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(54) Pool cleaning robot

(57) A pool cleaning robot (10) having an axis of symmetry (96) and a weight imbalance across the axis of symmetry. The robot is adapted to propel itself along a trajectory in the direction of the axis of symmetry (96) by

generating a first suction, and alter its trajectory as a result of the imbalance by generating a second suction which is of a lower power than the first suction.

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EUROPEAN SEARCH REPORT

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| Category | Citation of document with i | ndication where appropriate | Relevant | I OLAGOICIOATION OF THE |
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ANNEX TO THE EUROPEAN SEARCH REPORT ON EUROPEAN PATENT APPLICATION NO.

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