve 127 to the tank 112.

[0026] In addition, while a detailed description is omitted, the electro-hydraulic actuation system 100 has a unit 130 having a similar configuration to that of the unit 120.

[0027] Additionally, the electro-hydraulic actuation system 100 includes a selector valve 141 having formed therein a port 141a which communicates with the port 127e of the electro-hydraulic servo valve 127 of the unit 120, a port 141b which communicates with a port 137e of an electro-hydraulic servo valve 137 of the unit 130 and a port 141c and adapted to select the port having a maximum pressure of the port 141a and the port 141b for establishing a communication between the port so selected and the port 141c.

[0028] In addition, the electro-hydraulic actuation system 100 includes a two-position valve 142 having formed therein a port 142a which communicates with the tank 112, a port 142b and a port 142c which communicate with the variable displacement hydraulic pump 111, a port 142d which communicates with the port 141c of the selector valve 141 via a throttle valve 140a and a port 142e and adapted to take either of a first position 142A where the port 142a and the port 142e are made to communicate with each other in accordance with the pressure of a working fluid supplied to the port 142c and the port 142e and a second position 142B where the port 142b and the port 142e are made to communicate with each other.

[0029] Additionally, the electro-hydraulic actuation

system 100 includes a spring 143 for biasing the two-position valve 142 so that the two-position valve 142 takes the first position 142A when the pressure of a working fluid supplied to the port 142c of the two-position

5 valve 142 is equal to or lower than a pressure resulting from adding a predetermined set pressure to the pressure of a working fluid supplied to the port 142d of the two-position valve 142.

[0030] In addition, the electro-hydraulic actuation system 100 includes a discharge volume changing hydraulic cylinder 144 having formed therein a cylinder chamber 144a which communicates with the port 142e of the two-position valve 142 via a throttle valve 140b and a cylinder chamber 144b which communicates with the 15 variable displacement hydraulic pump 111, connected with the variable displacement hydraulic pump 111 in such a manner to increase the discharge volume of the variable displacement hydraulic pump 111 when retracted than extended and adapted to be extended when the 20 pressure of a working fluid within the cylinder chamber 144a is equal to or greater than the pressure of a working fluid within the cylinder chamber 144b and to be retracted when the pressure of the working fluid within the cylinder chamber 144a is smaller than the pressure of 25 the working fluid within the cylinder chamber 144b.

[0031] Here, the electro-hydraulic servo valve 127 of the unit 120, the electro-hydraulic servo valve 137 of the unit 130, the selector valve 141, the two-position valve 142, the spring 143 and the discharge volume changing 30 hydraulic cylinder 144 constitutes a discharge volume changing means for changing the discharge pressure of a working fluid discharged by the variable displacement hydraulic pump 111 based on a maximum pressure of pressures of the working fluid supplied to the hydraulic 35 motor 122 of the unit 120 and the hydraulic motor 132 of the unit 130 and the discharge pressure of the working fluid discharged by the variable displacement hydraulic pump 111.

[0032] In addition, the electro-hydraulic actuation system 100 includes a pressure gauge 145 for detecting the pressure of a working fluid supplied to the port 122a of the hydraulic motor 122 of the unit 120, a pressure gauge 146 for detecting the pressure of a working fluid supplied to the port 122b of the hydraulic motor 122, a 40 pressure gauge 147 for detecting the pressure of a working fluid supplied to the port 132a of the hydraulic motor 132 of the unit 130, a pressure gauge 148 for detecting the pressure of a working fluid supplied to the port 132b of the hydraulic motor 132, a pressure gauge 45 149 for detecting the working fluid discharge pressure of the variable displacement hydraulic pump 111 and a computer, not shown, to which pressures detected by the pressure gauge 145, the pressure gauge 146, the pressure gauge 147, the pressure gauge 148 and the pressure gauge 149 are inputted for changing the rotation speed of the electric motor 123 of the unit 120 and the electric motor 133 of the unit 130 based on the pressures so inputted at substantially the same ratio relative 50 55

to the electric motor 123 and the electric motor 133.

[0033] Here, the pressure gauge 145, the pressure gauge 146, the pressure gauge 147, the pressure gauge 148, the pressure gauge 149 and the computer, not shown, constitute a rotational speed changing means for changing the rotational speed of the electric motor 123 of the unit 120 and the electric motor 133 of the unit 130 at substantially the same ratio relative to the electric motor 123 of the unit 120 and the electric motor 133 of the unit 130 based on a maximum pressure of pressures of the working fluid supplied to the hydraulic motor 122 of the unit 120 and the hydraulic motor 132 of the unit 130 and the working fluid discharge pressure of the variable displacement hydraulic pump 111.

[0034] Note that the ratio at which the rotational speed of the electric motor 123 and the electric motor 133 may be a constant value at all times or a value which changes in accordance with pressures detected by the pressure gauge 145, the pressure gauge 146, the pressure gauge 147, the pressure gauge 148 and the pressure gauge 149.

[0035] Next, the operation of the electro-hydraulic actuation system according to the embodiment will be described.

[0036] Note that since the operations of the hydraulic motor 122 and the electro-hydraulic servo valve 127 are substantially similar to those of the conventional hydraulic motor and electro-hydraulic servo valve, the detailed description thereof will be omitted.

[0037] The selector valve 141 selects the port where a working fluid supplied shows a maximum pressure of the port 141a which communicates with the port 127e of the electro-hydraulic servo valve 127 of the unit and the port 141b which communicates with the port 137c of the electro-hydraulic servo valve 137 of the unit 130 and then establishes a communication between the port so selected and the port 141c.

[0038] In other words, the selector valve 141 selects a greater pressure of the pressure of the working fluid supplied to the port 127e of the electro-hydraulic servo valve 127 of the unit 120 or the load pressure of the hydraulic motor 122 of the unit 120 and the pressure of the working fluid supplied to the port 137e of the electro-hydraulic servo valve 137 of the unit 130 or the load pressure of the hydraulic motor 132 of the unit 130.

[0039] Since the selector valve 141 selects a greater pressure of the load pressure of the hydraulic motor 122 of the unit 120 and the load pressure of the hydraulic motor 132 of the unit 130, the pressure of the working fluid supplied to the port 142d of the two-position valve 142 which communicates with the port 141c of the selector valve 141 via the throttle 140a becomes the larger pressure of the load pressures of the hydraulic motor 122 and the hydraulic motor 132.

[0040] In addition, since the port 142c of the two-position valve 142 communicates with the variable displacement hydraulic pump 111, the pressure of the working fluid supplied to the port 142c of the two-posi-

tion valve 142 becomes the working fluid discharge pressure of the variable displacement hydraulic pump 111.

[0041] Then, the two-position valve 142 takes the first 5 position 142A where the port 142a which communicates with the tank 112 is made to communicate with the port 142e when the working fluid discharge pressure of the variable displacement hydraulic pump 111 becomes equal to or smaller than the pressure resulting from adding the predetermined set pressure by the spring 143 to the greater pressure of the load pressures of the hydraulic motor 122 and the hydraulic motor 132.

[0042] When the two-position valve 142 takes the first 15 position 142A, the pressure of the working fluid within the cylinder chamber 144b of the discharge volume changing hydraulic cylinder 144 which communicates with the port 142e of the two-position valve 142 via the throttle 140b becomes the pressure of the working fluid within the tank 112.

[0043] Here, since the pressure of the working fluid within the cylinder chamber 144b of the discharge volume changing hydraulic cylinder 144 which communicates with the variable displacement hydraulic pump 111 is the working fluid discharge pressure of the variable 25 displacement hydraulic pump 111, in the discharge volume changing hydraulic cylinder 144, the pressure of the working fluid within the cylinder chamber 144a becomes smaller than the pressure of the working fluid within the cylinder chamber 144b, whereby the discharge volume changing hydraulic cylinder 144 retracts to thereby increase the discharge volume of the variable displacement hydraulic pump 111.

[0044] In addition, the two-position valve 142 takes the second position 142B where the port 142b which 35 communicates with the variable displacement hydraulic pump 111 is made to communicate with the port 142e when the working fluid discharge pressure of the variable displacement hydraulic pump 111 becomes greater than the pressure resulting from adding the predetermined set pressure by the spring 143 to the greater pressure of the load pressures of the hydraulic motor 122 of the unit 120 and the hydraulic motor 132 of the unit 130.

[0045] When the two-position valve 142 takes the second position 142B, the pressure of the working fluid 45 within the cylinder chamber 144a of the discharge volume changing hydraulic cylinder 144 becomes the working fluid discharge pressure of the variable displacement hydraulic pump 111.

[0046] Here, as has been described above, since the 50 pressure of the working fluid within the cylinder chamber 144b of the discharge volume changing hydraulic cylinder 144 is the working fluid discharge pressure of the variable displacement hydraulic pump 111, in the discharge volume changing hydraulic cylinder 144, the pressure of the working fluid within the cylinder chamber 144a becomes equal to or greater than the pressure of the working fluid within the cylinder chamber 144b, whereby the discharge volume changing hydraulic cyl-

inder 144 extends to thereby decrease the discharge volume of the variable displacement hydraulic pump 111.

[0047] Thus, as has been described heretofore, the electro-hydraulic actuation system 100 changes the working fluid discharge volume of the variable displacement hydraulic pump 111 so that a differential pressure between the greater pressure of the load pressures of the hydraulic motor 122 of the unit 120 and the hydraulic motor 132 of the unit 130 and the working fluid discharge pressure of the variable displacement hydraulic pump 111 becomes the predetermined set pressure by the spring 143.

[0048] Consequently, when there occurs no shortage in volume of working fluid supplied to the hydraulic motor 122 of the unit 120 and the hydraulic motor 132 of the unit 130, a smallest pressure (hereinafter, referred to as a minimum differential pressure) of a differential pressure between a pressure detected by the pressure gauge 149 and a pressure detected by the pressure gauge 145, a differential pressure between the pressure detected by the pressure gauge 149 and a pressure detected by the pressure gauge 146, a differential pressure between the pressure detected by the pressure gauge 149 and a pressure detected by the pressure gauge 147, and a differential pressure between the pressure detected by the pressure gauge 149 and a pressure detected by the pressure gauge 148 becomes the predetermined set pressure by the spring 143.

[0049] Here, when there occurs even a slight shortage in volume of the working fluid supplied to the hydraulic motor 122 of the unit 120 and the hydraulic motor 132 of the unit 130, the pressure detected by the pressure gauge 149 or the working fluid discharge pressure of the variable displacement hydraulic pump 111 decreases, the minimum differential pressure becomes smaller than the predetermined set pressure by the spring 143.

[0050] Consequently, by determining whether or not the minimum differential pressure becomes smaller than the predetermined set pressure by the spring 143 based on pressures inputted from the pressure gauge 145, the pressure gauge 146, the pressure gauge 147, the pressure gauge 148 and the pressure gauge 149, the computer, not shown, can determine whether or not there occurs a shortage in volume of the working fluid supplied to either of the hydraulic motor 122 of the unit 120 and the hydraulic motor 132 of the unit 130.

[0051] Then, when the minimum differential pressure becomes smaller than the predetermined set pressure by the spring 143, the computer, not shown, determines that there occurs a shortage in volume of the working fluid supplied to either of the hydraulic motor 122 of the unit 120 and the hydraulic motor 132 of the unit 130 and then decreases the rotational speed of the electric motor 123 of the unit 120 and the electric motor 133 of the unit 130 at substantially the same ratio relative to the electric motor 123 and the electric motor 133.

[0052] When the computer, not shown, decreases the rotational speed of the electric motor 123 of the unit 120 and the electric motor 133 of the unit 130 at substantially the same ratio relative to the electric motor 123 and the electric motor 133, a total volume of working fluid needed to be supplied to the hydraulic motor 122 of the unit 120 and the hydraulic motor 132 of the unit 130 is decreased, and the shortage of working fluid that is occurring in either of the hydraulic motor 122 of the unit and the hydraulic motor 132 of the unit 130 can be eliminated.

[0053] As has been described heretofore, since the electro-hydraulic actuation system 100 can decrease the volume of the working fluid supplied to the hydraulic motor 122 of the unit 120 and the hydraulic motor 132 of the unit 130 at substantially the same ratio when there occurs a shortage in volume of working fluid supplied to the hydraulic motor 122 of the unit 120 and the hydraulic motor 132 of the unit 130, the occurrence of a shortage in volume of working fluid supplied to the hydraulic motor having a larger load pressure of the hydraulic motor 122 of the unit 120 and the hydraulic motor 132 of the unit 130 can be prevented.

[0054] In addition, since the electro-hydraulic actuation system 100 can decrease the volume of the working fluid supplied to the hydraulic motor 122 of the unit 120 and the hydraulic motor 132 of the unit 130 at substantially the same ratio, for example, in a case where the hydraulic motor 122 of the unit 120 is used for a right side caterpillar of a hydraulic shovel and the hydraulic motor 132 of the unit 130 is used for a left side caterpillar of the hydraulic shovel, when the operator attempts to move the hydraulic shovel straight forward by inputting substantially the same operation amounts into the unit 120 and the unit 130, even in case a load borne by the right side caterpillar becomes larger than a load borne by the left side caterpillar due to the right side caterpillar riding on a stone or the left side caterpillar entering a puddle, the movement of the right side caterpillar and the movement of the left side caterpillar can be made slower at substantially the same ratio.

[0055] Consequently, since the moving direction of the hydraulic shovel provided with the electro-hydraulic actuation system 100 is maintained while the moving speed thereof gets slower, a risk of a hydraulic shovel moving in a direction different from the direction intended by the operator can be prevented, which is the case with a hydraulic shovel provided with the conventional hydraulic actuation system 900 (refer to Fig. 22).

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(Second Embodiment)

[0056] Firstly, the configuration of an electro-hydraulic actuation system according to a second embodiment will be described.

[0057] As shown in Figs. 8 and 9, since an electro-hydraulic actuation system 300 as an electro-hydraulic actuation system according to the second embodiment

has a substantially similar configuration to that of the electro-hydraulic actuation system (refer to Fig. 1) according to the first embodiment, hereinafter, like reference numerals are imparted to constituent parts of the electro-hydraulic actuation system 300 which are substantially like to those of the electro-hydraulic actuation system 100 and the detailed description thereof will be omitted.

[0058] Instead of the unit 120 (refer to Fig. 1) and the unit 130 (refer to Fig. 1) of the electro-hydraulic actuation system 100 (refer to Fig. 1), the electro-hydraulic actuation system 300 includes an electro-hydraulic actuator 320 (refer to Figs. 10 to 14) and a unit 330, the detailed description of which will be omitted, having a similar configuration to that of the unit 320.

[0059] Instead of the hydraulic motor 122 (refer to Fig. 1) of the unit 120 (refer to Fig. 1), the unit 320 has a variable displacement hydraulic motor 322 as a hydraulic actuator having formed therein a port 322a and a port 322b which are made to communicate with a variable displacement hydraulic pump 111 or a tank 112 and adapted to impart a driving force to reduction gears 121 by virtue of the pressure of a working fluid supplied to the port 322a and the port 322b.

[0060] Here, the variable displacement hydraulic motor 322 has, as shown in Figs. 10 to 14, a box body 351, a box body 152 fixed to the box body 351, a swash plate 153, a motor shaft 154, a bearing 355 for rotatably supporting the motor shaft 154 on the box body 351, a bearing 156, a cylinder bock 157 having formed therein a plurality of cylinder chambers 157a, a plurality of pistons 158, shoe members 159, a spring 160 and a seal 162.

