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- **KAWAKAMI, Hideo**  
**Osaka 540-6207 (JP)**
- **TSUKADA, Shohei**  
**Osaka 540-6207 (JP)**
- **NAKAMURA, Tohru**  
**Osaka 540-6207 (JP)**

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(71) Applicant: **Panasonic Corporation**  
**Kadoma-shi**  
**Osaka 571-8501 (JP)**

(74) Representative: **Grünecker, Kinkeldey,**  
**Stockmair & Schwanhäusser**  
**Anwaltssozietät**  
**Leopoldstrasse 4**  
**80802 München (DE)**

(72) Inventors:  
• **KUME, Yohei**  
**Osaka 540-6207 (JP)**

(54) **TRAVELING VEHICLE AND BED**

(57) A traveling vehicle (12) is self-propelled and docked in a quadrilateral docking area (20) having an entrance (55) on one side thereof, and includes: a docking point obtainment unit which obtains first to fourth points indicating positions of four corners of the docking area and represented in relative coordinates with respect to a position of the traveling vehicle (12); a reference distance detection unit (35) which obtains a reference distance indicating a distance between the traveling vehicle (12) and the docking area (20); and a movement control unit (33) which controls movement of the traveling vehicle (12) moving to the docking area (20), based on the first and second points when the reference distance  $L_s$  is not shorter than a first correction distance  $N1$ , and based on at least the third and fourth points when the reference distance  $L_s$  is shorter than the first correction distance  $N1$ . The first and second points are located on an entrance (55) side of the docking area, and the third and fourth points are located on a rear side.

