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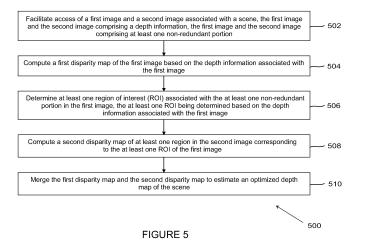
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- (54) Method, apparatus and computer program product for disparity estimation

(57) In an example embodiment, a method, apparatus and computer program product are provided. The method includes facilitating access of a first image and a second image associated with a scene. The first image and the second image includes depth information and at least one non-redundant portion. A first disparity map of the first image is computed based on the depth information associated with the first image. At least one region

of interest (ROI) associated with the at least one nonredundant portion is determined in the first image based on the depth information associated with the first image. A second disparity map of at least one region in the second image corresponding to the at least one ROI of the first image is computed. The first disparity map and the second disparity map are merged to estimate an optimized depth map of the scene.





EUROPEAN SEARCH REPORT

Application Number EP 14 19 2745

Category	Citation of document with in of relevant passa	ndication, where appropriate, ages	Relevant to claim	CLASSIFICATION OF THE APPLICATION (IPC)
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	XP002635672, * sections 2.1, 2.2	e and 3.1 *		TECHNICAL FIELDS SEARCHED (IPC)
	The present search report has	peen drawn up for all claims	-	
	Place of search	Date of completion of the search		Examiner
	The Hague	9 July 2015	ly 2015 Mikul	
CATEGORY OF CITED DOCUMENTS X: particularly relevant if taken alone Y: particularly relevant if combined with another document of the same category		T : theory or princip E : earlier patent do after the filing da her D : dooument cited	T: theory or principle underlying the invention E: earlier patent document, but published on, or after the filing date D: document cited in the application L: document cited for other reasons	

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ANNEX TO THE EUROPEAN SEARCH REPORT ON EUROPEAN PATENT APPLICATION NO.

EP 14 19 2745

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