[0061] In addition, instead of the electro-hydraulic servo valve 127 (refer to Fig. 1) of the unit 120 (refer to Fig. 1), the unit 320 has, as shown in Figs. 8 and 9, an electro-hydraulic servo valve 327 as a fluid volume changing valve having formed therein a port 327a which communicates with the variable displacement hydraulic pump 111, a part 327b which communicates with the tank 112, a port 327c which communicates with the port 322a of the variable displacement hydraulic motor 322, a part 327d which communicates with the port 322b of the variable displacement hydraulic motor 322, a port 327e and a port 327f, adapted to take any of a first position 327A, a second position 327B and a third position 328C based on the rotating amount of a second toothed shaft 125 and the driving amount of an electric motor 123 and adapted to change the volume of a working fluid discharged by the variable displacement hydraulic pump 111 for supply to the variable displacement hydraulic motor 322.

[0062] Note that the first position 327A is a position where the port 327a is made to communicate with the port 327c and the port 327e and a communication of the port 327b with the port 327d and the port 327f is established, the second position 327B is a position where the communication with the port 327a, the port 327b, the port 327c, the port 327d, the port 327e and the port 327f

is cut off, and the third position 327C is a position where the port 327a is made to communicate with the port 327d and the port 327f and a communication of the port 327d with the port 327c and the port 327e is established.

[0063] Here, as shown in Figs. 10 to 14, the electro-hydraulic servo valve 327 has a box body 151, a moving body 171 for changing the communication of the port 327a, the port 327b, the port 327c, the port 327d, the port 327e and the port 327f, a bearing 172 for transmitting an axial movement of the second toothed shaft 125 to the moving body 171 and a cap 173, a cap 174 and a seal 175 which prevent the leakage of a working fluid from the inside to the outside of the box body 151.

[0064] Note that the unit 320 has a bearing 361 and a bearing 362 which rotatably support a first toothed shaft 124 relative to the box body 151.

[0065] In addition, as shown in Figs. 8 and 9, the unit 320 has a load pressure selector valve 328 having formed therein a port 328a which communicates with the port 327c of the electro-hydraulic servo valve 327, a port 328b which communicates with the port 327d of the electro-hydraulic servo valve 327, a part 328c which communicates with the port 327e of the electro-hydraulic servo valve 327, a port 328d which communicates with the port 327f of the electro-hydraulic servo valve 327, a port 328e which communicates with the tank 112 and a port 328f which communicates with a port 141a of a selector valve 141, adapted to take any of the first position 328A, the second position 328B and the third position 328C based on the pressure of a working fluid supplied to the port 328c and the port 328d and adapted to make either of the port 328a and the port 328b to which a working fluid having a greater pressure is supplied communicate with the port 328e for selection of the load pressure of the variable displacement hydraulic motor 322.

[0066] Note that the first position 328A is a position where the port 328a is made to communicate with the port 328f and the communication between the port 328b and the port 328e is cut off, the second position 328B is a position where the communication of the port 328a and the port 328b is cut off and the port 328e is made to communicate with the port 328f, and the third position 328C is a position where the communication of the port 328a and the port 328e are cut off and the port 328b is made to communicate with the port 328f.

[0067] Here, the load pressure selector valve 328 has, as shown in Figs. 10 to 14, the box body 151, a moving body 371 for changing the communication of the port 328a, the port 328b, the port 328c, the port 328d, the port 328e and the port 328f, a spring 329a for biasing the moving body 371 so that the moving body 371 is located at a first position 328A (refer to Fig. 9), a spring 329b for biasing the moving body 371 so that the moving body is located at a third position 328C (refer to Fig. 9) and a cap 372 and a cap 373 which prevent the leakage of the working fluid from the inside to the outside of the box body 151.

[0068] Note that the electro-hydraulic servo valve 327 of the unit 320, the load pressure selector valve 328, an electro-hydraulic servo valve 337 of the unit 330, a load pressure selector valve 338, a selector valve 141, a spring 142 and a discharge volume changing hydraulic cylinder 144 constitutes a discharge volume changing means for changing the working fluid discharge volume of the variable displacement hydraulic pump 111 based on a maximum pressure of pressures of the working fluid supplied to the variable displacement hydraulic motor 322 of the unit 320 and a variable displacement hydraulic motor 332 of the unit 330 and the working fluid discharge pressure of the variable displacement hydraulic pump 111.

[0069] Next, the operation of the electro-hydraulic actuation system according to the embodiment will be described.

[0070] Note that the detailed description of those of operations of the electro-hydraulic actuation system 300 according to the embodiment will be omitted which are substantially similar to the operations of the electro-hydraulic actuation system 100 (refer to Fig. 1) according to the first embodiment.

[0071] The load pressure selector valve 328 takes the first position 328A where a communication of the port 328a and the port 328f is established when the pressure of the working fluid supplied to the port 328c is greater than the pressure of the working fluid supplied to the port 328d, and takes a second position 328B when the pressure of the working fluid supplied to the port 328c is the same as the pressure of the working fluid supplied to the port 328d, and takes the third position 328C where a communication of the port 328b and the port 328f is established when the pressure of the working fluid supplied to the port 328c is smaller than the pressure of the working fluid supplied to the port 328d.

[0072] In addition, the electro-hydraulic servo valve 327 allows the port 327c which communicates with the port 328a of the load pressure selector valve 328 to communicate with the port 327e which communicates with the port 328c of the load pressure selector valve 328 when the electro-hydraulic servo valve 327 makes the port 327a which communicates with the variable displacement hydraulic pump 111 or the port 327b which communicates with the tank 112 communicate with the port 327c, and allows the port 327d which communicates with the port 328d of the load pressure selector valve 328 to communicate with the port 327f which communicates with the port 328d of the load pressure selector valve 328 when the electro-hydraulic servo valve 327 makes the port 327a or the port 327b communicate with the port 327d.

[0073] Consequently, the pressure of the working fluid supplied to the port 328f of the load pressure selector valve 328 or the pressure of the working fluid supplied to a port 141a of the selector valve 141 becomes the load pressure of the variable displacement hydraulic motor 322 of the unit 320.

[0074] Similarly, the pressure of a working fluid supplied to a port 338f of the load pressure selector valve 338 or the pressure of a working fluid supplied to a port 141b of the selector valve 141 becomes the load pressure of the variable displacement hydraulic motor 332 of the unit 330.

[0075] Since the pressure of the working fluid supplied to the port 141a of the selector valve 141 becomes the load pressure of the variable displacement hydraulic motor 322 of the unit 320 and the pressure of the working fluid supplied to the port 141b of the selector valve 141 becomes the load pressure of the variable displacement hydraulic motor 332 of the unit 330, as has been described in the first embodiment, the electro-hydraulic actuation system 300 can change the working fluid discharge volume of the variable displacement hydraulic pump 111 so that a differential pressure between a larger load pressure of the load pressures of the variable displacement hydraulic motor 322 of the unit 320 and the variable displacement hydraulic motor 332 of the unit 330 and the working fluid discharge pressure of the variable displacement hydraulic pump 111 becomes a predetermined set pressure by the spring 143.

25 (Third Embodiment)

[0076] Firstly, the configuration of an electro-hydraulic actuation system according to a third embodiment will be described.

[0077] As shown in Figs. 15 and 16, since an electro-hydraulic actuation system 500 as an electro-hydraulic actuation system according to the embodiment has a configuration which is substantially similar to that of the electro-hydraulic actuation system 100 (refer to Fig. 1) according to the first embodiment or the electro-hydraulic actuation system 300 (refer to Fig. 8) according to the second embodiment, hereinafter, like reference numerals are imparted to constituent parts of the electro-hydraulic actuation system 500 which are substantially like to those of the electro-hydraulic actuation system 100 or the electro-hydraulic actuation system 300, and the detailed description thereof will be omitted.

[0078] The electro-hydraulic actuation system 500 includes, as electro-hydraulic actuators, a unit 520 (refer to Figs. 17 to 20) and a unit 530, the detailed description of which will be omitted, having a similar configuration to that of the unit 520, instead of the unit 120 (refer to Fig. 1) and the unit 130 (refer to Fig. 1) of the electro-hydraulic actuation system 100 (refer to Fig. 1).

[0079] The unit 520 has, instead of the electro-hydraulic servo valve 127 of the unit 120 (refer to Fig. 1), an electro-hydraulic servo valve 527 as a fluid volume changing valve having formed therein a port 527a which communicates with a variable displacement hydraulic pump 111, a port 527b which communicates with a tank 112, a port 527c which communicates with a port 122a of a hydraulic motor 122 and a port 527d which communicates with a port 122b of the hydraulic motor 122,

adapted to take any of a first position 527A, a second position 527B and a third position 527C based on the rotating amount of a second toothed shaft 125 and the driving amount of an electric motor 123 and adapted to change the volume of a working fluid discharged by the variable displacement hydraulic pump 111 for supply to the hydraulic motor 122.

[0080] Note that the first position 527A is a position where the port 527a is made to communicate with the port 527c, and the port 527b is made to communicate with the port 527d, the second position 527B is a position where the communication of the port 527a, the port 527b, the port 527c and the port 527d is cut off, and the third position 527C is a position where the port 527a is made to communicate with the port 527d, and the port 527b is made to communicate with the port 527c.

[0081] Here, as shown in Figs. 17 to 20, the electro-hydraulic servo valve 527 has a box body 151, a moving body 171 for changing the communication of the port 527a, the port 527b, the port 527c and the port 527d, a bearing 172 for transmitting an axial movement of the second toothed shaft 125 to the moving body 171 and a cap 173, a cap 174 and a seal 175 which prevent the leakage of a working fluid from the inside to the outside of the box body 151.

[0082] In addition, as shown in Fig. 15, the electro-hydraulic actuation system 500 includes a two-position electromagnetic valve 514 having formed therein a port 514a which communicates with a relief valve 113 and a port 514b which communicates with the tank 112 and adapted to take either of a first position 514A where the communication of the port 514a and the port 514b is cut off based on a signal inputted and a second position 514B where the communication of the port 514a and the port 514b is established.

[0083] In addition, instead of the selector valve 141 (refer to Fig. 1 or 8) of the electro-hydraulic actuation system 100 (refer to Fig. 1) or the electro-hydraulic actuation system 300 (refer to Fig. 8), the electro-hydraulic actuation system 500 includes a pressure setting valve 545 for setting a pressure for a working fluid supplied to a port 142d of a two-position valve 142 by being switched between a position where a working fluid discharged by the variable displacement hydraulic pump 111 is led to the port 142d of the two-position valve 142 via a throttle 140a and a position where the working fluid discharged by the variable displacement hydraulic pump 111 is led to the tank 112 based on the pressure of the working fluid supplied to the port 142d of the two-position valve 142 and a signal inputted via a signal wire 545a.

[0084] Additionally, a computer, not shown, of the electro-hydraulic actuation system 500 is configured to receive pressures detected by a pressure gauge 145, a pressure gauge 146, a pressure gauge 147, a pressure gauge 148 and a pressure gauge 149 for input thereinto, change the rotational speed of the electric motor 123 of the unit 520 and an electric motor 133 of the unit 530 at

substantially the same ratio relative to the electric motor 123 and the electric motor 133 based on the pressures so inputted, produce a signal based on the inputted pressures and input the signal so produced into the two-position electromagnetic valve 514.

[0085] Furthermore, the computer, not shown, is configured to select a driving side pressure while following the motor rotating direction of the hydraulic motors 122 and 132 based on values of the pressures inputted from the pressure gauge 145, the pressure gauge 146, the pressure gauge 147 and the pressure gauge 148, select a greatest pressure of the pressures of the hydraulic motor 122 and the hydraulic motor 132 and input the pressure so selected into the pressure setting valve 545 as a signal via the signal wire 545a.

[0086] Here, the pressure gauge 145, the pressure gauge 146, the pressure gauge 147, the pressure gauge 148, the pressure gauge 149, the computer, not shown, the pressure setting valve 545, the two-position valve 142, a spring 143 and a discharge volume changing hydraulic cylinder 144 constitutes a discharge volume changing means for changing the working fluid discharge volume of the variable displacement hydraulic pump 111 based on the greatest pressure of the pressures of the working fluid supplied to the hydraulic motor 122 of the unit 520 and the hydraulic motor 132 of the unit 530 and the working fluid discharge pressure of the variable displacement hydraulic pump 111.

[0087] Next, the operation of the electro-hydraulic actuation system according to the embodiment will be described.

[0088] Note that the detailed description of those of operations of the electro-hydraulic actuation system 500 according to the embodiment will be omitted which are substantially similar to the operations of the electro-hydraulic actuation system 100 (refer to Fig. 1) according to the first embodiment.

[0089] The computer, not shown, selects a driving side pressure while following the motor rotating direction of the hydraulic motors 122 and 132 based on values of the pressures inputted from the pressure gauge 145, the pressure gauge 146, the pressure gauge 147 and the pressure gauge 148, selects a greatest pressure of the pressures of the hydraulic motor 122 and the hydraulic motor 132 and inputs the pressure so selected into the pressure setting valve 545 as a signal via the signal wire 545a.

[0090] When the signal is inputted thereinto by the computer, not shown, the pressure setting valve 545 produces a force in accordance with the signal so inputted and changes positions based on the force so produced and the pressure of the working fluid supplied to the port 142d of the two-position valve 142.

[0091] To be specific, when the force produced in accordance with the signal inputted is greater than a force produced by virtue of the pressure of the working fluid supplied to the port 142d of the two-position valve 142, the pressure setting valve 545 is switched to a position

where the working fluid discharged by the variable displacement hydraulic pump 111 is led to the port 142d of the two-position valve 142 via the throttle 140a and when the force produced in accordance with the signal inputted is equal to or smaller than the force produced by virtue of the pressure of the working fluid supplied to the port 142d of the two-position valve 142, the pressure setting valve 545 is switched to a position where the working fluid discharged by the variable displacement hydraulic pump 111 is led to the tank 112.

[0092] Here, the pressure setting valve 545 is configured to produce a force which allows the computer, not shown, to implement a feedback using the pressure from the pressure gauge 149 so that the pressure of the working fluid supplied to the port 142d of the two-position valve 142 becomes a sum of the pressure selected from the hydraulic motor 122 of the unit 520 and the hydraulic motor 132 of the unit 530 and a pressure allowance that is determined in advance.

[0093] Consequently, the pressure of the working fluid supplied to the port 142d of the two-position valve 142 becomes substantially the same as the sum of the pressure selected from the hydraulic motor 122 of the unit 520 and the hydraulic motor 132 of the unit 530 and the pressure allowance that is determined in advance, and as has been described in the first embodiment, the electro-hydraulic actuation system 500 can change the working fluid discharge volume of the variable displacement hydraulic pump 111 so as to become the sum of the greater pressure of the pressures of the hydraulic motor 122 of the unit 520 and the hydraulic motor 132 of the unit 530 and the pressure allowance that is determined in advance.

[0094] In addition, as has been described in the first embodiment, when determining that there has occurred a shortage in volume of the working fluid supplied to either of the hydraulic motor 122 of the unit 520 and the hydraulic motor 132 of the unit 530 based on the pressures inputted from the pressure gauge 145, the pressure gauge 146, the pressure gauge 147, the pressure gauge 148 and the pressure gauge 149, the computer, not shown, generates a signal which locates the two-position electromagnetic valve 514 at the first position 514A and inputs the signal so generated into the two-position electromagnetic valve 545.

[0095] When the two-position electromagnetic valve 514 is located at the first position 514A in response to the signal inputted from the computer, not shown, since the set pressure of the relief valve 113 becomes largest within a designed range, the pressure of the working fluid discharged by the variable displacement hydraulic pump 111 for supply to the unit 520 and the unit 530 can be increased to a set pressure of the relief valve 113 which is greatest within the designed range.

[0096] In addition, as has been described in the first embodiment, when determining that there has occurred a shortage in volume of the working fluid supplied to either of the hydraulic motor 122 of the unit 520 and the

hydraulic motor 132 of the unit 530 based on the pressures inputted from the pressure gauge 145, the pressure gauge 146, the pressure gauge 147, the pressure gauge 148 and the pressure gauge 149, the computer,

5 not shown, reduces the rotational speed of the electric motor 123 and the electric motor 133 at the same or a predetermined ratio, thereby making it possible to prevent a state in which the volume of working fluid is short.

[0097] In addition, when determining that there is occurring no shortage in volume of the working fluid supplied to the hydraulic motor 122 of the unit 520 and the hydraulic motor 132 of the unit 530 based on the pressures inputted from the pressure gauge 145, the pressure gauge 146, the pressure gauge 147, the pressure gauge 148 and the pressure gauge 149, the computer, not shown, produces a signal which locates the two-position electromagnetic valve 514 at the second position 514B and inputs the signal so produced to the two-position electromagnetic valve 514.

[0098] When the two-position electromagnetic valve 514 is located at the second position 514B in response to the signal inputted from the computer, not shown, since the set pressure of the relief valve 113 becomes smallest within the designed range, the pressure of the working fluid discharged by the variable displacement hydraulic pump 111 for supply to the unit 520 and the unit 530 can only be increased to a set pressure of the relief valve 113 which is smallest within the designed range.

[0099] Consequently, when there is occurring no shortage in volume of the working fluid supplied to the hydraulic motor 122 of the unit 520 and the hydraulic motor 132 of the unit 530, the electro-hydraulic actuation system 500 can suppress the pressure of working fluid discharged by the variable displacement hydraulic pump 111 for supply to the unit 520 and the unit 530 to the set pressure of the relief valve 113 which is the smallest within the designed range or smaller and can reduce energy consumed by the variable displacement hydraulic pump 111 when compared with a case where the two-position electromagnetic valve 514 is provided. In addition, in a state where the rotational speed inputted is 0, the computer, not shown, outputs to the pressure setting valve 545 a signal which makes the discharge pressure

35 of the variable displacement hydraulic pump 111 become a predetermined low pressure based on the pressure of the pressure gauge 149, thereby making it possible to reduce energy consumed. Additionally, in the state where the rotational speed inputted is 0, the computer, not shown, outputs to the pressure setting valve 545 a signal which makes the discharge pressure of the variable displacement hydraulic pump 111 become a predetermined low pressure based on the pressure of the pressure gauge 149, thereby making it possible to

40 50 55 reduce energy consumed.

(Fourth Embodiment)

[0100] Firstly, the configuration of an electro-hydraulic actuation system according to a fourth embodiment will be described.

[0101] As shown in Fig. 21, since an electro-hydraulic actuation system 600 as an electro-hydraulic actuation system according to the embodiment has a substantially similar configuration to that of the electro-hydraulic actuation system 500 (refer to Fig. 15) according to the third embodiment, hereinafter, like reference numerals are imparted to constituent parts of the electro-hydraulic actuation system 600 which are substantially like to those of the electro-hydraulic actuation system 500.

[0102] The electro-hydraulic actuation system 600 includes, instead of the two-position electromagnetic valve 514 (refer to Fig. 15) of the electro-hydraulic actuation system 500 (refer to Fig. 15), a two-position electromagnetic valve 614 having formed therein a port 614a which communicates with a variable displacement hydraulic pump 111, a unit 520 and a unit 530, a port 614b which communicates with a tank 112 and a port 614c which communicates with a relief valve 113 and adapted to take based on a signal inputted either of a first position where the communication of the port 614a and the port 614b is established and a second position where the communication of the port 614a and the port 614c is established.

[0103] In addition, a computer, not shown, of the electro-hydraulic actuation system 600 is configured to receive pressures detected by a pressure gauge 145, a pressure gauge 146, a pressure gauge 147, a pressure gauge 148 and a pressure gauge 149 for input thereinto, produce a signal based on the pressures inputted and input the signal produced into the two-position electromagnetic valve 614.

[0104] Next, the operation of the electro-hydraulic actuation system 600 according to the invention will be described.

[0105] Note that the detailed description of those of operations of the electro-hydraulic actuation system 600 will be omitted which are substantially similar to the operations of the electro-hydraulic actuation system 500 (refer to Fig. 15) according to the third embodiment.

[0106] As has been described in the first embodiment, when determining that there has occurred a shortage in volume of the working fluid supplied to either of the hydraulic motor 122 of the unit 520 and the hydraulic motor 132 of the unit 530 based on the pressures inputted from the pressure gauge 145, the pressure gauge 146, the pressure gauge 147, the pressure gauge 148 and the pressure gauge 149, the computer, not shown, generates a signal which locates the two-position electromagnetic valve 614 at the second position 614B and inputs the signal so generated into the two-position electromagnetic valve 614.

[0107] When the two-position electromagnetic valve 614 takes the second position 614B in response to the

signal inputted from the computer, not shown, since the port 614a which communicates with the variable displacement hydraulic pump 111, the unit 520 and the unit 530 communicates with the port 614c which communicates with the relief valve 113, the pressure of a working fluid discharged by the variable displacement hydraulic pump 111 for supply to the unit 520 and the unit 530 can be increased to a set pressure for the relief valve 113.

[0108] In addition, when determining that there is occurring no shortage in volume of the working fluid supplied to the hydraulic motor 122 of the unit 520 and the hydraulic motor 132 of the unit 530 based on the pressures inputted from the pressure gauge 145, the pressure gauge 146, the pressure gauge 147, the pressure gauge 148 and the pressure gauge 149, the computer, not shown, generates a signal which locates the two-position electromagnetic valve 614 at the first position 614A and inputs the signal so generated into the two-position electromagnetic valve 614.

[0109] When the two-position electromagnetic valve 614 takes the first position 614A in response to the signal inputted from the computer, not shown, since the port 614a which communicates with the variable displacement hydraulic pump 111, the unit 520 and the unit 530 communicates with the port 614b which communicates with the tank 112, the pressure of the working fluid discharged by the variable displacement hydraulic pump 111 for supply to the unit 520 and the unit 530 is reduced when compared to the case where the two-position electromagnetic valve 614 takes the second position 614B.

[0110] Consequently, the electro-hydraulic actuator system 600 can suppress the pressure of the working fluid discharged by the variable displacement hydraulic pump 111 for supply to the unit 520 and the unit 530 when there is occurring no shortage in volume of the working fluid supplied to the hydraulic motor 122 of the unit 520 and the hydraulic motor 132 of the unit 530 to a smaller value when compared with when there is occurring a shortage in volume of the working fluid supplied to the hydraulic motor 122 of the unit 520 and the hydraulic motor 132 of the unit 530 and can reduce energy consumed by the variable displacement hydraulic pump 111 when compared with a case where the two-position electromagnetic valve 614 is not provided.

Industrial Application

[0111] As has been described heretofore, the liquid pump according to the invention is a liquid pump for discharging a liquid from a liquid storage portion to at least one predetermined position and is configured to have at least one cylinder chamber formed for induction of the liquid thereinto from the liquid storage portion, a piston disposed in the cylinder chamber, a liquid discharge port formed in the cylinder chamber and a driving means for driving the piston so as to drive, in turn, a cylinder in axial directions within the cylinder chamber. By this con-

figuration, for example, it can be ensured that a required constant and minute volume of lubricating oil is supplied to bearings and gears, the heat generation at the supply points can be suppressed, and the power consumed by the apparatus can be suppressed to a lower level.

[0112] In the liquid pump according to the invention, the piston is inserted from one end portion of the cylinder chamber, and the liquid discharge port is disposed at the other end portion of the cylinder chamber. By adopting the configuration like this, a minute volume of liquid can be discharged, the discharge amount can be adjusted finely, the pump can instantaneously be stopped to stop the flow of the liquid, and the operation can be controlled so as to enable the intermittent discharge of the liquid.

[0113] In the liquid pump according to the invention, a pair of cylinder chambers is disposed at both ends of the piston, a piston is inserted from one end of each cylinder chamber, and a liquid discharge port is opened in the other end of each cylinder chamber.

[0114] By adopting the configuration like this, liquid can be supplied to two locations per one piston.

[0115] In the liquid pump according to the invention, in the piston and the cylinder chamber, the cross-sectional shape and/or length is optimized in accordance with the supply volume of liquid. By adopting the configuration like this, the volume of fluid supplied can be adjusted even in case the operation frequency of the piston is identical. In addition, even in case the plurality of cylinder chambers and the pistons are operated at the same frequency, the supply volume of fluid per cylinder chamber can be altered.

[0116] In the liquid pump according to the invention, the piston is inserted into the cylinder chamber, and a single or a plurality of liquid discharge ports are formed in the cylinder chamber. By adopting the configuration like this, liquid can be supplied to a plurality of locations or two or more locations per piston.

[0117] In the liquid pump according to the invention, a construction is adopted in which a single or a plurality of stepped portions are formed in the cylinder chamber, the piston is formed so as to have a substantially equal shape to that of the cylinder chamber, and a liquid discharge port is disposed at the single or each of the plurality of stepped portions formed in the cylinder chamber. By adopting the configuration like this, liquid can be supplied to a plurality of locations or two or more locations per piston with the simple construction.

[0118] In the liquid pump according to the invention, the single or the plurality of stepped portions in the cylinder chamber are formed in such a manner as to be substantially symmetrical in the axial direction, the piston is formed into a substantially equal shape to the formation of the substantially symmetrical stepped portions, and a liquid discharge port is formed in the single or each of the plurality of stepped portions formed in the cylinder chamber. By adopting the configuration like this, liquid can be supplied to a plurality of locations or

two or more locations per piston with the simple construction.

[0119] In the liquid pump according to the invention, a member is disposed for forming the single or the plurality of stepped portions substantially symmetrically in the cylinder chamber. By adopting the configuration like this, after the piston having the symmetrical stepped portions is inserted into the cylinder chamber, the member for forming the substantially symmetrical stepped portions is disposed, whereby the assembly can be facilitated.

[0120] In the liquid pump according to the invention, as to the shape of a liquid reservoir defined between the cylinder chamber and the piston, the relative axial length of the cylinder chamber and the piston and/or cross sectional areas thereof which are normal to their axes are optimized in accordance with the volume of liquid supplied. By adopting the configuration like this, even in case the operation frequency of the piston is identical, the volume of fluid supplied can be adjusted. In addition, even in case the plurality of cylinder chambers and the pistons are operated at the same frequency, the supply volume of fluid per cylinder chamber can be altered.

[0121] In the liquid pump according to the invention, a liquid bleeder hole is provided in the cylinder chamber. By adopting the configuration like this, a liquid stored between the end portion of the piston and the cylinder chamber can be removed, when the piston is driven, so that the motion of the piston is not disturbed.

[0122] In the liquid pump according to the invention, a plurality of constructions are disposed in series in which a single or a plurality of stepped portions are formed in a hollow portion of the cylinder chamber and a cross-sectional area of each stepped portion which is normal to the axis thereof is gradually increased as it extends along the axial direction thereof. By adopting the configuration like this, liquid can be supplied to a plurality of locations or two or more locations per piston with the simple construction.

[0123] In the liquid pump according to the invention, the piston and the cylinder chamber are provided in a plural number for a single driving means. By adopting the configuration like this, there is no need to provide a plurality of driving means for moving the pluralities of pistons and cylinder chambers, thereby making it possible to reduce the number of components.

[0124] In the liquid pump according to the invention, the driving means is made up of a solenoid which is made up of, in turn, a shaft portion which is wholly or partially made of a magnetic material and a solenoid coil which are adapted to move relative to each other, the shaft portion and the solenoid coil are separated by a bulkhead so that the shaft portion and the solenoid coil are not in contact with each other, and the shaft portion and the piston are made to interlock with each other by a predetermined connecting means. By adopting the configuration like this, even in the event that the shaft portion and the piston, which are driving portions of the

liquid pump, is submerged in a liquid within a completely sealed space, since the shaft portion and the piston can be operated in a non-contact fashion by the solenoid coil from the outside, the leakage of liquid from the liquid piston pump can be prevented. Namely, by the invention, a rotating shaft of a rotary pump is eliminated, and rotary and sliding motions at an O ring for separating the liquid from the external atmosphere and a shaft seal portion are eliminated, whereby it is possible to eliminate the possibility of leakage of liquid from the shaft portion or intrusion of air into a lubricating path when the lubricating path is in a vacuum state.

[0125] In the liquid pump according to the invention, a bulkhead made of a non-magnetic material is used for the bulkhead. By adopting the configuration like this, a magnetic field produced in the solenoid coil is allowed to pass only a plunger made of a magnetic material, thereby making it possible to increase an attractive force between the plunger and a base.

[0126] In the liquid pump according to the invention, the solenoid is used as the driving means, and furthermore, the liquid pump is used as a lubricating oil circulating pump, whereby portions needing lubrication and lubricating paths, and a lubricating oil discharge main part of the lubricating oil circulating pump are sealed. By adopting the configuration like this, the portions where lubricating oil is circulated and the piston, which is a sliding part of the lubricating oil circulating pump, and the driving portion therefor can be sealed, whereby no seal is needed at portions where sliding or/and rotating motions occur, thereby making it possible to reduce the possibility of lubricating oil leakage. In particular, the lubricating oil circulating portion resides in a vacuum, it is possible to eliminate as much as possible a concern that outside air intrudes from seals at the sliding or/and rotating portions to thereby deteriorate the degree of vacuum.

[0127] In the liquid pump according to the invention, in an apparatus having rotating portions needing lubricating oil for lubrication of bearings, a lubricating storage tank for storing lubricating oil, which is in communication for induction of the lubricating oil thereinto, is formed, and a lubricating oil supply pump and supply paths are disposed in the apparatus having rotating portions for supplying the oil from the lubricating oil storage tank to predetermined portions such as the bearings and gears. By adopting the configuration like this, the necessity of rotating shafts and gears being submerged in the lubricating oil is obviated, whereby the resistance can be reduced which would occur when the apparatus is driven, thereby making it possible to attain saving energy. As the apparatus having the configuration, there are raised rotary vacuum pumps and reduction gears.

[0128] The apparatus having rotating portions according to the invention is characterized in that the main part for discharging a lubricating oil of the lubricating oil supply pump is formed integrally in the lubricating oil storage tank. By adopting the configuration like this,

there is no need to provide a means for supplying a lubricating oil to the lubricating oil supply pump, and furthermore, a space where the lubrication oil supply pump is disposed can also be reduced.

5 **[0129]** In the apparatus having rotating portions according to the invention, the lubricating oil storage tank is disposed at a position where the lubricating oil in the apparatus having rotating portions flows into by virtue of its own gravity. By adopting this configuration, there 10 is no need to provide a complex means for returning the lubricating oil to the lubricating oil storage tank.

[0130] In the apparatus having rotating portions according to the invention, the liquid pumps set forth in 15 Claims 1 to 15 are used as the pump. By adopting this configuration, a simple and easy construction can be attained.

Claims

20 1. An electro-hydraulic actuation system being characterized by comprising a pump, a plurality of electro-hydraulic actuators each having an electric motor, a hydraulic actuator and a fluid volume changing 25 valve for changing the volume of a fluid discharged by the pump based on driving amounts of the electric motor and the hydraulic actuator for supply to the hydraulic actuator, discharge volume changing 30 means for changing the volume of the fluid discharged by the pump based on a maximum pressure of pressures of the fluid supplied to the hydraulic actuators of the plurality of electro-hydraulic actuators and the discharge pressure of the fluid discharged by the pump, and rotational speed changing 35 means for changing the rotational speed of the electric motors of the plurality of electro-hydraulic actuators at substantially the same ratio relative to the electric motors of the plurality of electro-hydraulic actuators based on a maximum pressure of pressures of the fluid supplied to the hydraulic actuators of the plurality of electro-hydraulic actuators and the discharge pressure of the fluid discharged by the 40 pump.

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FIG. 1

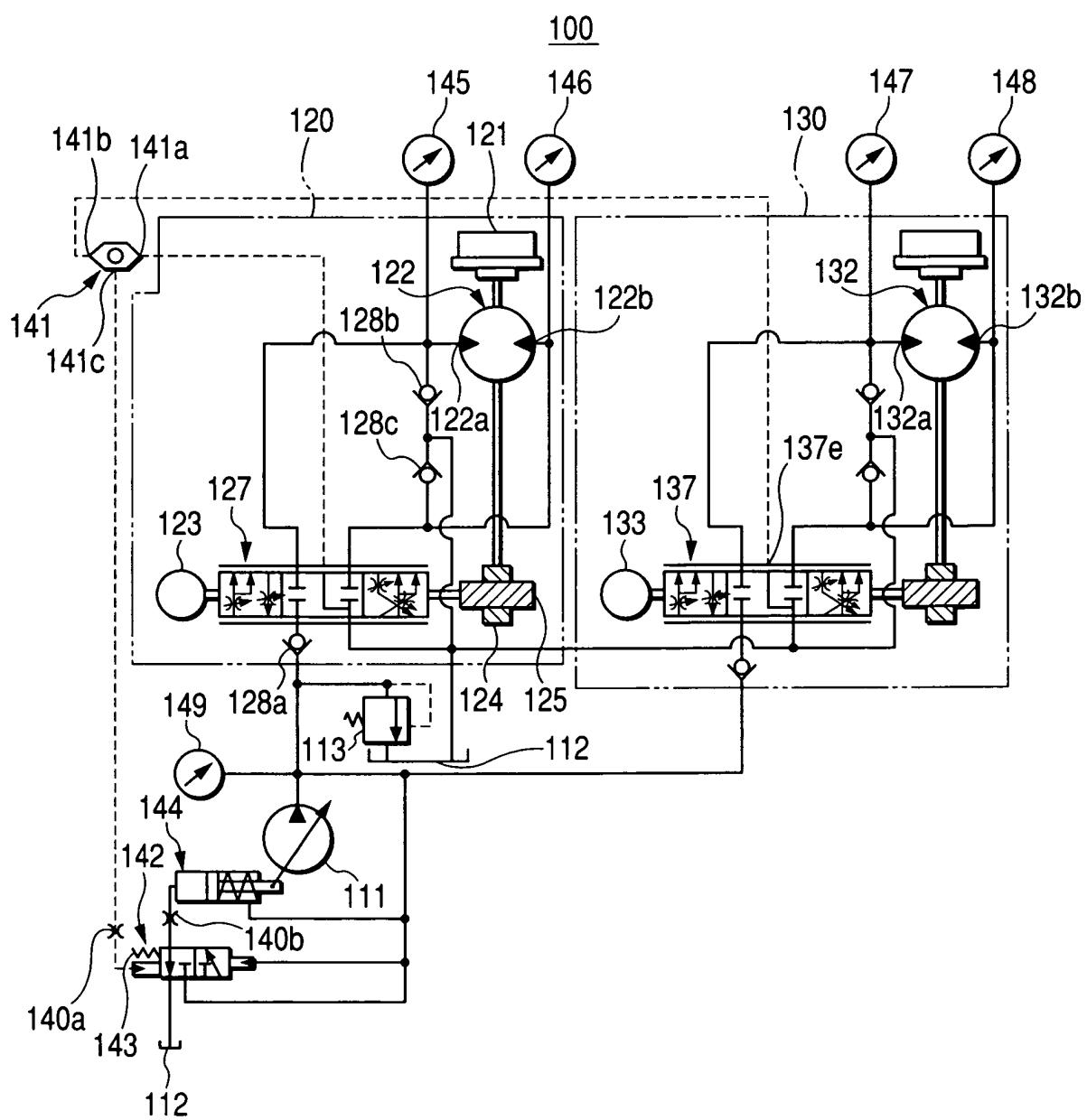


FIG. 2

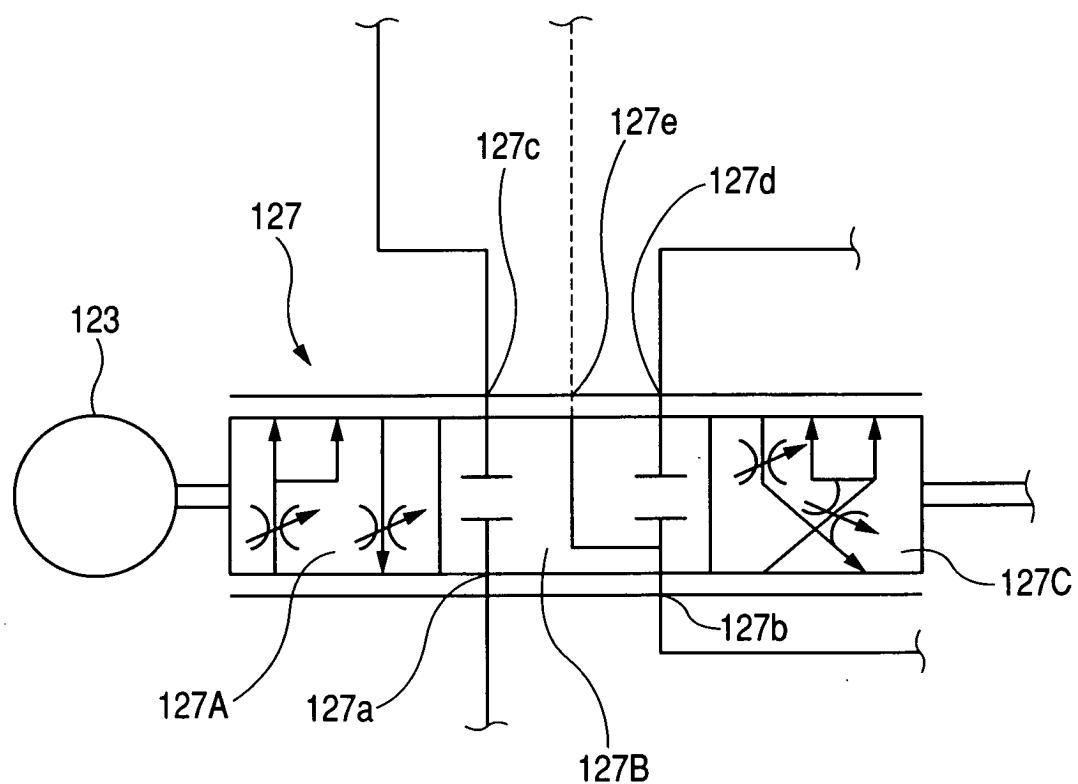


FIG. 3

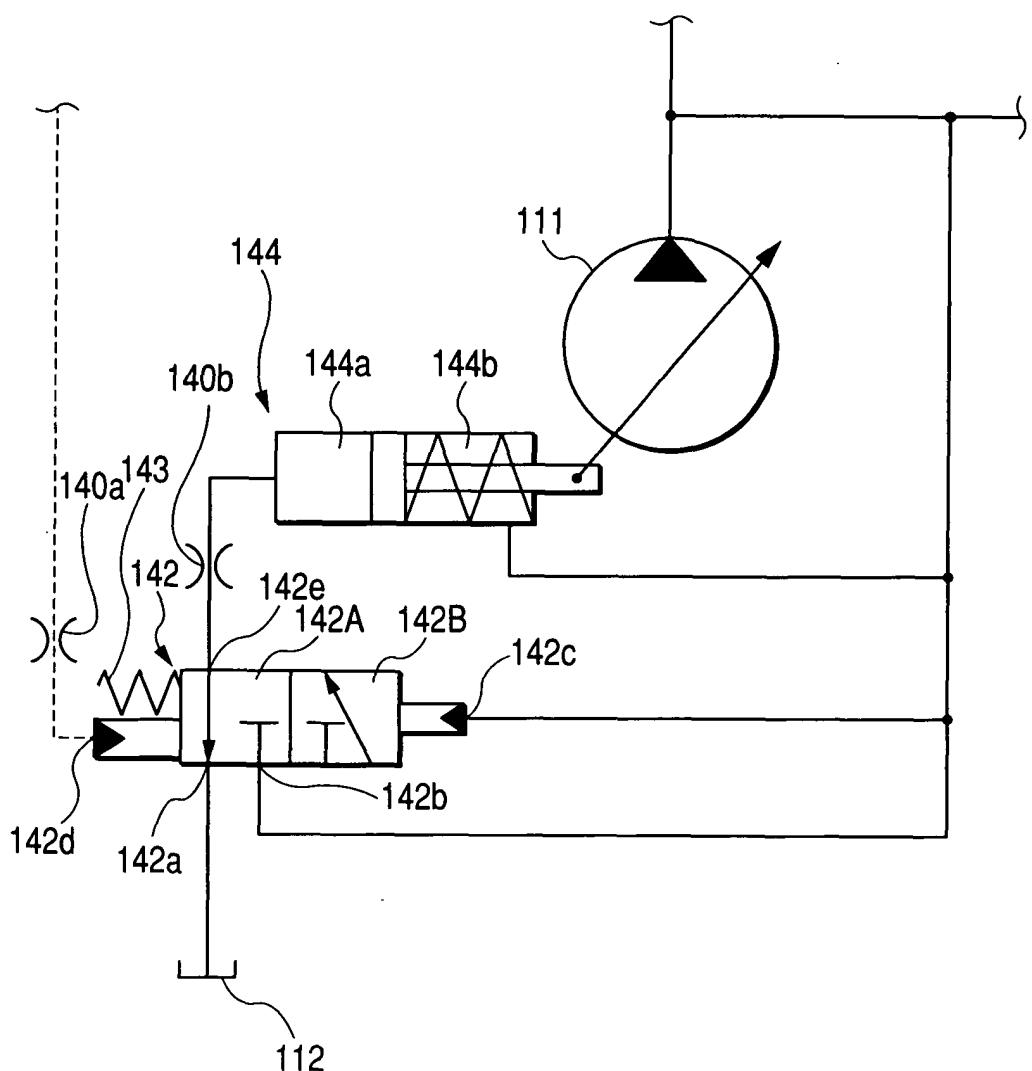


FIG. 4

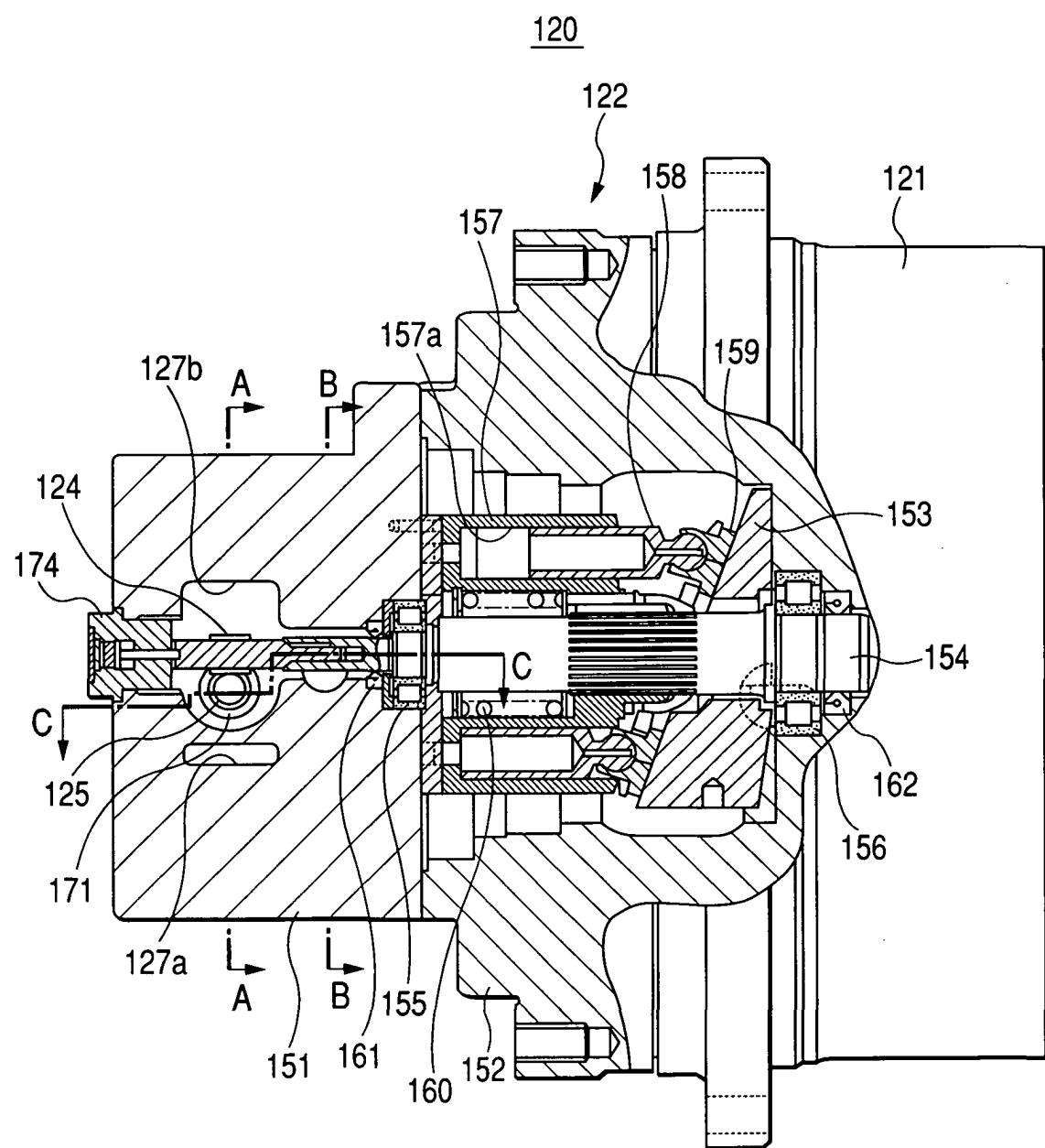


FIG. 5

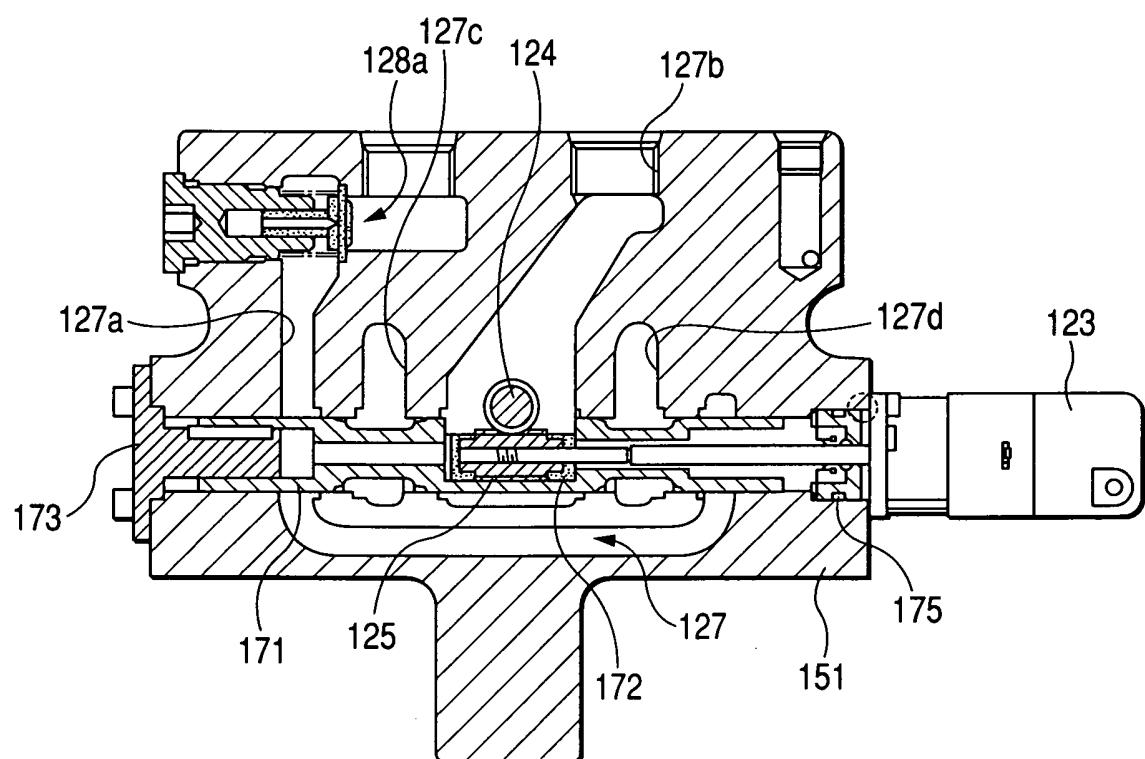


FIG. 6

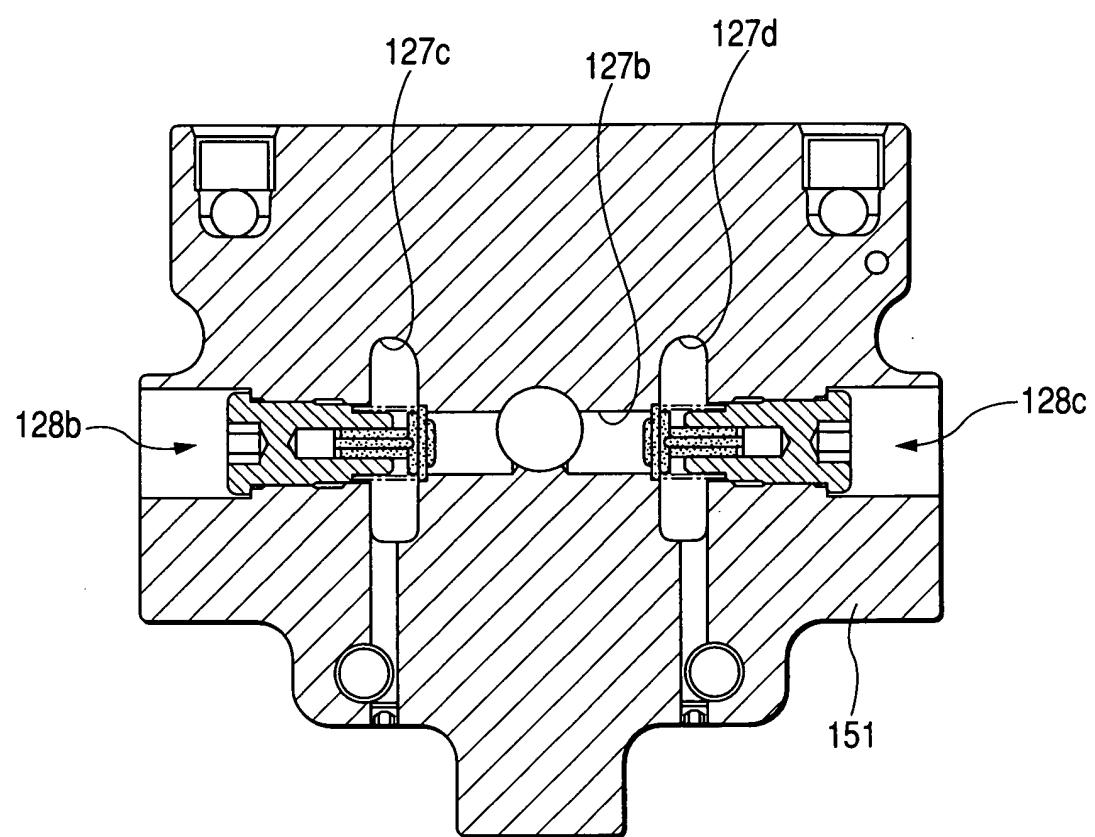


FIG. 7

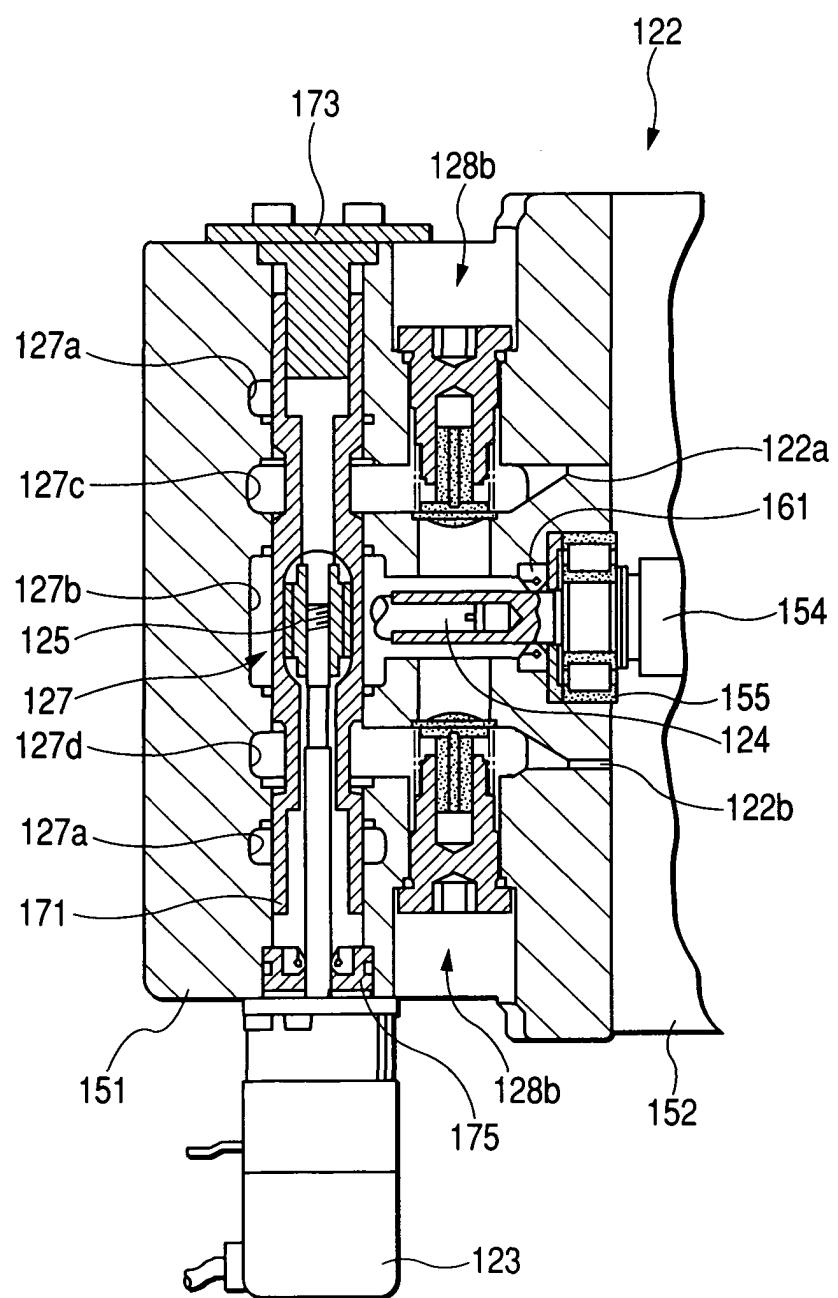


FIG. 8

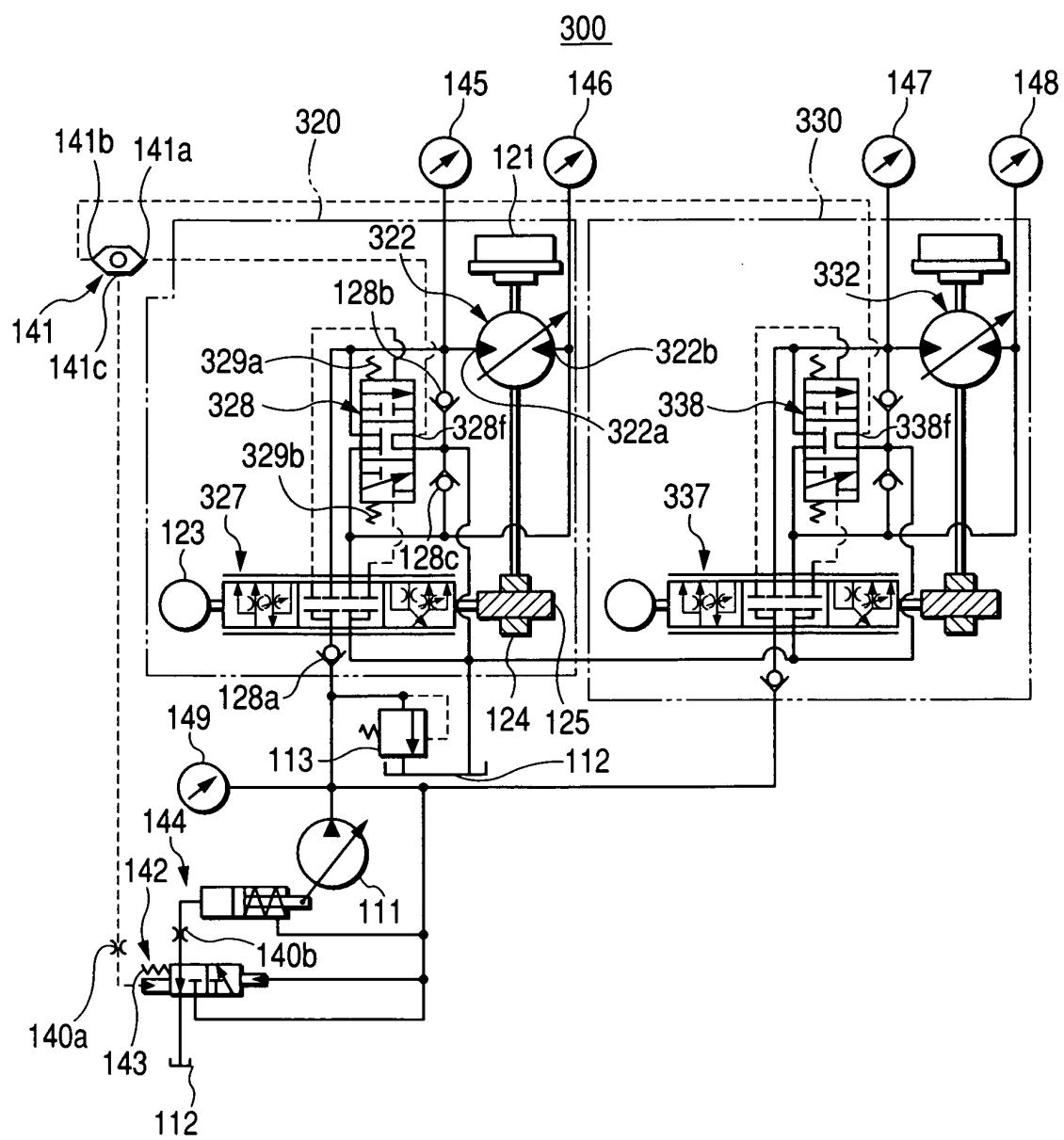


FIG. 9

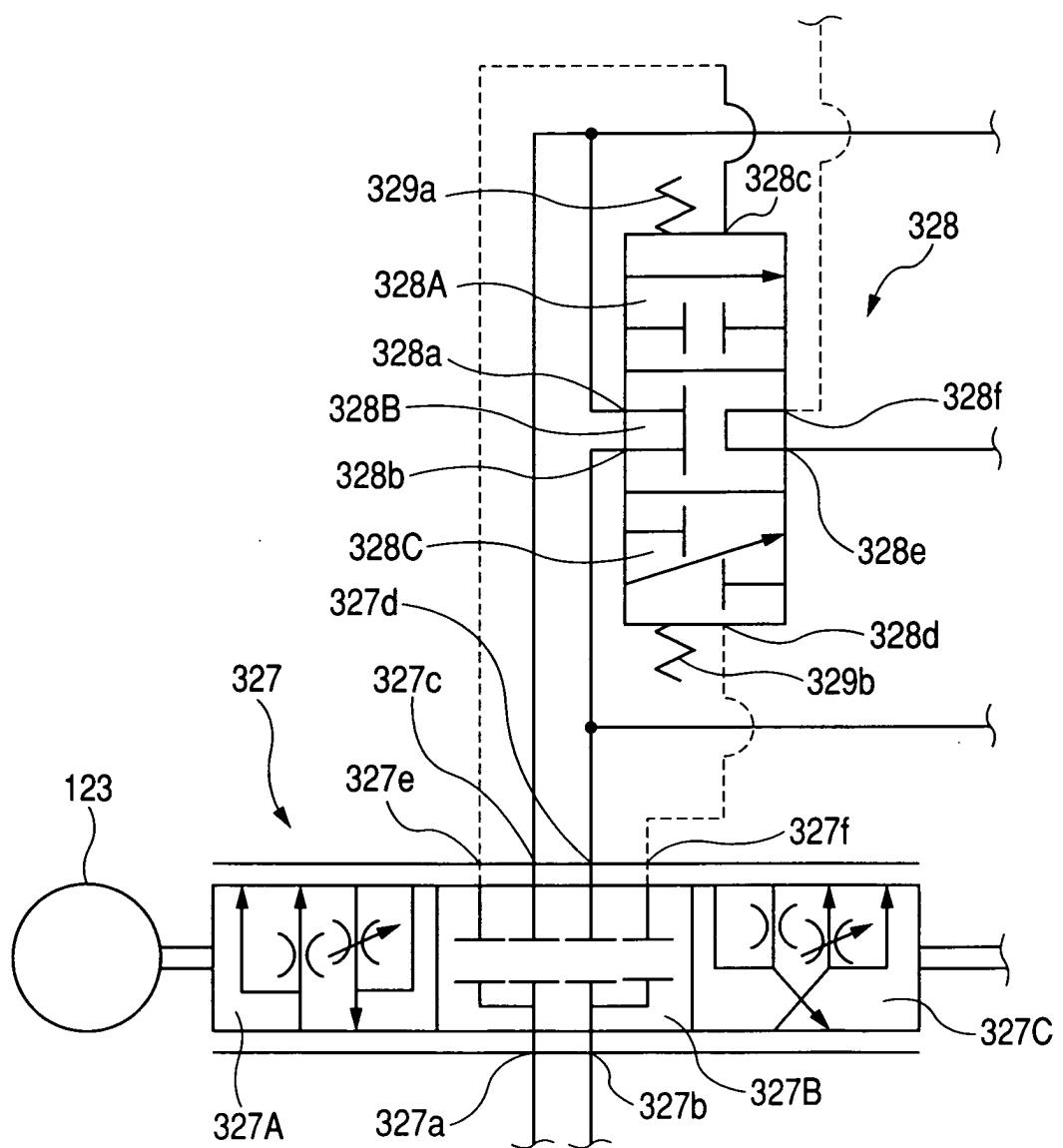


FIG. 10

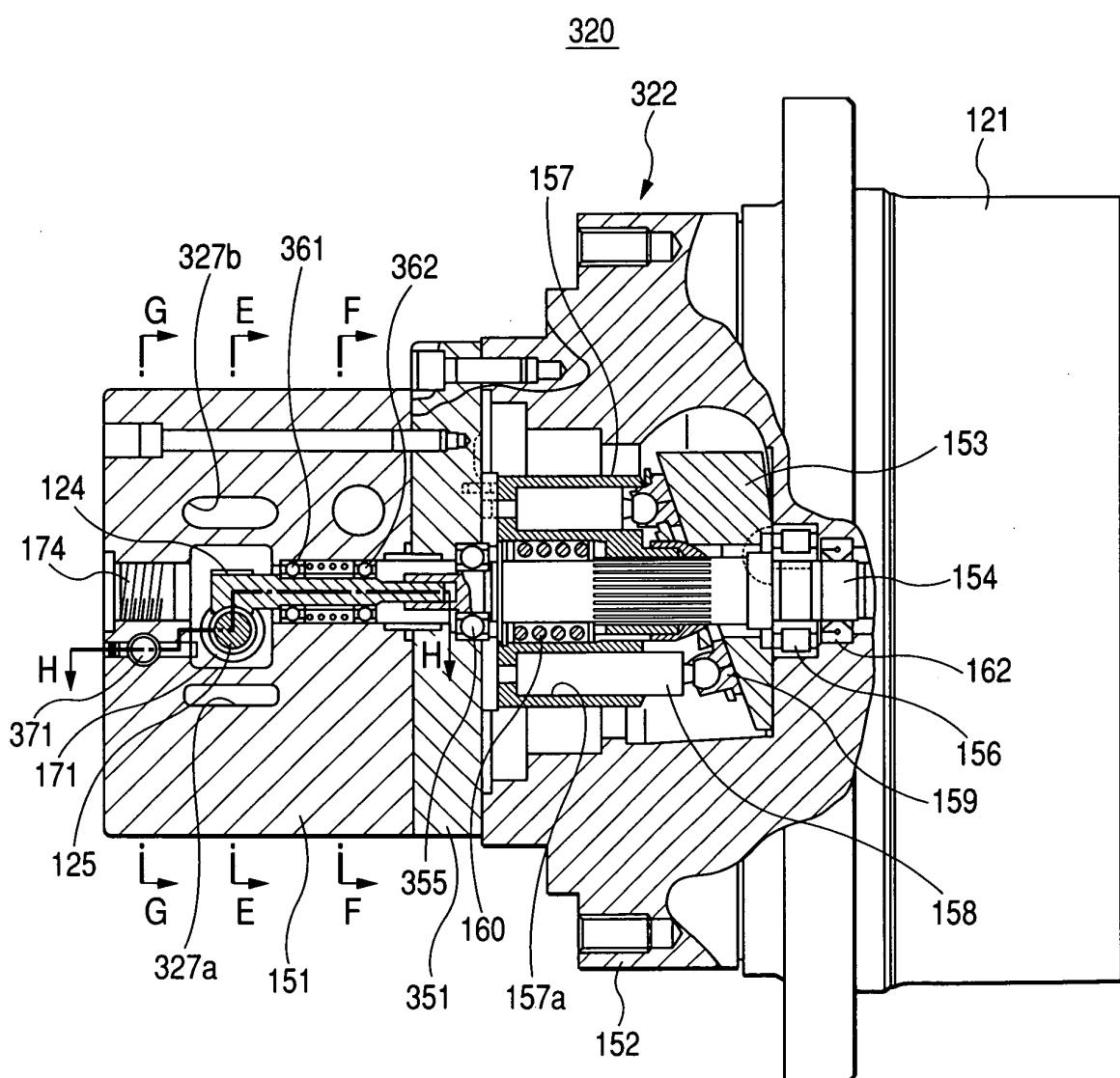


FIG. 11

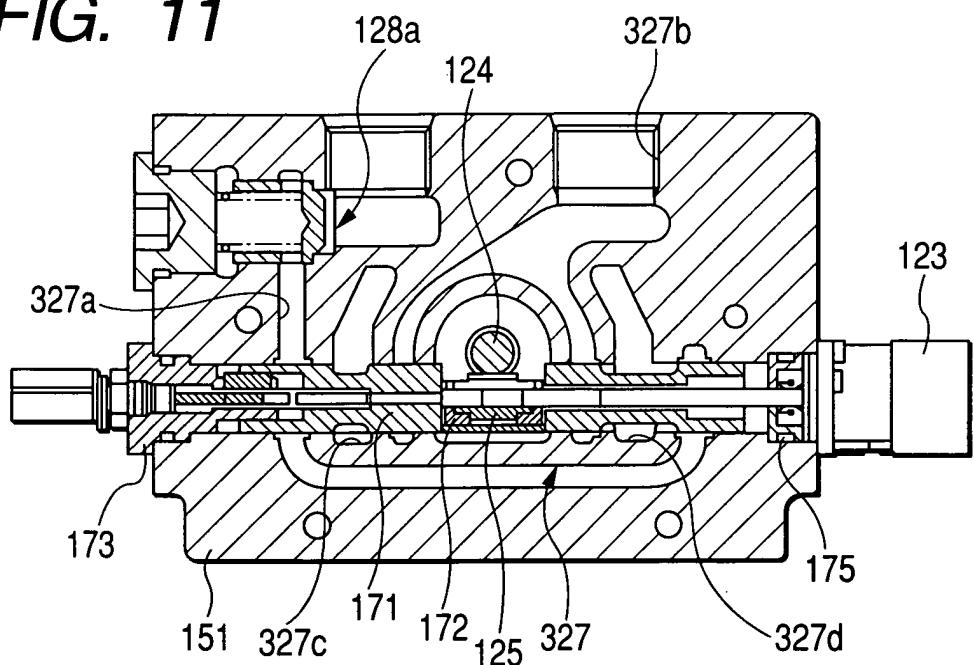


FIG. 12

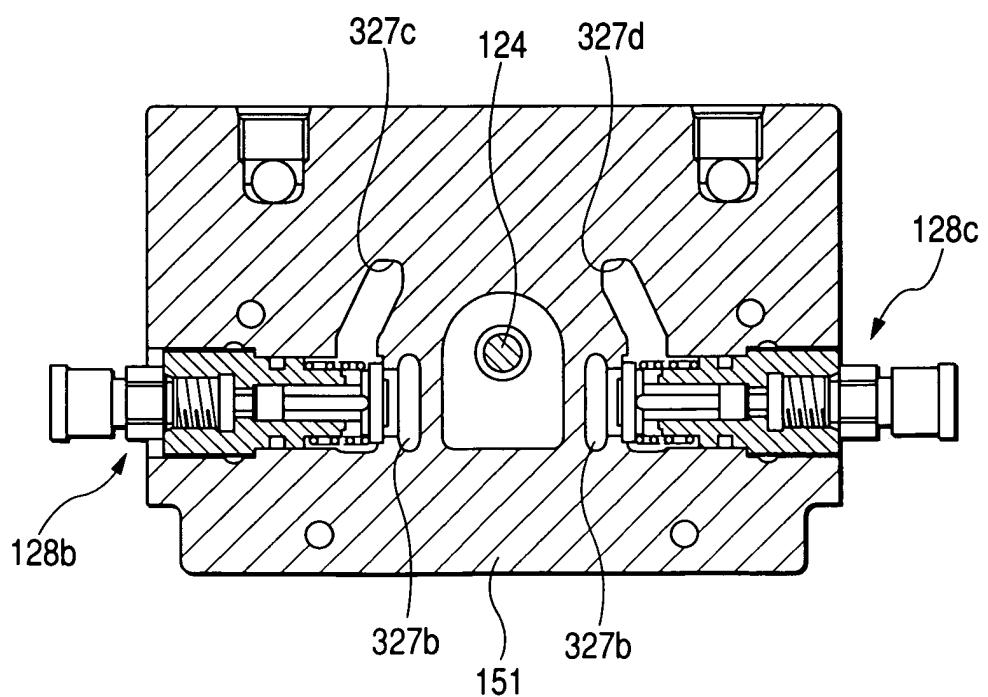


FIG. 13

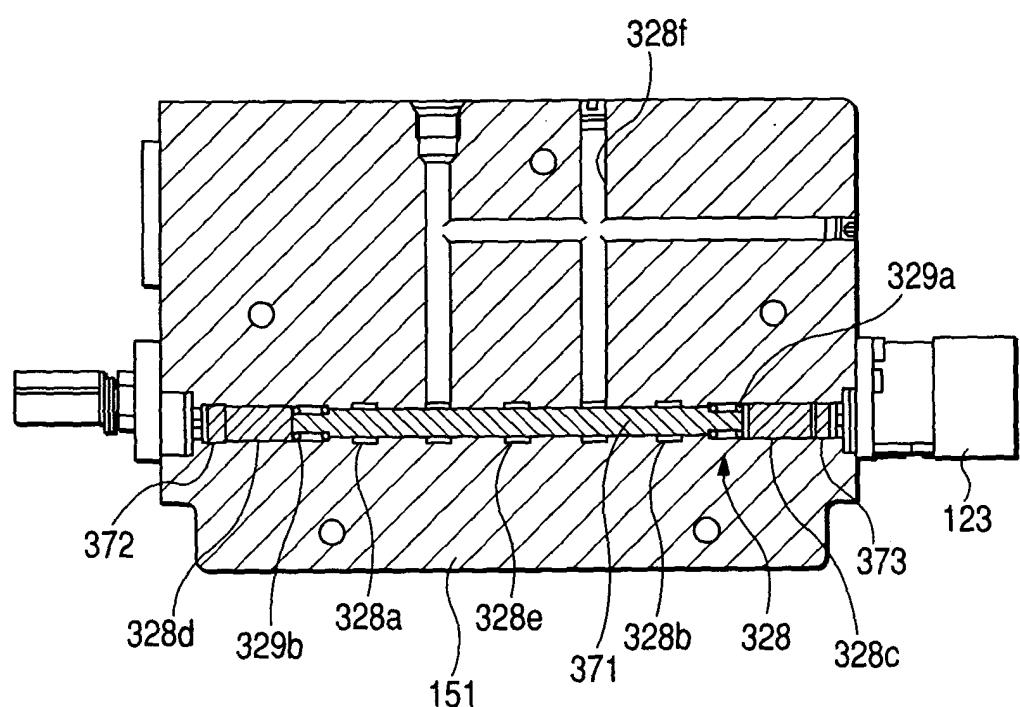


FIG. 14

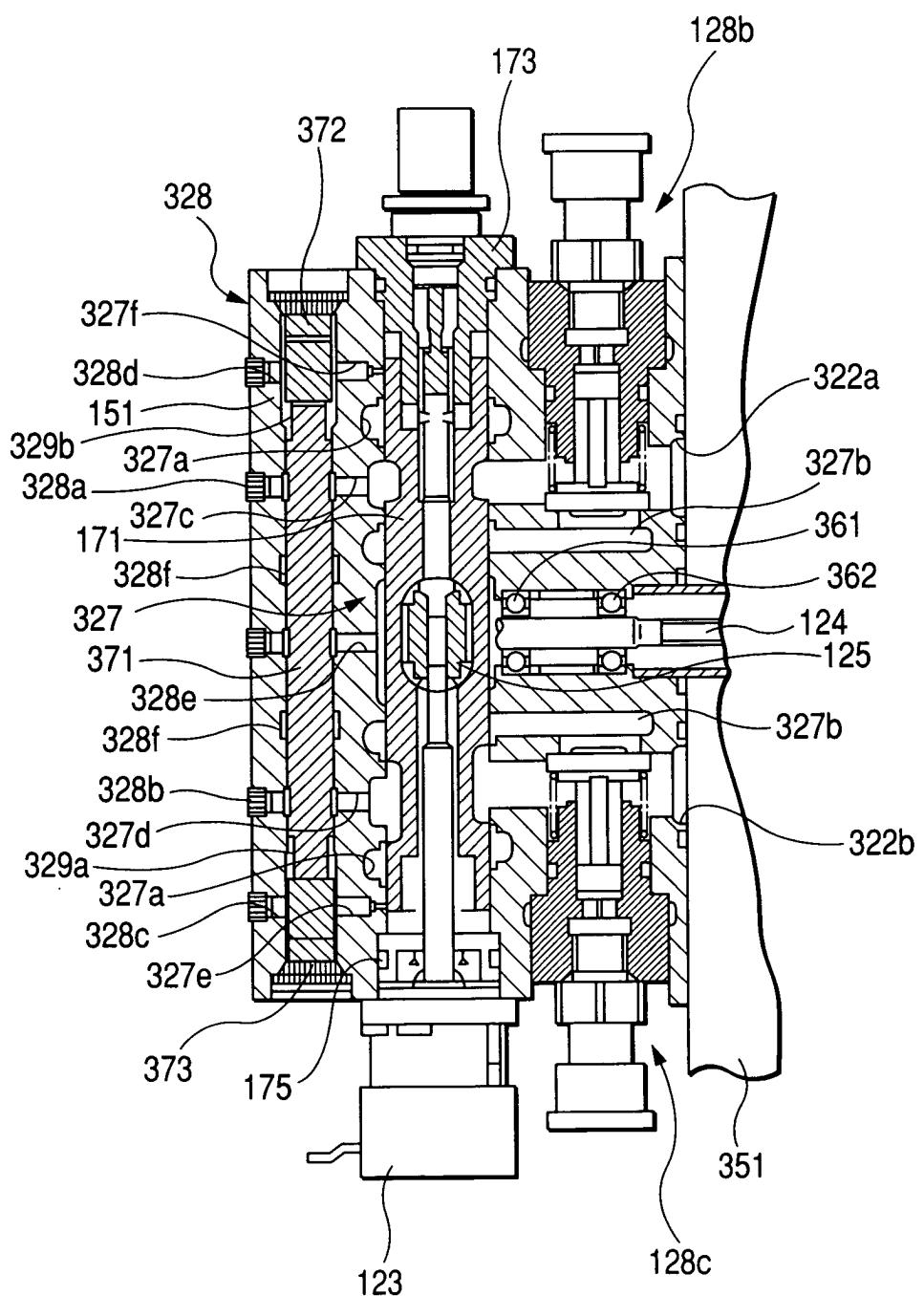


FIG. 15

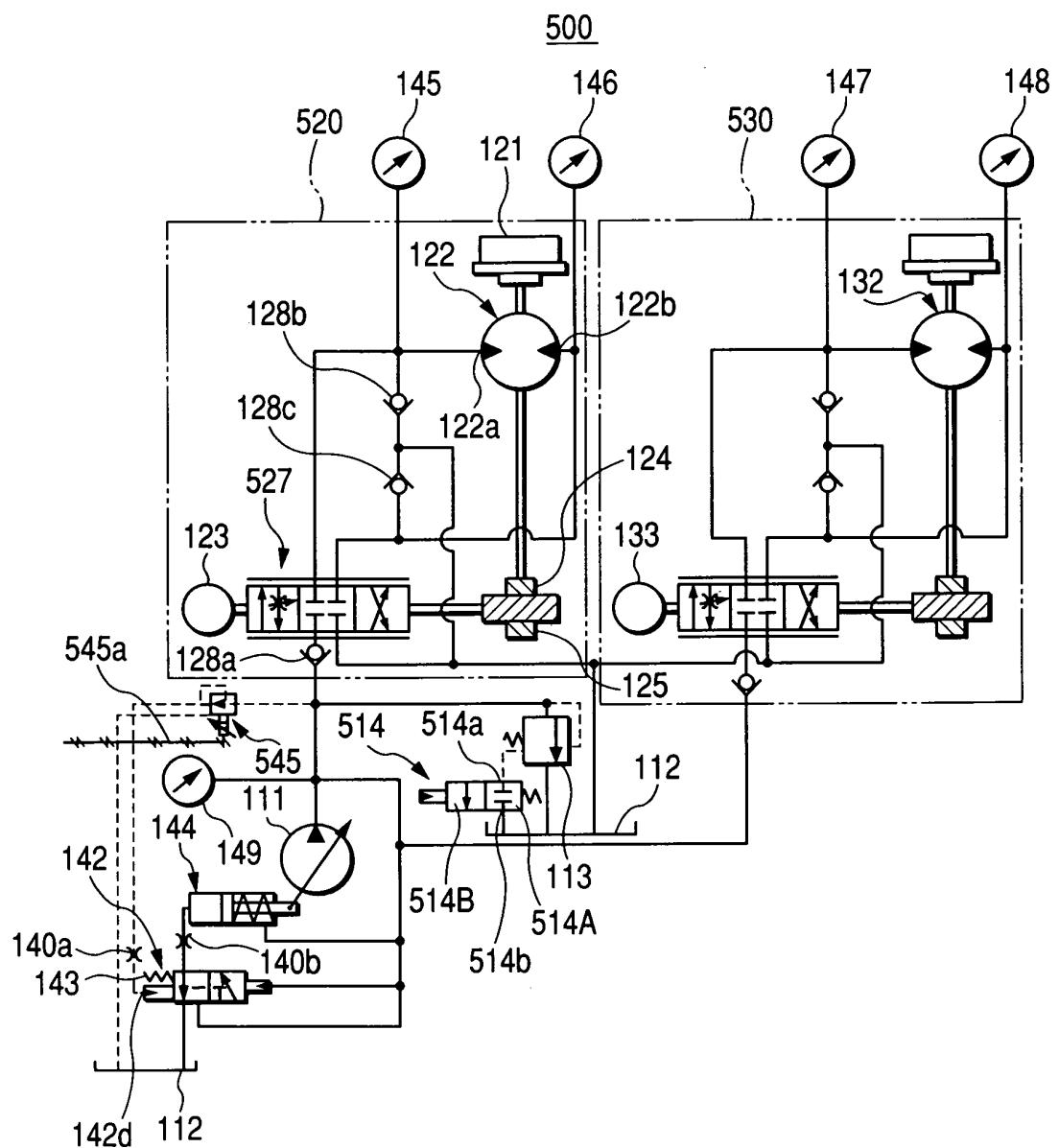


FIG. 16

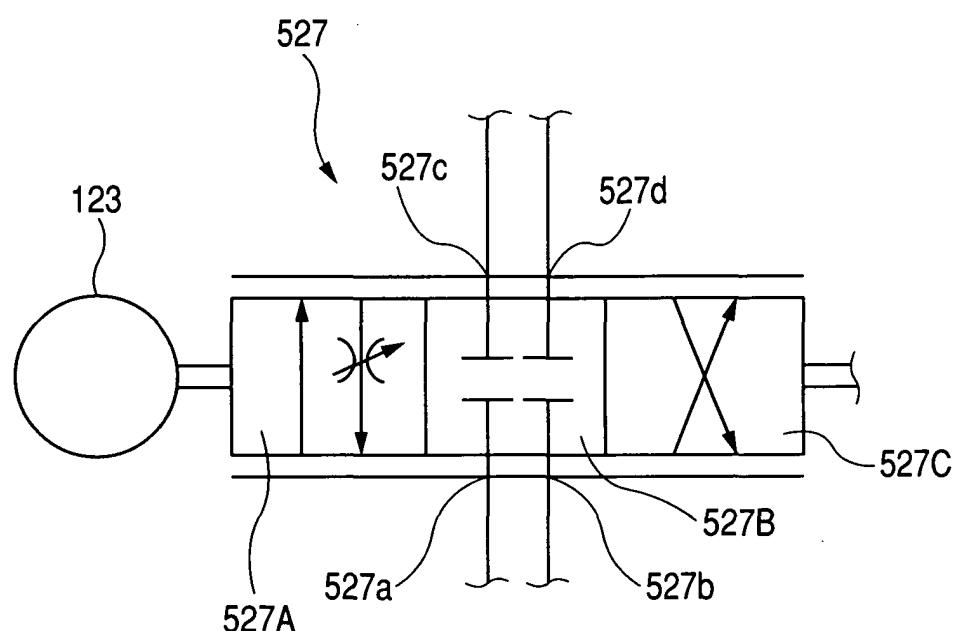


FIG. 17

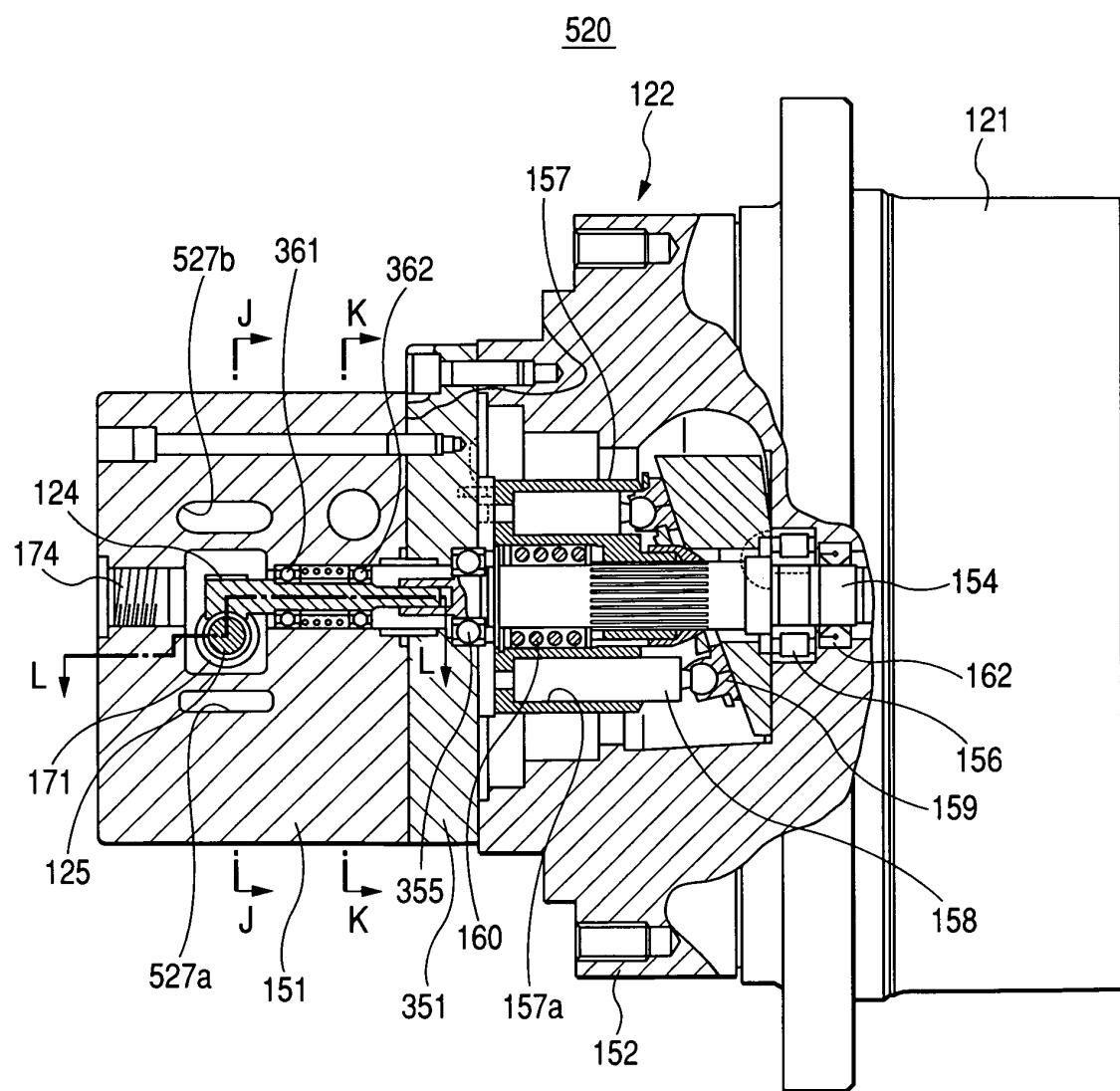


FIG. 18

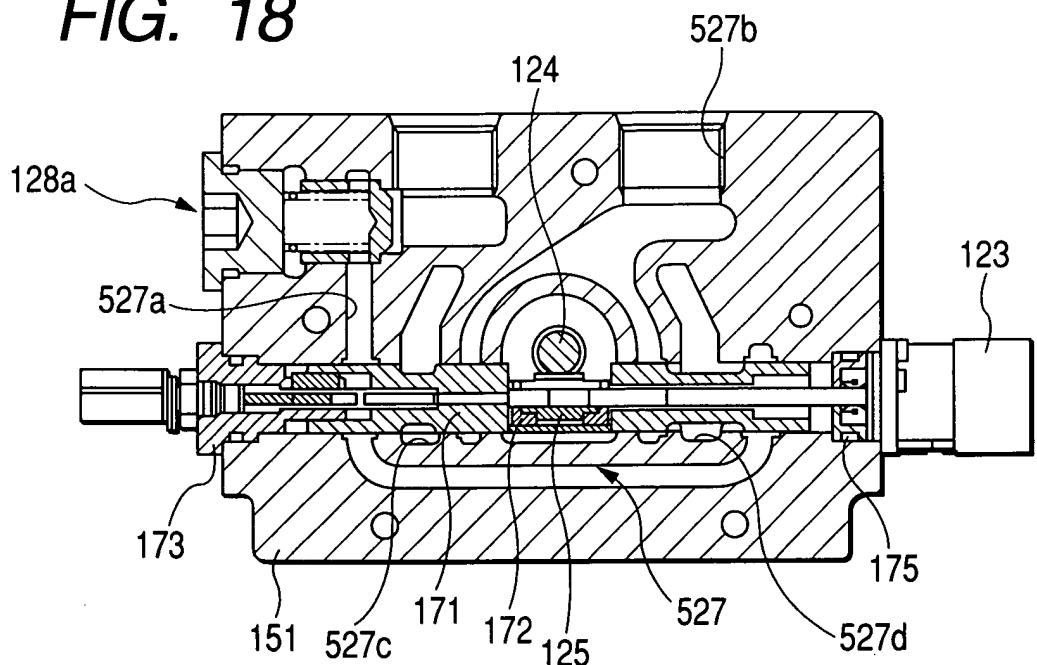


FIG. 19

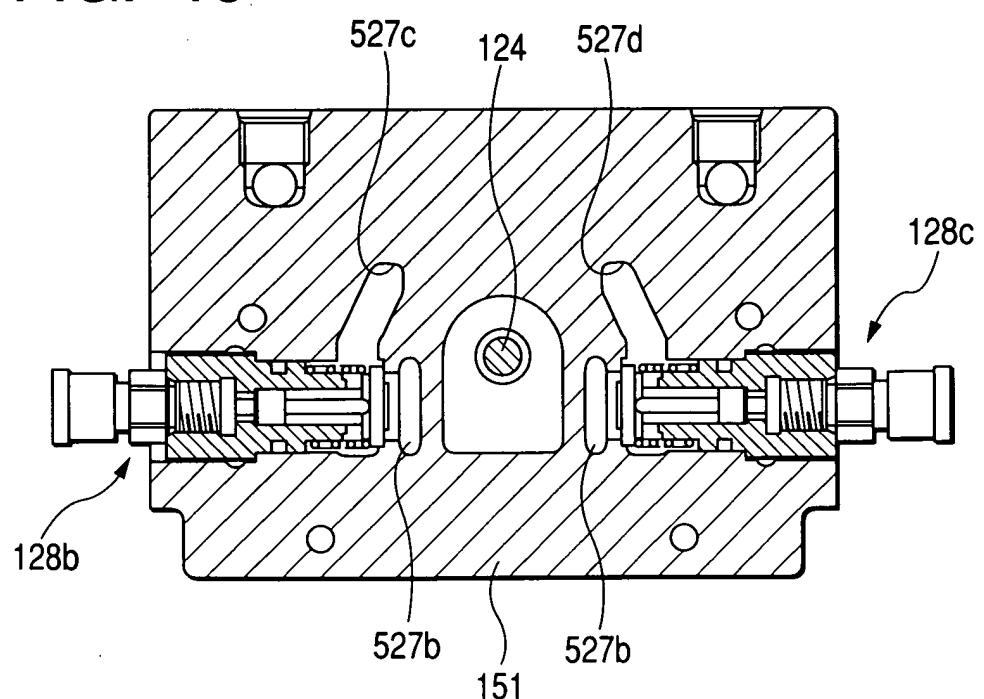


FIG. 20

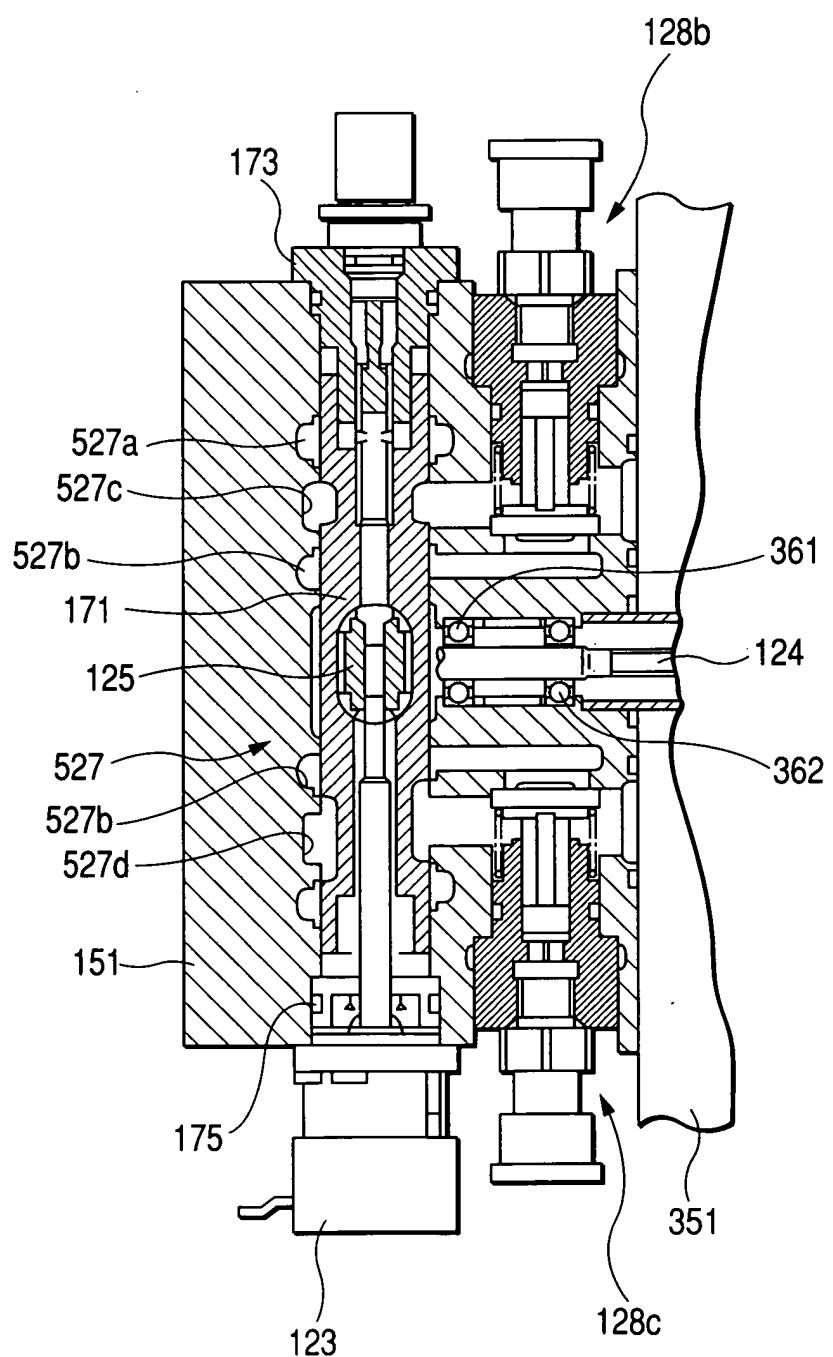


FIG. 21

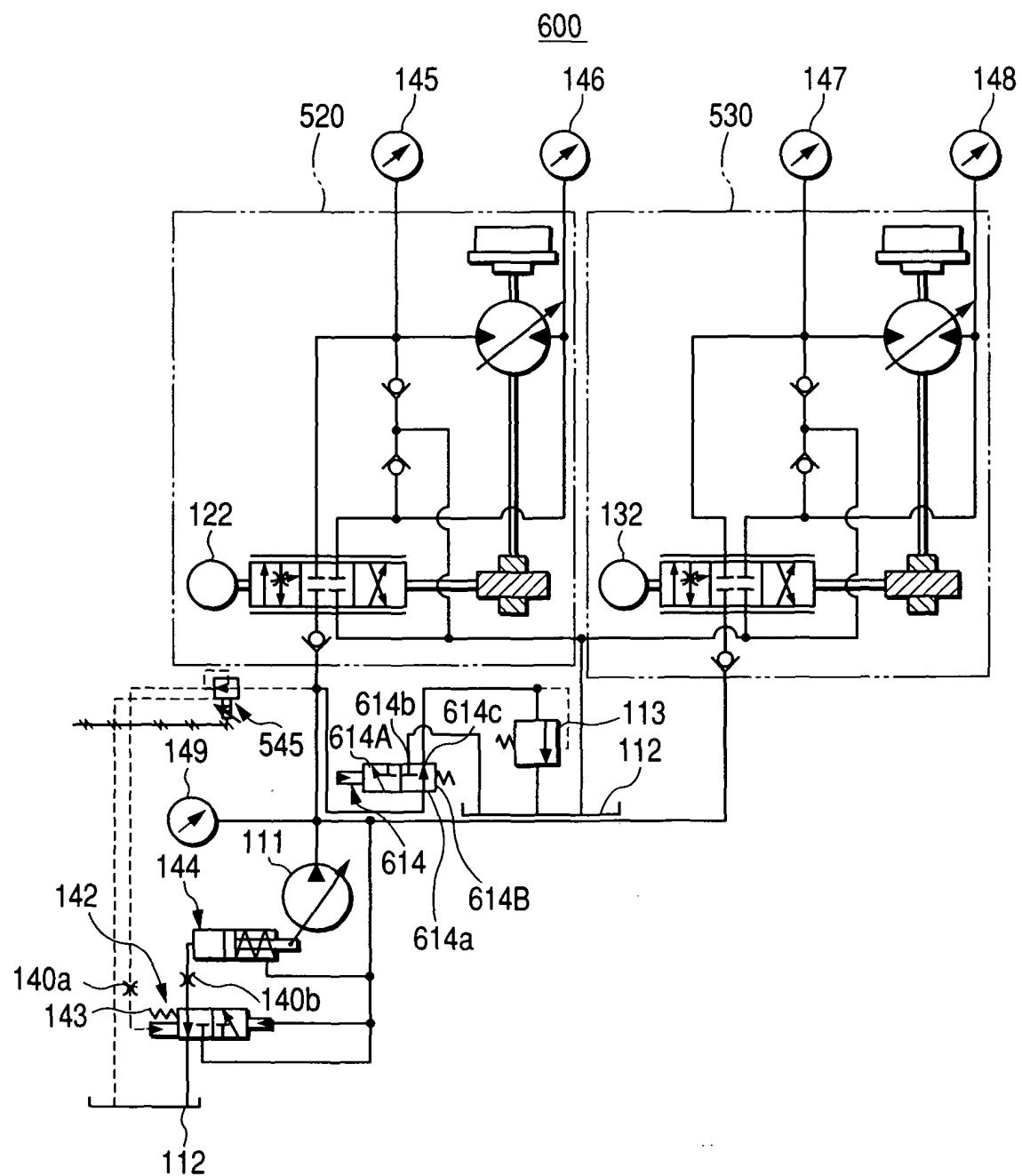


FIG. 22

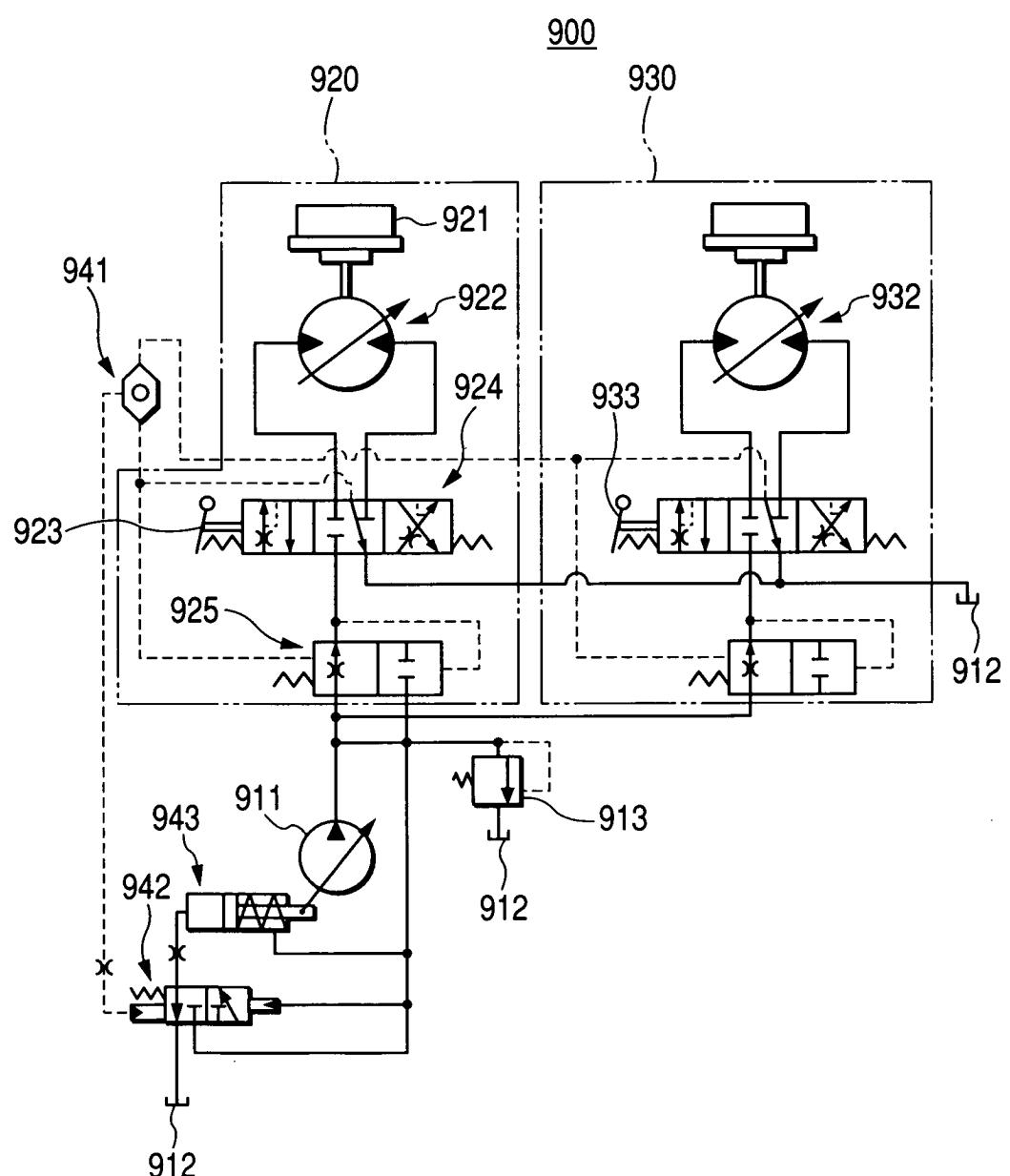
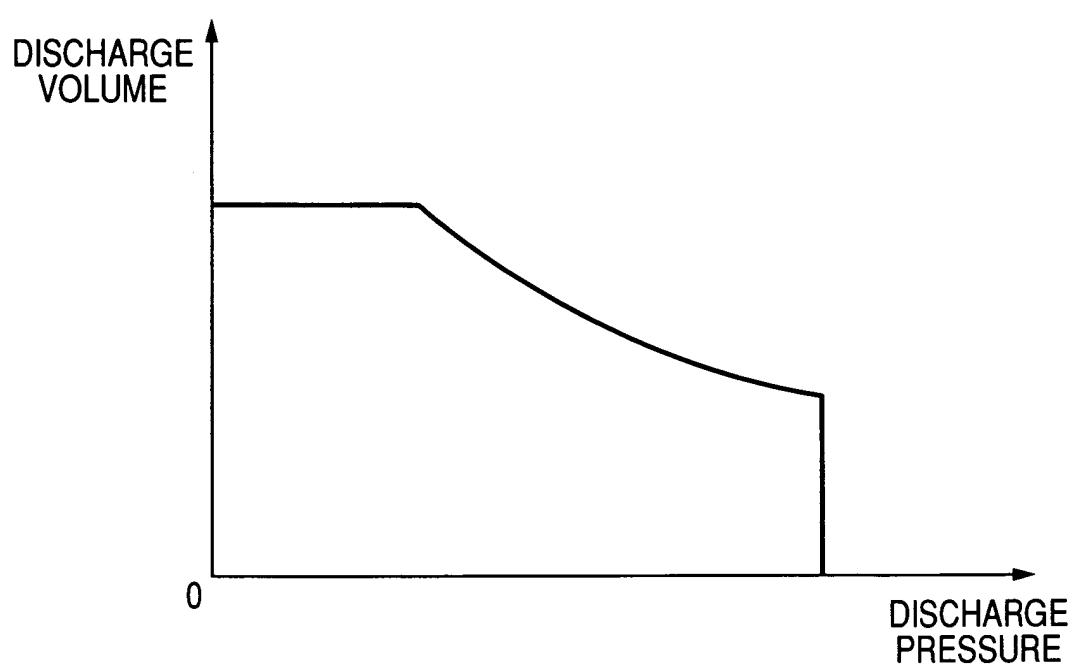


FIG. 23



INTERNATIONAL SEARCH REPORT		International application No. PCT/JP03/08865
A. CLASSIFICATION OF SUBJECT MATTER Int.Cl ⁷ F15B11/00		
According to International Patent Classification (IPC) or to both national classification and IPC		
B. FIELDS SEARCHED Minimum documentation searched (classification system followed by classification symbols) Int.Cl ⁷ F15B11/00		
Documentation searched other than minimum documentation to the extent that such documents are included in the fields searched Jitsuyo Shinan Koho 1926-1996 Toroku Jitsuyo Shinan Koho 1994-2003 Kokai Jitsuyo Shinan Koho 1971-2003 Jitsuyo Shinan Toroku Koho 1996-2003		
Electronic data base consulted during the international search (name of data base and, where practicable, search terms used)		
C. DOCUMENTS CONSIDERED TO BE RELEVANT		
Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
Y	US 5159812 A (REXROTH MANNESMANN GMBH.), 03 November, 1992 (03.11.92), Column 4, line 41 to column 5, line 2 & DE 3943357 A & JP 4-136510 A	1
Y	JP 1-006501 A (Hitachi Construction Machinery Co., Ltd.), 11 January, 1989 (11.01.89), Full text (Family: none)	1
Y	JP 4-290603 A (Kayaba Industry Co., Ltd.), 15 October, 1992 (15.10.92), Column 4, Par. Nos. [0015], [0016] (Family: none)	1
<input checked="" type="checkbox"/> Further documents are listed in the continuation of Box C. <input type="checkbox"/> See patent family annex.		
* Special categories of cited documents: "A" document defining the general state of the art which is not considered to be of particular relevance "E" earlier document but published on or after the international filing date "L" document which may throw doubts on priority claim(s) or which is cited to establish the publication date of another citation or other special reason (as specified) "O" document referring to an oral disclosure, use, exhibition or other means "P" document published prior to the international filing date but later than the priority date claimed		
Date of the actual completion of the international search 08 September, 2003 (08.09.03)		Date of mailing of the international search report 24 September, 2003 (24.09.03)
Name and mailing address of the ISA/ Japanese Patent Office		Authorized officer
Facsimile No.		Telephone No.

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INTERNATIONAL SEARCH REPORT

International application No.
PCT/JP03/08865

C (Continuation). DOCUMENTS CONSIDERED TO BE RELEVANT

Category*	Citation of document, with indication, where appropriate, of the relevant passages	Relevant to claim No.
Y	EP 1092868 A (TEIJIN SEIKI CO., LTD.), 18 April, 2001 (18.04.01), Fig. 1 & US 6439101 A & JP 2001-165102 A	1
Y	JP 2001-65501 A (Teijin Seiki Co., Ltd.), 16 March, 2001 (16.03.01), Figs. 1, 4 (Family: none)	1
A	WO 97/13929 A (CATERPILLAR MITSUBISHI LTD.), 17 April, 1997 (17.04.97), Full text & EP 796952 A	1
A	US 4759183 A (REXROTH MANNESMANN GMBH.), 26 July, 1988 (26.07.88), Full text & DE 3546336 A & FR 2592440 A & JP 62-159802 A	1

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